

Ans-1

s	a	s'	r	$P(s', r s, a)$
high	search	high	r_{search}	α
high	search	low	r_{search}	$1 - \alpha$
high	wait	low high	r_{wait}	1
low	search	high	-3	$1 - \beta$
low	search	low	r_{search}	β
low	wait	low	r_{wait}	1
low	recharge	high	0	1

If $s = \text{high}$, we can search or wait & get corresponding rewards.
If $s = \text{low}$, we can search, wait or recharge. If we search, then, we can drain the battery & have to be recharged; we get -3 reward. If we choose to recharge, then we get 0 reward & transition to high state.

Ans-5

$$v_*(s) = \max_{a \in A(s)} q_*(s, a) \quad \forall s$$

Ans-3

3.15

$$G_t = R_{t+1} + \gamma R_{t+2} + \gamma^2 R_{t+3} + \dots$$

new rewards are —

$$R_{t+1} + C, R_{t+2} + C, \dots$$

$$\begin{aligned} G_t' &= (R_{t+1} + C) + \gamma(R_{t+2} + C) + \gamma^2(R_{t+3} + C) + \dots \\ &= (R_{t+1} + \gamma R_{t+2} + \gamma^2 R_{t+3} + \dots) + C + \gamma C + \gamma^2 C + \dots \\ \Rightarrow G_t' &= G_t + \frac{C}{1-\gamma} \quad ; \quad v_C = \frac{C}{1-\gamma} \end{aligned}$$

As G_t' is changed by a constant term
 \Rightarrow value of ^{all} the states is increased by v_C .
As $v_q(s) = E[G_t]$
 $\Rightarrow v_q(s) = \frac{v(s)}{\pi} + v_C$

3.16

$$\text{Now, } G_t = R_{t+1} + \gamma R_{t+2} + \dots + \gamma^{N-1} R_{t+N}$$

Let $N = \text{episode length}$

$$G'_t = (R_{t+1} + c) + \gamma(R_{t+2} + c) + \dots + \gamma^{N-1}(R_{t+N} + c)$$

$$= (R_{t+1} + \gamma R_{t+2} + \dots + \gamma^{N-1} R_{t+N}) + c + \gamma c + \dots + \gamma^{N-1} c$$

$$\Rightarrow G'_t = G_t + c \left(\frac{1 - \gamma^N}{1 - \gamma} \right)$$

This would change the task, as G'_t depends on episode length N .

$$v_{\pi}(s_t) = E \left[R_{t+1} + \gamma v_{\pi}(s_{t+1}) \right]$$

current value of state depends on future values of successor states. To both of these we add different constants according to N .

If N is small, value of all states change by less amount than for states with large N .