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Tribhuvan University Institute of Science and Technology

FINAL REPORT

On

PLANT TECH SOLUTIONS- "Detection of Plant Diseases"

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ABSTRACT

Manually detection of plant disease is very difficult, costly and time consuming. Inaccuracy in identification of plant disease may cause the great loss in the production and economical value of market. Detection of plant disease may require huge amount of knowledge and work on plant disease. Therefore, we use the image processing technique for detection of plant's leaf detection. Initially, user i.e. farmer clicks a picture of the affected leaf and uploads the picture it to the server via the android application. The proposed system aims to overcome the pitfalls of the existing system and provides features such as detection of plant disease, feature extraction, analysis of data. Then the result consisting of the disease name with the accuracy is retrieved using CNN algorithm.

Keywords: Leaf Disease, CNN.

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LIST OF ABBREVIATIONS

CNN Convolutional Neural Network

API Application Programming Interface

JPG/JPEG Joint Photographic Experts Group

RGB Red-Green-Blue

Adam Adaptive Moment Estimation

AdaDelta Adagrad Delta

ConvNet Convolutional Network

ReLU Rectified Linear Unit

ANN Artificial Neuron Network

SGD Stochastic Gradient Descent

CHAPTER 1

INTRODUCTION

1.1. Overview

Nepal is a developing country and agriculture is the backbone for the earlier development of the country. Nepali Economy is highly dependent on agriculture. Around 60% of people are directly engaged on farming [1]. Now a day's technology plays a vital role in all fields but we are still using the old methodologies in agriculture. Identifying plant disease is high yield, money, time and quality product. Identifying the condition of plant is very important in successful cultivation. An experienced person does identification manually but due to the environmental condition, prediction is very tough. Thus, we can use image-processing technique for the detection of plant diseases.

Plant Tech Solutions is a mobile application that detects the disease of the plant and gives the information about the plant to the user. System architecture and algorithms used in each stage is described in this proposal. The "Plant Tech Solutions" is an application of disease detection. Conventional neural network algorithm is used to develop this project. Generally, the system can detect the leaf disease of the plant but here we have used the Paddy leaf for the identification of disease.

1.2. Statement of Problem

Farmer's economic growth depends on the quality of food that they produce. In an agriculture, detection of plant disease is very important. However, it is very difficult to identify the disease manually. Plants are highly prone to disease that affect the growth of plant which turns affect the ecology of the farmer [1]. Plant disease may affect the different part of the plants like leaves, stems, seeds, etc. Manually detection of plant disease is very difficult, costly and time consuming. Inaccuracy in identification of plant disease may cause the great loss in the production and economical value of market. Hence, it is required to detect the disease in computational method by the classification of leaf automatically.

1.3. Objectives

The main objectives of the project are:

- To detect the disease of Paddy leaf.
- To display the result about the leaf disease to the user.

1.4. Limitations

The limitations of the project are:

- The PlantTechSolutions only detects the Paddy leaf,
- This project cannot determine the disease on stem, roots, seeds, of paddy,
- This project determines few of the diseases name only.

1.5. Report Organization

Our report is organized into 5 chapters:

Chapter 1: Introduction

In this section the brief introduction of our project, statement of the problem and its objectives are discussed.

Chapter 2: Requirement analysis

The previous work related to our projects were studied and different feasibility analysis are summarized in this section.

Chapter 3: System Design

In this section, we have designed the structuring system requirement like activity diagram, sequence diagram, database, etc.

Chapter 4: Implementation and Testing

In this section, various implementation method and tools are described. This part also contains the description of various testing and results we got after performing.

Chapter 5: Conclusion and Enhancement

CHAPTER 2

REQUIREMENT ANALYSIS

2.1. Literature Review

Plant diseases have turned into a dilemma as it can cause significant reduction in both quality and quantity of agricultural products [1]. Finding whether the plant leaf has disease or not is common issue to farmer. Farmers used to predict the plant disease manually with their naked eyes. However, some techniques were implemented but are limited in practice. Also, there is an application called "E-agrovet" which detects whether the plant is healthy or not. It also shows the pH value, temperature, water level and soil moisture.

The project called image-processing technique for Leaf & Stem disease detection used a set of leaf images from Jordan's AI Ghor Area. The five plant diseases namely: Early scorch, ashen mold, late scorch, Cottony mold and tiny white less is tested by image processing technique. In this technique at starting, image acquisition is obtained and then K-Means clustering method is used for segmentation. After that in feature extraction, CCM (Color Co-occurrence Method) is used for texture for neural network in classification of plant diseases. Result of this image processing technique shows accurate detection and classification of plant disease [2].

A web enabled disease detection system (WEDDS) based on compressed sensing (CS) is proposed to detect and classify the diseases in leaves [3]. The diseased leaf is segmented using statistical based on thresholding. The analysis and classification are done using support vector machine classifier. The performance of the proposed WEDDS has been evaluated in terms of accuracy and also evaluated experimentally using Raspberry pi 3 board [3].

In Vision Based Plant Leaf Disease Detection on The Color Segmentation through Fire Bird V Robot [4], the detection of plant leaf disease is based on the texture of the leaf. The processing scheme consists of image acquisition through digital camera connecting to the Fire Bird V Robot [4]. It uses the image pre-processing techniques that includes image enhancement and image segmentation where the affected leaf are segmented feature extraction and classification.

The main difference between these projects and our plant tech solutions is that it has high Image transformation in frequency domain, which gives better classification. Specifically, we are working on paddy Leaf for detecting diseases. The Convolutional Neural Network uses the different layers i.e. input layer, output layer and other hidden layers. The image is passed through a series of convolutional, nonlinear, polling layers and fully connected layers, and then generated the output. Result of our Plant tech solutions technique will show accurate detection and classification of plant diseases with high accuracy.

2.2. Requirement Analysis

2.2.1 Functional Requirements

Functional requirements identify the provision of the system and the system's reaction to the certain output and how the system should behave in day to day basis. This system is focused on capturing the image of paddy leaf, classify and detect the disease.

The functional requirements of "Plant Tech Solutions" includes the following tasks: -

- System should upload the image of plant leaf and classify them in no time.
- System should not take long to classify and test the image.
- System should detect the disease correctly.
- The result must be display to the user after detection.

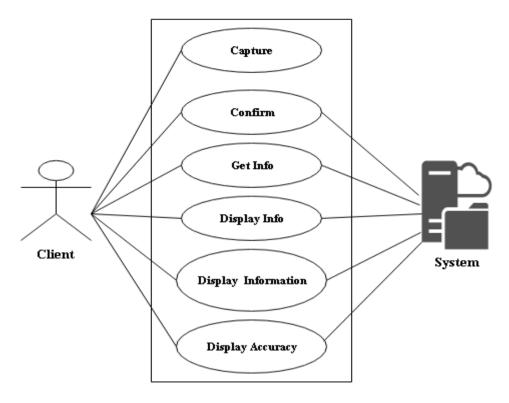


Figure 2. 1 Use Case Diagram

2.2.2 Non-Functional Requirements

- **Usability:** The system needs to be usable by every user.
- **Maintenance:** The system needs to be maintainable.
- Extendable and Scalability: The system is extendable and scalable for future enhancements.

2.3. Feasibility Analysis

2.3.1. Economic Feasibility

The purpose of economic feasibility assessment is to determine the positive economic benefits to the organization that proposed system will provide. It includes quantification and identification of all the benefits expected. This assessment typically involves a cost/benefit analysis. The probable cost at the first step of the project includes all the hardware and software costs, which are minimal for our project. This may increase as we scale the app for more users and more UX elements. Hence, we can say that this project has been found to be economically feasible.

2.3.2. Technical Feasibility

This assessment is based on an outline design of system requirements to determine whether the company/team has the technical expertise to handle completion of the project. It is an evaluation of the hardware and software and how it meets the need of proposed system.

As per the requirement analysis, it was observed that technical expertise in the programming language Python, Machine Learning, JAVA and in the markup language XML is involved in the project. Familiarity with the application development in the Android environment is necessary. Owing to our familiarity with OOP based programming language and markup language we found the project will be technically feasible.

2.3.3. Operational Feasibility

Operational Feasibility is the measure of how a proposed system solves a problem and takes advantages of the opportunities identified during scope definitions and how it satisfies the requirements identified in the requirement analysis phase of the project development. To ensure success, desired operational outcomes must be imparted during design and development. These include such design-dependent parameters such as reliability, maintainability, usability, productivity, sustainability and others. This project "Plant Tech Solutions" an android application makes all of these parameters. Hence, we will be able to say that our project is operationally feasible.

CHAPTER 3 SYSTEM DESIGN

3.1. System Architecture

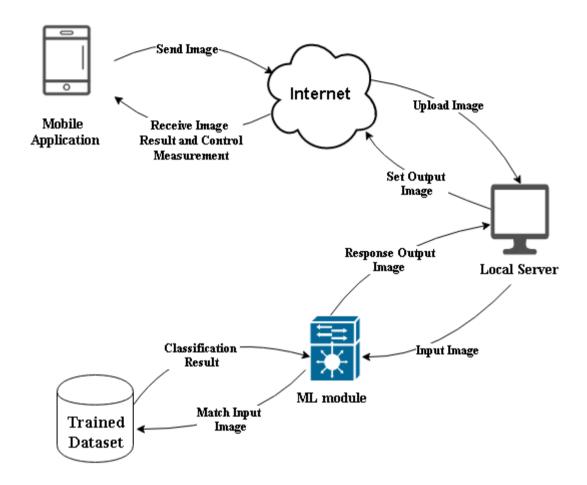


Figure 3. 1 System Architecture

3.2. Flow Diagram of a System

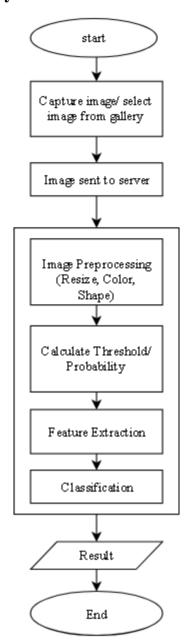


Figure 3. 2 Flow Diagram of a System

3.3. Sequence Diagram

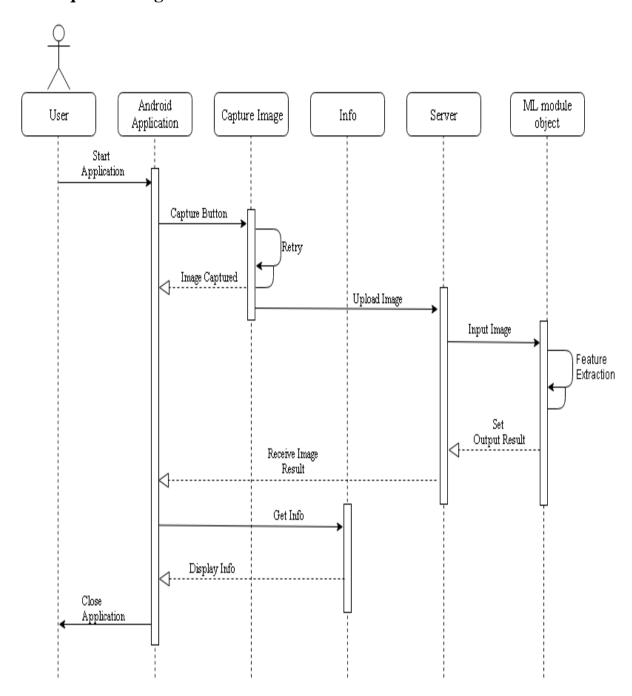


Figure 3. 3 Sequence Diagram

3.4. Class Diagram

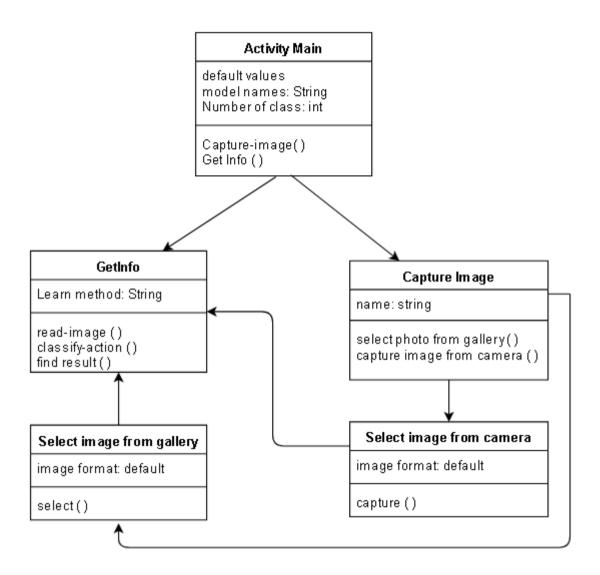


Figure 3. 4 Class Diagram

4.4 Algorithm for PlantTechSolutions

The system is based on a supervised classification algorithm. The supervised learning algorithms require labeled data to classify the input. The algorithms learn from the labeled data and then classify the input to predefined class. The system implements a Convolutional Neural Network to recognize the image. The system's ConvNet model is feed with 2066 training sample.

INPUT: Image

OUTPUT: Recognized Image

Step 1: Start

Step 2: Create training and testing dataset

Step 3: Train NN model

Step 4: Save model and fit it to the flask i.e. a local server

Step 5: Load model to android device through ngrok

Step 6: Input test image

Step 7: Feed image to pre-trained model

Step 8: Display output

Step 9: Stop

CHAPTER 4

IMPLEMENTATION AND TESTING

4.1. Methodology

4.1.1. Data Collection and Algorithms

The data used in this project are the images of the Paddy leaf among which of them were fed into the model for the training model and some were used for testing purpose and we downloaded it by creating the account from Kaggle.

Kaggle

Kaggle is an online platform that allows user to find and publish datasets. An open dataset forum helps the user and the researcher to build models and solve the data science problems [5].

The detailing of data collection and modification is described below:

- 1. Downloaded dataset from Kaggle. We downloaded dataset labelled into four categories:
 - i) BrownSpot
 - ii) Healthy
 - iii) Hispa
 - iv) LeafBlast

Each label consists of multiple images of different size.

Attribute Information:

The format of all images is .jpg format. The images were reduced to the desired resolution for processing. The below table contains the dataset attributes that describes the shape, size, color and datatype of the dataset.

Datatype	Attribute		Numb	er of Ins	tances		Number
	Characteristics						
Image	Categorical	S.No.	BrownSpot	Hispa	Healthy	LeafBlast	Around 5
		i.	523	565	1488	779	
		ii.	117	31	54	94	

Table 4. 1 Secondary Dataset

The secondary dataset is merged

- (i) from Kaggle
- (ii) from google by running script.

These datasets of different class are used for training the ML module. First, these datasets are split into training, testing and validation set with the ratio 6:2:2 by running script to train the dataset using CNN algorithm.

	BrownSpot	Hispa	Healthy	LeafBlast	Total
Train	384	320	839	523	2,066
Test	128	107	297	175	707
Validation	128	107	298	175	708
	640	534	1,434	873	3,481

Table 4. 2 Dataset Partition

Image Processing Techniques

For the software development methodology for our project, we have chosen digital image processing. The phase in Image Processing are organized in such a way that current step provides the deliverables for the next phase. The figure below shows the following steps:

-

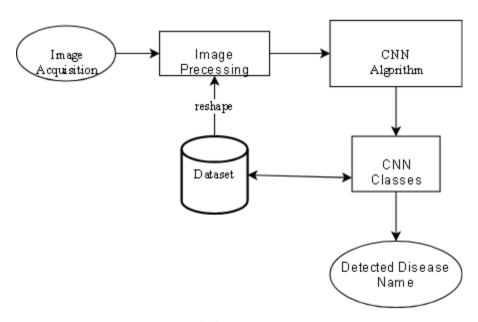


Figure 4. 1 Image Processing

Initially, input image is given from the android application. The input image is then preprocessed by using library called OpenCv. The color image format is read by using Cv2.IMREAD_COLOR method and the image is resized by using the Cv2.resize() function.

Classification

We have used Convolutional Neural Network Algorithm as an image classifier. A CNN consist of number of convolutional and sampling layers optionally followed by fully connected layers. The network will consist of several convolutional neural networks mixed with non-linear and pooling layers.

4.2. Implementation

Incremental Prototyping Model

Based on the Incremental Prototyping Model we first design a prototype of the script that uses the Kaggle datasets and Sklearn's CNN functions which detect the disease on paddy leaves and then confirms whether the data is healthy or not, if not healthy then gives the unhealthy percentage.

At First, we capture the image, which is then send to the system and after then analysis is done; the result of image is thus given back to the user. Here, the CNN algorithm is implemented in the script with our datasets collected from the system server. Further components (detection of diseases occurred on stem, root) can be added in the future as per the user needs.

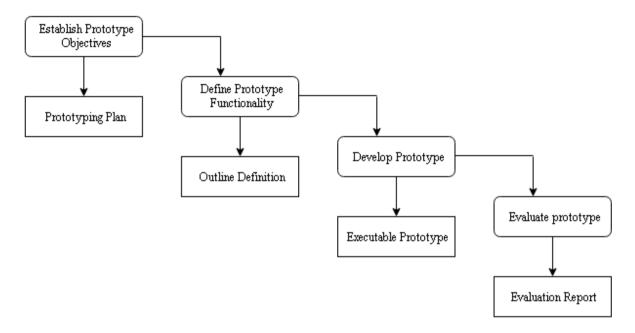


Figure 4. 2 Incremental Prototyping Model

Implementation is the process of building properly working system, and installing it to use its services. Implementation usually consists of coding, testing, installation, documentation, training and support. The implementation consists of 5 modules:

- Preprocessor: prepares the images from the dataset for the NN
- Model: creates the model as described above, loads and saves models, and provides an interface for training and inference
- PassToLocalServer: Pass saved models to Server Flask.
- AndroidInterface: Develop Interface through for user interaction.
- RunLocalServer: To run CNN classifier.

Preprocessor

For preprocessing two function create_training_data and create_test_data were created. This function takes image path and read all the images from different classes and append append all image to training_data list after resizing the image. The same process is done for creating test data.

4.1.1. Analysis and Design Tools

There is various presence of designing tools to create figures and diagrams like use case diagram, sequence diagram and another desired diagram. In this project, Draw.io (i.e. flow chart maker and Online Diagram Software) was used for diagrammatic design of the proposed system.

Client Side

Front end

We have used the following tools for our Front-End design:

XML- Android provides a straightforward XML vocabulary that corresponds to the view classes and sub-class such as for widgets and layouts. We used XML for android app design layout.

Back end

Java- A general-purpose computer programming language that is object-oriented. We have implemented to design the required dependencies in application.

Android Software Development Kit (SDK)

The Android SDK includes a comprehensive set of development tools. This includes a debugger, libraries, sample code, etc.

o Android Implementation

The API level we used is API 22. We used real device as our android virtual device to launch our application. Our application will run on Minimum API level API 15 Android 4.0.3 (Ice Cream Sandwich). App will run on approximately 100 % of device. Android studio version we used is 3.4.1 for windows.

Server Side

We have used the following tools for our Server-side design:

- **Python:** interpreted high-level programming language. Both train and testing data is done.
- **NumPy:** a library for programming language, which support language, multi-dimensional arrays and matrices.
- **SK Learn:** software Machine Learning library for the Python programming language. This helps to designed python Numerical and scientific libraries NumPy and SciPy.

 Matplotlib: a plotting library for Python programming language and for numerical mathematics extension.

Flask API

Flask API provides an implementation of browsable APIs (Application Platform Interface). APIs is a set of functions and procedures allowing the creation of applications that access the features or data of an operating system, application, or other service. Flask API gives proper content negotiated-responses and smart request parsing. It is designed to start quickly and easily, with the ability to scale up to complex application.

In our case, we use simple API for uploading ML module to the local server. To make local server, flask API is accessed through a URL. We import the different utils such as redirect, URL, etc. which is used to connect with android application.

ngrok

ngrok is simply secure tunnels to localhost. Tons of programmers and designers rely on ngrok for quick testing of websites and apps on their mobile devices. When ngrok is running, it listens on the same port that our local web server is running on and proxies' external requests to our local machine.

This means, connect the local server with android application with the URL, which returns and load it on our phone for immediate access to app.

In our case, it is a step to get it to listen to our local web server i.e. generated using Flask. We ran the local server on port 5000. In terminal, we type ngrok http 5000. This starts ngrok listening on port 5000 and creates the secure tunnel.

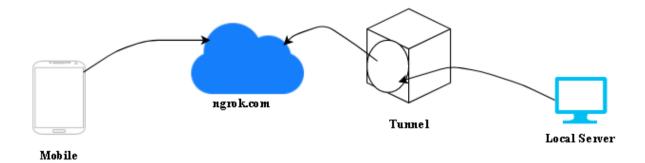


Figure 4. 3 ngrok Architecture

It also creates two sets of publicly available URLs (https://8020a793.ngrok.io) that map to our local server. These unique URLs created each time we restart ngrok making it easy to share these out for one-time testing sessions across a team. The benefit to this, of course, is that we are now able to use RemoteIE with these public URLs to load and test your local site since to the service, your local site now looks like a staged or production system. Jinja is full feature template engine for Python.

4.1.2. Others Tools and Platforms

• GitHub

GitHub is a platform for code sharing and version controlling. In this project team members were from different residential location so, there was necessity of distributing working environment and for that GitHub was used for sharing the code. Each team member would pull the project, add some functionality and push those changes to the central repository to the GitHub.

• Visual Studio Code

Visual Studio Code is a versatile and fun text editor developed by Microsoft repetitive tasks so you can focus the important stuff. It works on OS X, Windows and Linux. It is highly customizable, allowing the user to change the theme, keywords shortcut, preferences, and install extensions that add additional functionality.

• Android Studio

Android Studio is an official integrated development environment (IDE) for Google's Android operating system. It is built on JetBrains' IntelliJ IDEA

software and designed especially for Android development. It is available for windows, macOS and Linux based operating system.

• Word Processer

Word Processor is used for documentation.

4.3. Algorithm implemented

4.3.1. Convolutional Neural Network

The system uses CNN to extract features and classify the image by the user in the user interface (android). Convolutional Neural Networks are very similar to ordinary Neural Networks. They are made up of neurons that have learnable weights and biases.

A convolutional Neural Network is comprised of convolutional layer and then followed by fully connected layer as in standard multilayer neural network.

The architecture of Convolutional Neural Network is:

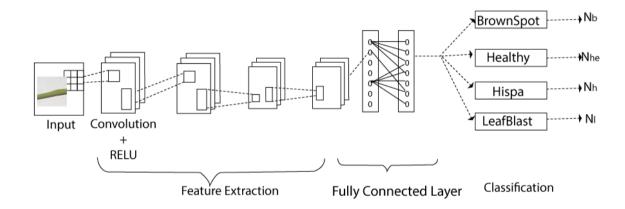


Figure 4. 4 Convolutional Neural Network Architecture

Various Layers in CNN

Convolution Layer

The main building block of CNN is the convolutional layer. Convolution is a mathematical operation to merge two sets of information. The primary purpose of Convolution in case of ConvNet is to extract features from the input image Convolution preserves the spatial relationship between pixels by learning image features using small squares of input data. A

convolutional Neural Network is comprised of convolutional layer which is applied on the input data using a convolution filter to produce a feature map.

In our case first input image are stored in convent with image size as height, width and number of channels. Next we have 5 layers of convolution and pooling; we added a convolution layer by using the "Conv2D" function. The Conv2D function is taking 4 arguments, the first is the convent of image input size of previous, second is the dimension, third one filter, the fourth argument is the activation function i.e. ReLU activation to make all negative value to zero here 'relu' stands for a rectifier function.

$$W = \left(\frac{w - F + 2P}{s}\right) + 1$$

$$H = \left(\frac{H - F + 2P}{s}\right) + 1$$

Where,

W = width of input

H = height of input

F = filter size

P = padding

S = Stride

D = Depth or channel

Pooling Layer

A pooling layer perform a down sampling operation along the spatial dimensions (Width, Height), resulting dimensionality reduction. The primary aim of pooling operation is to reduce the size of the images as much as possible. This scan across the image using a window and compresses the image extracting features.

Max pooling and average pooling are the most common method used in pooling layers. Max pooling takes the largest value from the window of the image currently covered but the kernel, while average pooling takes the average of all values in the window.

For a given input the size of (W1xH1xD1), the output from the max pooling layer can be calculated using the formula:

Requiring two hyper parameters:

- o Filter size f
- o Strides S
- Produces a volume of size (W2xH2xD2) where,
 - \circ W2 = (w1-F)/s+1
 - \circ H2 = (H1-F)/s+1
 - o D2=D1

This layer contains only three parameter feature map, pool size and stride. The feature map is the output from Convolutional layer passing through activation function. We use 2*2 pool size and stride of 2 for our project. This reduce the feature size into half of its original size or input size.

Fully Connected Layer

After the convolution + (plus) pooling layers we add a couple of fully connected layers to wrap up the CNN architecture. It connects neurons in one layer to neurons in another layer. It is used to classify images between different categories by training. This layer takes an input volume (whatever the output is of the conv or ReLU of pool layer) and output an N dimensional vector where N is number of classes that the program has to choose from.

Basically, a FC layer looks at what high level features most strongly correlate to a particular weight so that when you compute the products between the weights and the previous layer, you get the correct probabilities for the different classes.

Dropout Layer

Dropout is used to prevent overfitting and the idea is very simple. During training time, at each iteration, a neuron is temporarily "dropped" or disabled with probability p. This means all the inputs and outputs to this neuron will be disable at the current iteration. The dropped-out neurons are resampled with probability p at every training step, so a dropped-out neuron at one-step can be active at the next one. The hyperparameter p is called the dropout-rate and it is typically a number around 0.5, corresponding to 50% of the neurons being dropped out.

Activation Function

Activation function decides, whether a neuron should be activated or not by calculating

weighted sum and further adding bias with it. The purpose of the activation function is to

introduce non-linearity into the output of a neuron.

There are various types of activation function available such as sigmoid, Tanh, ReLU,

Softmax, etc. ReLU activation is used in hidden layers and Softmax at last layer.

ReLU:

Stands for Rectified linear unit. It is the most widely used activation function. Chiefly

implemented in hidden layers of neural networks.

• Equation: A(x) = max(0, x). It gives an output x if x is positive and 0 otherwise.

• Value Range: - [0, inf)

• Nature: - non-linear, which means we can easily back propagate the errors and

have multiple layers of neurons being activated by the ReLU function.

• Uses: - ReLU is less computationally expensive than Tanh and sigmoid because it

involves simpler mathematical operations. At a time only, a few neurons are

activated making the network sparse making it efficient and easy for computation.

In simple words, RELU learns much faster than sigmoid and Tanh function.

 $F(z) = \begin{cases} z: z \ge 0 \\ 0: z < 0 \end{cases}$

The output of convolutional layer and dense layer's neuron is passed through relu function.

This function returns all negative values or value less than or equal to zeros to zero and

positive value as same.

Softmax Function

The softmax function is also a type of sigmoid function but is handy when we are trying to

handle classification problems.

Nature: - non-linear

Uses: - Usually used when trying to handle multiple classes. The softmax function would

squeeze the outputs for each class between 0 and 1 and would also divide by the sum of the

outputs.

Output: - The softmax function is ideally used in the output layer of the classifier where

we are actually trying to attain the probabilities to define the class of each input.

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$$S(y) = \frac{e^{y_i}}{\sum_{e} y_i}$$

We create Softmax_function () function that returns probability of multiple class. The exp and max function of NumPy were user for softmax implementation. The exp function returns the exponential and max function returns maximum number.

Then the model is compiled using categorical_crossentropy loss function and Adam optimizer. The categorical_crossentropy takes true label and predicted label as input and return the error rate on prediction. Adam update the weight and bias using learning rate.

Stride

Stride is the number of pixels by which sliding is done in the filter matrix over the input matrix When stride is 1 then filters are moved one pixel at a time. Having a large stride will produce smaller feature maps.

Training

When the CNN starts, the weights or filter values are randomly initialized. The filter doesn't know to look for edge and curves. The idea of being given image and labels is training process that CNN go through.

The way the computer is able to adjust its filter value (or weights) is through a training process called back propagation can be separated into 4 distinct sections. The forward pass, the loss function. The backward pass and weight update.

Epochs, Batch Size, Iteration

One epoch is when an entire dataset is passed forward and backward through the NN only once. Since one epoch is too big to feed to the computer at once, it is divided in several smaller batches.

Batch Size is the total number of training examples present in single batch.

Iteration is the number of batches needed to complete one epoch.

Learning Rate is a hyper parameter that controls how much adjusting of weights is needed with respect the loss gradient. It takes a long time to coverage.

$$Wi +1 = Wi - n*gradient$$

If the learning rate is set too low, training will progress very slow as there are tiny updates to the weight in the network. However, if there is the learning rate is set too high it can cause undesirable divergent behavior in the loss function.

Optimizers

Optimizer helps to minimize (or maximize) an error function E(x) which is simply a mathematical function dependent on the model's internal learnable parameters which are used in computing the target values (Y) from the set of predictors (X) used in the model. Various optimizer is Adam, AdaDelta, Gradient Descent, SGD, Momentum, Mini Batch Gradient Descent, etc.

Adam

Adam stands for Adoptive Moment Estimation; Adam is a method that computes adaptive learning rates for each parameter. In addition, storing an exponentially decaying average of past squared gradients. Adam keeps an exponentially decaying average of past gradients M (t)

4.4. Testing

During our development process we have carried out a series of testing to check the differences between the given input and the expected output of our system. Finally, to see whether or not the CNN works, different set of images and labels (other than the training image) were passed through the CNN and the output results are seen and compared to calculate accuracy and loss.

4.4.1. Unit Testing

After the work was divided and coding completed the modules were parallel tested and after getting bug it was made bug free.

Test	Test	Pre-	Expected	Actual	Status
Id	Unit	Condition/Test	Outcome	Result	
		Data			

1	Test if the	Android	Show the	Captured	Pass
	system	camera	capture	Image	
	captures the	permission	image to		
	image	must be turned	user		
		on			
2	Test if the	Android	View all	Select	Fail
	system	gallery	images of	single	
	captures	permission	gallery to	image	
	through	must be turned	the users		
	gallery	on			
3	Test if the	Android	View all	Select	Pass
	system	gallery	images of	single	
	captures	permission	gallery to	image	
	through	must be turned	the users		
	gallery	on			
4	Test if get	Image should	Viewed the	Nothing	Fail
	info button	be select either	information	displays	
	gives the	from gallery	images to		
	information	or capture	the user		
	or not	image from			
		camera			

 $Table\ 4.\ 3\ Unit\ Testing\ of\ Android\ Application$

Test Id	Test Unit	Pre-	Expected	Actual	Status
		condition/	Outcome	Result	
		Test Data			
1	Run the	Load the	Script	Script gives	Fail
	script for	images	should able	the accuracy	
	training data	compiled			

		model and	to give more		
		start training	accuracy		
		network.			
2	Run the	Load the	Script	Script gives	Pass
	script for	images	should able	the accuracy	
	training data	compiled	to give more	with 99%	
		model and	accuracy		
		start training			
		network.			
3	Run the	Load the	Script	Fits an	Pass
	script for	images	should able	image to the	
	training data	compiled	to give more	custom	
	and gives	model and	accuracy	model with	
	images from	start training		the given	
	test set	network.		dataset and	
				gives result	
4	Run the	Load the	Script	Problem in	Fail
	script to	images	should able	fitting the	
	classify	compiled	to give more	custom	
	given	model and	accuracy	model with	
	images	start training		given dataset	
		network.			
5	Run the	Load the	Script	Fits an	Pass
	script to	images	should able	image to the	
	classify	compiled	to give more	custom	
	given	model and	accuracy	model with	
	images	start training		given dataset	
		network.		by adding	
				probability	
				value and	
				gives result	

6	Run the	Proper	Script	Script is able	Pass
	script of	POST or	should able	to give result	
	flask APIs	GET method	to fit and	as a URL.	
		should	provides the		
		specify in	URL with		
		script.	port number		

Table 4. 4 Unit Testing of Script

Test	Test Unit	Pre-	Expected	Actual	Status
Id		Condition /	Outcome	Result	
		Test Data			
1	Run the	Live	Capture real	Image	Pass
	script by	captured to	time through	captured and	
	integrating	the	camera and	single image	
	capture	respective	viewed an	is selected	
	image	image where	image of	from gallery	
	through	permission	gallery to a		
	camera and	must be	user.		
	the gallery	turned on.			
2	Run the	Live	Proper result	Predicted	Pass
	script by	captured	by predicting	result	
	integrating	dataset.	the input	appears	
	training and		image in		
	classify file		console.		
3	Run the	Proper	Gives an	It gives URL	Fail
	system	GET/POST	URL in	through	
	script by	method with	terminal	which it	
	integrating	value should	through	imports an	
	the flask	be specify.	which	image but	
	APIs and		performance	failed to	
	classify file		is measured.		

				predict the	
				information.	
4	Run the	Proper	Gives an	It gives URL	Pass
	system	GET/POST	URL in	through	
	script by	method with	terminal	which it	
	integrating	value should	through	imports an	
	the flask	be specify.	which	image and	
	APIs and		performance	predict the	
	classify file		is measured.	information.	
5	Run the	Using port	Session	Connection	Pass
	script by	generated by	online with	status	
	integrating	flask will	proper	successful	
	URL	accept by	connection	message.	
	generated by	ngrok.	status		
	task APIs				
	with secure				
	tunnel i.e.				
	ngrok.				

Table 4. 5 Integration Testing

Test ID	Test Unit	Pre-	Expected	Actual	Status
		condition/	Outcome	Results	
		Text Data			
1	Open the	Live	Show the	Show	Fail
	application	captured to	captured	proper	
	and choose	the real	image to	information	
	camera	image	the user and	according	
	option to	where	provide	to input	
	capture	permission	proper	image	
	image.		information	captured.	

		must turn	with get		
		on.	info button.		
2	Open the	Live	Show the	Show	Pass
	application	captured to	captured	proper	
	and choose	the real	image to	information	
	camera	image	the user and	according	
	option to	where	provide	to input	
	capture	permission	proper	image	
	image.	must turn	information	captured.	
		on.	with get		
			info button.		
3	Open the	Live select	Show the	Show	Pass
	application	image	selected	proper	
	and choose	where	image to	information	
	to the	permission	the user and	according	
	gallery	must be	provide	to input	
	option to	turned on.	proper	image	
	select an		information	selected.	
	image.		with get		
			info button.		

Table 4. 6 System Testing

CHAPTER 5

RESULT AND ANALYSIS

In this Section, each steps of methodology are implemented and results are described. The parameter sample of model is taken with Input Dimensions, Epochs, Batch Size, Training and Testing Data's, Kernel Size, Optimizer, Activation, Network Classification with Bias on and off.

Model	Input	Epochs	Batch	Data		Kernel	Optimi	Activ	Network	Bias
Name	Dime		Size	Train	Test	Size	zer	ation	classifier	
	nsion									
Model	50*50*1	11	40	2066	707	3*3	Adam	Relu	softmax	off
1.1										
Model	50*50*1	11	40	2066	707	3*3	Adam	Relu	softmax	on
1.2										

Table 5. 1 Description for Parameter of model

Similarly, the description of model along with Accuracy and Loss of both Train Data and Test Data is also shown in table below.

Model	Networks Layer	Train Data		Test Data		
Name		Accuracy	Loss	Accuracy	Loss	
Model	Convolutional*3,poolong*2	0.9715	0.1787	0.9723	0.0440	
1.1	(dropout, dense)*2					
Model	Convolutional*3,poolong*2	0.9850	0.0889	0.9920	0.0366	
1.2	(dropout, dense)*2					

Table 5. 2 Description of model

Thus, CNN is able to classify the input data correctly with the testing accuracy 97.23% and 99.20% in Model 1.1 and Model 1.2 respectively.

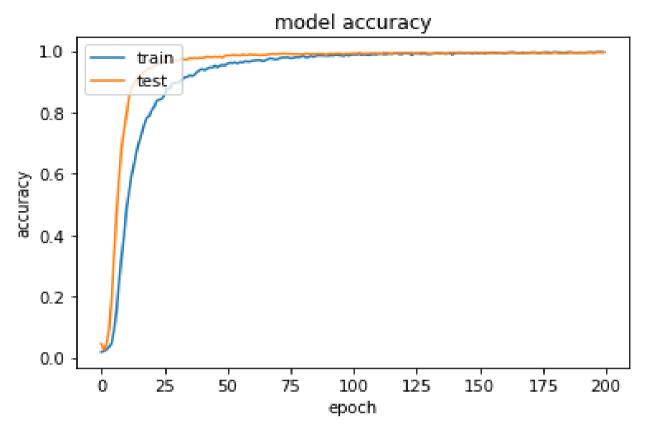


Figure 5. 1 Accuracy of model using Adam optimizer

We have run the model to find Accuracy of model using Adam optimizer with respect to training sets and testing sets.

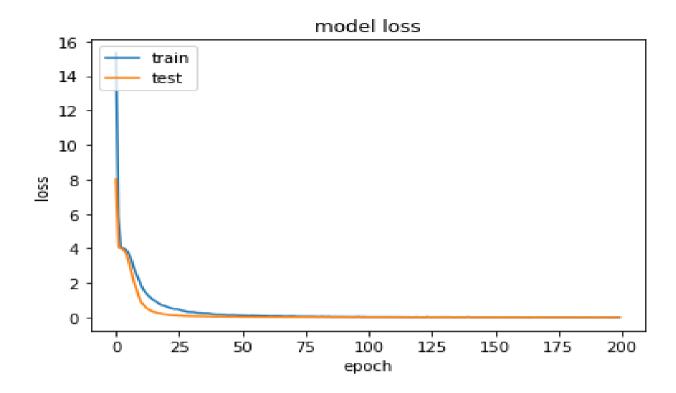


Figure 5. 2 Loss of model using Adam optimizer

We have run the model to find Loss of model using Adam optimizer with respect to training sets and testing sets.

CHAPTER 6

CONCLUSION AND FUTURE ENHANCEMENT

6.1 Conclusion

The project has been developed successfully and the performance of the system has been found good. Since, the project primary focuses on implementation of Plant Tech Solution module, the system successfully implemented a Convolutional Neural Network and trained it to detect the diseases on paddy leaves. The system is able to detect the diseases belongs to 4 classes.

6.2 Future Enhancement

This work can be further extended to the detection of diseases on several plants such as maize, wheat, sugarcane and so others. It can be used to determine the best remedy for curing the diseases. In order to detect the diseases on plants, multiple CNN, ANN for classification can be used. It can be used for the development on agricultural sector in order to increase the quantity and quality of crops.

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APPENDICES

1. Screenshot of UI



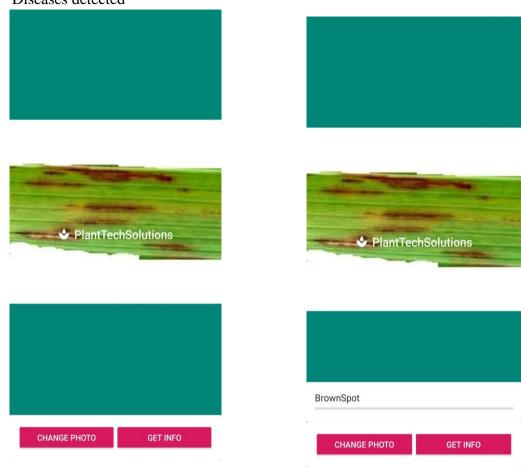


2. Not Matched

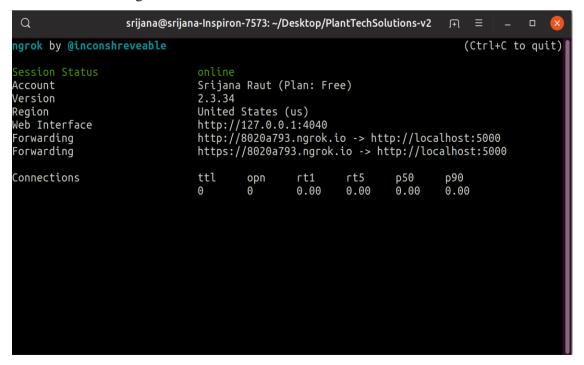




3. Diseases detected



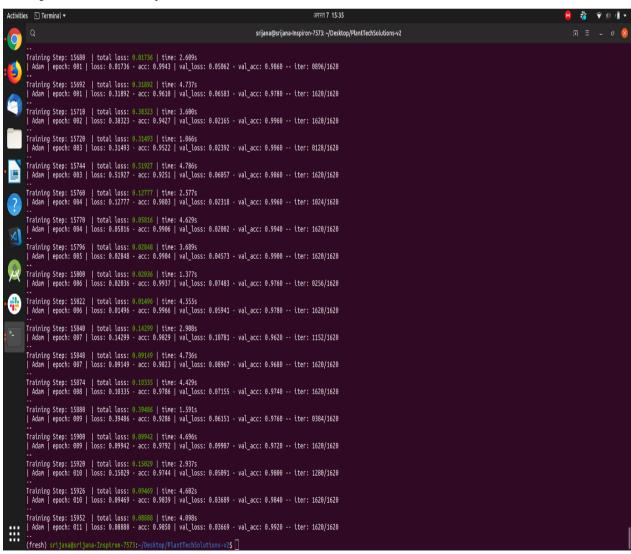
4. Screenshot of ngrok



5. Gantt Chart

Work Time	March	March	April	April	April	April	May	May	June	August
	15	30	1	20	21	25	1	31	1	8
Planning										
Research &										
Analysis										
Design										
Coding										
Implementation										
Testing										
Documentation										

6. Up-to-date Accuracy



7. Source Code

```
import numpy as np
import tensorflow as tf # ML library for graphs
#HYPERPARAMETERS
steps = 2066 # number of samples in training set
epochs = 11#number of epochs
step\_size = 40 #
total_batch = int(steps/step_size)
LR = 1e-3
def init_weights(shape):
  init_random_dist = tf.truncated_normal(shape, stddev=0.1)
  return tf.Variable(init_random_dist)
def init_bias(shape):
  init_bias_vals = tf.constant(0.1, shape=shape)
  return tf.Variable(init_bias_vals)
def conv2d(x, W):
  return tf.nn.conv2d(x, W, strides=[1, 1, 1, 1], padding='SAME')
def max_pool_2by2(x):
  return tf.nn.max_pool(x, ksize=[1, 2, 2, 1],
                strides=[1, 2, 2, 1], padding='SAME')
def convolutional_layer(input_x, shape):
  W = init_weights(shape)
  b = init\_bias([shape[3]])
  return tf.nn.relu(conv2d(input_x, W) + b)
def normal_full_layer(input_layer, size):
```

```
input_size = int(input_layer.get_shape()[1])
  W = init_weights([input_size, size])
  b = init_bias([size])
  return tf.matmul(input_layer, W) + b
#Defining placeholders
x = tf.placeholder(tf.float32,shape=[None,50,50,3])
y_true = tf.placeholder(tf.float32,shape=[None,4])
#Defining the graph
with tf.name_scope('Model'):
convnet = input_data(shape=[None, IMG_SIZE, IMG_SIZE, 3], name='input')
convnet = conv_2d(convnet, 32, 3, activation='relu')
convnet = max_pool_2d(convnet, 3)
convnet = conv_2d(convnet, 64, 3, activation='relu')
convnet = max_pool_2d(convnet, 3)
convnet = conv_2d(convnet, 128, 3, activation='relu')
convnet = max_pool_2d(convnet, 3)
convnet = conv_2d(convnet, 32, 3, activation='relu')
convnet = max_pool_2d(convnet, 3)
convnet = conv_2d(convnet, 64, 3, activation='relu')
convnet = max_pool_2d(convnet, 3)
convnet = fully_connected(convnet, 1024, activation='relu')
convnet = dropout(convnet, 0.5)
convnet = fully_connected(convnet, 4, activation='softmax')
```

```
convnet = regression(convnet, optimizer='adam', learning_rate=LR,
loss='categorical_crossentropy', name='targets')
#Defining Loss Function
with tf.name_scope('Loss'):
  cross_entropy =
tf.reduce_mean(tf.nn.softmax_cross_entropy_with_logits_v2(labels=y_true,logits=y_pre
d))
#Defining objectve
with tf.name_scope('ADAM'):
  train = tf.train.AdamOptimizer(learning_rate=LR).minimize(cross_entropy)
#Defining Accuracy
with tf.name_scope('Accuracy'):
  matches = tf.equal(tf.argmax(y_pred,1),tf.argmax(y_true,1))
  acc = tf.reduce_mean(tf.cast(matches,tf.float32))
#Starting variables
init = tf.global_variables_initializer()
tf.summary.scalar("loss", cross_entropy)
tf.summary.scalar("accuracy", acc)
merged_summary_op = tf.summary.merge_all()
#Defining empty lists to keep results
acc_list = []
cross_entropy_list = []
acc_train = []
#Creating a Saver object to save results
saver = tf.train.Saver()
#Training and saving the result
```

```
with tf.Session(config=config) as sess:
  sess.run(init)
  summary_writer = tf.summary.FileWriter(TRAIN_DIR, graph=tf.get_default_graph())
  for i in range(epochs):
    for i in range(0, steps, step size):
       _{\rm }, c, summary,d =
sess.run([train,cross entropy,merged summary op,acc],feed dict={x:X[j:j+step size],
y_true:Y[j:j+step_size],hold_prob1:0.5,hold_prob2:0.5,hold_prob3:0.5,hold_prob4:0.5})
       summary_writer.add_summary(summary, i * total_batch + j)
       acc_train.append(d)
       mean_of_cross_entropy = sess.run(cross_entropy,feed_dict={x:cv_x,y_true:cv_y
,hold_prob1:1.0,hold_prob2:1.0,hold_prob3:1.0,hold_prob4:1.0})
       mean_of_acc = sess.run(acc,feed_dict={x:cv_x,y_true:cv_y}
,hold_prob1:1.0,hold_prob2:1.0,hold_prob3:1.0,hold_prob4:1.0})
       cross entropy list.append(mean of cross entropy)
       acc_list.append(mean_of_acc)
    print(i,mean of cross entropy,mean of acc)
  saver.save(sess,
"/content/drive/ImageClassificationSOP/PlantVillageDataset/models/CNN_MC.ckpt")
  print("test accuracy =
",np.mean([sess.run(acc,feed_dict={x:test_x[:230],y_true:test_y[:230]}
,hold_prob1:1.0,hold_prob2:1.0,hold_prob3:1.0,hold_prob4:1.0}),sess.run(acc,feed_dict=
\{x:\text{test } x[230:460], y \text{ true:test } y[230:460] \}
,hold_prob1:1.0,hold_prob2:1.0,hold_prob3:1.0,hold_prob4:1.0}),sess.run(acc,feed_dict=
{x:test_x[460:],y_true:test_y[460:]
,hold_prob1:1.0,hold_prob2:1.0,hold_prob3:1.0,hold_prob4:1.0})))
  print("cross_entropy loss =
",np.mean([sess.run(cross_entropy,feed_dict={x:test_x[:230],y_true:test_y[:230]}
,hold_prob1:1.0,hold_prob2:1.0,hold_prob3:1.0,hold_prob4:1.0}),sess.run(cross_entropy,
feed_dict={x:test_x[230:460],y_true:test_y[230:460]
,hold_prob1:1.0,hold_prob2:1.0,hold_prob3:1.0,hold_prob4:1.0}),sess.run(cross_entropy,
feed_dict=\{x:test_x[460:],y_true:test_y[460:]\}
,hold_prob1:1.0,hold_prob2:1.0,hold_prob3:1.0,hold_prob4:1.0})))
```