

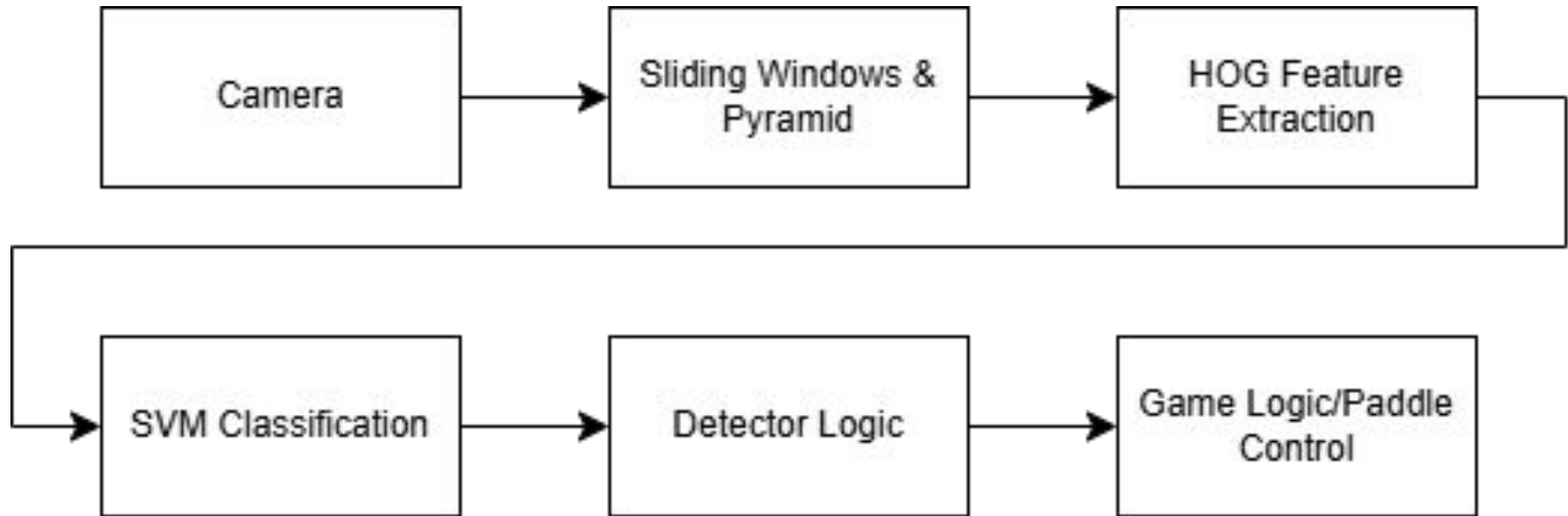
# Hand-Controlled Ping Pong Game w/ HOG + SVM

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Robot Vision Fall 25  
12/9/25

# Reimagining Traditional Ping Pong Game

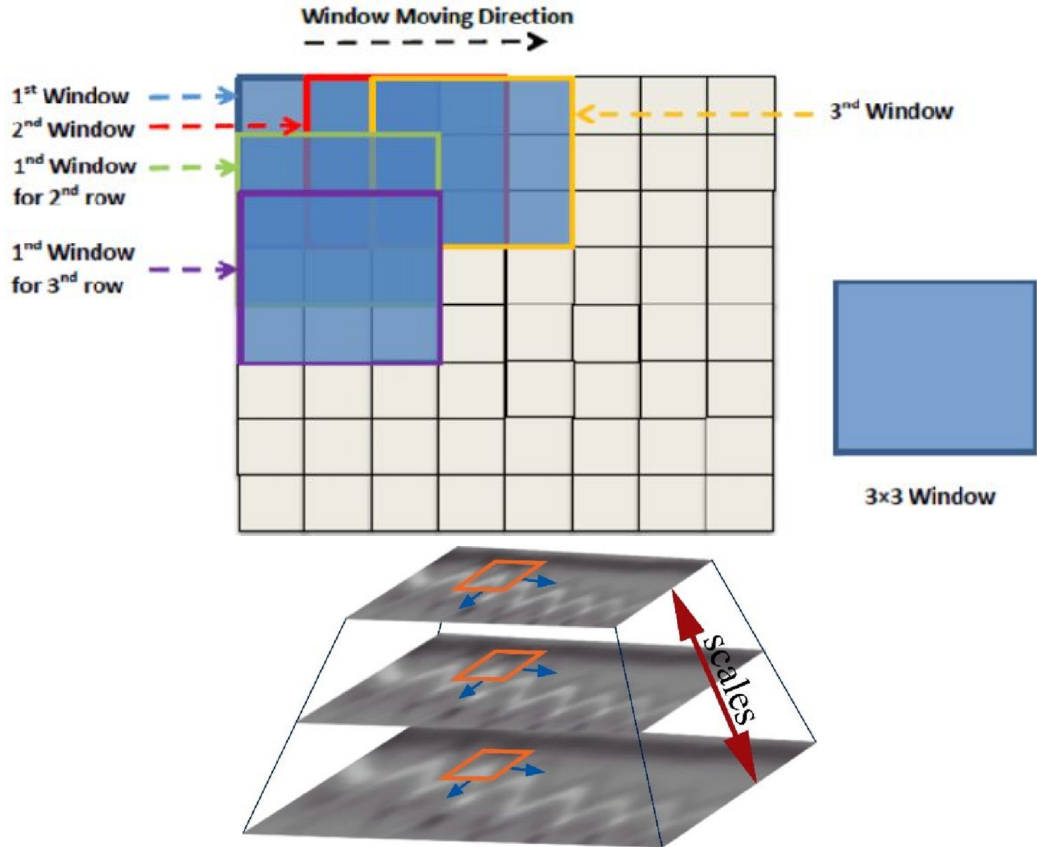
- **Motivation:**
  - Learn more about implementation of HOG + SVM object detection algorithms
  - Explore the efficiency and effectiveness of the algorithm
- **Goal:** Replace mouse/keyboard input with hand input
  - Detect finger/hand in live webcam feed
  - Map hand motion -> paddle motion
  - Maintain useable frame rate
- **Roles:**
  - Sharmarke -> GameUI & Design, Manual Hand/Finger Input Model
  - Shin -> 11k Hand Model

# High Level Overview



# Sliding Window

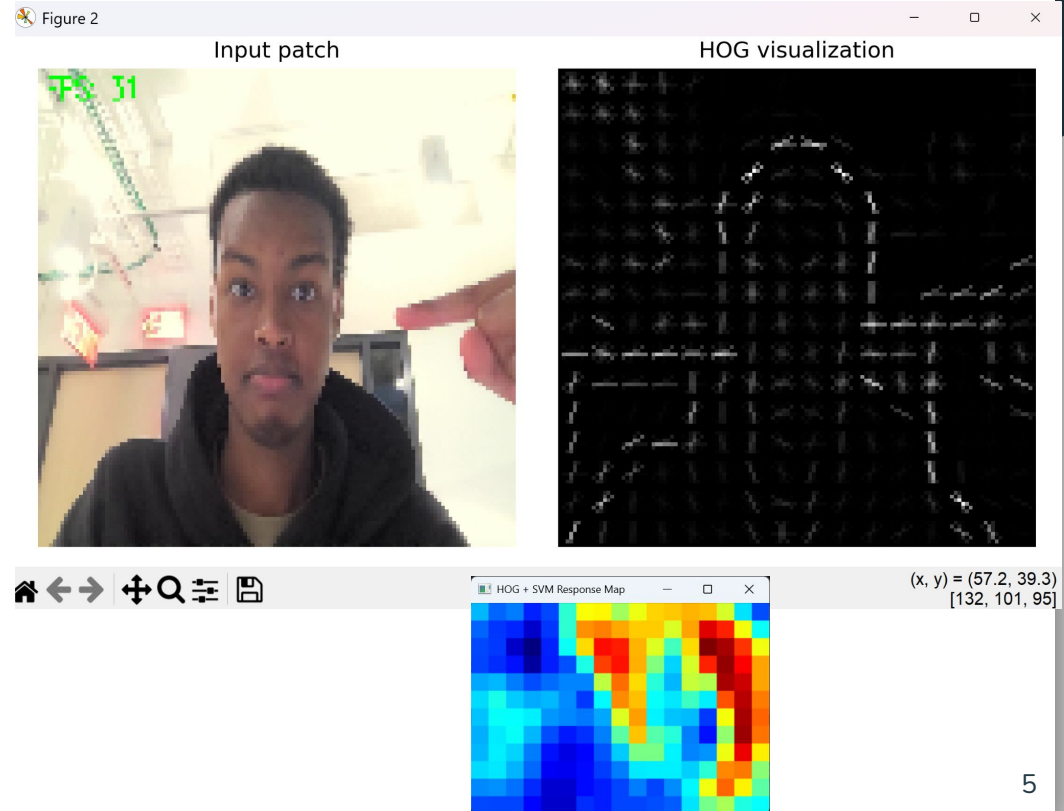
- **Sliding Window:** Move a 64x64 window across the image
- **Image Pyramid:** Scale image to three different sizes (small, medium, large)
- Extract HOG features from each window and get SVM confidence score
- High score -> Hand detected!



# HOG Feature Extraction

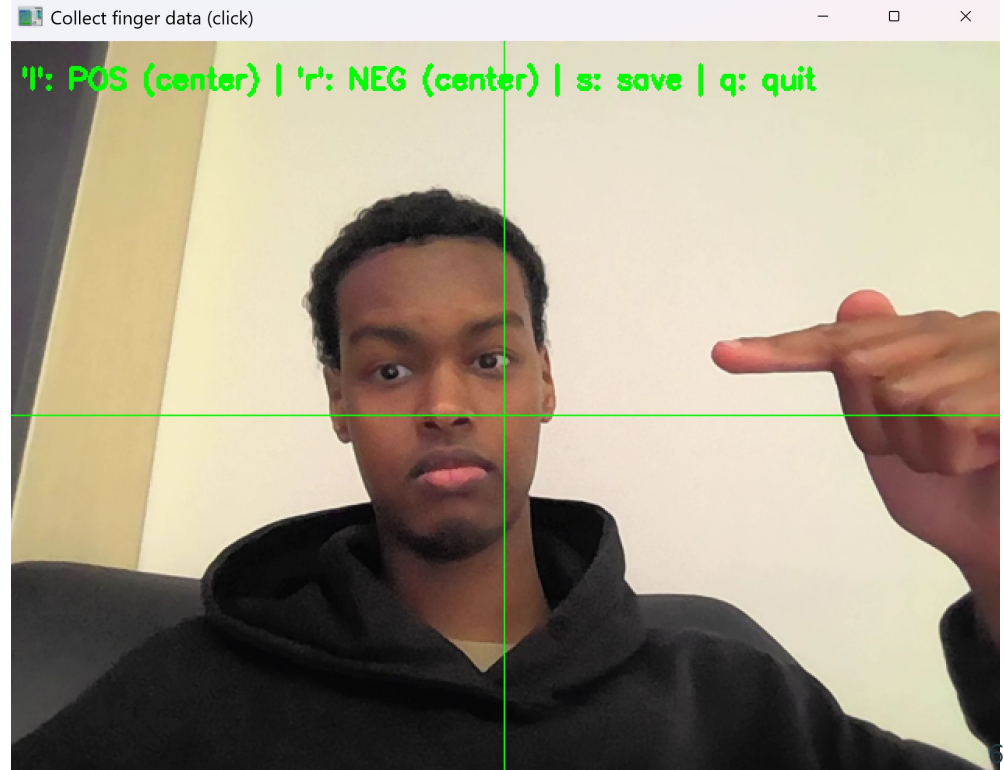
## HOG Parameters:

- Uses OpenCV HOG functions
  - Window: 64x64
  - Cells: 8x8
  - Blocks: 16x16 stride 8
  - 9 orientation bins
- Converts frame into features
- Good for capturing shapes

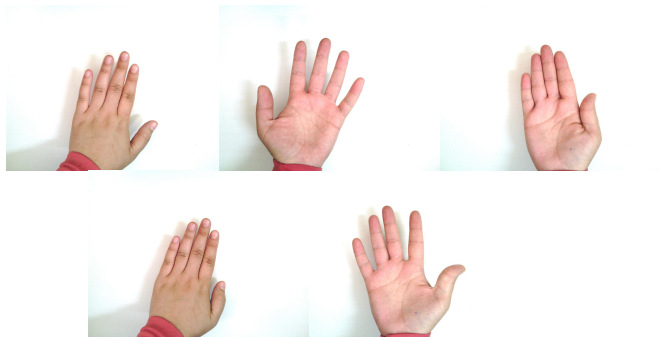


# Training SVM: Data Collection (Manual Hand Input Model)

- **hog\_finger\_data.py**
  - Store positive & negative HOG finger samples in a joblib file
- **train\_finger\_svm.p**
  - Using LinearSVC() from sklearn library
  - Run SVM on positive & negative samples to be used for finger detection



# Training with External Datasets



Positive Images

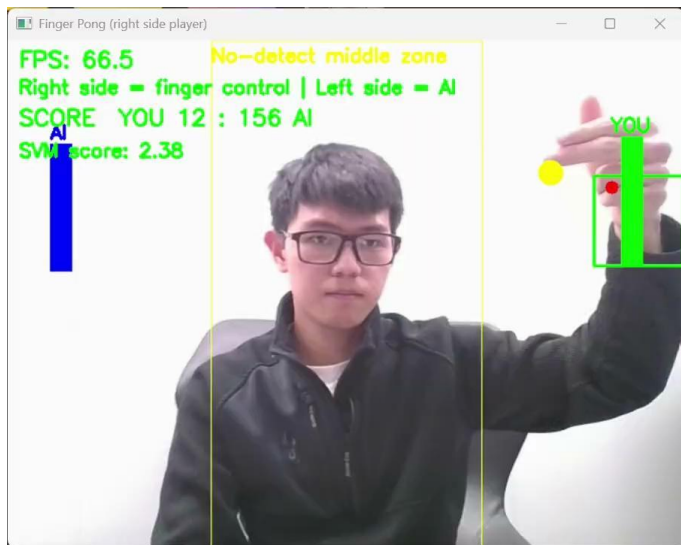
(100 images from 11k Hands dataset)



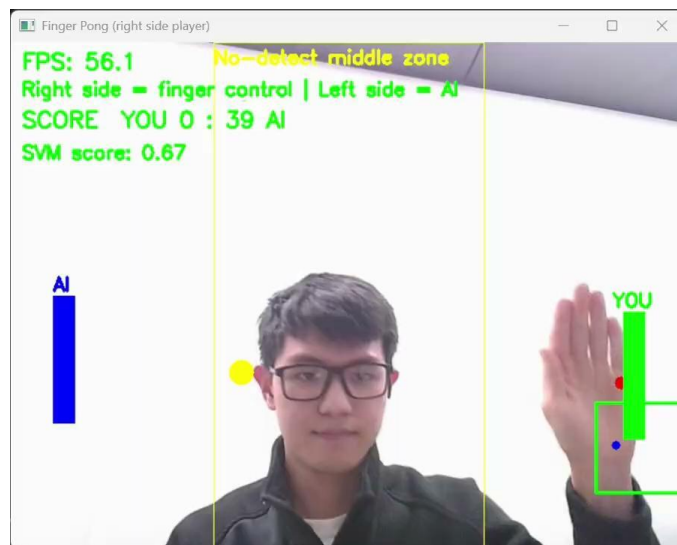
Negative Images

(50 images from Imagenet dataset)

# Demo Videos



Trained with Manual Hand Data



Trained with 11k Hands Dataset



# Main Challenges

- Finding hand datasets with complex background
- Highly dependent on a clear background
- Poor detection with different hand gestures and orientation

# Further Improvements

- Background robustness
- Orientation invariance
- Game UI and Complexity

Thank you!  
Q&A