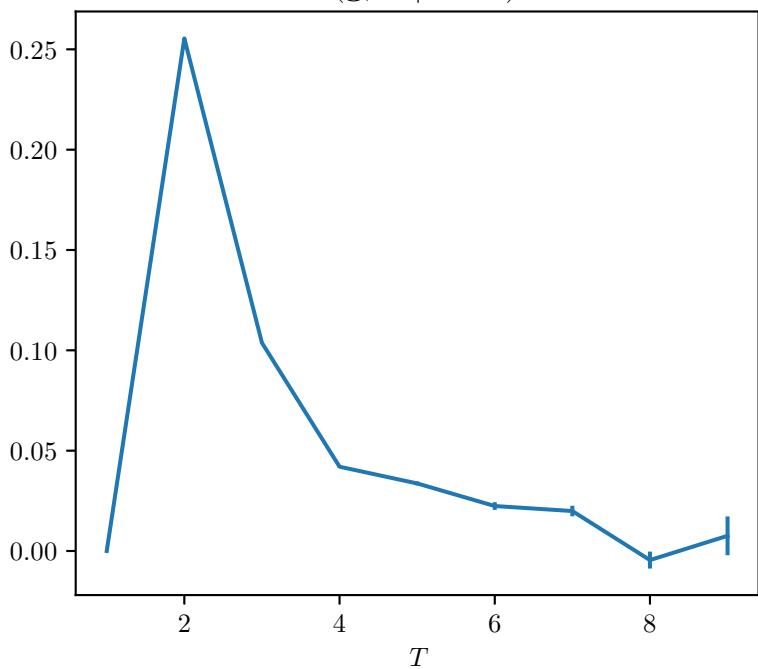


N=2, L=2

$I(\mathbf{g}, \mathbf{x}_T | \mathbf{x}_{1:T-1})$



$I(\mathbf{g}, \mathbf{X})$

