# **HW-4**

## **Problem-1**

### 1 i)

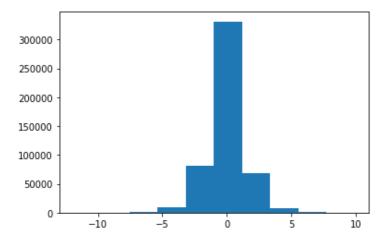
```
In [49]:
```

```
import math
import numpy as np
import random
def target distribution(x):
   return 0.5 * math.exp(-abs(x))
def proposal normal distribution(mean, sd, num of samples):
    return np.random.normal(mean, sd, num of samples)[0]
x = [0] * 500000
x[0] = 0
for i in range(1,500000):
   current x = x[i-1]
   proposed x = proposal normal distribution(current x, 1, 1)
   A = target distribution(proposed x)/target distribution(current x)
    if (random.uniform(0.0,1.0) < A):
                             # accept move with probabily min(1,A)
       x[i] = proposed x
    else:
                             # otherwise "reject" move, and stay where we are
       x[i] = current x
```

### In [50]:

```
plt.hist(x)
```

#### Out[50]:



The sampled values seem to converge to a distribution centered at 0 and resembles like an standard double exponential distribution.

### 1 ii)

```
In [81]:
```

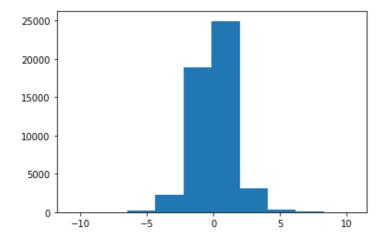
```
x2 = [0]*50000

for i in range(50000):
    u2 = random.uniform(0.0,1.0)
    if u2 < 0.5:
        x2[i] = math.log(2*u2)
    else:
        x2[i] = -1*math.log(2-2*u2)</pre>
```

#### In [101]:

```
plt.hist(x2)
```

#### Out[101]:



The curve generated using inverse sampling is comparable to the one generated in part-a) and can be seen following the double exponential distribution

### **Problem 2**

#### In [72]:

```
def target_distribution(x):
    return 1/6

def transition_probabilities(state, given_state):
    if given_state == 1:
        if state == 2: return 1
        else: return 0

    elif given_state == 2:
        if state == 1 or state == 3: return 0.5
        else: return 0

    elif given_state == 3:
        if state == 2 or state == 4: return 0.5
        else: return 0

    elif given_state == 4:
        if state == 3 or state == 5: return 0.5
```

```
else: return 0
   elif given state == 5:
       if state == 4 or state == 6: return 0.5
       else: return 0
    else:
       if state == 5: return 1
       else: return 0
def sampling from proposal distr(current state):
   if current state == 1: return 2
   elif current state == 2: return random.choice([1, 3])
   elif current state == 3: return random.choice([2, 4])
   elif current state == 4: return random.choice([3, 5])
   elif current state == 5: return random.choice([4, 6])
   else: return 5
y = [0] * 50000
y[0] = 2
for i in range(1,50000):
   current_y = y[i-1]
   proposed y = sampling from proposal distr(current y)
   A = transition probabilities(current y, proposed y)/transition probabilities(proposed
_y, current_y)
   if (random.uniform(0.0,1.0) < A):
                             # accept move with probabily min(1,A)
       y[i] = proposed y
    else:
                                # otherwise "reject" move, and stay where we are
       y[i] = current y
```

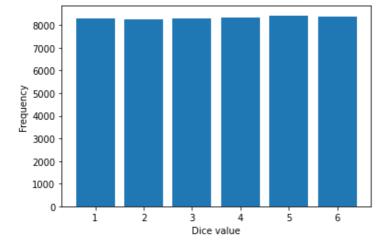
#### In [73]:

```
import collections
c = collections.Counter(y)
c = sorted(c.items())

freq = [i[1] for i in c]
dice_value = [i[0] for i in c]

plt.bar(dice_value, freq)
plt.xlabel("Dice value")
plt.ylabel("Frequency")

plt.show()
```



The sample distribution of dice values shows all the values occuring almost the same number of times. Above is the frequency distribution of dice values. It resembles the target distribution wherein each dice value had equal probability.

