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#LAB3 CANDIDATE ELIMINATION
                                                                       #Naive-bayesian
                                                                       from sklearn.naive_bayes import GaussianNB
import csy
with open("trainingexamples.csv") as f:
                                                                       from sklearn.datasets import load_iris
  csv file = csv.reader(f)
                                                                       from sklearn import metrics
  data = list(csv_file)
                                                                       from sklearn.model_selection import train_test_split
  specific = data[0][:-1]
                                                                       dataset = load_iris()
  general = [['?' for i in range(len(specific))] for j in
                                                                       X = dataset. data
range(len(specific))]
                                                                       y = dataset. target
  step=1 #for printing purpose
                                                                       X_train, X_test, y_train, y_test = train_test_split(X, y,
                                                                       test_size=0.2, random_state=1)
  for i in data:
    if i[-1] == "Y":
                                                                       gnb = GaussianNB()
      for j in range(len(specific)):
                                                                       classifier = gnb.fit(X train, y train)
        if i[j] != specific[j]:
                                                                       y_pred = classifier.predict(X_test)
           specific[j] = "?"
                                                                       print( 'Accuracy metrics:', metrics.classification_report(y_test,
           general[j][j] = "?"
                                                                       y_pred))
    elif i[-1] == "N":
                                                                       print( 'Accuracy of the classifier is:',
      for j in range(len(specific)):
                                                                       metrics.accuracy_score(y_test, y_pred))
                                                                       print("Confusion matrix:")
        if i[j] != specific[j]:
           general[j][j] = specific[j]
                                                                       print(metrics.confusion_matrix(y_test, y_pred))
                                                                       #AO*
                                                                       class Graph:
           general[j][j] = "?"
    print("\nStep {} of candidate elimination algo".format(step))
                                                                         def __init__(self, graph, heuristicNodeList, startNode):
                                                                           self.graph = graph
    step+=1
    print(specific)
                                                                           self.H = heuristicNodeList
                                                                           self.start = startNode
    print(general)
  gh = [] # gh = general Hypothesis
                                                                           self.parent = {}
  for i in general:
                                                                           self.status = {}
    for j in i:
                                                                           self.solutionGraph = {}
      if j != '?':
                                                                         def applyAOStar(self):
        gh.append(i)
                                                                           self.aoStar(self.start, False)
                                                                         def getNeighbors(self, v):
        break
  print("\nFinal Specific hypothesis:\n", specific)
                                                                           return self.graph.get(v, ")
 print("\nFinal General hypothesis:\n", gh)
                                                                         def getStatus(self, v):
                                                                           return self.status.get(v, 0)
def aStarAlgo(start_node, stop_node):
                                                                         def setStatus(self, v, val):
                                                                           self.status[v] = val
  open_set = set(start_node)
                                                                         def getHeuristicNodeValue(self, n):
  closed_set = set()
  g = {} # store distance from starting node
                                                                           return self.H.get(n, 0)
  parents = {} # parents contains an adjacency map of all nodes
                                                                         def setHeuristicNodeValue(self, n, value):
  g[start_node] = 0
                                                                           self.H[n] = value
  parents[start_node] = start_node
                                                                         def printSolution(self):
                                                                           print("FOR GRAPH SOLUTION, TRAVERSE THE GRAPH FROM
  while len(open_set) > 0:
    n = None # n is node refering
                                                                       THE START NODE:", self.start)
                                                                           print("-----
    for v in open_set:
      if n == None \text{ or } g[v] + heuristic(v) < g[n] + heuristic(n):
                                                                           print(self.solutionGraph)
                                                                           print("-----
    if n == stop_node or Graph_nodes[n] == None:
                                                                         def computeMinimumCostChildNodes(self, v):
                                                                           minimumCost = 0
      pass
                                                                           costToChildNodeListDict = {}
                                                                           costToChildNodeListDict[minimumCost] = []
      for (m, weight) in get neighbors(n):
        if m not in open set and m not in closed set:
                                                                           flag = True
                                                                           for nodeInfoTupleList in self.getNeighbors(v):
           open set.add(m)
           parents[m] = n
                                                                             cost = 0
           g[m] = g[n] + weight
                                                                             nodeList = []
                                                                             for c, weight in nodeInfoTupleList:
           if g[m] > g[n] + weight:
                                                                                cost = cost + self.getHeuristicNodeValue(c) + weight
             g[m] = g[n] + weight
                                                                                nodeList.append(c)
             parents[m] = n
                                                                              if flag == True:
           if m in closed set:
                                                                                minimumCost = cost
                                                                                costToChildNodeListDict[minimumCost] = nodeList
             closed set.remove(m)
             open_set.add(m)
                                                                                flag = False
    if n == None:
                                                                              else:
      print('Path does not exist!')
                                                                                if minimumCost > cost:
      return None
                                                                                  minimumCost = cost
                                                                                  costToChildNodeListDict[minimumCost] = nodeList
    if n == stop_node:
      path = []
                                                                           return minimumCost.
      while parents[n] != n:
                                                                       costToChildNodeListDict[minimumCost]
        path.append(n)
                                                                         def aoStar(self, v, backTracking):
                                                                           print("HEURISTIC VALUES :", self.H)
print("SOLUTION GRAPH :", self.solutionGraph)
        n = parents[n]
      path.append(start_node)
                                                                           print("PROCESSING NODE :", v)
      path.reverse()
      print('Path found: {}'.format(path))
                                                                           print("----
      return path
    open_set.remove(n)
                                                                           if self.getStatus(v) >= 0:
    closed_set.add(n)
                                                                             minimumCost, childNodeList =
  print('Path does not exist!')
                                                                       self.computeMinimumCostChildNodes(v)
  return None
                                                                             self.setHeuristicNodeValue(v, minimumCost)
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def get_neighbors(v):
                                                                                 self.setStatus(v, len(childNodeList))
  if v in Graph nodes:
                                                                                 solved = True
    return Graph_nodes[v]
                                                                                 for childNode in childNodeList:
                                                                                   self.parent[childNode] = v
    return None
                                                                                   if self.getStatus(childNode) != -1:
def heuristic(n):
                                                                                     solved = solved & False
  H_dist = {
                                                                                 if solved == True:
    'A': 10,
                                                                                   self.setStatus(v, -1)
    'B': 8,
                                                                                   self.solutionGraph[v] = childNodeList
    'C': 5,
                                                                                 if v != self.start:
                                                                                   self.aoStar(self.parent[v], True)
    'D': 7.
    'E': 3,
                                                                                 if backTracking == False:
    'F': 6.
                                                                                   for childNode in childNodeList:
    'G': 5,
                                                                                     self.setStatus(childNode, 0)
    'H': 3,
                                                                                     self.aoStar(childNode, False)
                                                                         h2 = {'A': 1, 'B': 6, 'C': 12, 'D': 10, 'E': 4, 'F': 4, 'G': 5, 'H': 7}
    'l': 1,
                                                                         graph2 = {
    'J': 0
                                                                            'A': [[('B', 1), ('C', 1)], [('D', 1)]],
                                                                            'B': [[('G', 1)], [('H', 1)]],
  return H_dist[n]
                                                                            'D': [[('E', 1), ('F', 1)]]
Graph_nodes = {
  'A': [('B', 6), ('F', 3)],
  'B': [('C', 3), ('D', 2)],
                                                                         G2 = Graph(graph2, h2, 'A')
  'C': [('D', 1), ('E', 5)],
                                                                         G2.applyAOStar()
  'D': [('C', 1), ('E', 8)],
                                                                         G2.printSolution()
  'E': [('I', 5), ('J', 5)],
                                                                         #Ann
  'F': [('G', 1), ('H', 7)],
                                                                         import numpy as np
  'G': [('I', 3)],
                                                                         import matplotlib.pyplot as plt
  'H': [('I', 2)],
                                                                         def local_regression(x0, X, Y, tau):
  'I': [('E', 5), ('J', 3)],
                                                                            x0 = [1, x0]
                                                                            X = [[1, i] \text{ for } i \text{ in } X]
aStarAlgo('A', 'J')
                                                                            X = np.asarray(X)
                                                                            xw = (X.T) * np.exp(np.sum((X - x0) ** 2, axis=1) / (-2 *)
#knn
from sklearn.model_selection import train_test_split
from sklearn.neighbors import KNeighborsClassifier
                                                                            beta = (np.linalg.pinv(xw @ X)) @ (xw @ Y)
from sklearn import datasets
                                                                            return (beta @ x0)
iris=datasets.load iris()
                                                                         def draw(tau):
print("Iris Data set loaded...")
                                                                            prediction = [local_regression(x0, X, Y, tau) for x0 in domain]
x_train, x_test, y_train, y_test =
                                                                            plt.plot(X, Y, 'o', color='black')
train_test_split(iris.data,iris.target,test_size=0.1)
                                                                            plt.plot(domain, prediction, color='red')
print("Dataset is split into training and testing...")
                                                                            nlt.show()
print("Size of training data and its
                                                                         X = np.linspace(-3, 3, num=1000)#evenly spaced numbers over [-
label",x train.shape,y_train.shape)
                                                                         3,3] totally num(1000) numbers
print("Size of training data and its label",x_test.shape,
                                                                         domain = X
y test.shape)
                                                                         Y = np.log(np.abs((X ** 2) - 1) + .5)#just creating y values...chosing
for i in range(len(iris.target_names)):
                                                                         this to get W shaped curve
 print("Label", i , "-",str(iris.target_names[i]))
                                                                         draw(10)
classifier = KNeighborsClassifier(n_neighbors=1)
                                                                         draw(0.1)
classifier.fit(x train, y train)
                                                                         draw(0.01)
                                                                         draw(0.001)
y_pred=classifier.predict(x_test)
print("Results of Classification using K-nn with K=1")
                                                                         #ID3
for r in range(0,len(x_test)):
                                                                         import math
  print(" Sample:", str(x_test[r]), " Actual-label:", str(y_test[r]), "
                                                                         import csv
                                                                         def load_csv(filename):
Predicted-label:",str(y_pred[r]))
print("Classification Accuracy :" , classifier.score(x_test,y_test));
                                                                            lines=csv.reader(open(filename,"r"))
                                                                            dataset = list(lines)
from sklearn.metrics import classification_report,
                                                                            headers = dataset.pop(0)
confusion_matrix
print('Confusion Matrix')
                                                                            return dataset, headers
print(confusion_matrix(y_test,y_pred))
                                                                          class Node:
print('Accuracy Metrics')
                                                                            def __init__ (self,attribute):
print(classification_report(y_test,y_pred))
                                                                              self.attribute=attribute
                                                                              self.children=[]
#k-means
from sklearn.model_selection import train_test_split
                                                                              self.answer="
from sklearn.neighbors import KNeighborsClassifier
                                                                         def subtables(data,col,delete): #col is basically a column header
from sklearn import datasets
iris=datasets.load iris()
                                                                            coldata=[row[col] for row in data]
print("Iris Data set loaded...")
                                                                            attr=list(set(coldata)) #set returns only unique values in
x_train, x_test, y_train, y_test =
                                                                         coldata
train_test_split(iris.data,iris.target,test_size=0.1)
                                                                            counts=[0]*len(attr) #create empty list for every unique
print("Dataset is split into training and testing...")
                                                                          value
print("Size of training data and its
                                                                            r=len(data) #no of rows
label",x train.shape,y train.shape)
                                                                            c=len(data[0]) #no of columns in each row
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print("Size of training data and its label",x_test.shape,
                                                                         for x in range(len(attr)): #no of unique values in the "col"
y test.shape)
                                                                       column
for i in range(len(iris.target_names)):
                                                                            for y in range(r):
  print("Label", i , "-",str(iris.target names[i]))
                                                                              if data[y][col]==attr[x]:
classifier = KNeighborsClassifier(n_neighbors=1)
                                                                                 counts[x]+=1
                                                                          for x in range(len(attr)):
classifier.fit(x_train, y_train)
y_pred=classifier.predict(x_test)
                                                                            dic[attr[x]]=[[0 for i in range(c)] for j in range(counts[x])]
print("Results of Classification using K-nn with K=1")
                                                                       #initialing the dictionary items
                                                                            pos=0
for r in range(0,len(x_test)):
 print(" Sample:", str(x_test[r]), " Actual-label:", str(y_test[r]), "
                                                                            for y in range(r):
Predicted-label:",str(y_pred[r]))
                                                                              if data[y][col]==attr[x]:
print("Classification Accuracy :" , classifier.score(x_test,y_test));
                                                                                 if delete:
from sklearn.metrics import classification report,
                                                                                   del data[y][col] #removing tat particular column
confusion matrix
                                                                        (upper in the tree/parent)
print('Confusion Matrix')
                                                                                 dic[attr[x]][pos]=data[y] #all rows for each unique value
                                                                                 pos+=1
print(confusion_matrix(y_test,y_pred))
print('Accuracy Metrics')
                                                                          return attr,dic #attr is a list, dic is a set
print(classification_report(y_test,y_pred))
#localWeightRegression
                                                                        def entropy(S):
                                                                          attr=list(set(S)) #S will basically have last column data(not
import numpy as np
import matplotlib.pyplot as plt
                                                                       necessarily of all rows)
def local_regression(x0, X, Y, tau):
                                                                          if len(attr)==1:
 x0 = [1, x0]
                                                                            return 0 #if there is either only yes/ only no =>entrop is 0
  X = [[1, i] \text{ for } i \text{ in } X]
                                                                          counts=[0,0]
                                                                          for i in range(2):
  X = np.asarray(X)
  xw = (X.T) * np.exp(np.sum((X - x0) ** 2, axis=1) / (-2 *
                                                                            counts[i]=sum([1 for x in S if attr[i]==x])/(len(S)*1.0) #find no
(tau**2)))
                                                                        of yes and no of no
  beta = (np.linalg.pinv(xw @ X)) @ (xw @ Y)
                                                                          sums=0
  return (beta @ x0)
                                                                          for cnt in counts:
                                                                            sums+=-1*cnt*math.log(cnt,2) #base 2(second parameter)
def draw(tau):
  prediction = [local_regression(x0, X, Y, tau) for x0 in domain]
  plt.plot(X, Y, 'o', color='black')
                                                                       def compute_gain(data,col): #col is column-header
  plt.plot(domain, prediction, color='red')
                                                                          attr,dic = subtables(data,col,delete=False) #here no deletion,
  plt.show()
                                                                       we just calculate gain
X = np.linspace(-3, 3, num=1000)#evenly spaced numbers over [-
                                                                          total_size=len(data) # |S| value in formula
3,3] totally num(1000) numbers
                                                                          entropies=[0]*len(attr) #entropies of each value
                                                                          ratio=[0]*len(attr) # to maintain |Sv|/|S| values
                                                                          total_entropy=entropy([row[-1] for row in data])
Y = np.log(np.abs((X ** 2) - 1) + .5)#just creating y values...chosing
this to get W shaped curve
                                                                          for x in range(len(attr)):
draw(10)
                                                                            ratio[x]=len(dic[attr[x]])/(total_size*1.0) #len of dic=> |Sv|
draw(0.1)
                                                                       value
                                                                            entropies[x]=entropy([row[-1] for row in dic[attr[x]]])
draw(0.01)
draw(0.001)
                                                                            total_entropy-=ratio[x]*entropies[x] #acc to formula
                                                                         return total entropy
                                                                       def build_tree(data,features):
                                                                         lastcol=[row[-1] for row in data]
                                                                         if(len(set(lastcol)))==1: #if last column contains either only
                                                                        "yes" or only "no"
                                                                            node=Node("")
                                                                                                  #we are not building the tree further(so
                                                                       no attribute)
                                                                            node.answer=lastcol[0] #it'll be either yes/no
                                                                            return node
                                                                          n=len(data[0])-1 #-1 boz we dont need the last column values
                                                                                         # gain is initialized to be 0 for all attributes
                                                                          gains=[0]*n
                                                                          for col in range(n):
                                                                            gains[col]=compute_gain(data,col) #compute gain of each
                                                                        attribute
                                                                         split=gains.index(max(gains))
                                                                                                             # split will have the index of
                                                                       attribute with "highest gain"
                                                                          node=Node(features[split])
                                                                                                             # features list will have
                                                                       attribute headings(col names)
                                                                          fea = features[:split]+features[split+1:]
                                                                          attr,dic=subtables(data,split,delete=True)
                                                                                                   #dic will have all rows for all those
                                                                        attributes(key: values)
                                                                          for x in range(len(attr)):
                                                                            child=build_tree(dic[attr[x]],fea) #for each value of the
                                                                            node.children.append((attr[x],child)) #again build the tree
                                                                        (but fea exclude the one already taken)
                                                                         return node
```

```
def print tree(node,level):
  if node.answer!="":
                             #if its a leaf node
    print(" "*level,node.answer) #just print "level" no of spaces,
followed by answer (yes/no)
  print(" "*level,node.attribute) #attribute in the node
  for value,n in node.children:
    print(" "*(level+1),value)
    print_tree(n,level+2)
                            # recursive call to the next node
(child)
def classify(node,x_test,features): #features: column headers
  if node.answer!="": #this will be true only for leaf
nodes(answer: yes/no)
    print(node.answer)
    return
  pos=features.index(node.attribute) #node.attribute will have
the col header
  for value, n in node.children: #for every value of that attribute
    if x_test[pos]==value: # for that particular value go along
that value
      classify(n,x_test,features) #go deeper in the tree
dataset,features=load_csv("traintennis.csv")
#lastcol=[row[-1] for row in dataset]
node1=build_tree(dataset,features)
print("The decision tree for the dataset using ID3 algorithm is")
print_tree(node1,0)
testdata,features=load_csv("testtennis.csv")
for xtest in testdata: #xtest is each row in testdata
  print("The test instance:",xtest)
  print("The label for test instance:",end=" ")
  classify(node1,xtest,features)
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