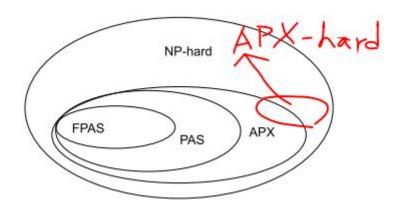
## PTAS, FPTAS, FPRAS and APX

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## Definition (Approximation Scheme)

An algorithm is an approximation scheme for a minimization (resp. maximization) problem if, given some error parameter  $\epsilon>0$ , it acts as a  $(1+\epsilon)$ -approximation algorithm (resp.  $(1-\epsilon)$ -approximation algorithm).

## Definition (Polynomial Time Approximation Scheme - PTAS)

An approximation scheme is a polynomial time approximation scheme, if for each fixed  $\epsilon>0$ , the running time is bounded by a polynomial in the size of the problem instance I.

For example, an approximation scheme with running time

- $O(|I|^{1/\epsilon})$ : a PTAS,
- $O(|I|^2 \cdot (1/\epsilon)^3)$ : a PTAS,
- $O(2^{|I|} \cdot (1/\epsilon)^3)$ : not a PTAS.

### Definition (Polynomial Time Approximation Scheme - PTAS)

An approximation scheme is a polynomial time approximation scheme, if for each fixed  $\epsilon > 0$ , the running time is bounded by a polynomial in the size of the problem instance I.

### Definition (Fully Polynomial Time Approximation Scheme - FPTAS)

A fully polynomial time approximation scheme is a PTAS with the modied constraint that the running time is bounded by a polynomial in the size of the problem instance I and  $1/\epsilon$ .

For example, an approximation scheme with running time

- $O(|I|^{1/\epsilon})$ : a PTAS, but not an FPTAS,
- $O(|I|^2 \cdot (1/\epsilon)^3)$ : a PTAS, and also an FPTAS.

### Randomness

### Definition (Polynomial Randomized Approximation Scheme - PRAS)

For cost metric c, an algorithm A is a polynomial randomized approximation scheme if

- ullet For any  $\epsilon>0$ ,  $\Pr[|c(A(I)-c(OPT(I))|\leq \epsilon\cdot c(OPT(I))]>1/2$ ,
- A runs in poly(|I|).

# Definition (Fully Polynomial Randomized Approximation Scheme - FPRAS)

For cost metric c, an algorithm A is a fully polynomial randomized approximation scheme if

- For any  $\epsilon > 0$ ,  $\Pr[|c(A(I) c(OPT(I))| \le \epsilon \cdot c(OPT(I))] > 1/2$ ,
- A runs in  $poly(|I|, 1/\epsilon)$ .

### Definition (Polynomial Time Approximation Scheme - PTAS)

An approximation scheme is a polynomial time approximation scheme, if for each fixed  $\epsilon > 0$ , the running time is bounded by a polynomial in the size of the problem instance I.

### Definition (APX)

APX: class of problems for which approximation algorithms exist with a constant approximation ratio.

### Remark

- APX is different from the PTAS / FPTAS setting where we can get arbitrarily good approximations.
- Problems with an (F)PTAS are in APX.
- For example, Minimum Vertex Cover Problem is in APX because it has a 2-approximation algorithm. (Find a maximal matching and collect all endpoints of these edges.)

### Definition (APX, APX-hard and APX-complete)

- APX: class of problems for which approximation algorithms exist with a constant approximation ratio.
- APX-hard: class of problems for which there is a constant c such that it is NP-hard to find an approximation algorithm with approximation ratio better than c.
- APX-complete: problems that are APX-hard and also in APX .

#### Remark

APX-hard problems do not admit PTAS.

