

# Sharath Jotawar

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Country: Singapore (Visa: EP)

Nationality: Indian

## Professional Summary

- 6 years of software development experience in C++, Python.
- Specialized in the development of algorithms on computer vision, machine learning, deep learning for robotic automation.

## Skill Sets

- **Programming Languages:** C++, Python, HTML, JavaScript
- **Operating System:** Linux Ubuntu, Windows
- **Version Control Systems:** Git
- **Software Libraries:** OpenCV, PCL, Keras, Tensorflow, numpy, matplotlib, pandas, ROS, MoveIt, Gazebo

## Experience

**Transforma Robotics Pte Ltd, Singapore as Software Engineer**

**Mar '18 to Present**

- Semantic segmentation and detection in an indoor environment for autonomous painting robot using Mask R-CNN deep learning model.
- High-level task planner for complex behavior of robot and backend communication for human machine interface through WebApp.

**Tata Consultancy Services Innovation Labs, Bangalore, India as Researcher**

**Aug '14 to Mar '18**

### Projects:

- Real time object detection in a cluttered environment using Faster R-CNN deep learning model [Video](#).
- Primitives shapes-based object model matching using SUPER4PCS for estimation of grasp pose [Video](#).
- Localization of grasp regions on novel objects through 3D geometric surface fitting [Video](#).
- Motion planning for an automated pick and place robot in a retail warehouse using MoveIt [Video1](#), [Video2](#).

**Continental Automotive Components India Pvt Ltd as Graduate Engineer Trainee**

**Aug '10 to May '11**

**Responsibilities:** Conducting verification of circuit design of different modules in prototype Engine Control Unit.

## Self-Learning Projects

- CNN model for multi-class classification of 43 different German traffic signs. Achieved classification accuracy of 97.2% on test dataset. Link: [https://github.com/sharathrjtr/german\\_traffic\\_sign\\_classification](https://github.com/sharathrjtr/german_traffic_sign_classification).
- Prediction of steering angles through the images obtained from a dashboard camera for a simulated autonomous vehicle using CNN model. Link: [https://github.com/sharathrjtr/autonomous\\_car\\_driving](https://github.com/sharathrjtr/autonomous_car_driving).
- Model for multi-label tagging of fashion products trained using transfer learning on VGG16 model with imbalanced training dataset. Achieved train data F2 score: 0.71, test data F2 score: 0.66. Link: [https://github.com/sharathrjtr/CNN\\_model\\_fashion\\_products\\_multi\\_label\\_tagging](https://github.com/sharathrjtr/CNN_model_fashion_products_multi_label_tagging)

## Achievements & Publications

- Member of [Team IITK-TCS](#) which participated in **Amazon Robotics Challenge**, held in RoboCup 2017, Nagoya, Japan. Won 3<sup>rd</sup> place in pick task and 4<sup>th</sup> place in the final round out of 16 teams in the competition.
- **Paper:** Design and development of an automated robotic pick & stow system for an e-commerce warehouse. Available at <https://arxiv.org/pdf/1703.02340.pdf>

## Academic Background

<b>M Tech. in Electronics &amp; Electrical Engineering with Specialization in Signal Processing</b> <b>Institute: Indian Institute of Technology Guwahati (IIT Guwahati), India</b>	Yr: 2012-14 CPI: 8.34
<b>B.E. in Electronics &amp; Communication Engineering</b> <b>Institute: BMS College of Engineering, Bangalore, India.</b>	Yr: 2006-10 Avg: 71.9 %