## **Sharath Jotawar**

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Country: Singapore (Visa: EP)

**Nationality: Indian** 

### **Professional Summary**

• 6 years of software development experience in C++, Python.

• Specialized in the development of algorithms on computer vision, machine learning, deep learning for robotic automation.

#### **Skill Sets**

 Programming Languages: C++, Python, HTML, JavaScript

• Operating System: Linux Ubuntu

• Version Control Systems: Git

• **Software Libraries:** OpenCV, PCL, Keras, Tensorflow, numpy, matplotlib, pandas, ROS,

MoveIt, Gazebo

## **Experience**

### Transforma Robotics Pte Ltd, Singapore as Software Engineer

Mar '18 to Present

- Semantic segmentation and detection in an indoor environment using Mask R-CNN deep learning model to extract information and segment out objects present on wall.
- High-level task planner for complex behavior of robot and backend communication for human machine interface through WebApp.

Tata Consultancy Services Innovation Labs, Bangalore, India as Researcher

Aug '14 to Mar '18

#### **Projects:**

- Real time object detection in a cluttered environment using Faster R-CNN deep learning model <u>Video</u>.
- Primitives shapes-based object model matching using SUPER4PCS for estimation of grasp pose <u>Video</u>.
- Localization of grasp regions on novel objects through 3D geometric surface fitting Video.
- Motion planning for an automated pick and place robot in a retail warehouse using MoveIt Video1, Video2.

Continental Automotive Components India Pvt Ltd as Graduate Engineer Trainee Aug '10 to May '11 Responsibilities: Conducting verification of circuit design of different modules in prototype Engine Control Unit.

# **Self-Learning Projects**

- CNN model for multi-class classification of 43 different German traffic signs. Achieved classification accuracy of 97.2% on test dataset. Link: <a href="https://github.com/sharathrjtr/german traffic sign classification">https://github.com/sharathrjtr/german traffic sign classification</a>.
- Prediction of steering angles through the images obtained from a dashboard camera for a simulated autonomous vehicle using CNN model. Link: <a href="https://github.com/sharathrjtr/autonomous car driving">https://github.com/sharathrjtr/autonomous car driving</a>.
- Model for multi-label tagging of fashion products trained using transfer learning on VGG16 model with imbalanced training dataset. Achieved train data F2 score: 0.71, test data F2 score: 0.66. Link: <a href="https://github.com/sharathrjtr/CNN">https://github.com/sharathrjtr/CNN</a> model fashion products multi label tagging

#### **Achievements & Publications**

- Member of <u>Team IITK-TCS</u> which participated in **Amazon Robotics Challenge**, held in RoboCup 2017, Nagoya, Japan. Won 3<sup>rd</sup> place in pick task and 4<sup>th</sup> place in the final round out of 16 teams in the competition.
- **Paper:** Design and development of an automated robotic pick & stow system for an e-commerce warehouse. Available at <a href="https://arxiv.org/pdf/1703.02340.pdf">https://arxiv.org/pdf/1703.02340.pdf</a>

## **Academic Background**

M Tech. in Electronics & Electrical Engineering with Specialization in Signal Processing	Yr: 2012-14
Institute: Indian Institute of Technology Guwahati (IIT Guwahati), India	CPI: 8.34
B.E. in Electronics & Communication Engineering	Yr: 2006-10
Institute: BMS College of Engineering, Bangalore, India.	Avg: 71.9 %