Controls

W

Increase speed

S

Decrease speed

A

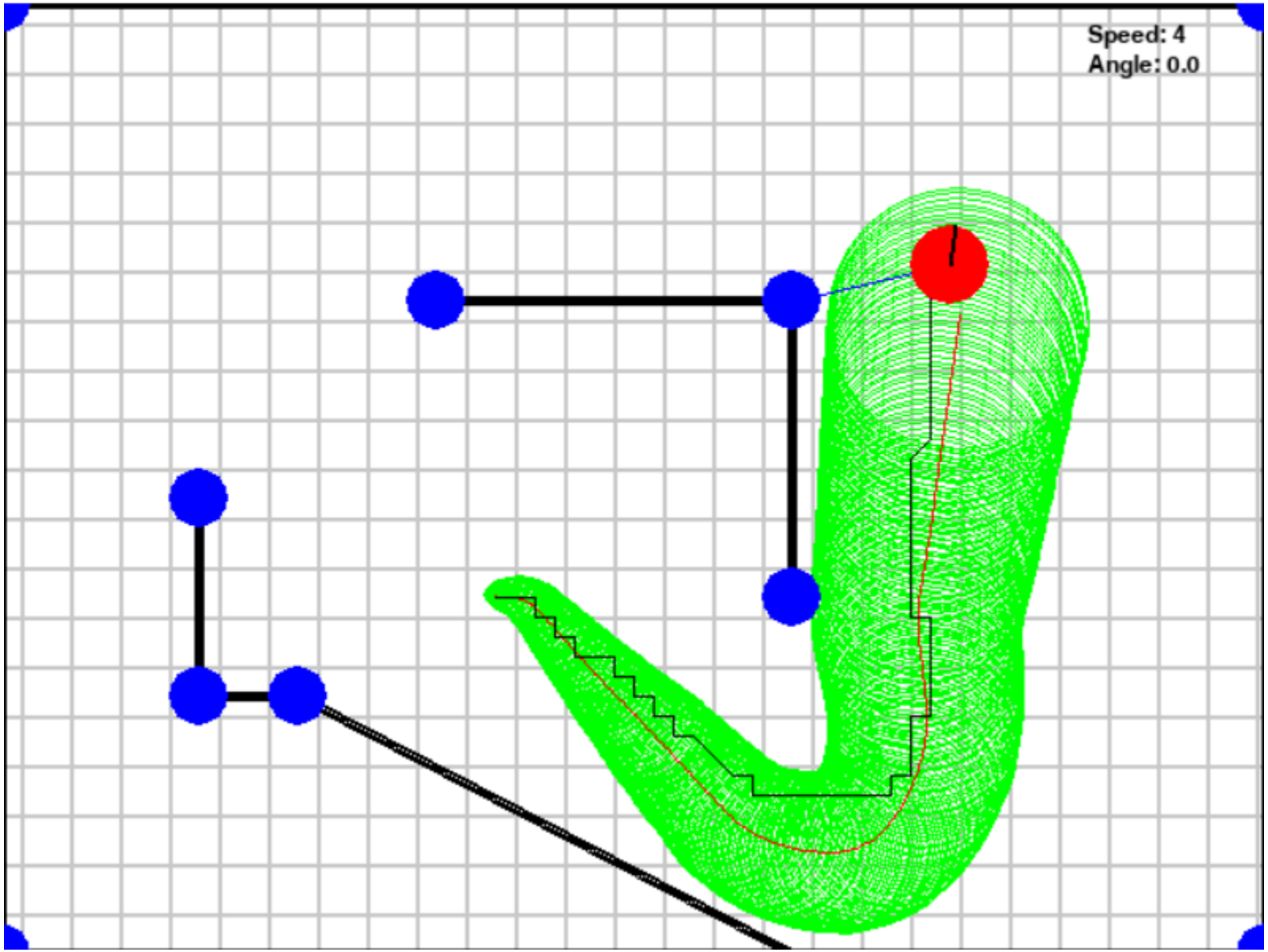
Decrease rotation

D

Increase rotation

Esc

Exit program



Visuals

Robot

Actual path

Predicted path

Certainty of position

Beacon

Connection to Beacon in range