

Bus Arrival Time Prediction

Sharipkhanova Dariya BDA-2201

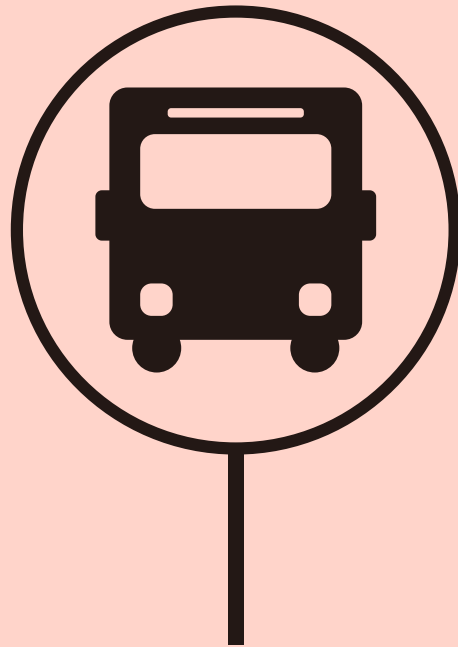


Introduction

- Improving reliability of public transportation.
- Reducing waiting times with accurate bus arrival predictions.
- Integrating real-time GPS, traffic, and weather data.



Goals and Objectives



Goal:

Develop and evaluate models for accurate predictions.

Objectives:

- Integrate various data sources.
- Implement machine learning models.
- Evaluate model performance.

Methods and metrics

Data Sources:

- GTFS schedules
 - GPS data
- Traffic & weather data

Models:

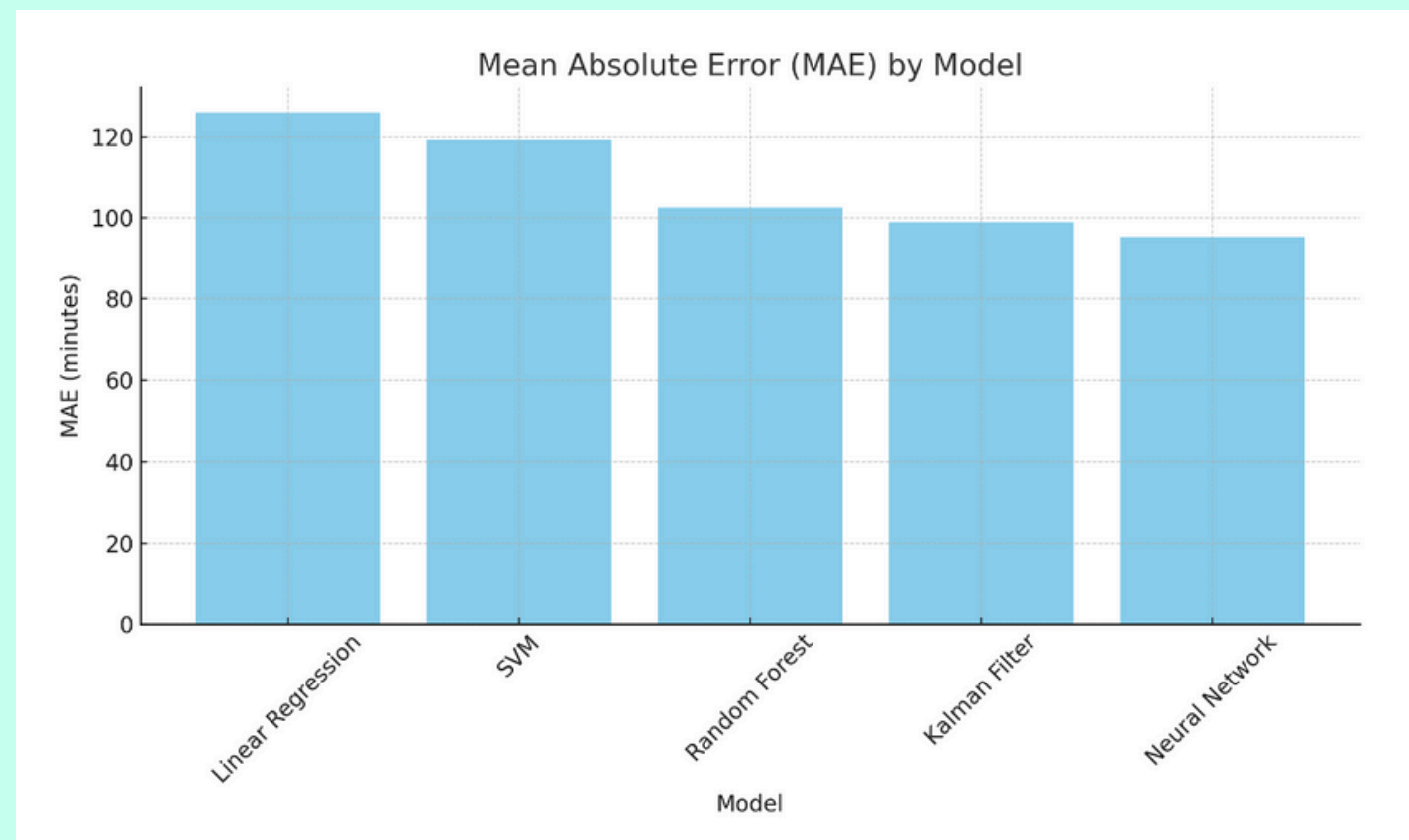
- Linear Regression
 - SVM
- Random Forest
- Kalman Filter

Evaluation Metrics

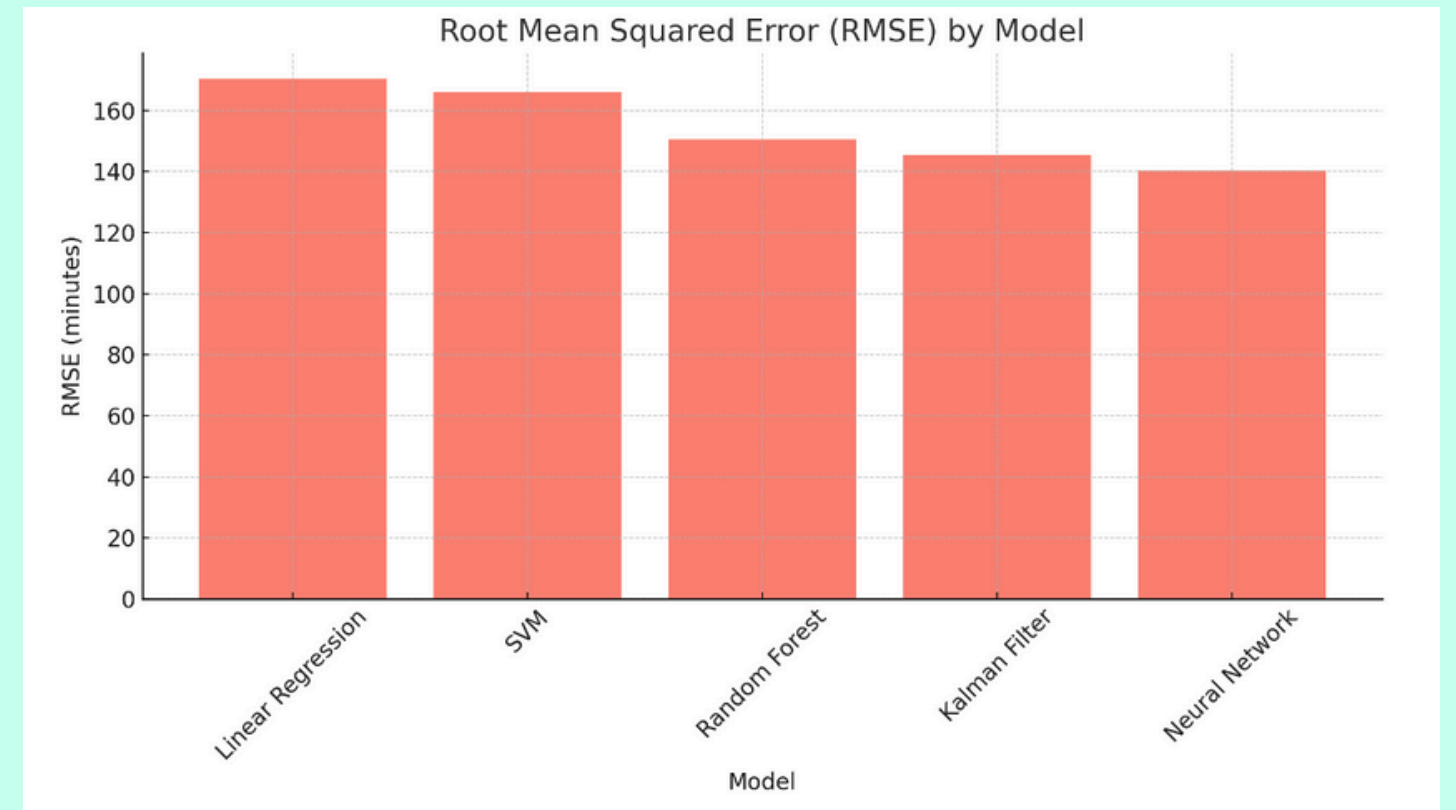
- Mean Absolute Error (MAE): Measures average prediction error.
- Root Mean Squared Error (RMSE): Penalizes larger errors.

Results

- Neural Network achieved the lowest error.
- Kalman Filter improved sequential estimations.
- Random Forest captured non-linear patterns effectively.



MAE by Model



RMSE by Model

Discussion and Conclusion

- Neural Networks provide the most accurate predictions.
- Kalman Filtering improves real-time accuracy.
- Future work:

Hyperparameter tuning

Real-time deployment

Weather and traffic data integration



References

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3. <https://www.kaggle.com/datasets/charvibannur/gtfs-traffic-prediction-dataset>
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5. <https://docs.2gis.com/ru/api/navigation/directions/overview>
6. <https://pro.arcgis.com/ru/pro-app/3.1/help/analysis/networks/historical-traffic.htm>
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Thanks for your
attention!