

#### **ELECTRONIC CITY CAMPUS**

(Established under Karnataka Act no. 16 of 2013)
Hosur Road, Near Electronic City, Bangalore-100

## **SCI LAB**

# Subject: LINEAR ALGEBRA AND ITS APPLICATIONS

**Subject Code: UE19MA251** 

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Section: E Branch: CSE

Marks awarded: Name of the faculty: Dr.Girish. V.R.

Class Number	Topic			
1	Gaussian Elimination			
2	The LU Decomposition			
3	Inverse of a Matrix by the Gauss- Jordan Method			
4	The Span of Column Space of a Matrix			
5	The Four Fundamental Subspaces			
6	Projections by Least Squares			
7	The Gram-Schmidt Orthogonalization			
8	Eigen values and Eigen Vectors of a Matrix			

## **Topic: Gaussian Elimination**

**PROBLEM 1:** Solve the following system of equations by Gaussian Elimination. Identify the pivots.

```
2x - 3y = 3, 4x - 5y + z = 7, 2x - y - 3z = 5.
```

## **CODE:**

```
P1-Guassian elemination_PES2UG19CS309.ace (C\User\sharm\P1-Guassian elemination_PE
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```

```
Sciab 6.1.0 Console

"Matrix before Gaussian Elimination: "

2. -3. 0.
4. -5. 1.
2. -1. -3.

"Values of x,y,z:"

3. 1.
0.

"Matrix after Gaussian Elimination: "

2. -3. 0. 3.
0. 1. 1. 1.
0. 0. -5. 0.

"The pivots are: "

-5.

1.
2.
--> |
```

#### **Topic:** LU decomposition of a matrix

**PROBLEM 2:** Factorize the following matrices as A = LU2x + 3y + z = 8, 4x + 7y + 5z = 20, -2y + 2z = 0

#### **CODE:**

```
P2-LU Decomposition_PES2UG19CS309.sce (C:\Users\sharm\P2-LU Decomposition_PES2UG19
<u>File Edit Format Options Window Execute</u>?
P2-LU Decomposition_PES2UG19CS309.sce (C:\Users\sharm\P2-LU Decomposition_PES2UG19CS309.sc
P1-Guassian elemination_PES2UG19CS309.sce 🕱 P2-LU Decomposition_PES2UG19CS309.sce 🕱
1 clear; clc;;
2 A = [2 · 3 · 1; 4 · 7 · 5; · 0 · -2 · 2];
3 U -= -A;
4 disp(A, . "The . given . matrix . is: ");
5 m = det(U(1,1));
 6 n = - det (U(2,1));
 7 | \mathbf{a} = \frac{n}{m}
 8 U(2,:) = U(2,:) - U(1,:) / (m/n);
9 n = det(U(3,1));
10 b = n/m;
11 U(3,:) -= -U(3,:) -- -U(1,:)/(m/n);
12 m = det(U(2,2));
13 n -= -det(U(3,2));
14 c -= - n/m;
15 U(3,:) -= -U(3,:) -- -U(2,:)/(m/n);
16 disp(U, "The upper triangular matrix is:");
17 L = [1,0,0;a,1,0;b,c,1];
18 disp(L, "The ·lower ·triangular ·matrix ·is:");
```

```
Scilab 6.1.0 Console
   2.
        з.
             1.
   4.
        7.
             5.
   0. -2.
             2.
  "The given matrix is:"
        3.
             1.
   0.
        1.
             з.
        0.
             8.
  "The upper triangular matrix is:"
        0.
             0.
   2.
        1.
             0.
   0. -2.
             1.
  "The lower triangular matrix is:"
```

#### **Topic:** The Gauss - Jordan method of calculating A -1

**PROBLEM 3:** Find the inverse of the following matrix  $A = \{[2,-1,0],[-1,2,-1],[0,-2,2]\}$ 

#### **CODE:**

```
P3-Gauss-Jordan for inverse_PES2UG19CS309.sce (C:\Users\sharm\P3-Gauss-Jordan for inverse_
File Edit Format Options Window Execute ?
P2-LU Decomposition_PES2UG19CS309.sce 🕱 P3-Gauss-Jordan for inverse_PES2UG19CS309.sce 🕱
1 clc;clear;
2 A = \cdot [2 \cdot -1 \cdot 0; -1 \cdot 2 \cdot -1; 0 \cdot -1 \cdot 2];
3 n = \operatorname{length}(A(1,:));
4 Aug = (A, eye(n, n));
5 //Forward Elimination
6 for .j=1:n-1
7 ----for-i=j+1:n
9 ----end
10 end
11 //Backward Elimination
12 for · j · = · n: -1:2
13 ---- Aug (1:j-1,:) -= -Aug (1:j-1,:) -Aug (1:j-1,j) /Aug (j,j) *Aug (j,:);
14 end
15 //Diagonal Normalization
16 for j=1:n
17 - - - Aug (j,:) -= - Aug (j,:) / Aug (j,j);
18 end
19 B = Aug(:, n+1:2*n);
20 disp ("The inverse of Ais:");
21 disp(B);
```

```
"The inverse of A is:"

0.75   0.5   0.25

0.5   1.   0.5

0.25   0.75
```

## **Topic: Span of the Column Space of A**

**PROBLEM 4:** Identify the columns that are in the column space of A where  $A=\{[2,4,6,4],[2,5,7,6],[2,3,5,2]\}$ 

#### **CODE:**

```
P4-Span of column space_PES2UG19CS309.sce (C:\Users\sharm\P4-Span c
<u>F</u>ile <u>E</u>dit Format Options Wi<u>n</u>dow <u>Execute</u> ?
P4-Span of column space_PES2UG19CS309.sce
1 clc;clear;
2 a -= - [2 - 4 - 6 - 4; 2 - 5 - 7 - 6; 2 - 3 - 5 - 2];
3 disp("The -given -matrix -is:");
4 disp(a);
5 a(2,:) = a(2,:) - (a(2,1)/a(1,1))*a(1,:);
6 | a(3,:) = a(3,:) - (a(3,1)/a(1,1))*a(1,:);
7 disp(a);
8 a(3,:) = a(3,:) - (a(3,2)/a(2,2))*a(2,:);
g disp(a);
10 a(1,:) = a(1,:)/a(1,1);
11 a(2,:) = a(2,:)/a(2,2);
12 disp(a);
13 for · i=1:3
     ---for-j=i:4
14
15
         ...if(a(i,j)<>0)
           ----disp("is-a-pivot-column",j,"column");
16
             ---break;
17
18
          --end
    ---end
19
20 end
```

```
#The given matrix is:"

2. 4. 6. 4.
2. 5. 7. 6.
2. 3. 5. 2.

2. 4. 6. 4.
0. 1. 1. 2.
0. -1. -1. -2.

2. 4. 6. 4.
0. 1. 1. 2.
0. 0. 0. 0.

1. 2. 3. 2.
0. 1. 1. 2.
0. 0. 0. 0.

#Is a pivot column

1.

"column"

"is a pivot column"

2.

"column"

-->
```

## **Topic: The Four Fundamental Subspaces**

**PROBLEM 5:** Find the four fundamental subspaces of  $A = \{[1,2,0,1],[0,1,1,0],[1,2,0,1]\}$ 

#### **CODE:**

```
P5-Four fundamental subspaces_PES2UG19CS309.sce (C:\Users\sharm\P5-Four fundamental subspaces_PES2UG19CS309.sce)
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P4-Span of column space_PES2UG19CS309.sce 🛛 P5-Four fundamental subspaces_PES2UG19CS309.sce
2 A -= · [1 · 2 · 0 · 1; 0 · 1 · 1 · 0; 1 · 2 · 0 · 1];
3 disp("The given matrix is:");
4 disp(A);
5 [m, n] -= -size(A);
 6 disp(m, "m -= - ");
7 disp(n, "n -= - ");
8 [v,pivot] -= - rref(A);
g disp(rref(A), "Row-Reduced-Echelon-Form: -");
10 r -= ·length (pivot);
11 disp(r, "Rank: .");
12 colspace -= -A(:,pivot);
13 disp(colspace, "Column - Space: - ");
14 nullspace -= · kernel (A);
15 disp(nullspace, "Null-Space: .");
16 rowspace -= v(1:r,:)';
17 disp(rowspace, "Row - Space: - ");
18 leftnullspace -= · kernel (A');
19 disp(leftnullspace, "Left - Null - Space: - ");
```

```
"Row Reduced Echelon Form: "

2.

"Rank: "

1. 2.

0. 1.

1. 2.

"Column Space: "

3.909D-17 -0.8660254 -0.4082483 0.2886751 0.4082483 -0.2886751 0.8164966 0.2886751

0.8164966 0.2886751

"Null Space: "

1. 0.

0. 1.

-2. 1.

1. 0.

"Row Space: "

-0.7071068

1.106D-16

0.7071068

"Left Null Space: "
```

## **Topic: Projections by Least Squares**

**PROBLEM 6:** Find the solution x = (C, D) of the system Ax = b and the line of best fit C + Dt = b given  $A = \{[1,0],[0,1],[1,1]\}$  and  $b = \{[1,1,0]\}$ 

#### **CODE:**

```
P6-Projection of least squares_PES2UG19CS309.sce (C:\Use
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P6-Projection of least squares_PES2UG19CS309.sce
1 clc;clear;
2 A -= - [1 -0;0 -1;1 -1];
 3 b = [1;1;0];
 4 | disp("The .given .matrix .A .is:")
 5 disp(A);
 6 disp(b, . "b: . ");
 7 \times - (A' *A) \setminus (A' *b)
8 C = -x(1,1);
 9 D = -x(2,1);
10 disp(C, "C: . ");
11 disp(D, "D: . ");
12 disp ("The .best .fit .line .is .b .= .C+Dt")
13
```

```
Solab 6.1.0 Console

"The given matrix A is:"

1. 0.
0. 1.
1. 1.
1.
0.
"b: "
0.3333333

"C: "
0.3333333

"D: "

"The best fit line is b = C+Dt"

-->
```

## **Topic: The Gram- Schmidt Orthogonalization**

**PROBLEM 7:** Apply the Gram – Schmidt process to the following set of vectors and find the orthogonal matrix:

```
(1,0,1),(1,1,0),(2,1,1)
```

#### **CODE:**

```
P7-Gram-schmidt orthogonalisation_PES2UG19CS309.sc
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P7-Gram-schmidt orthogonalisation_PES2UG19CS309.sce (C:\Us
P7-Gram-schmidt orthogonalisation_PES2UG19CS309.sce
1 clc;clear;
2 A= - [1 -0 -1; 1 -1 -0; 2 -1 -1];
3 disp(A, -"The -given -matrix -A - is:");
4 [m, n] -= size(A);
5 for - k=1:n
6 \cdot \cdot \cdot \cdot V(:,k) = \cdot A(:,k);
7 ----for-j=1:k-1
8 -----R(j,k) -= -V(:,j) '*A(:,k);
10 ----end
11 - - - R(k, k) -= - norm(V(:, k));
12 - - V(:, k) = -V(:, k) / R(k, k);
13 end
14 disp(V, "Q: . ");
15
```

```
1. 0. 1.
1. 1. 0.
2. 1. 1.

"The given matrix A is:"

0.4082483 -0.7071068 -0.842701
0.4082483 0.7071068 0.2407717
0.8164966 -3.140D-16 -0.4815434

"Q: "
```

## Topic: Eigen values and Eigen vectors of a given square matrix

**PROBLEM 8:** Find the Eigen values and the corresponding Eigen vectors of  $A=\{[8,-6,2],[-6,7,-4],[2,-4,3]\}$ 

#### **CODE:**

```
👺 P8-Eigen values and vectors_PES2UG19CS309.sce (C:\Users\sharm\P8-Eigen valu
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P8-Eigen values and vectors_PES2UG19CS309.sce (C:\Users\sharm\P8-Eigen values and v
P8-Eigen values and vectors_PES2UG19CS309.sce
1 clc;clear;
2 A = [8 - 6 - 2; -6 - 7 - 4; 2 - 4 - 3];
3 disp(A, "The given matrix A is: ")
4 | lam -= .poly(0,"lam");
5 charMat -= A-lam*eye(3,3);
   disp(charMat, "The -Characteristic -Matrix -is: -");
   charPoly -= · poly(A, "lam");
  disp(charPoly, "The - Characteristic - Polynomial - is: ");
g lam = spec(A);
10 disp(lam, "Eigen · Values: · ");
1 function [x, lam] -= eigenvectors (A)
     ···[n,m] ·=·size(A);
      ---lam -= - spec (A) ';
4 5
     . . . x .= . [];
      ---for-k=1:3
      ... B = A-lam(k) *eye(3,3);
       ... C = B(1:n-1,1:n-1);
      b = a - B (1:n-1,n);
       y = x \cdot C \cdot b;
10
      ....y = [y;1];
       - - - y - = - y/norm(y);
11
          \mathbf{x} \cdot \mathbf{x} \cdot \mathbf{x} = \mathbf{x} \cdot [\mathbf{x} \cdot \mathbf{y}];
12
14 endfunction
25 [x,lam] = eigenvectors (A);
26 disp(x, "Eigen · Vectors · of · A: · ");
```

```
Scalab 6.1 O'Console

8. -6. 2.
-6. 7. -4.
2. -4. 3.

"The given matrix A is: "

8 -lam -6 2
-6 7 -lam -4
2 -4 3 -lam

"The Characteristic Matrix is: "

-7.128D-14 +45lam -18lam<sup>2</sup> +lam<sup>3</sup>

"The Characteristic Polynomial is:"

1.584D-15
3.
15.

"Eigen Values: "

0.3333333 -0.6666667 0.6666667
0.6666667 -0.3333333 -0.6666667
0.6666667 0.6666667 0.3333333 -0.6666667
```