CS 677 Final Project

Integral Image and Detection
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Problem Description

General Purpose

Detect largest area with a given color.



R=162 G=16 B=12



Computation

- Two major steps.
- 1. Computing Integral Image

The area of an arbitrary rectangle can be obtained by using 4 numbers.

2. Find the largest rectangle

These two parts can use GPU to accelerate computing speed.

Integral Image on GPU

2D Prefix Sum

Apply prefix sum on each row first and then apply it on each col.

- Consider 1D Prefix Sum on CPU -> O(N)
 1D Prefix Sum on GPU -> O(logN)
- For Integral Image

 $O(M*N) \rightarrow O(logM*logN)$

Find the max on GPU

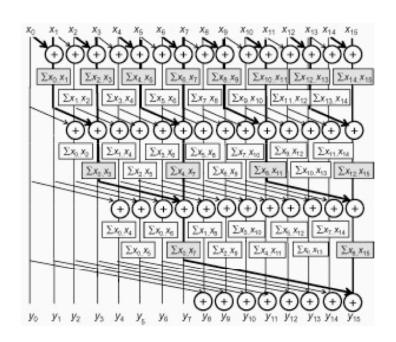
- Consider finding on CPU -> O(N)
- Consider finding on GPU -> O(logN), use reduction.

Steps

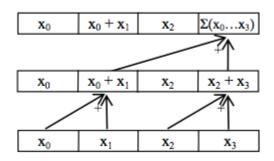
1, Read source image and given color. Then, convert the image to a matched image.

matched image, int[M*N], 1 is given color, 0 is not.

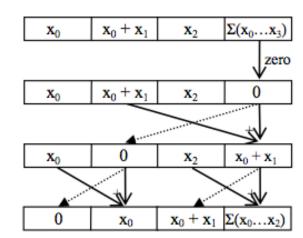
Computing integral image. computeOnDeviceNaive()



Computing integral image.computeOnDevice()

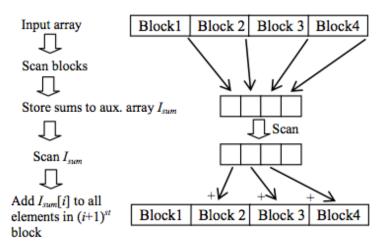


Reduce Phase

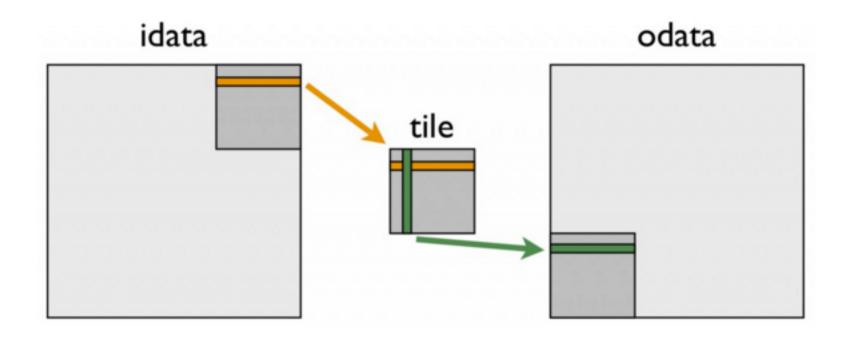


Down Sweep Phase

scanBlocks()



2, Computing integral image. transpose()



• 3, If use CPU, the finding part looks like

```
for each (x, y)

for each (w, h)

area = integral_img(x, y, w, h)

Largest = max(area, Largest)
```

In GPU, I use

```
for each (w, h) -> on CPU

area = findLargest(any (x,y)) -> on CPU

Largest = max(area, Largest)
```

findLargest(any(x, y))

Reduction tree with interleaved addressing.

findLargestInBlocks()

CPU find largest in blocks. This can be paralleled in GPU.

Scan Part

```
dim3 threadsPerBlock(SECTION_SIZE);
dim3 blocks((int)ceil((float)N/SECTION_SIZE));
```

Transpose Part

```
dim3 block_dim(BLOCK_DIM,BLOCK_DIM);
dim3 grid_dim((int)ceil((float)N/BLOCK_DIM), (int)ceil((float)M/BLOCK_DIM));
```

Finding Largest

```
dim3 threadsPerBlock(256);
dim3 blocks((int)ceil((float)width*height/256));
```

Scan Part

__shared__ int partialSum[SECTION_SIZE];

Transpose Part

__shared__ int tile[BLOCK_DIM][BLOCK_DIM];

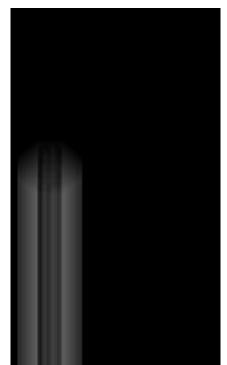
Finding Largest

__shared__ float sdata[256];

__shared__ float sIndices[256];









Result







