



Overview

In this exercise you will learn:

- How to create a new project with Code Composer Studio (CCS)
- Learn how to blink the on-board Red LED on the MSP430 Launchpad
- Change the speed of the blinking Red LED
- Learn how to toggle between the Red and Green LED

Things you will need:

- MSP430F5529 Launchpad Evaluation Kit
 - MSP-EXP430F5529LP
- Code Composer Studio (Software Development Environment)
- 10-15 minutes

Hardware Setup

- The MSP430F5529 LaunchPad kit includes everything you need out of the box
- To start programming, you'll first have to install CCS which contains the required drivers for your new MSP430F5529 LaunchPad kit
- Plug your F5529 LaunchPad into the PC with the included USB cable
- If prompted, let Windows automatically install the software.

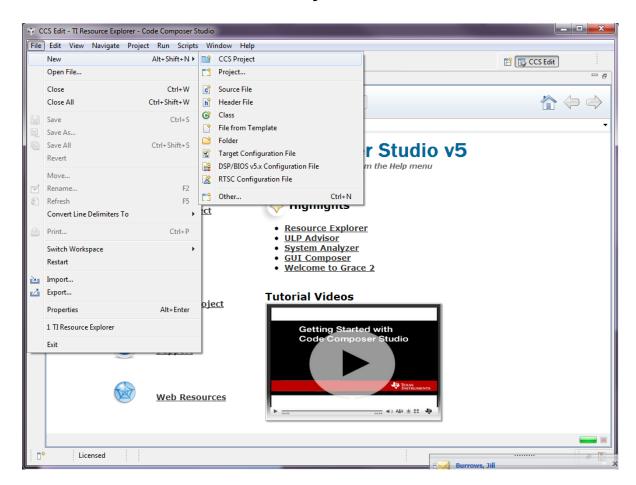
Create a New CCS Workspace

- Upon opening CCS, it will ask you to select a workspace
- A workspace is where all of your CCS projects will be stored. Create a workspace folder, then *press OK*



Create a New CCS Project

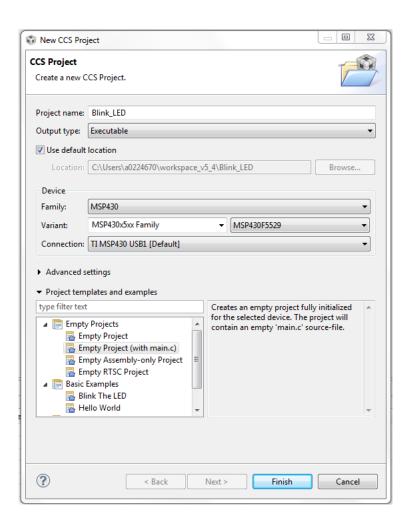
 Once CCS is opened, we can create a new project by going to to File > New > CCS Project



Choose CCS Project Settings

This will open up the "New CCS Project" window. Within this window, we need to do 2 things.

- 1. Name our project
- 2. Choose our Device Variant.
- 1. Let's name our project "Blink LED"
- 2. We also need to choose the appropriate MSP430 device. For this tutorial, we will program the MSP430F5529 device that comes prepopulated on the MSP430F5529 LaunchPad



Write Code

In the main.c file we have a blank canvas to write our code!

```
#include <msp430.h>
unsigned int i = 0;
                                 // Initialize variables. This will keep count of how many cycles between LED toggles
void main(void)
    WDTCTL = WDTPW + WDTHOLD;
                                               // Stop watchdog timer. This line of code is needed at the beginning of most MSP430 projects.
                                               // This line of code turns off the watchdog timer, which can reset the device after a certain period of time.
                                      // P1DIR is a register that configures the direction (DIR) of a port pin as an output or an input.
    P1DIR = 0x01;
                                       // To set a specific pin as output or input, we write a '1' or '0' on the appropriate bit of the register.
                                       // P1DIR = <PIN7><PIN6><PIN5><PIN4><PIN3><PIN2><PIN1><PIN0>
                                       // Since we want to blink the on-board red LED, we want to set the direction of Port 1, Pin 0 (P1.0) as an output
                                       // We do that by writing a 1 on the PIN0 bit of the P1DIR register
                                       // P1DIR = <PIN7><PIN6><PIN5><PIN4><PIN3><PIN2><PIN1><PIN0>
                                       // P1DIR = 0000 0001
                                       // P1DIR = 0x01 <-- this is the hexadecimal conversion of 0000 0001
     for (;;)
                                        // This empty for-loop will cause the lines of code within to loop infinitely
          P1OUT ^= 0x01;
                                        // Toggle P1.0 using exclusive-OR operation (^=)
                                        // P1OUT is another register which holds the status of the LED.
                                        // '1' specifies that it's ON or HIGH, while '0' specifies that it's OFF or LOW
                                        // Since our LED is tied to P1.0, we will toggle the 0 bit of the P1OUT register
          for(i=0; i< 20000; i++);
                                        // Delay between LED toggles. This for-loop will run until the condition is met.
                                        //In this case, it will loop until the variable i increments to 20000.
```



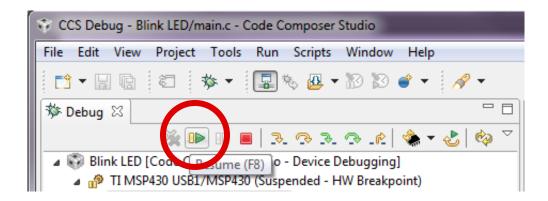
Download Code

- Now that we have written our code, we can download it to our MSP430 LaunchPad that is plugged into the USB port!
- Code is downloaded by clicking the debug button



Run Code

• Clicking the Debug button will take us to the CCS Debug View. Here, we can *press the Run button* to start running the code we just wrote.



• At this point, your red LED should be blinking.

Congratulations!

Additional Exercises

- Now that we have our LED blinking, play around with the number inside of the for-loop to change the speed of the blinking LED. The smaller the number, the shorter the delay between LED toggles, or the faster the blinking. Alternatively, the larger the number, the longer the delay. Try values like 5000, 40000, etc.
- Another exercise is getting the green LED to blink as well. The green LED is tied to Port P4.7. Using the P4DIR and P4OUT registers we used above, see if you can get both LEDs to blink. Can you make them blink in unison? Can you make them blink alternatively?

Other ideas!

- Congratulations! You've just developed your first MSP-EXP430F5529LP LaunchPad project using TI's Code Composer Studio!
- There are other development tools out there. One example is a community-driven code editing tool called **Energia**.
- You can get Energia @ www.energia.nu

```
Blink | Energia 0101E0009
File Edit Sketch Tools Help
  Blink§
  Blink
  Turns on an LED on for one second, then off for one second, repeatedly.
  This example code is in the public domain.
void setup() {
  // initialize the digital pin as an output.
 pinMode (P2_0, OUTPUT):
void loop () {
  digitalWrite (P2 0, HIGH);
                            // set the LED on
  delay (1000):
                            // wait for a second
                           // set the LED off
  digitalWrite(P2_0, LOW);
                            // wait for a second
  delay (1000);
                                     LaunchPad w/ msp430g2553 (16MHz) on COM30
```



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