

1(b).

$$\text{For } y > y_0, \ddot{y} = -g \rightarrow \int_{y_0}^y \ddot{y} dy = \int_0^t -g dt$$

- Integrating we get, $\dot{y} = -gt + \dot{y}_0$
- Assuming $\dot{y}_0 = 0$ and energy conservation, apex could be found when $t=0$ (defining x_0 for Poincaré surface)

$$\therefore \dot{y} @ \text{apex} = 0$$

- Integrating again we get, $y = -\frac{g t^2}{2} + \dot{y}_0 t + y_0$
- Using same assumptions as before, we find y @ apex from setting $t=0$
- $\therefore y @ \text{apex} = \text{constant} = y$ (initial height)

$$\therefore P(x) = \begin{bmatrix} y \\ 0 \end{bmatrix}$$

1(c).

There is one fixed point at $x^* = \begin{bmatrix} y \\ 0 \end{bmatrix}$

- This is truly a fixed point since,
 $P(x^*) = x^*$ (with energy conservation)
- For linear approximation, $P(x)$ is already linear so this is not applicable.
- x^* is stable iff $|\lambda_i(\frac{\partial P}{\partial x}|_{x^*})| < 1$
- $\frac{\partial P}{\partial x}|_{x^*} = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$
- The eigenvalues of $\frac{\partial P}{\partial x}|_{x^*}$ are 0 and 1

\therefore The fixed point is stable in the sense of Lyapunov