Dynamic Programming Forward Approach Stage Vestex innext
stage 7 Cost(i,j) = Min((j,r) + Cost(i+1),r)Slage Wastex \* Destination to Source to some d[j] = 8 \* To find Shootest distance source to destination Backward Approach  $God(i,j) = Min\{c(x,j) + God(i-1,x)\}$ d[j]=8 \* Source to Deshiation \* To find Shootest distance destination to Source Oll Knapsach Tabular Melhod, T[i,j]= Max {T[i-1,j], Pi+T[i-1,j-y]} は Wi>=j 作(7(1)力+每下[1-1)内 1=1-1 & K= K-W, )

20(04)

 $W(i,j) = \sum_{k=i}^{j} P_k + \sum_{k=i}^{j} q_k \quad j \mid k \mid j$ W(isj) - P;+Qj+W(isj-1) J-1=0,1,4,3,4. ...  $C(i)j) = Min \{ ((i)k-1) + c(k,j) \} + Wij$ (i, k-1) (k, j) r(inj)= K TRAVVELLING SALESPERSON PROBLEM g(i,5) = Min [c(i,j) + g(j,5-{j}) P[i,5] = 5 All pairs Shorlest Path Poblem (Flojd Warshell Ago) Ar(i)j)= Ar-1(i)K) + Ar-1(K)j) , Ar-1(i)j) Single Source Shooted path Using DP (Bellman) Ford Angoriam) distr[u] = Minfdistr[u], Minfdistr[u]+CoA[iu])

$$* single Source (Bellman prol)$$
 $T(=|[E|*n-1)=) O((n-1)*(n-1)) = O(n^2)$ 

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JREFD Y
+ Fractional Knapsach
 Time Complexis
a) uinimum time to soon one corray: O(nlogn)
5) Time required to choose the jeasible set: \(\frac{n}{2}\) = n = o(n)
   7C = O(nlog n) + \alpha(n) = O(nlog n)
* Krushal
 Consmission of heap O(IFI)
  soons one Edge bond on weights:
    TC= O(IELlogIEI) E> Edge Set 9 G
X PRIM
 1(= 0(n²) 0R0(v²) where n=v= vonces
  10 ears & reduced using Binary heap
 * Dijkstra's MgonDin
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O((n+IE))log n