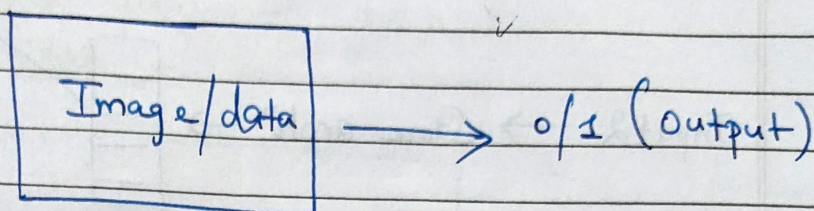


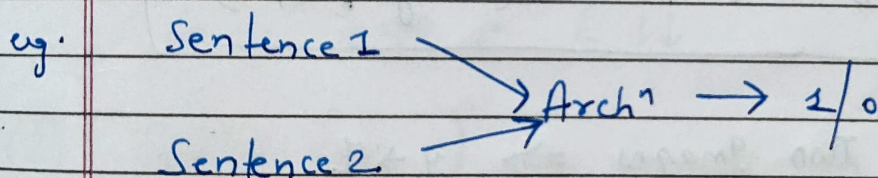
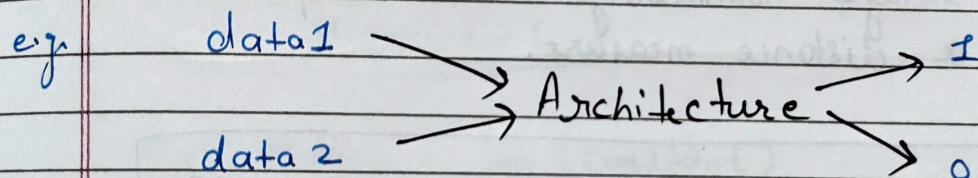
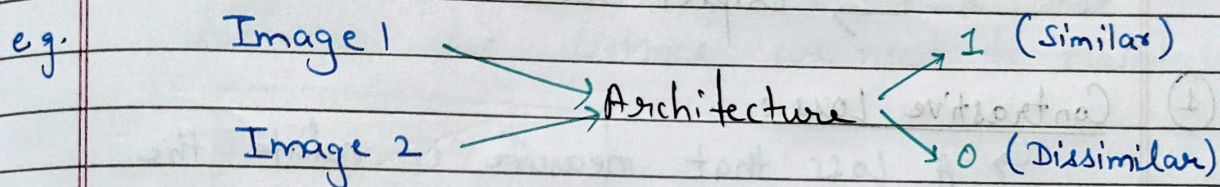
⊕ Siamese :-

↳ Specially used in Facial Recognition System.

↳ Till Now :



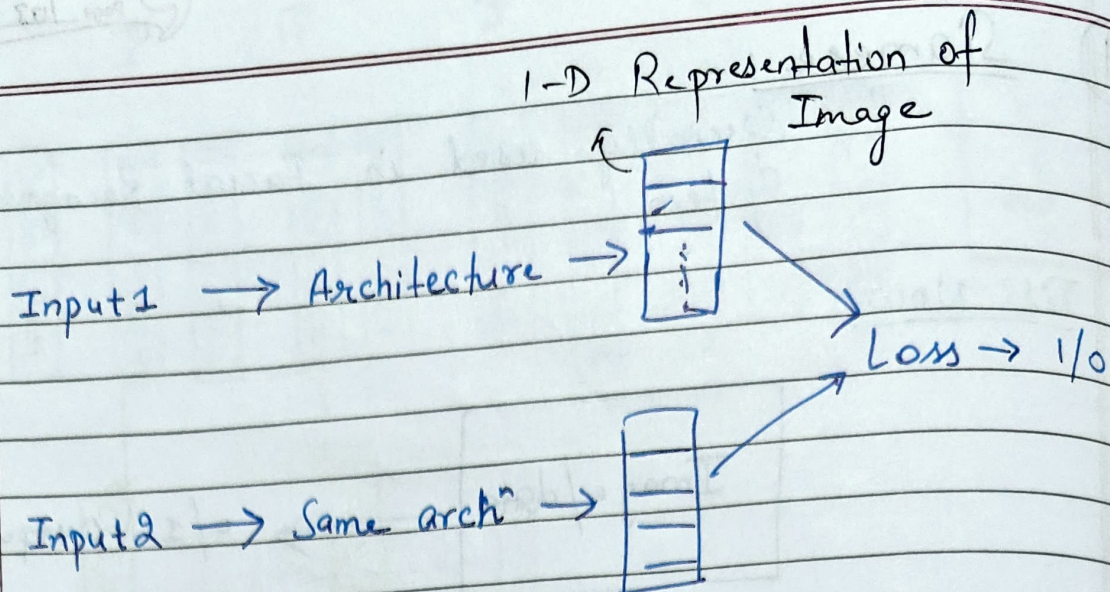
↳ Now : (Comparison Architecture) :-



↳ Image Aspect (Face Recognition) :

↳ Image 1 : While creating Face lock
(Giving multiple angles' images)

↳ Image 2 : Live image to unlock
(physical image phone)



↳ Loss :-

- Contrastive Loss
- Triplet loss

① Contrastive Loss :

↳ A loss that measure or relate the image similarity with respect to a distance measure.

$$L = yD^2 + (1-y) \max(\text{margin} - D, 0)^2$$

↳ When Two Images $\Rightarrow y \rightarrow 1$
are similar

Otherwise $\Rightarrow y \rightarrow 0$

∴ When images are similar,

$$L = D^2$$

$D \rightarrow$ Euclidean distance b/w the encoded vectors (Dissimilarity)

So When images are similar, we have to reduce D^2 to "0"

Reduce $\rightarrow D^2 \rightarrow 0$

\hookrightarrow When images are dissimilar $\Rightarrow \boxed{y=0}$

$$\boxed{L = \max(\text{margin} - D, 0)^2}$$

• "Margin" is a kind of benchmark that determines the distance we need to maintain.

$$\begin{array}{c} \text{Maximize} \rightarrow D \\ \Downarrow \\ \text{Minimize} \rightarrow L \end{array}$$

e.g. Margin = 100 (constant)

So, $D \uparrow \Rightarrow L \downarrow$

② Triplet Loss [By Google in 2015]

\hookrightarrow specially used for facial recognition systems.

Triplet \rightarrow Means \rightarrow Three Elements

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Three elements →

- Anchor Image
- Positive Image
- Negative Image.

* Anchor Image :-

↳ Reference Image.

e.g. Image while creating Face Lock.

* Positive Image :

↳ Logging in the system any time after that. (That person's image)

* Negative Image :

↳ Another person's image.

$$d(A, P) - d(A, N) < 0$$

A → Anchor Image

P → Positive "

N → Negative "

Adding some Margin

$$L = \max(d(a, n) - d(a, p), 0)$$

$$L = \max(d(a, n) - d(a, p) + \text{margin}, 0)$$