# MACHINE LEARNING ALGORITHMS

# **ALGORITHMS LIST:**

# 1. Regression Algorithms

- Linear Regression
- Ridge Regression
- Lasso Regression

## 2. Dimensionality Reduction Algorithms

- Principal Component Analysis (PCA)
- Linear Discriminant Analysis (LDA)

# 3. Classification Algorithms

- Support Vector Machine (SVM)
- Decision Tree
- Random Forest

# 4. Clustering Algorithms

- K-Means Clustering
- Spectral Clustering
- · Hierarchical Clustering

# 5. Deep Learning Algorithms

• Convolutional Neural Network (CNN)

## **1.REGRESSION ALGORITHMS**

## LINEAR REGRESSION

1. Initialize parameters:

```
w = 0 // weight

b = 0 // bias

learning_rate = \alpha

max_iterations = N
```

- 2. Repeat until convergence or for max\_iterations times:
  - a. Compute the predicted values:

```
y_pred = w * x + b
```

b. Calculate the cost function (Mean Squared Error):

```
J = (1 / m) * \Sigma((y_pred[i] - y[i])^2) for i = 1 to m
```

c. Compute the gradients:

```
dw = (2 / m) * \Sigma((y_pred[i] - y[i]) * x[i]) for i = 1 to m
db = (2 / m) * \Sigma(y_pred[i] - y[i]) for i = 1 to m
```

d. Update the parameters using Gradient Descent:

```
w = w - \alpha * dw

b = b - \alpha * db
```

- 3. End Repeat
- 4. Output the final parameters:

```
Print "Final weight (w): ", w
Print "Final bias (b): ", b
```

5. Predict new values:

```
y_new = w * x_new + b
Return y_new
```

## **RIDGE REGRESSION**

1. Initialize parameters:

```
w = 0 // weights b = 0 // bias learning\_rate = \alpha regularization\_parameter = \lambda max\_iterations = N
```

- 2. Repeat until convergence or for max\_iterations times:
  - a. Compute the predicted values:

```
y_pred = w * x + b
```

b. Calculate the cost function (Regularized Mean Squared Error):

```
J = (1 / m) * \Sigma((y_pred[i] - y[i])^2) + \lambda * \Sigma(w^2) for i = 1 to m
```

c. Compute the gradients:

```
dw = (2 / m) * \Sigma((y_pred[i] - y[i]) * x[i]) + 2 * \lambda * w
db = (2 / m) * \Sigma(y_pred[i] - y[i])
```

d. Update the parameters:

```
w = w - \alpha * dw

b = b - \alpha * db
```

- 3. End Repeat
- 4. Output the final parameters:

```
Print "Final weights (w): ", w
Print "Final bias (b): ", b
```

5. Predict new values:

```
y_new = w * x_new + b
Return y_new
```

## LASSO REGRESSION

1. Initialize parameters:

```
w = 0 // weights b = 0 // bias learning\_rate = \alpha regularization\_parameter = \lambda max\_iterations = N
```

- 2. Repeat until convergence or for max\_iterations times:
  - a. Compute the predicted values:

```
y_pred = w * x + b
```

b. Calculate the cost function (Regularized Mean Squared Error):

```
J = (1 / m) * \Sigma((y_pred[i] - y[i])^2) + \lambda * \Sigma(|w|) for i = 1 to m
```

c. Compute the gradients:

```
dw = (2 / m) * \Sigma((y\_pred[i] - y[i]) * x[i])
Adjust dw for L1 regularization:
if w > 0: dw += \(\lambda\)
if w < 0: dw -= \(\lambda\)
db = (2 / m) * \Sigma(y\_pred[i] - y[i])
```

d. Update the parameters:

```
w = w - \alpha * dw

b = b - \alpha * db
```

- 3. End Repeat
- 4. Output the final parameters:

```
Print "Final weights (w): ", w
Print "Final bias (b): ", b
```

5. Predict new values:

```
y_new = w * x_new + b
Return y_new
```

## 2.DIMENSIONALITY REDUCTION ALGORITHMS

## PRINCIPAL COMPONENT ANALYSIS (PCA)

- 1. Input:
  - Dataset X of size (m x n), where m is the number of samples and n is the number of features.
- 2. Preprocessing:
  - a. Standardize the dataset:
    - For each feature j:
    - i. Compute mean  $\mu_{\underline{\ }}$  and standard deviation  $\sigma_{\underline{\ }}$ .
    - ii. Standardize:  $X_{standardized[i][j]} = (X[i][j] \mu_j) / \sigma_j$
- 3. Compute the Covariance Matrix:
  - Cov\_matrix = (1 / m) \* (X\_standardized^T \* X\_standardized)
- 4. Compute Eigenvalues and Eigenvectors:
  - Find the eigenvalues and eigenvectors of Cov\_matrix.
- 5. Sort Eigenvalues and Eigenvectors:
  - Sort the eigenvalues in descending order.
  - Arrange eigenvectors accordingly.
- 6. Select Principal Components:
  - Choose the top k eigenvectors corresponding to the k largest eigenvalues.
- 7. Project Data:
  - Project the standardized data onto the selected eigenvectors:
  - X\_reduced = X\_standardized \* Eigenvectors\_selected
- 8. Output:
  - Reduced dataset X\_reduced of size (m x k).

# LINEAR DISCRIMINANT ANALYSIS (LDA)

- 1. Input:
  - Dataset X of size (m x n) and class labels y of size (m).
- 2. Compute Class Statistics:
  - For each class c:
    - a. Compute the mean vector  $\mu$ \_c for all features in class c.
    - b. Compute the overall mean vector  $\mu$  for all samples.
- 3. Compute Within-Class Scatter Matrix (S\_W):
  - Initialize S W = 0
- For each class c:
  - a. Compute the scatter matrix for class c:

$$S_c = \Sigma (x_i - \mu_c) * (x_i - \mu_c)^T$$
 for all  $x_i$  in class  $c$ 

- b. Add to  $S_W: S_W += S_c$
- 4. Compute Between-Class Scatter Matrix (S\_B):
  - Initialize S\_B = 0
- For each class c:
  - a. Compute S\_B += N\_c \*  $(\mu_c \mu)$  \*  $(\mu_c \mu)^T$  where N\_c is the number of samples in class c.
- 5. Solve Generalized Eigenvalue Problem:
  - Solve:  $S_B * w = \lambda * S_W * w$
  - Find eigenvalues (λ) and eigenvectors (w).
- 6. Sort Eigenvalues and Eigenvectors:
  - Sort eigenvalues in descending order.
  - Arrange eigenvectors accordingly.
- 7. Select Discriminant Directions:
- Choose the top k eigenvectors corresponding to the k largest eigenvalues.
- 8. Project Data:
  - Project the original data onto the selected eigenvectors:
  - X\_reduced = X \* Eigenvectors\_selected
- 9. Output:
  - Reduced dataset X\_reduced of size (m x k).

## 3. CLASSIFICATION ALGORITHMS

## SUPPORT VECTOR MACHINE (SVM)

- 1. Input:
  - Dataset X of size (m x n) and labels y of size (m), where  $y \in \{+1, -1\}$ .
- Regularization parameter C (for Soft Margin SVM).
- Learning rate  $\alpha$ .
- Maximum iterations N.
- 2. Initialize:
- Initialize weights w = 0 (size n).
- Initialize bias b = 0.
- 3. Repeat until convergence or for N iterations:
  - a. For each training example (x\_i, y\_i):
  - i. Compute the decision function:

$$f(x_i) = (w \cdot x_i) + b$$

ii. Check the classification condition:

If 
$$y_i * f(x_i) >= 1$$
:

- Update weights with no penalty:

$$w = w - \alpha * \lambda * w$$

Else:

- Update weights and bias with penalty:

$$w = w - \alpha * (\lambda * w - y_i * x_i)$$
  
 $b = b + \alpha * y_i$ 

iii.  $\lambda = (1 / C)$  for soft margin SVM,  $\lambda = 0$  for hard margin SVM.

- 4. Output:
  - Final weight vector w and bias b.
- 5. Prediction:
  - For a new input x, predict:

$$y_pred = sign((w \cdot x) + b)$$

### **DECISION TREE**

#### TRAINING PHASE

- 1. Input:
  - Dataset D with features X and target variable y.
  - Stopping criteria (e.g., max depth, minimum samples per node).
- 2. Define:
  - Impurity measure:
  - For classification: Entropy (ID3) or Gini Index (CART).
  - For regression: Mean Squared Error (MSE).
  - Splitting criteria:
  - Choose the feature and threshold that minimize impurity or maximize information gain.
- 3. Function: BuildTree(D, depth)
  - a. Check for stopping criteria:
    - If all examples in D belong to the same class, return a leaf node with the class label.
- If depth exceeds the max depth or D has fewer than the minimum samples, return a leaf node with the majority class (classification) or mean value (regression).
  - b. Find the best split:
    - i. For each feature x\_j in X:
      - For each possible threshold t:
      - Split D into left (D\_left) and right (D\_right) subsets:

```
D_left = {examples in D where x_j <= t}</pre>
```

D\_right = {examples in D where x\_j > t}

- Compute impurity for the split (weighted by subset sizes):

- ii. Select the feature x\_j and threshold t with the lowest impurity.
- c. Create a decision node:
  - Feature: x j
  - Threshold: t
- d. Recursively build left and right subtrees:

```
left_subtree = BuildTree(D_left, depth + 1)
right_subtree = BuildTree(D_right, depth + 1)
```

- e. Return the decision node with:
  - Feature: x j
  - Threshold: t
  - Left Subtree: left\_subtree- Right Subtree: right\_subtree
- 4. Call BuildTree(D, 0) to build the tree.

## PREDICTION PHASE:

- 1. Input:
  - Decision tree T.
  - New input example x.
- 2. Traverse the tree:
  - a. Start at the root node.
  - b. At each decision node:
    - Check the feature and threshold:

If x[feature] <= threshold:

Move to the left subtree.

Else:

Move to the right subtree.

- 3. When a leaf node is reached:
  - Return the class label (classification) or mean value (regression) stored in the leaf.
- 4. Output:
  - Predicted value or class for x.

#### RANDOM FOREST

## TRAINING PHASE

- 1. Input:
- Dataset D with features X and target variable y.
- Number of trees T.
- Number of features to select for each tree f (default: sqrt(total features)).
- Maximum tree depth, minimum samples per leaf, or other stopping criteria.
- 2. Initialize:
- Forest = [] // List to store all decision trees.
- 3. For t = 1 to T:
  - a. Bootstrap Sampling:
    - Create a bootstrap sample D\_t by randomly sampling with replacement from D.
  - b. Feature Subset Selection:
    - Randomly select f features from the total features.
  - c. Train a Decision Tree:
    - BuildTree(D\_t, selected\_features) using the decision tree algorithm.
  - Use only the selected f features for splitting at each node.
  - d. Add the trained tree to the Forest:
    - Forest.append(tree)
- 4. Output:
  - Trained random forest (Forest containing T trees).

#### PREDICTION PHASE:

- 1. Input:
- Trained Random Forest (Forest).
- New input example x.
- 2. Initialize:
- Predictions = [] // To store predictions from all trees.
- 3. For each tree in the Forest:
  - a. Traverse the tree to predict the value or class for x:
    - prediction = tree.predict(x)
  - b. Append prediction to Predictions.
- 4. Aggregate Predictions:
  - For classification:
  - Final\_prediction = Majority vote from Predictions.
  - For regression:
  - Final\_prediction = Average of Predictions.
- 5. Output:
  - Final\_prediction (class or value).

# 4. CLUSTERING ALGORITHMS

## K-MEANS CLUSTERING

- 1. Input:
  - Dataset D with n data points {x\_1, x\_2, ..., x\_n}.
- Number of clusters k.
- Maximum number of iterations max\_iter.
- Tolerance value tol for convergence.
- 2. Initialize:
  - a. Randomly select k points from D as initial centroids {c\_1, c\_2, ..., c\_k}.
  - b. Set iteration counter iter = 0.
- 3. Repeat until convergence or max iter is reached:
  - a. Assign each data point to the nearest centroid:
  - For each data point x\_i in D:
    Assign x\_i to cluster j such that:
    j = argmin(||x\_i c\_j||^2) for all j in {1, 2, ..., k}.
  - b. Update centroids:
  - For each cluster j in {1, 2, ..., k}:
     Update centroid c j = Mean of all points assigned to cluster j.
  - c. Check for convergence:
    - If the change in centroids (||c\_old c\_new||) is less than tol for all centroids, break.
  - d. Increment iteration counter: iter = iter + 1.
- 4. Output:
- Final cluster centroids {c\_1, c\_2, ..., c\_k}.
- Cluster assignments for all data points.

## SPECTRAL CLUSTERING

- 1. Input:
  - Dataset D with n data points {x\_1, x\_2, ..., x\_n}.
  - Number of clusters k.
- 2. Construct the Similarity Matrix:
  - a. Compute a similarity matrix S of size (n x n):
    - For each pair of points  $(x_i, x_j)$ :  $S[i][j] = similarity(x_i, x_j)$  (e.g., Gaussian similarity:  $S[i][j] = exp(-||x_i x_j||^2 / (2\sigma^2))$ ).
  - b. Set diagonal elements S[i][i] = 0 (self-similarity is not considered).
- 3. Construct the Graph Laplacian:
  - a. Compute the degree matrix D:
    - $D[i][i] = \sum S[i][j]$  for all j.
  - b. Compute the unnormalized Laplacian L:
  - -L = D S.
  - c. (Optional) Normalize the Laplacian:
  - $L_{sym} = D^{(-1/2)} * L * D^{(-1/2)}$  (symmetric normalization).
  - L rw =  $D^{(-1)} * L$  (random walk normalization).
- 4. Compute Eigenvalues and Eigenvectors:
- a. Compute the first k eigenvectors of L (or L\_sym/L\_rw) corresponding to the k smallest eigenvalues.
- 5. Form the Feature Matrix:
  - Construct a matrix U of size (n x k), where the columns are the k eigenvectors.
- 6. Normalize the Rows of U (Optional):
  - For each row i in U, normalize it to have unit length:

```
U[i] = U[i] / ||U[i||.
```

- 7. Apply K-Means Clustering:
  - Treat each row of U as a point in k-dimensional space.
  - Use the K-Means algorithm to cluster the rows into k clusters.
- 8. Output:
  - Cluster assignments for all data points in D.

### HIERARCHICAL CLUSTERING

#### 1. Input:

- Dataset D with n data points {x 1, x 2, ..., x n}.
- Linkage criterion (e.g., single linkage, complete linkage, average linkage, or ward linkage).
- Desired number of clusters k or stopping condition (e.g., a distance threshold).

#### 2. Initialize:

- Each data point is its own cluster. So, initially, there are n clusters.
- Create a distance matrix to store pairwise distances between all points.
- For each pair of points (x\_i, x\_j), compute the distance d(x\_i, x\_j).
- Typically, Euclidean distance is used:

$$d(x_i, x_j) = ||x_i - x_j||.$$

- 3. Repeat until there are k clusters or no further merging possible:
- a. Find the two clusters (C\_i, C\_j) with the smallest distance (based on the chosen linkage criterion).
  - For \*\*single linkage\*\*: Use the minimum pairwise distance between clusters.
  - For \*\*complete linkage\*\*: Use the maximum pairwise distance between clusters.
  - For \*\*average linkage\*\*: Use the average pairwise distance between clusters.
  - For \*\*Ward's linkage\*\*: Minimize the total variance of the merged clusters.
  - b. Merge the two closest clusters C\_i and C\_j into a single cluster C\_ij.
    - Remove C\_i and C\_j from the list of clusters.
    - Add the new merged cluster C\_ij to the list of clusters.
  - c. Update the distance matrix:
    - Recalculate the distances from the newly formed cluster C\_ij to all other clusters.
- If using \*\*single linkage\*\*, update the distance to the minimum distance between C\_ij and any other cluster.
- If using \*\*complete linkage\*\*, update the distance to the maximum distance between C\_ij and any other cluster.
- If using \*\*average linkage\*\*, update the distance to the average distance between C\_ij and any other cluster.

### 4. Output:

- Dendrogram: A tree structure representing the merging process of clusters.
- Cluster assignments (if stopping at a desired number of clusters k).

## 5. DEEP LEARNING ALGORITHMS

## CONVOLUTIONAL NEURAL NETWORK (CNN)

### 1. Initialize parameters:

- Define the number of layers, filters, filter sizes, stride, padding, and activation functions.
- Initialize weights and biases for all filters and fully connected layers.

### 2. Input:

- Provide the input image or feature map (e.g., size HxWxC, where H=height, W=width, C=channels).

### 3. Forward Propagation:

- a. Convolutional Layer:
  - For each filter in the layer:
    - i. Slide the filter over the input (using stride and padding as defined).
    - ii. Perform element-wise multiplication between the filter and the input region.
    - iii. Sum the results to produce a single value.
    - iv. Add the bias term.
  - Generate an output feature map.

#### b. Apply Activation Function:

- Apply the chosen activation function (e.g., ReLU) to each value in the feature map.

#### c. Pooling Layer (if applicable):

- Divide the feature map into pooling regions.
- Perform the pooling operation (e.g., max-pooling or average-pooling) within each region.
- Reduce the spatial dimensions of the feature map.
- d. Repeat steps 3a–3c for each convolutional and pooling layer.

### e. Flattening:

- Convert the final feature maps into a 1D vector.

#### f. Fully Connected Layers:

- Multiply the flattened vector by the weights of the fully connected layer and add biases.
- Apply the activation function.

### 4. Output Layer:

- Use the final layer to output predictions:
  - For classification tasks, apply softmax for probabilities.
  - For regression tasks, output the raw values.

#### 5. Backpropagation:

- a. Compute Loss:
- Calculate the loss using a suitable loss function (e.g., cross-entropy for classification, MSE for regression).

## b. Compute Gradients:

- Use backpropagation to calculate the gradients of the loss with respect to weights and biases for all layers.

## c. Update Parameters:

- Update weights and biases using Gradient Descent or an optimization algorithm like Adam:
 weight = weight - learning\_rate \* gradient
 bias = bias - learning\_rate \* gradient

## 6. Repeat:

- Iterate over multiple epochs and batches of the training data.

### 7. Prediction:

- Use the trained CNN to make predictions on new inputs.