9.17

9.17

9.16, a) =
$$E_{\pi}[G_{e}|S_{e}=s, A_{e}=a]$$
 # by def

= $E_{\pi}[\sum_{k=0}^{\infty} \delta^{k}R_{t+k+1}|S_{e}=s, A_{e}=a]$

= $E_{\pi}[R_{t+1} + \gamma \sum_{k=0}^{\infty} \delta^{k}R_{t+k+2}|S_{e}=s, A_{e}=a]$

= $\sum_{s'es} p(s'|s,a) \cdot r(s,a,s')$ # by oblin of expectation and two only the object to the one of the object to the one of the object to the one of the object to the object to

9π(s,a) = Σ p(s|a,s') · [π(s,a,s') + γ π(a'ls') 9π(s',a') # By linearity of expectation 3.19 V_ (S) = \(\sum_{a \in A} \) (a1s) \q_{\pi}(s,a) Note from a bove 9 n(s,a) = E p(s|as') - [n(s,a,s') + XVn(s')] 9π(s,a) = E[R_{t+1} | S_t=s, A_t=a] + δΕ[V_π(s_{t+1}) | S_t=s, A_t=a]

βrom, otenivation in q 3.17

Just backward

9π(s,a) = Ε[R_{t+1} + δ V_π(S_{t+1}) | S_t=s, A_t=a] Now we sumply apply (3.4) to (3) p(s'15,a) = \(\sigma\) p(s', \(\sigma\)) 9 T(S,a) = \(\sum_{\sistem} \sigma \) \(\s