Ritesh Sharma

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Education

Ph.D. in Computer Science (CGPA 4.0/4.0)

August, 2018 - Present

Research Area: Computer Graphics, Navigation, Path planning, Spatial representation and Visualization

Advisor: Professor Marcelo Kallmann University of California, Merced, California

M.S. in Computer Science (CGPA 3.45/4.0)

March, 2017

Computer Graphics and Visualization

Thesis: Interactive Design and Transition Point Analysis of 3D Linear Symmetric Tensor Fields

Advisor: Professor Eugene Zhang

Oregon State University, Corvallis, Oregon

B. Tech. in Computer Science and Engineering (CGPA 8.45/10)

August, 2010

West Bengal University of Technology, India

Professional Experience

Graduate Student Researcher, University of California, Merced, United States

May 19 - Present

• Investigating research topics in Path planning, Navigation and Crowd Simulation in 2D and 3D and visualization of navigation metrics in 2D.

PhD Researcher(Intern), Hasso-Plattner-Institut, Potsdam, Germany

May 20 - present

• Investigating topics in geometry interaction related to laser cutting.

Senior Graphics Programmer, Passur Aerospace Inc., United States

May 17 - August 18

- Software Development
 - Developed interactive graphical user interface and visualize shape files for new functionalities in Passur's web tracker and desktop-based flight tracking system.
 - Contributed to back-end by writing server side code to communicate with database.
 - Contributed to the foundation of the company's product used by major airlines and airports, US and International, by building core functionality and integration with React/Redux from scratch.

Intern (Mathematica Algorithm R&D), Wolfram Research Inc., United States

Apr 16 - Aug 16

- Software Development
 - Developed software package to connect Wolfram's Mathematica with Pixar's Renderman.
 - Software package testing for geometry primitives, plot functions and functionalities used for 3D Printing.

Graduate Research Assistant, Oregon State University, United States

Mar, 14 - Dec, 16

- 3D Symmetric Tensor Field Analysis and Visualization
 - Improved topology extraction techniques using A-Patches and by solving analytical solutions.

Research Assistant, Indian Institute of Technology Bombay, India

Oct, 10 - Dec, 13

- Virtual Laboratory for Urban Transportation System Planning Course
 - Developed an accurate, reliable and autodidactic web-based virtual laboratory

Publications

- Sharma, R., Weiss, T., Kallmann, M., Formation-Aware Planning and Navigation, Eurographics (Full paper), 2021 (Submitted).
- Sharma, R., Weiss, T., Kallmann, M., Plane-Based Local Behaviors for Multi-Agent 3D Simulations with Position-Based Dynamics, IEEE International Conference on Artificial Intelligence and Virtual Reality (IEEE AIVR), 2020.

- Sharma, R., Weiss, T., Kallmann, M., 3D Behaviors for Multi-Agent Simulations with Position-Based Dynamics, ACM SIGGRAPH Symposium of Interactive 3D Graphics and Games(I3D) 2020 (Poster paper), San Francisco, United States, 14th-18th September, 2020.
- Sharma, R., Farias, R., Kallmann, M., Integrating Local Collision Avoidance with Shortest Path Maps, EuroGraphics 2020 (Poster paper), Norrkoping, Sweden, May 25th-29th, 2020.
- Sharma, R., Tomson, A., Lobato, E., Kallmann, M., Padilla, L., Data Driven Multi-Hazard Risk Visualization, Euro Vis 2020 (Poster paper), Norrkoping, Sweden, May 25th-29th, 2020.
- Zhang, Y., Sharma, R., Zhang, E., Maximum Number of transition points in a 3D Linear Symmetric Tensor Fields, TopoInVis 2017, Tokyo, Japan, Feb 27th-28th, 2017
- Jenny, B., Stephen, D. M., Muehlenhaus, I., Marston, B. E., Sharma, R., Zhang, E., Jenny, H, Force-directed layout of origin-destination flow maps, International Journal of Geographic Information Science (IJGIS), 2017
- Zhang, E., Palacios, J., Yeh, H., Wang, W., Zhang, Y., Laramee, B., **Sharma, R.**, Schultz, T., Feature Surfaces in Symmetric Tensor Fields Based on Eigenvalue Manifold, IEEE TVCG, Issue 99, March 1, 2016. Also featured at **ACM SIGGRAPH ASIA 2016** and **IEEEVIS 2016**.
- Jenny, B., Stephen, D. M., Muehlenhaus, I., Marston, B. E., **Sharma, R.**, Zhang, E., Jenny, H, Design Principles for Origin-destination Flow Maps, Cartography and Geographic Information Science (CaGIS), 2016
- Nelson, V., Sharma, R., Zhang, E., Schmittner, A., Jenny, B., 3D visualization of global ocean circulation, AGU Fall Meeting, San Fransisco, CA, Dec 18, 2015
- Stephen, D., Jenny, B., Sharma, R., Zhang, E., Muehlenhaus, I. (2015). Automatic Flow map creation using a force-directed layout. North American Cartographic Information Society Annual Meeting, Minneapolis, MN Oct. 15, 2015
- Sharma, R., Jadhav, S., Tripathy, D., Sardar, V. H., Patil, G. R., Virtual Laboratory: An alternative approach to Urban Transportation Systems Planning Lab, Transportation Research Board, 93rd Annual Meeting, Washington, D.C, USA, 2014

Technical Skills

- Programming and Scripting Languages: C(Proficient), C++(Proficient), GLSL, PHP, HTML, CSS, Javascript, JQuery, Wolfram Language
- Frameworks and Platforms: wxWidgets, QT, OpenGL, OpenMP, OpenCL, EmberJS, React, Redux, GitHub, GitLab and Stash
- Software: Microsoft Visual Studio, Matlab, Eclipse, Netbeans, Renderman, Mathematica, Wolfram Workbench, Rhinoceros 3D, Unity3D, Unreal Engine 4.0, WebStorm 2018

Teaching Experience

Teaching Assistant, University of California Merced

August 18 - June 20

- CS 020: Introduction to Computing I: Java (Spring 2020)
- CS 030: Data Structures (Fall 2018, Spring 2019)
- CS 165: Introduction to Object Oriented Programming: C++ (Spring 2020)
- CS 170: Computer Graphics (Fall 2019)

Graduate Teaching Assistant, Oregon State University

Jan, 14 - March, 17

- CS 325: Analysis of Algorithm (Winter 2016)
- CS 340: Introduction to Databases (Spring 2014, Spring 2015, Summer 2015)
- CS 344: Operating Systems I (Winter 2017)
- CS 480: Translators (Winter 2014)

Academic Projects

• Predictive Modeling of Flood Susceptibility, Phase 1

- Worked with group of researcher from different discipline at UC Merced and USRA (University Space Research Association) for modeling and visualization of predictive based flood visualization.
- Realtime Multi-Agent Crowd Simulation
 - Implemented algorithm from the paper titled Position-Based Multi-Agent Dynamics for Real-Time Crowd Simulation by T. weiss et. al. (2017), as part of Computer Animation and Simulation Class at UC Merced.
- 3D visualization of global ocean circulation
 - Developed a visualization tool for showcasing mixing of ocean water at different density level and its effect on the distribution of tracers such as carbon isotopes.
- Isosurface Extraction using A-Patches
 - Achieved a better isosurface defined by a polynomial of any degree using A-Patch.
- Smoke Simulation
 - Implemented particle based method to simulate smoke.
- Pool Game Animation
 - Implemented Pool game simulation.
- Flow Visualization
 - Implemented Line Integral Convolution to visualize vector field using streamlines.

Graduate Course Highlights

University of California Merced • EECS 287: Computer Animation and Simulation A Oregon State University • CS 551: Computer Graphics • CS 554: Geometric Modeling • CS 557: Computer Graphics Shaders • CS 575: Intro to Parallel Computing Awards

- GRAD EXCEL Peer Mentorship Award 2020
- UC Merced EECS Bobcat Travel Fellowship 2020
- Travel award for NSF sponsored SOCG 2019, Portland, Oregon
- UC Merced EECS Bobcat Fellowship 2019
- UC Merced EECS Bobcat Travel Fellowship 2019
- Graduate Assistantship (Full tuition & Stipend) at University of California Merced (2018- Present)
- Graduate Assistantship (Full tuition & Stipend) at Oregon State University (2014-2017)
- Received Honorary Citizenship of Corvallis, Oregon for contributions and achievements at Oregon State University by the mayor of city of Corvallis, Oregon, United States

Journal/Proceedings Reviewer

• ACM MIG 2019, ACM MIG 2020, ICAPS 2019, CASA 2019, CASA 2020

Co-Curricular

• Peer mentor for two first year PhD students under UC Merced GRAD-EXCEL Peer Mentor Program for the academic year 2020-2021.

- Served as the Secretary of the Merced Indian Graduate Student Association (MIGSA) at University of California Merced for the academic year 2019-2020, California, USA
- Poster Presentation on "3D Symmetric Tensor Field Visualization" at Engineering Research Expo held at Portland Art Museum, Portland, Oregon, Mar 1, 2016.
- Mentored a senior undergraduate student under REU (Research Experience for Undergraduate) Program during Summer 2015, funded by NSF.
- Poster Presentation on "Mode Surface Extraction Using A-Patches" at Engineering Research Expo held at Oregon Convention Center, Portland, Oregon, Mar 4, 2015.
- ACM and ACM SIGGRAPH Student Member since 2015
- Served as Student Volunteer at ACM SIGGRAPH 2019 held at Los Angeles, July 28th August 1st, 2019

References

Professor Marcelo Kallmann (PhD Advisor)

University of California, Merced, USA Email: mkallmann@ucmerced.edu

Professor Patrick Baudisch

Hasso-Plattner-Institut, Potsdam, Germany Email: patrick.baudisch@hpi.de

Professor Tomer Weiss

New Jersey Institute of Technology, USA Email: tweiss@njit.edu

Matt Marcella

 $SVP,\ Software\ Development,\ Passur\ Aerospace\ Inc.,\ USA\\ Email:\ mattmarcella@passur.com$

Charles Pooh

Manager, Mathematica Algorithm R & DWolfram Research Inc., USA Email: charlesp@wolfram.com