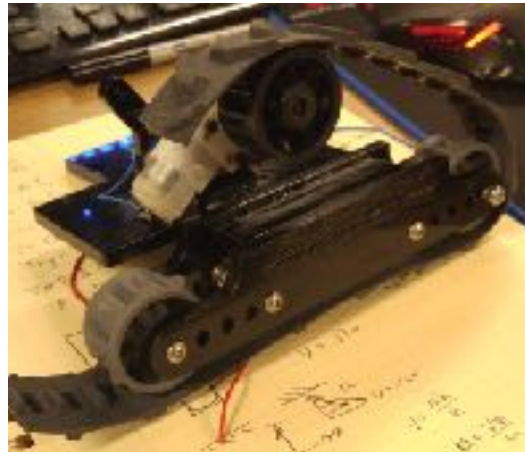
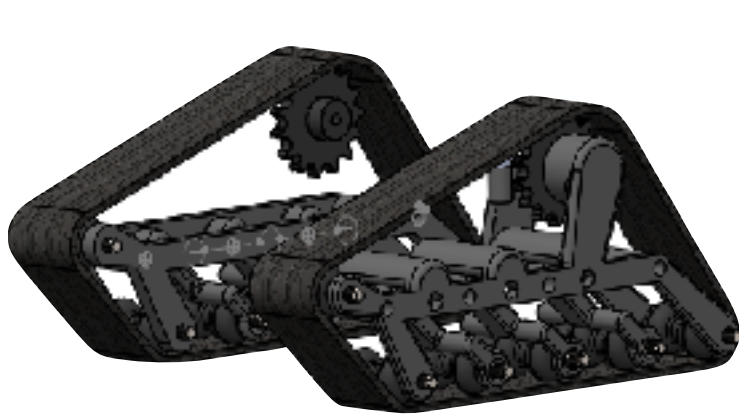


RC Robot(s)

Project goal

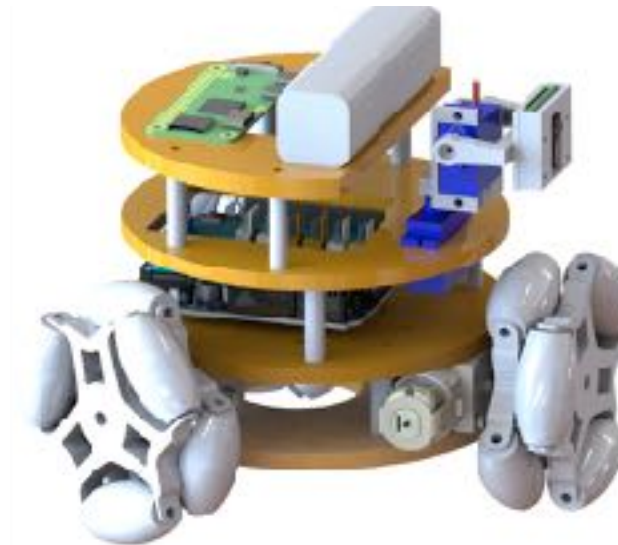
To experiment with different types of RC robots with different locomotion systems



Tank tread robot design



Walking robot with servo motors



Different omni-wheel robot designs (using a Form 2)