# Compilation

The code compiles without any errors with the provided makefiles

# Accuracy

Code meets the accuracy requirements with an RMSE of [0.0977, 0.0855,0.4406,.4608]

# Algorithm

The code follows the correct algorithm

* First measurement is used for initialization
* Prediction and measurement update are done in the correct sequence
* Code handles both Radar and Lidar data

# Code Efficiency

The code is written efficiently to avoid any duplication of computation by using temporary variables.