

SHAUNAK SRIVASTAVA

Course: M.Sc. (Hons.), Mathematics and B.E. (Hons.), Electronics

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CGPA: 6.76



ACADEMIC DETAILS						
COURSE	INSTITUTE/COLLEGE	BOARD/UNIVERSITY	SCORE	YEAR		
CLASS XII	CMR National Public School, Bangalore	CBSE	94.6 %	2017		
CLASS X	Sishu Griha Montessori and High School, Bangalore	CISCE	94.4 %	2015		

Subjects / Electives	Discrete Mathematics, Linear Algebra, Mathematical Optimization, Numerical Analysis, Applied Stochastic Processes, Statistical Inferences and Applications, Probability and Statistics, Differential Equations; Data Structures and Algorithms, Algorithms on Graphs, Algorithmic Toolbox, Graphs & Networks, Cryptography, Deep Learning; Digital Design, Signals and Systems, Control Systems, Microprocessors and Interfacing, Digital Signal Processing	
Technical Proficiency	- J, -,,	

SUMMER INTERNSHIP / WORK EXPERIENCE

Project Intern, Carraro India Pvt. Ltd.

May 2019 - Jul 2019

Researched on Statistical Process Control and its use in optimizing Six Sigma Processes. Analyzed manufacturing process data to find variations using statistical tools.

Conducted statistical studies to find Process Capability (Cp), Process Capability Index (Cpk).

PROJECTS

Multi-Object Tracking - Computer Vision Link

June 2020 - July 2020

Designed an algorithm for Multi-Object Tracking which has been tested on the MOT

Challenge benchmark and the **KITTI dataset**. Studied various **online tracking** algorithms such as **SORT, DeepSORT** etc.

 $\label{lem:explored} \textbf{Explored} \ \textbf{CNN} \ \textbf{and} \ \textbf{colour} \ \textbf{histogram} \ \text{based feature descriptors for data associations}.$

Worked with algorithms such as **Kalman Filters**, **Hungarian Association Method**, **Linear Assignment**, **Feature Extraction** and **Track Management**.

Implemented using Python, NumPy and OpenCV.

Localization and Path Planning for Autonomous Vehicles - Mobile Robotics

Created a working simulation which demonstrates **autonomous Aug 2018 - Dec 2018 navigation** of a vehicle on an a path with obstacles.

Used the ${f ROS}$ framework and ${f Python}$ for programming along with ${f Gazebo}$ for the simulation environment.

Used **Sensor Fusion** data, such as 3D depth data from RGB-D sensors, IMU data and GPS data for the simulation.

Implemented algorithms like **SLAM, GMapping** and **Extended Kalman Filters** for localization.

Dynamic Hand Gesture Control using Deep Learning - Computer Vision Link

Implemented a Hand Gesture recognition system and its application for **Jul 2020 - Jul 2020** Power Point Presentations.

Used **Google's mediapipe** hand-tracking model for hand detection followed by classical techniques for gesture recognition using **Python** and **OpenCV**.

Ant Exploration using RL - Reinforcement Learning Link No

Nov 2020 - Nov 2020

Created a **Reinforcement Learning** agent using **NEAT-python** for environment exploration and collision avoidance.

Used **pygame** for creating the game environment. NEAT-python implements an **evolutionary neural network** to perform learning. Experimented with different environment layouts to understand effect on learning speed.

Projects under Image Processing and Computer Vision Course - Computer Vision Object Detection and Blurring using Haar Cascades for privacy Dec 2019 - Jan 2020

protection.

Object Tracking using Dense Optical Flow.

Projects under Deep Learning Specialization Course - Deep Learning

Non-maximal suppression on bounding boxes detected using YOLO.May 2020 - May 2020 Created a voice activation tool, similar to Siri and Alexa, using Attention Models.

Performed **Sentiment Analysis** using **LSTM** and **word embedding**.

Facial Identification System using Siamese Networks.

Projects under Data Structures & Algorithms Course - Data Structures and Algorithms Bi-Directional Dijkstra's algorithm for searching in social networking Jun 2020 - Jul 2020 graphs.

Contrast Hierarchy and **A* algorithms** for road network traversals.

Bellman-Ford algorithm for optimal currency-exchange.

Voice Digitizer - Microprocessors and Interfacing

Mar 2020 - May 2020

Designed a voice digitizer system using an 8-bit ADC to convert analog to digital signals and reproduce the signals with modifications. Design used an **8086 microprocessor** chip along with chips like **8255**, **8254**, **8259** for peripheral device interfacing and interrupt control. Created a digital simulation using **Proteas** software and coded it using Assembly Language.

The One Game - Computer Programming

Nov 2016 - Jan 2017

Made a hybrid game out of classic school games of hand-cricket, hangman and rock-paper-scissors.

Used **C++ programming** to make a digital application.

POSITION OF RESPONSIBILITIES

Core Member - Mime Club

Aug 2019 - May 2020

As a Core Member, my primary role was as Director for a crew of 30 members. Content creation and stage execution came under responsibility.

President - MUN Club, CMR National Public School

Jun 2016 - Mar 2017

My duties included mentoring students in Model UN and creating a strong debating culture among peers. My team won several awards during my tenure including team delegation awards at national level Model UN competitions.

EXTRA CURRICULAR ACTIVITIES

Event Organization

Worked for the **Department of Sponsorship and Marketing** to raise funds and manage on fest marketing for our cultural, technical and sports festivals.

Acting and Direction

I have been active member for the Mime Club for the last three years and was a core member for the 2019-20 team. I was part of 7 productions as an actor and director. Apart from these, I have also been part of 2 short film productions.

Sports and Athletics

Won several accolades in individual events such as sprints and long jump along with several team events like Football, Relay and Kho-Kho.

AWARDS AND RECOGNITIONS

4th State Rank in Math Olympiad | Silverzone Foundation

CERTIFICATIONS					
CERTIFICATION	CERTIFYING AUTHORITY	DESCRIPTION			
Algorithms on Graphs	Coursera	Djikstra's Algorithm, Bellman-Ford, Kruskal's Algorithm			
Deep Learning Specialization	Coursera	Neural Networks, Hyper-parameter Tuning, CNNs, Sequence Models			
Algorithmic Toolbox	Coursera	Time Complexity, Greedy Algorithms, Dynamic Programming			
Data Structures	Coursera	Binary Search Tree, Priorty Queue, Hash Table, Stack, List			

COMPETITIONS

Cottons Model United Nations - Aug, 2015 Secured the Best Position Paper Award.

Sishu Griha Model United Nations - Jun, 2014 Secured the Best Position Paper Award.

Indian Robotics Olympiad - Sep, 2013 Secured Third Position a the regional round and qualified to compete at the National Level.

First Lego League - Jan, 2012 Awarded the Best Design for our Robot.

SCHOLOARSHIPS

National Talent Search Examination (NTSE)

May 2015

The National Talent Search Examination (NTSE) is a prestigious award given to students excelling in the studies related to science and encouraging further studies by giving a scholarship. I successfully cleared the NTSE examination at the state level.

LANGUAGES KNOWN

English: Native proficiencyHindi: Native proficiency

German: Elementary proficiency