

Stochastic Processes

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Definition 1 (Stochastic Process). Let $\mathcal{T} \subseteq \mathbb{R}$. For any $t \in \mathcal{T}$, let X_t be a random variable with support D . Then $X := \{X_t : t \in \mathcal{T}\}$ is called a stochastic process on state-space D and time \mathcal{T} . Usually, \mathcal{T} is either $\mathbb{Z}_{\geq 0}$ (discrete-time) or $\mathbb{R}_{\geq 0}$ (continuous-time).

1 Discrete-Time Markov Chains

Definition 2 (Markov Chain). Let $X := [X_0, X_1, \dots]$ be a stochastic process on state-space D and time $\mathbb{Z}_{\geq 0}$. X is called a discrete-time markov chain if $\Pr(X_{t+1} = d \mid X_t, X_{t-1}, \dots, X_0) = \Pr(X_{t+1} = d \mid X_t)$. If $\Pr(X_{t+1} = d \mid X_t) = \Pr(X_1 = d \mid X_0)$, then X is called time-homogeneous.

Definition 3 (Transition function). Let X be a markov chain on state space D . Define $P^{(k)} : D \times D \mapsto [0, 1]$ as $P^{(k)}(i, j) = \Pr(X_k = j \mid X_0 = i)$. Then $P^{(k)}$ is called the k -step transition function of X . For $k = 1$, we simply write P instead of $P^{(1)}$. For a finite state space, we can represent P as a matrix.

Lemma 1 (Chapman-Kolmogorov Equation). $P^{(m+n)}(i, j) = \sum_k P^{(m)}(i, k)P^{(n)}(k, j)$.

1.1 Classification of States, Recurrence, Limiting Probabilities

Definition 4. Let $f_{i,j} := \Pr\left(\bigvee_{t \geq 1} (X_t = j) \mid X_0 = i\right)$. Then $f_{i,j}$ is called the eventual transition probability from i to j . If $i = j$, then we write $f_{i,i}$ as f_i , and call it the recurrence probability of state i .

Definition 5. For a state i , let N_i be the random variable that counts the number of times we are in state i , i.e., $N_i := \sum_{t=0}^{\infty} \mathbf{1}(X_t = i)$. Then N_i is called the visit-count of i .

Definition 6. A state i of a markov chain is recurrent iff (the following are equivalent):

- the recurrence probability (f_i) of i is 1.
- i is visited infinitely often, i.e., $\Pr(N_i = \infty \mid X_0 = i) = 1$.
- i is visited infinitely often in expectation, i.e., $E(N_i \mid X_0 = i) = \infty$.

A non-recurrent state is called a transient state.

Lemma 2. $\Pr(N_i = k \mid X_0 = i) = f_i^{k-1}(1 - f_i)$.

Lemma 3. $E(N_i \mid X_0 = i) = 1/(1 - f_i) = \sum_{t=0}^{\infty} P^{(t)}(i, i)$.

Definition 7. State j is accessible from state i if $P^{(t)}(i, j) > 0$ for some t . States i and j communicate (denoted as $i \leftrightarrow j$) if i and j are both accessible from each other.

Lemma 4. Accessibility is reflexive and transitive. Communication is an equivalence relation. The equivalence classes of communicability are called state classes. A markov chain is irreducible if it has just one state class.

Definition 8. Let T_i be the time when a markov chain moves to state i , i.e., $T_i := \min_{t \geq 1} (X_t = i)$. When conditioned on $X_0 = i$, T_i is called the recurrence time of i . State i is called positive recurrent if $E(T_i | X_0 = i)$ is finite, otherwise it is null recurrent.

Lemma 5. Recurrence and positive recurrence are class properties, i.e., they are same for all states in a class.

Lemma 6. In a finite-state markov chain, all recurrent states are positive recurrent, and there is at least one recurrent state.

Definition 9 (Periodicity). For a state i , its period is defined as $\gcd(\{t : \Pr(T_i = t | X_0 = i) > 0\})$. A state is aperiodic if its period is 1.

Lemma 7. Periodicity is a class property.

Definition 10 (Ergodicity). A state is ergodic if it is positive recurrent and aperiodic. A markov chain is ergodic if all its states are ergodic.

Lemma 8. In an irreducible ergodic markov chain, for every state j , $\lim_{t \rightarrow \infty} P^{(t)}(j, i) = \pi_i$ for a unique real number π_i . π_i is called the limiting probability of state i . Furthermore, π_i is the unique solution to this system of equations: $\pi_i = \sum_j \pi_j P(j, i)$ for all i ($\pi = P^T \pi$ in matrix form) and $\sum_i \pi_i = 1$.

Lemma 9. In an irreducible ergodic markov chain, $E(T_i | X_0 = i) = 1/\pi_i$.

Corollary 9.1. A state i is null recurrent iff $\pi_i = 0$.

Theorem 10. If the transition function of markov chain X is doubly-stochastic (i.e., each row and each column sums to 1), then the limiting probability of each state is $1/n$, where n is the number of states.

1.2 Time-Reversibility

Definition 11. For an irreducible ergodic markov chain X with limiting probabilities π . Let Y be a markov chain whose transition function is $Q(i, j) = P(j, i)(\pi_j/\pi_i)$. Then Y is called the time-reversed markov chain of X . X is called time-reversible if $Q = P$.

Theorem 11. Let X be a time-reversible markov chain with limiting probabilities π . Then π is the unique solution to this system of equations: $x_j P(j, i) = x_i P(i, j)$ for all states i and j , and $\sum_i x_i = 1$.

Theorem 12. If the transition function of markov chain X is symmetric, then X is time-reversible.