



University  
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# Evaluating and comparing models

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# Is the posterior model any good?

Obtaining a good looking 3D reconstruction is easy.



But does it also explain the data and the uncertainty?

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# Posterior predictive checks

Repeat prior-predictive checks, but with posterior distribution

1. Take samples  $\theta_1, \dots, \theta_n$  from posterior  $p(\alpha|C)$
2. Generate data (contours) and compare them to target



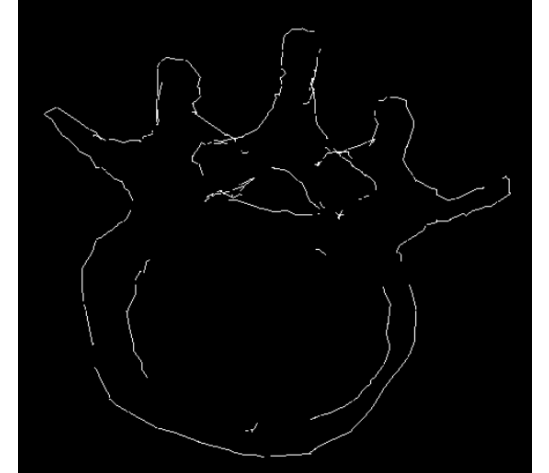
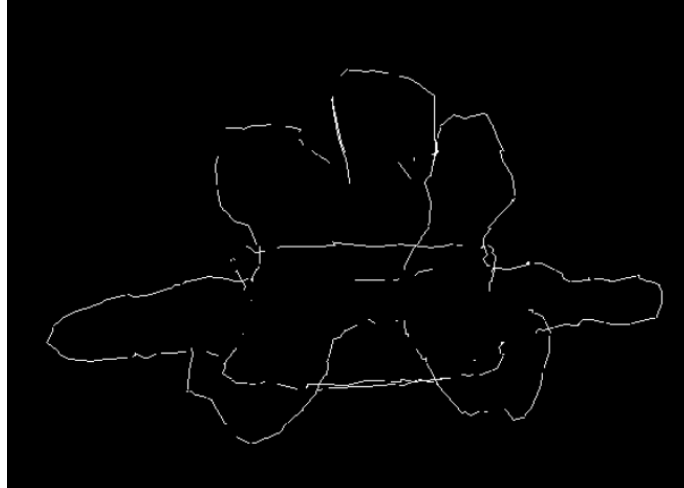
# Cross-validation

Use parts of the data

- Use different subset of contour
- Use different (generated) contours (if full-shape is available)

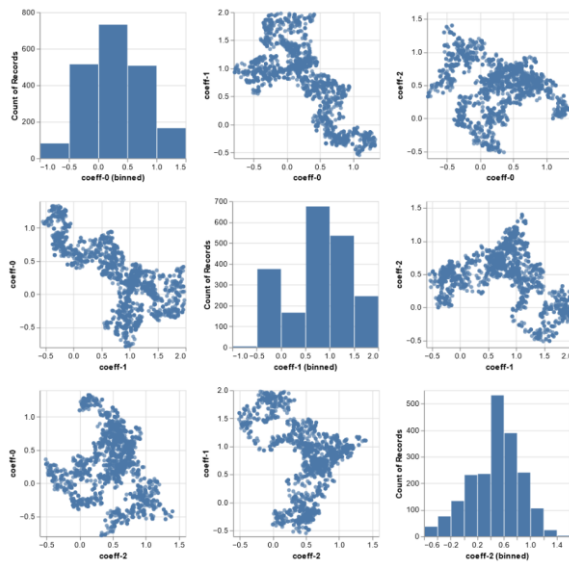
Question:

- Which subset of the data does affect the prediction most?

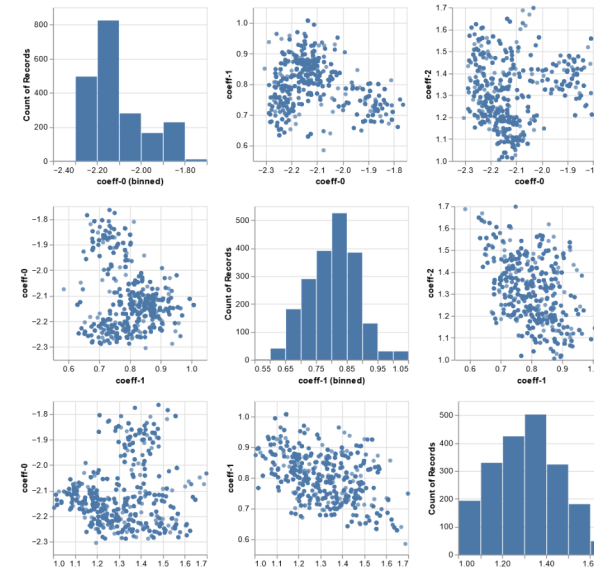


# Influence of Prior information

- Does changing the prior distribution affect the results?
  - Refit with multiple different priors
- Simple test: Shrinkage
  - How does posterior of parameter shrink the prior information



Prior



Posterior

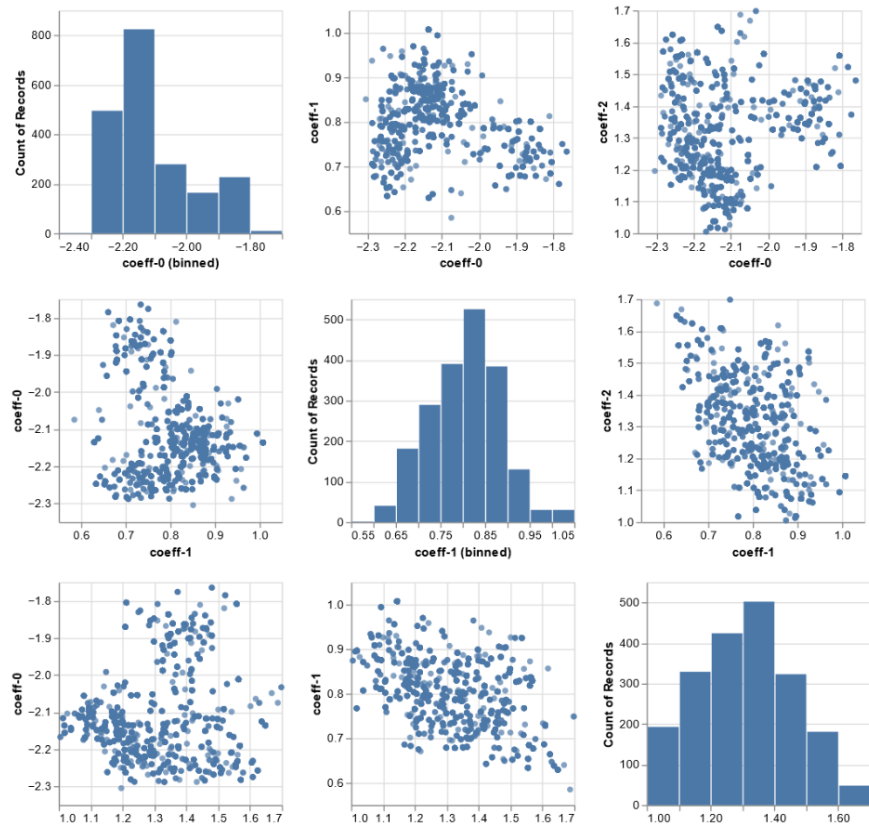
# Uncertainty

*Whenever we do inference there is uncertainty!*

- How big is the uncertainty?
    - Is it expected in this range?
    - Are we overconfident or is uncertainty too large?
  - What does it imply for the inference?
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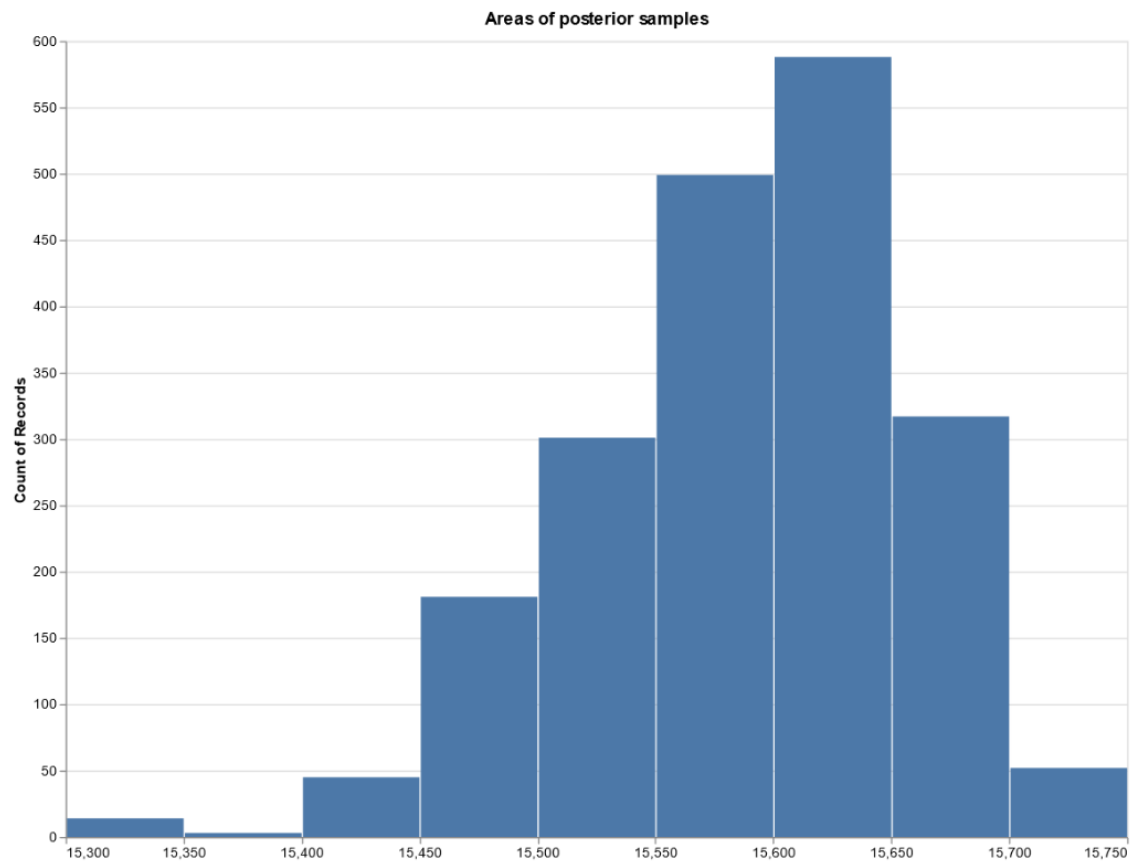
# Visualizing uncertainty (I)

## Visual assessment: Pair plots



# Visualizing uncertainty (II)

*Histograms of intuitive measurements (such as area, volume, etc.) can help to understand what uncertainty implies.*

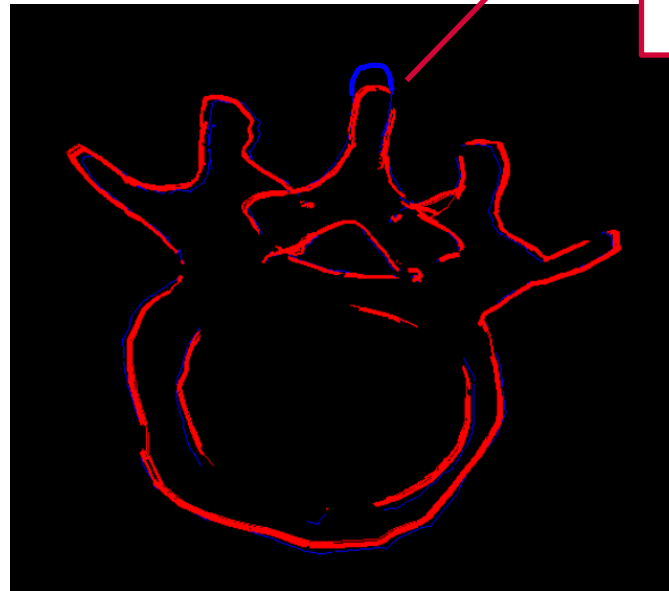
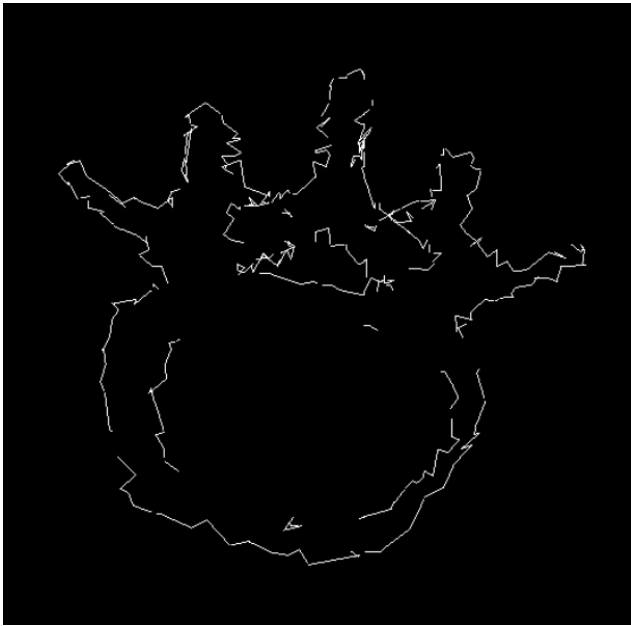




# Inspecting the data model

What is the influence of the chosen likelihood function (data model)

- Is the noise model okay
- Did we account for bias or correlation in noise?



Model cannot explain  
shape

# Comparing multiple models

- Which factors to include as parameters, which are fixed?
- Is posed fixed? Is sensor-distance fixed?
- Is noise level fixed?
  - Does modelling additional factors affect the result?

