

What is sparse coding and why it works

- ① Undirected graphical models (Markov Random Fields, Energy models)
- ② Restricted Boltzmann Machine (generative vs discriminative = undirected vs directed?)
- ③ Deep Belief Networks
- ④ Hidden nodes in terms of visible nodes? (Sigmoid function)
- ⑤ Sparse coding

CRASH COURSE ON GRAPHICAL MODELS

X_1, X_2, \dots, X_s random variables; $X = (X_1, \dots, X_s)$

$X_i \in \{1, 2, \dots, k_i\}$

$S \subseteq \{1, 2, \dots, s\}$, $X_S := (X_i)_{i \in S}$

$G = (V, E)$ directed acyclic graph

$pa(i) = \{j : j \rightarrow i \text{ is an edge}\}$ parents of node i

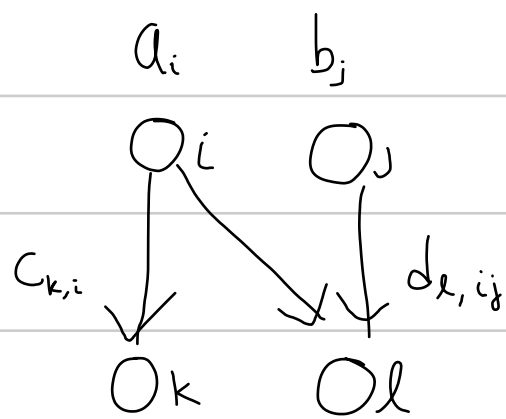
A prob dist on X factor according to G iff

$$p(X=x) = \prod_{i=1}^s p(X_i = x_i | X_{pa(i)} = x_{pa(i)})$$

Directed Graphical Model on G is family of prob dists which

factor according to G . BAYESIAN NETWORK.

Parameters $\theta_{x_i, x_{pa(i)}} = P(X_i = x_i | X_{pa(i)} = x_{pa(i)})$



$$p_{ijkl} = a_i c_{k,i} b_j d_{l,i,j}$$

$$i, j, k, l \in \{0, 1\}$$

$$c_{0,i} + c_{1,i} = 1 \quad \forall i \quad a_0 + a_1 = 1$$

$$d_{0,i,j} + d_{1,i,j} = 1 \quad \forall i, j \quad b_0 + b_1 = 1$$

CAUSAL
STRUCTURE

$G=(V,E)$ undirected, simple graph (no loop, multiedges)

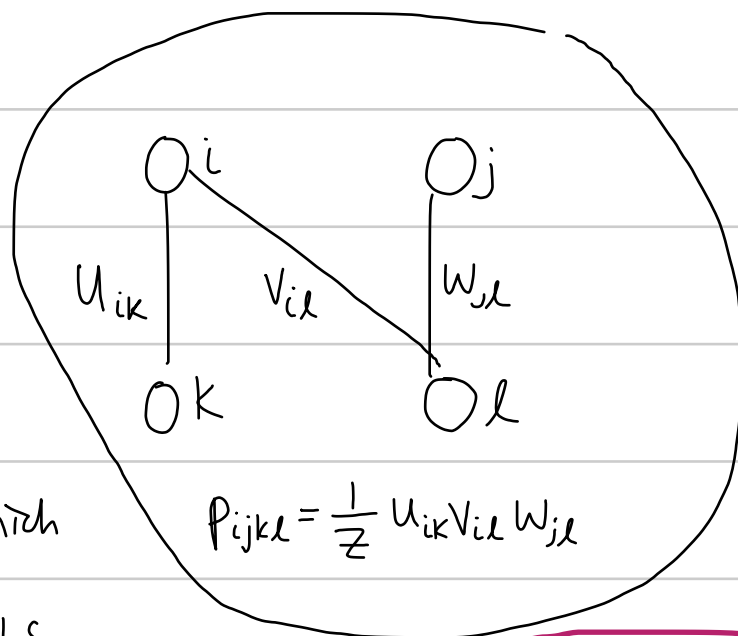
A clique is a complete subgraph. \mathcal{C} set of (max) cliques.

A prob dist factors according to G if

$$p(X=x) = \frac{1}{Z(w)} \prod_{C \in \mathcal{C}} w_{X_C}^{(C)}$$

Undirected Graphical Model on G is family of all prob dists which

factor according to G . MARKOV RANDOM FIELD. ENERGY MODELS.

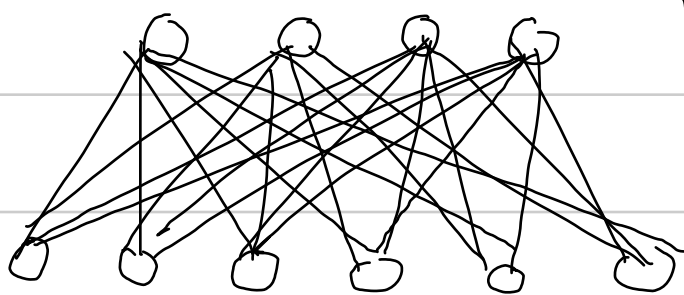


$$p_{ijkl} = \frac{1}{Z} U_{ik} V_{il} W_{jl}$$

CORRELATION
STRUCTURE

BOLTZMANN MACHINE = Undirected graphical model with binary variables

RESTRICTED BOLTZMANN MACHINE = Boltzmann machine on bipartite graphs



hidden variables

observed variables

Write parameters $w_{ij} = e^{W_{ij}}$, $\beta_i = e^{b_i}$, $\gamma_j = e^{c_j}$

$$h_i \in \{0,1\}, v_j \in \{0,1\}$$

$$\begin{aligned} p(v,h) &= \frac{1}{Z} \prod_{ij} w_{ij}^{h_i v_j} \prod_i \beta_i^{h_i} \prod_j \gamma_j^{v_j} \\ &= \frac{1}{Z} e^{\sum_{ij} h_i w_{ij} v_j + \sum_i b_i h_i + \sum_j c_j v_j} \\ &= \frac{1}{Z} \exp(h^T W v + b^T h + c^T v) \end{aligned}$$

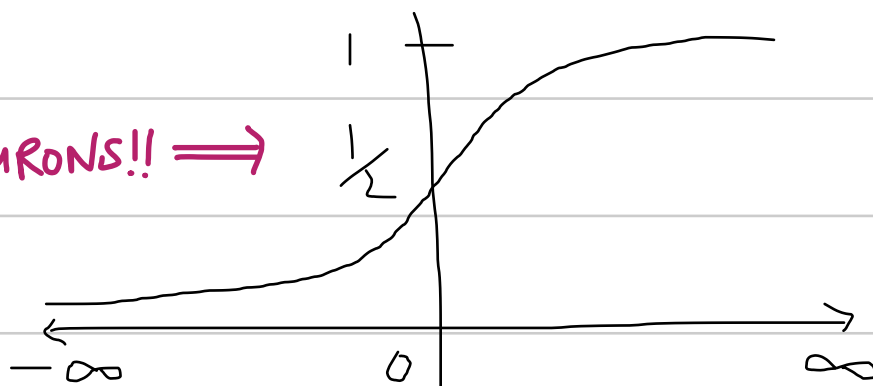
$$p(h_i=1|v) = \frac{p(v, h_i=1)}{p(v)}$$

$$= \frac{\sum_{h: h_i=1} p(v, h)}{\sum_h p(v, h)}$$

$$= \text{Sigmoid}(c_i + W_i \cdot v)$$

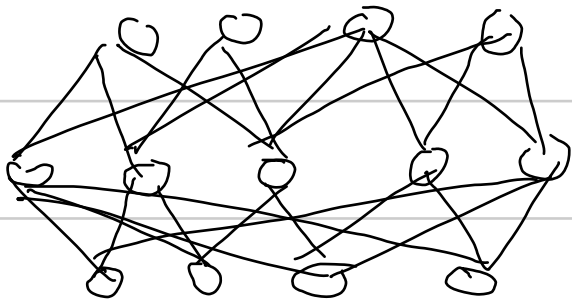
$$\text{Sigmoid}(z) = \frac{1}{1+e^{-z}}$$

ACTIVATION OF NEURONS!! \Rightarrow



DEEP BOLTZMANN MACHINES

Stacking restricted boltzmann machines



DEEP BELIEF NETWORKS

Learning weights one layer at a time

HISTORY OF NEURAL NETWORKS

① Perceptrons ~ 1960s

Hand-coded weights, directed graphical models

② 2nd Gen neural networks ~ 1985

Learned weights using back-propagation

③ Deep Learning ~ 1996

Undirected graphical models

Restricted Boltzmann Machines

Sparse coding