

Convolutional Neural Networks

- Convolutional Neural Networks (CNN's) are the most common type of neural networks used in deep learning
 - Recurrent Neural Networks are catching up though!
- Oldest form for deep learning (over 20 years old)
- Efficient way to capture features in image processing
- Original purpose: automatic check processing
 - Digit recognition
- Now used for image identification in general with more levels of target
- Lots of ongoing research

The Convolution in CNN's

- Convolution is a general process which involves a combination of data across domains
- Example: take a sequence of data: 1, 3, 5, 2, 3, 6, 6, 10, 4, 6
- Some convolutions of this one dimensional data
 - Moving average: taking average of last, current, and next:
 - 3, 3.3, 3.3, 3.7, 5, 7.3, 6.7, 6.7
 - In image resolution, this is called blurring
 - Sharpening: $x_n' = -1x_{n-1} + 4x_n x_{n+1}$
- Other types of convolutions can find edges in images or other types of features
- The above example is 1-dimensional, but can carry over to 2-dimensional images
- Color can add further features for the data

Pooling for Images

- Pooling is another common way of feature extraction for images
- Method of dimension reduction
- Steps in pooling:
 - Pool Pixels into grid
 - Make calculation for each grid
 - Max Pooling
 - Average Pooling
- Filter = size of grid
- Stride Length = shift in data on grid

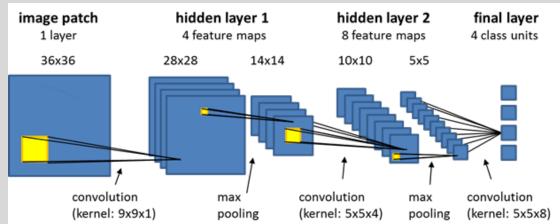


Data Augmentation for Image Recognition

- There are some simple transformations that can make the dataset richer for modeling with CNN's
 - Artificially increasing the dataset size so that models are better
- Suppose we have dataset which contains labeled targets (such as images of digits, where target has 10 levels: 0-9). We can
 - Translate the digits (move up/down/left/right)
 - Expand/shrink the digits
 - Rotate the digits
 - Any combination of the above
- The transformed data can be added to the original dataset for a larger set of data
 - Adding data to make modeling better is called data augmentation

Structure of Modeling with CNN

- Steps
 - Convolution
 - Pooling
 - Neural Network
- Convolution and Pooling are described as layers
 - no fitting happens in these layers
- Often are multiple layers at each level
- Hidden layers in neural network are usually fully connected
 - ReLU is most common activation function



Regularization in Neural Networks

- Our structure has a crazy number of parameters
- We will need to clamp down on parameter explosion by regularization process
- Types of regularization for neural networks
 - Penalty regularization
 - Penalize for parameter sizes
 - Can be L₁ or L₂ just like with lasso/ridge regression
 - Dropout regularization
 - A random set of nodes are "turned off"
 - The dropout rate is a hyperparameter which gives the probability of any individual neuron to be turned off

Convolutional Neural Networks in R

- We will use keras for processing CNN's
- Lots of things to do in keras
- Let's jump straight to sample code