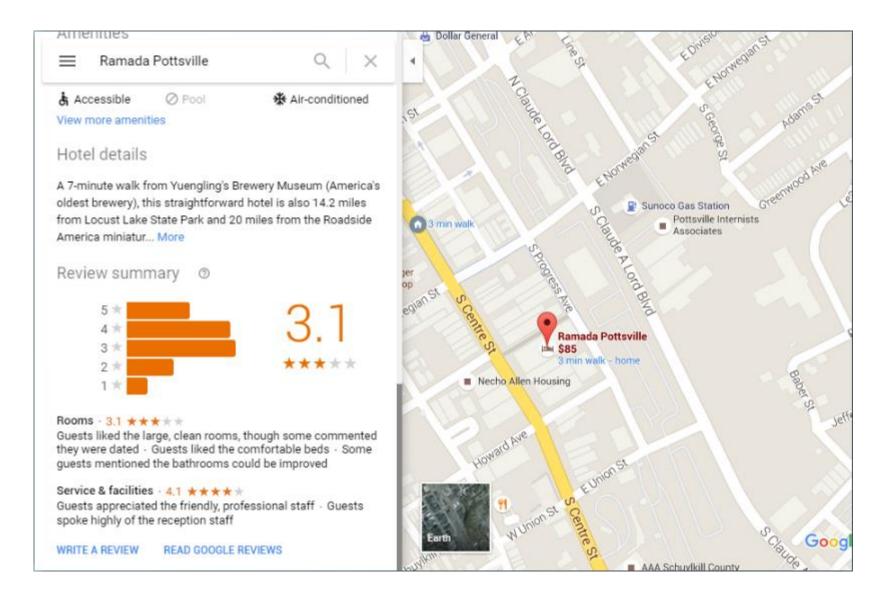
Peer Prediction on Peer Grading System

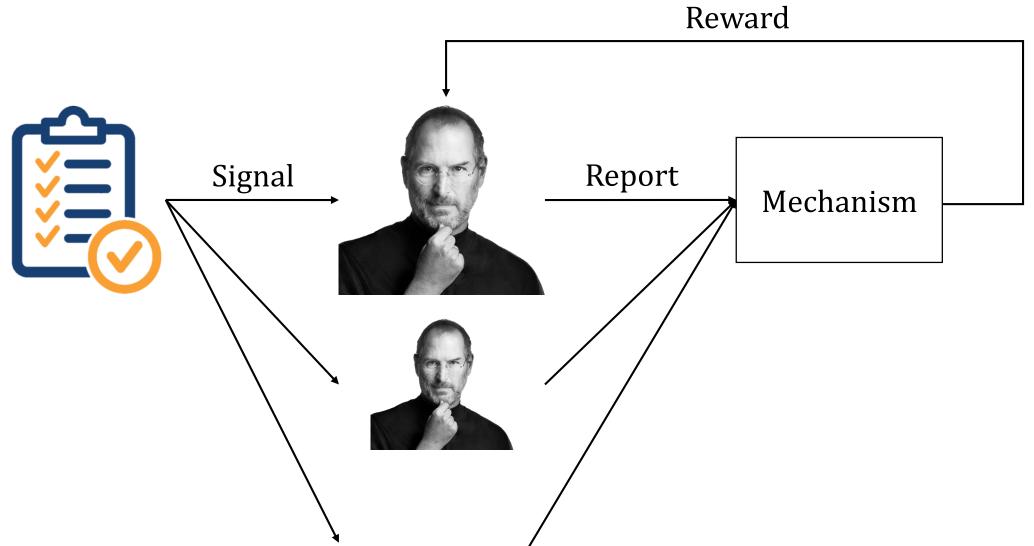
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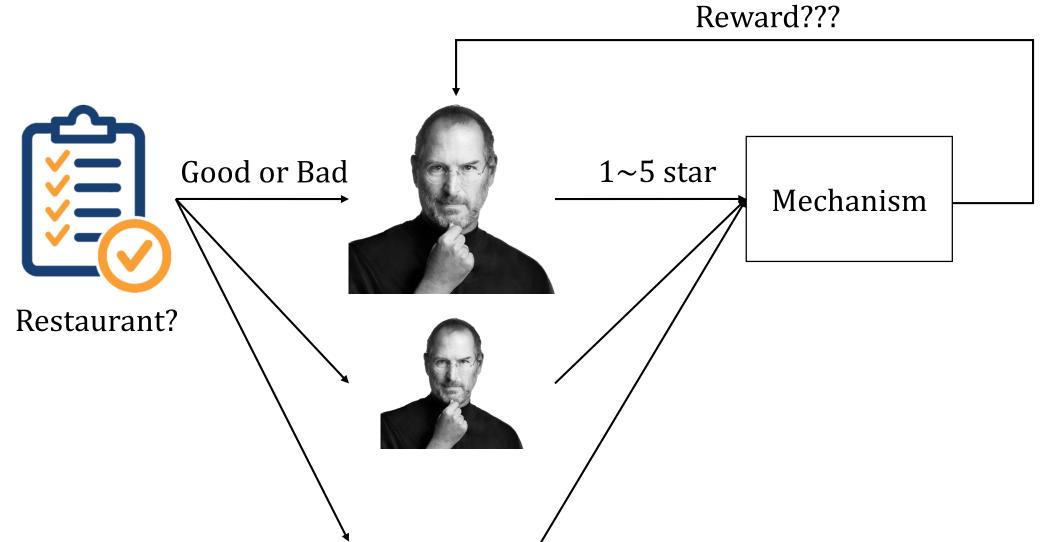
Outline

- Peer Prediction
- Previous Work
- Peer Grading Re-model
- Truthfulness
- Conclusion
- Reference



- Ask participants for feedback on questions
 - Elicit information without verification
- Example:
 - Peer-grading
 - Labeling in a machine learning task
- Encourage truthfulness and efforts

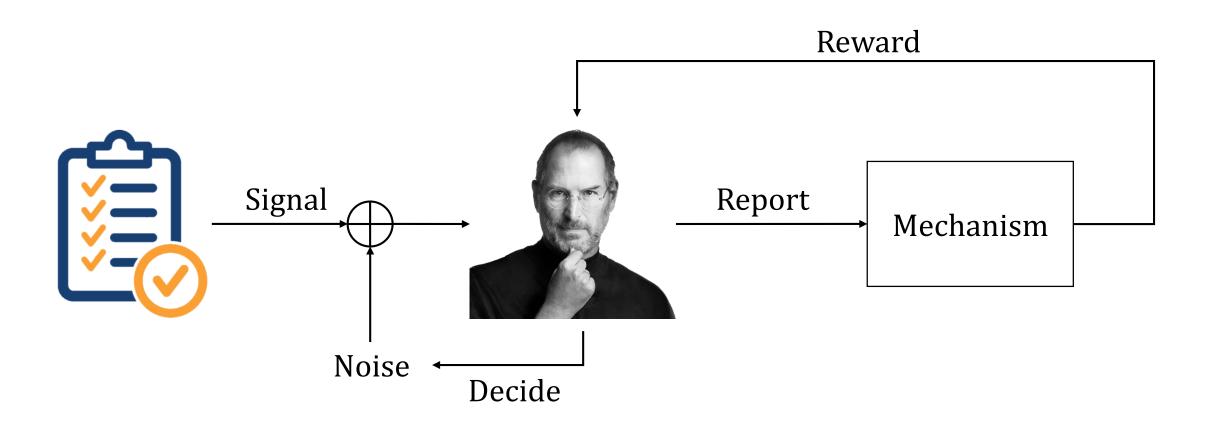




Previous Work

- Shao-Heng Ko [2017]
 - Peer Grading
 - Encouraging Conditions
 - ⇒ At least one pure Nash equilibrium
 - Homogeneous
 - \Rightarrow pure Nash $\{t_1^*, t_2^*, ..., t_N^*\}, t_1^* = t_2^* = \cdots = t_N^*$

- Agents: $a_0, a_1, ..., a_n$
- Signals: $(s_0, s_1, ..., s_n) \sim S$
- Noise: ϵ_i , $\forall i \in [0, n]$
 - Mean = 0, variance = σ_i^2
 - Independent
 - No-bias
 - Effort time $t_i \ \widehat{1} \Rightarrow \sigma_i \ \overline{\downarrow}$
- Received Signal = $s_i + \epsilon_i$ = Report r_i
 - Always Truthful



- Mechanism
 - Each agent is paired with another agent randomly
 - Difference in reports $\hat{1} \Rightarrow \text{Reward } \emptyset$
 - Mean Square Error:

$$E\left[\left(r_i-r_j\right)^2\right]$$

• Expected Utility:

$$U_i = U - C_i - f(t_i)$$

- *U*: constant
- *C_i*: report difference
- $f(t_i)$: effort cost
- $\max U_i$
 - Unrelated to others ⇒ **Dominant Strategy**
 - If σ , f are homogeneous to every agent $\Rightarrow t_0^* = t_1^* = \dots = t_n^*$

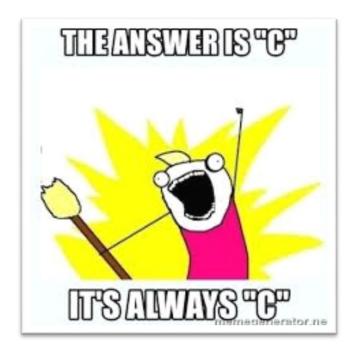
- Encouraging Condition
 - (0) EC-1
 - Suppose $\sigma_i(t_i)$ is positive, convex, decreasing
 - (X) EC-2
- Encourage efforts?
 - Suppose $f(t_i) = k \cdot t_i$
 - Effort cost ratio $k \Downarrow \Rightarrow$ effort time $t_i \Lsh$

What's the difference

	Shao-Heng Ko [2017]	This Work
Signal Distribution	$F_p(v_i, t_j^i)$	$s_i + \epsilon_i$
Encouraging Conditions	Yes	No
Settings	Gaussian Distributions	ϵ_i is independent

- What's the same
 - Pure Nash Equilibrium exists
 - homogeneous ⇒ symmetric equilibrium
 - Encourage efforts

- What if agents can be untruthful
 - Everyone always reports the same feedback
 - (No effort, r^*) \leftarrow Best equilibrium



- Dasgupta and Ghosh [2013]
 - Reward = agreement on **common tasks** agreement on **separate tasks**
 - (All effort, truthful) and (no effort, random guess) are both equilibrium
 - (All effort, truthful) ← Best equilibrium
- Kong and Schoenebeck [2016]
 - Mutual Information MI(X; Y)
 - $MI(M(X); Y) \leq MI(X; Y)$

- Allow verification
 - TA score in peer grading
 - Minimize TA's workload
- Dasgupta and Ghosh [2013]
 - Reward = agreement on <u>common tasks</u> agreement on <u>separate tasks</u> $\propto \rho(r_i, r_j)$
 - Assume: $\rho(M(r_i), r_j) \le \rho(r_i, r_j)$
 - Any **independent** modification ⇒ the correlation coefficient û
 - Mutual Information (Kong and Schoenebeck [2016])

	Dasgupta and Ghosh [2013]	This Work
Signal Type	Discrete	Continuous
Agreement	Exactly the same	Negative correlation to Squared Euclidean Distance
Assumption	$\Pr[s_j = s s_i] < \Pr[s_j = s],$ $\forall s \neq s_i$	$\rho(M(r_i), r_j) \le \rho(r_i, r_j)$
Best Equilibrium (no effort cost)	(All effort, truthful)	(All effort, truthful)

Conclusion

- Describe effort as a noise to the real signal
- No need to be Gaussian
- Always truthful ⇒ relaxed
- Discrete ⇒ Continuous

Reference

- [1] Dasgupta, Anirban, and Arpita Ghosh. "Crowdsourced judgement elicitation with endogenous proficiency." Proceedings of the 22nd international conference on World Wide Web. ACM, 2013.
- [2] Kong, Yuqing, and Grant Schoenebeck. "An information theoretic framework for designing information elicitation mechanisms that reward truth-telling." ACM Transactions on Economics and Computation (TEAC) 7.1 (2019): 2.