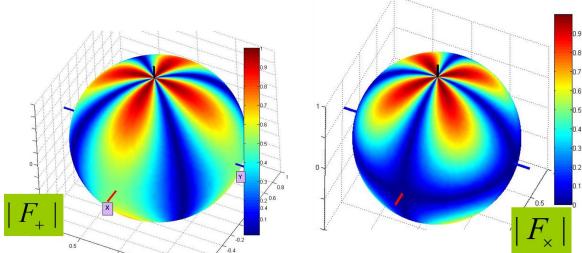
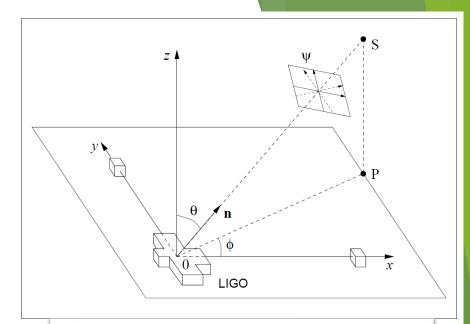
Lab Topic 2

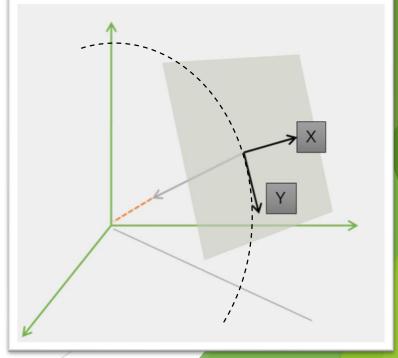
#### **Antenna Patterns for LIGO**

- Long wavelength and static detector approximation
- Write a code to calculate  $F_+$  and  $F_\times$  in an interferometer's local frame for input source direction
  - **Source direction:**  $(\theta, \phi)$  in detector frame
  - Plot them on a sphere using the GWSIG/skyplot.m function

► **Use burst convention:** Should agree with the pictures in the lecture slides

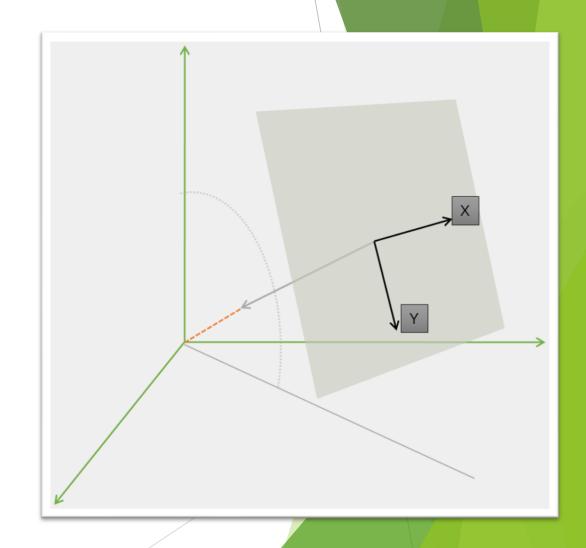






## Obtaining wave tensor

- Use the expression for (a) polarization tensors, (b) Detector tensor, and (c) Contraction of polarization and detector tensors
- Use vector cross products (all vector components in detector frame):
  - Use GWSIG/vcrossprod.m
  - ▶ Detector frame  $\hat{Z} = (0,0,1)$
  - Source direction in detector frame (for polar angles  $\theta$  and  $\phi$ ):  $\hat{n}$
  - ▶ Wave frame  $\hat{x} \propto \hat{Z} \times \hat{n}$  (Note: must normalize)
  - ▶ Wave frame  $\hat{y} = \hat{x} \times \hat{n}$
- ▶ If x and y are row matrices in Matlab:
  - $\triangleright$  x' is the transpose of x (Column matrix)
  - $\triangleright x' * y$  is the same as  $x \otimes y$



# Strain signal

Detector tensor:

$$\overrightarrow{D} = \frac{1}{2} (\widehat{n}_X \otimes \widehat{n}_X - \widehat{n}_Y \otimes \widehat{n}_Y)$$

Wave tensor:

$$\overrightarrow{W} = h_{+}(t) \overrightarrow{e}_{+} + h_{\times}(t) \overrightarrow{e}_{\times}$$

$$\overrightarrow{e}_{+} = \widehat{x} \otimes \widehat{x} - \widehat{y} \otimes \widehat{y}; \quad \overrightarrow{e}_{\times} = \widehat{x} \otimes \widehat{y} + \widehat{y} \otimes \widehat{x}$$

Matlab can calculate direct product:

Matlab

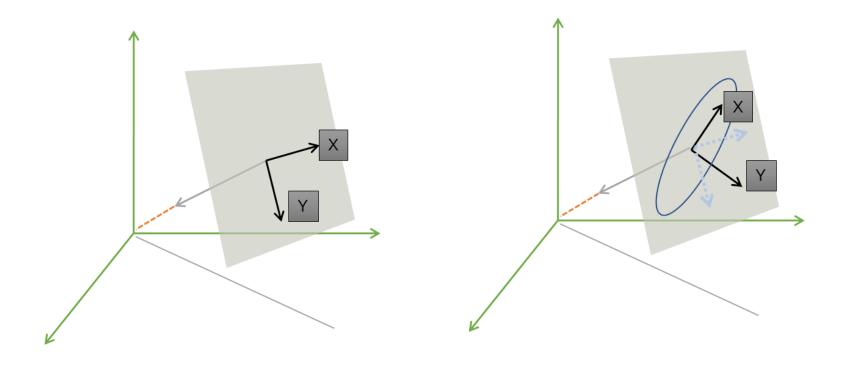
$$\underbrace{a = \begin{bmatrix} a_1, & a_2, & a_3 \end{bmatrix}}_{b = \begin{bmatrix} b_1, & b_2, & b_3 \end{bmatrix}} \rightarrow \underbrace{a' * b}_{Matlab} \rightarrow \widehat{a} \otimes \widehat{b} = \begin{pmatrix} a_1 \\ a_2 \\ a_3 \end{pmatrix} (b_1 \quad b_2 \quad b_3) = \begin{bmatrix} a_1b_1 & a_1b_2 & a_1b_3 \\ a_2b_1 & a_2b_2 & a_2b_3 \\ a_3b_1 & a_3b_2 & a_3b_3 \end{bmatrix}$$

Strain signal: "Contraction of wave and detector tensors"

$$s(t) = \sum_{i,j=1}^{3} W_{ij} D_{ij} = W^{ij} D_{ij} = \overrightarrow{W} : \overrightarrow{D}$$

$$\rightarrow \text{sum}(W(:) * D(:))$$

To use the above formula, all unit vector components must be written down in the same reference frame



### Wave frame conventions

Include rotation due to polarization angle into the polarization tensors

# Strain signal from a non-evolving binary

Use the sinusoidal signal generation function to generate

$$h_{+}(t) = A \sin(2\pi f_0 t)$$
  
$$h_{\times}(t) = B \sin(2\pi f_0 t + \phi_0)$$

- Pick your own values of  $A, B, f_0, \phi_0$  (Respect Nyquist theorem!)
- Plot the strain signal for different values of  $\theta$ ,  $\phi$ , and  $\psi$

# General strain signal for a static interferometer

- Write a function:
  - ► Inputs:
    - $\triangleright h_+$  and  $h_\times$  time series
    - $\triangleright \theta, \phi$
  - Output:
    - ► Strain signal

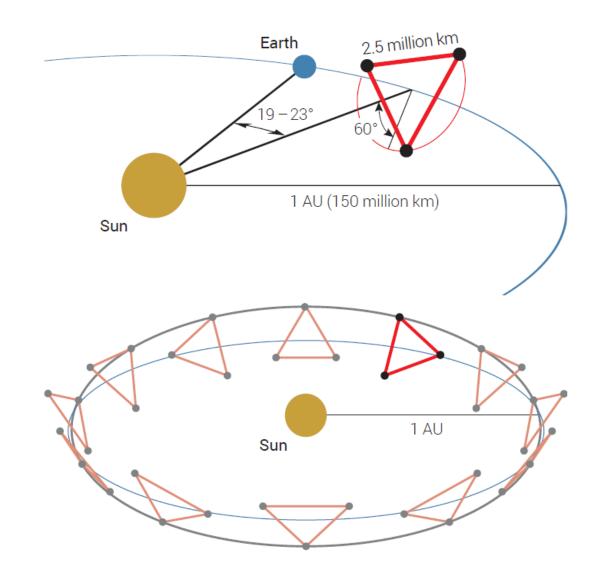
# Antenna patterns for LISA

## Toy LISA

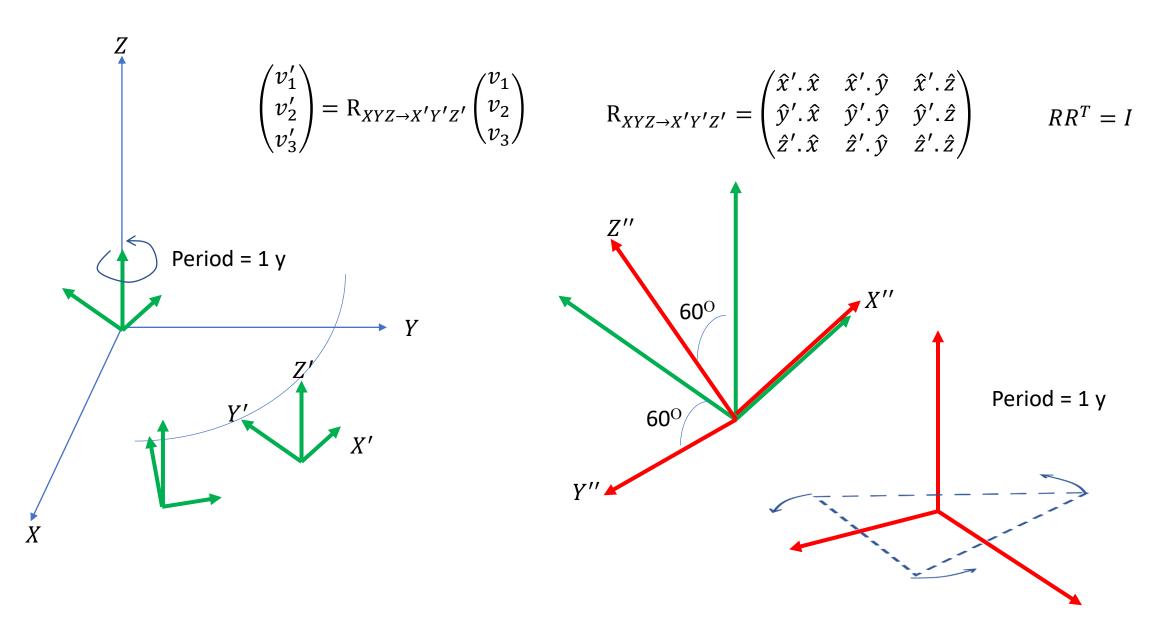
- Rigid equilateral triangle formation of three satellites
- Actual LISA cannot be rigid because the satellites must follow Keplerian orbits
- ► Toy LISA is good for practicing data analysis because it allows fast generation of signals and templates
- ► However, Mock LISA Challenge Data requires more accurate LISA models

# Reference frames and rotations needed

- We need to find the components of LISA arm vectors in the Solar System Barycentric (SSB) frame
- Get the detector tensor from the arm vectors
- The wave tensor will be written as usual (e.g., detector local frame) in the SSB
- Do contractions to get antenna pattern functions
- Introduce time delay: light travel travel time between the SSB and LISA centroid



# Obtain the arm components in the SSB frame



## Antenna patterns

- ► Use the expressions in Sec IIIB of the paper arXiv:1207.4956v1 to obtain the detector tensors for the two Michelson TDI combinations
- Obtain the antenna patterns for each TDI combination by contracting each polarization tensor with the respective detector tensor
- Write a code:
  - ► Inputs: Source direction, time instant
  - ► Outputs: F\_+, F\_x for each TDI combination

#### To do

- Generate h\_+, h\_x that are sinusoidal
- Assume some sky location and polarization angle for the GW source
- Generate the detector response of LISA (no doppler shift included)
- ► Take FFT of the detector response and compare to the FFT of h\_+

# LISA response

- LISA antenna pattern generation
  - ▶ Use detector tensors from arXiv:1207, Sec III.B (one TDI combination only)
- ► LISA detector response including doppler shift
  - $h_{+,\times}(t) \to h_{+,\times}(t \frac{\hat{n}.\bar{x}_d}{c})$
  - $\triangleright$   $\hat{n}$ : Wave propagation direction
  - $ightharpoonup \bar{x}_d(t)$ : LISA centroid
- Plot LISA response for a monochromatic source
  - $h_{+}(t) = A \sin(\omega_{0}t); h_{\times}(t) = \left(\frac{A}{2}\right) \cos \omega_{0}t$
  - One parameter missing: polarization angle (but we will ignore it)
  - $\blacktriangleright$  Compare FFT of the response to that of  $h_+(t)$

# Doppler shifts

# Detector response: Moving detector

- Detector located at  $\bar{x}_d$  in the plane GW wave field
- ► Response:  $s(t) = W_{ij}D^{ij} = F_+(\hat{n})h_+(\omega t \bar{k}.\bar{x}_d) + F_\times(\hat{n})h_\times(\omega t \bar{k}.\bar{x}_d)$
- $\hat{n}$ : Direction to GW source
- For a moving detector,  $\bar{x}_d$  is a function of time

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### To do

- Write a code to calculate the position vector of the LISA centroid
- ► Take the same GW sinusoidal signals as before and calculate the two TDI responses but including the doppler shifts this time.

# Direction determination

# Effect of sky location

- ► Take the same h\_+, h\_x but at different sky locations and see that the waveforms differ.
- ► This allows LISA to acquire directionality for long-lived sources.