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The Embedded Systems Experts

# Trends in Embedded Software Development

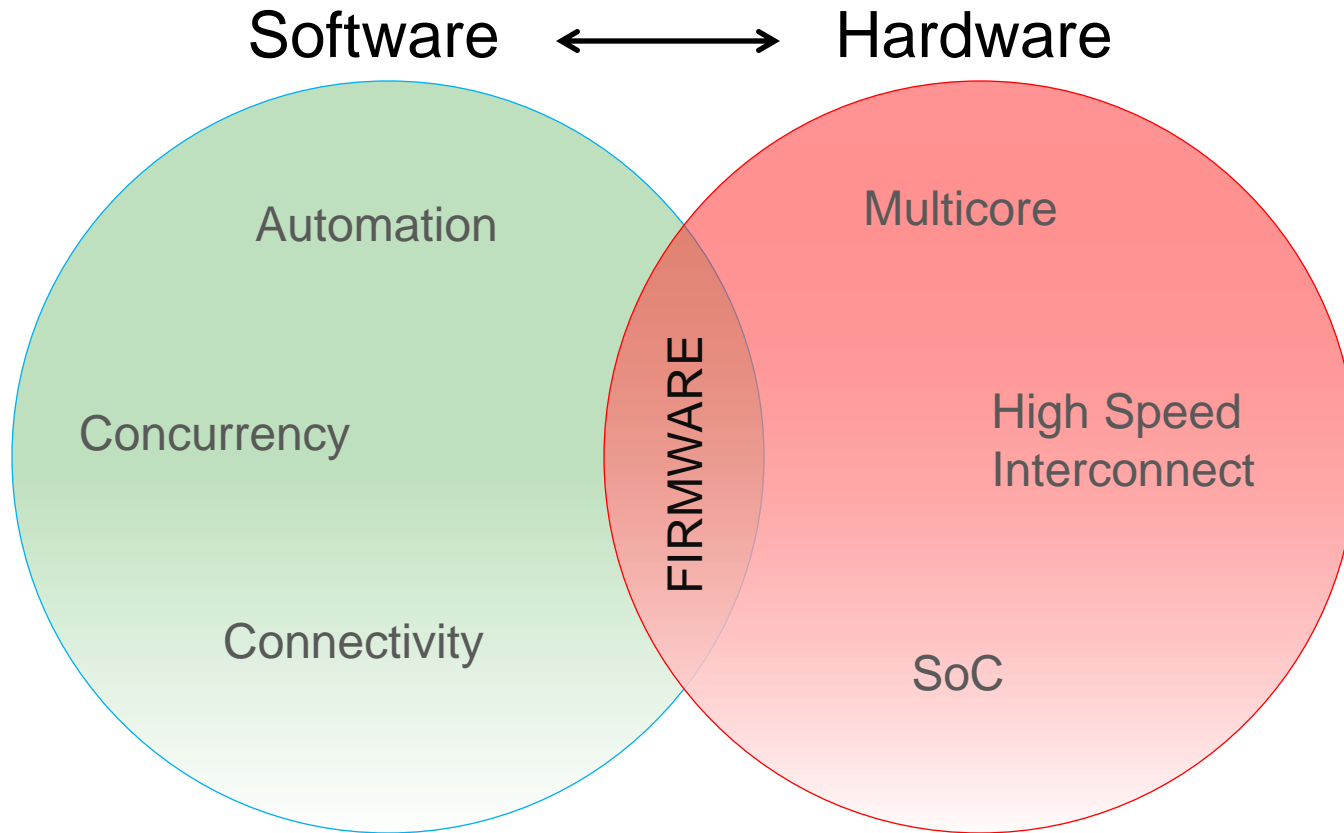
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**Principal Engineer, Barr Group**

Renesas Electronics America Inc.

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# Topic: "Trends in *Embedded Software*"



Advances in hardware and software impact each other

# About the Presenter

- Principal Engineer, Barr Group
  - Consulting – Architecture and Process
  - Product Development
  - Expert Witness
- B.S.E.E., Princeton University
  - Computer Architecture
  - Microprocessor Design
- Industry experience
  - Telecom & Datacom
  - Industrial Control
  - Low-power Devices & Consumer Electronics
- Range of processor architectures, RTOSs, etc.



# About Barr Group

- Internationally recognized leader in embedded systems
  - CTO – Michael Barr (Netrino, Embedded Systems Design, ...)
- Focus on reliability and security
  - Training
  - Consulting on process and architecture
  - Design services
- Renesas RX62N Development board
  - Center of 5-day Embedded Bootcamp course
  - Also available: “Bootcamp in a Box”
- More information:
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# Foundation for this presentation

## ■ Personal experience

- 20+ years of embedded development
- Wide variety of industries, code sizes, and processors

## ■ Barr Group experience

- Even wider range of experience and exposure
- Survey of our customers and partners

## ■ Industry Research and Reports

- Necessary to stay on top of emerging trends
- Identify emerging processes, architectures, standards...

## ■ Personal Connections & Contacts

- e.g. Michael Barr, former editor of “Embedded Systems Programming” magazine

# Renesas Technology & Solution Portfolio

DEVCON



# Role of firmware in embedded products

- Firmware is largest part of embedded product development...
  - *By staff / headcount*
  - *By cost*
  - *By time*
  
- Also considered to be riskiest
  - In terms of product security & stability
  - In terms of schedule slips
  
- Why?
  - Beginning without requirements
  - Changing requirements
  - We can always sneak in “one more feature”
  - We can always “fix it in the field”



# Importance of firmware correctness

## ■ Quoting Jack Ganssle:



- "Firmware is the most expensive thing in the universe"

## ■ Quoting Michael Barr:



- "Neither reliability nor security can be tested, debugged, or patched into a product. They must be designed into embedded systems"

## ■ The bottom line:

- Important to get firmware right (as close to "right" as possible)
  - the first time



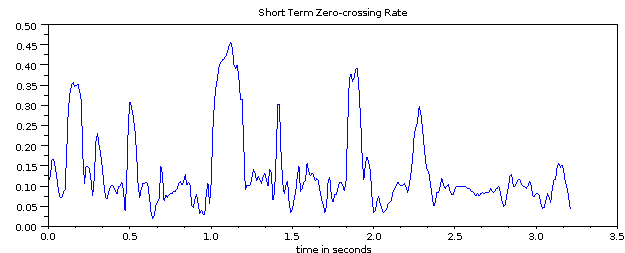
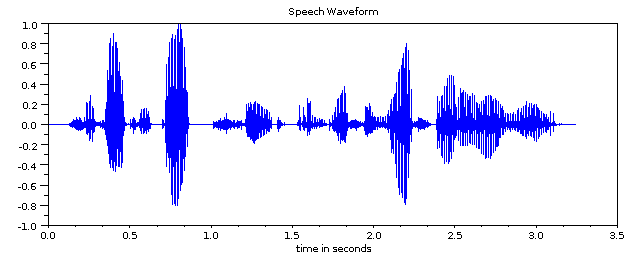
# What's driving the trends?

- More functionality being pushed into firmware
  - “Has to be done in hardware” – not necessarily!
  - Some products have a large up-front cost
  - Easier to update in the field
  - Easier to release feature upgrades (\$\$\$)
- More powerful processors
  - Less focus on conserving bytes & CPU cycles
  - More focus on writing correct, robust, maintainable firmware
- Better tools
  - Easier than ever to prototype something quickly
  - More time focusing on product-specific requirements and functionality

# Signal processing

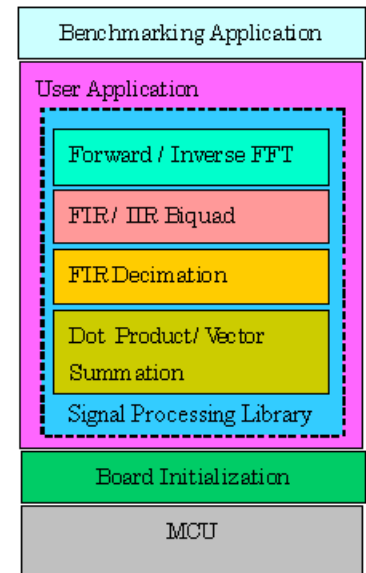
# Increased use of Signal Processing

- Not necessarily requiring DSP anymore
  - Microcontrollers are becoming more and more capable
  - Custom instructions, faster memories, bus architectures, etc.
- Multimedia is one driver
  - Audio encoding / decoding
  - Video encoding / decoding
  - Image processing
- Real-time control systems
  - Signal Conditioning / Filtering
  - Control loops



# Renesas MCUs and Signal Processing Library

- Dual CPU (MCU + DSP) can often be replaced by single MCU
  - Cost reduction, simpler design
- Renesas MCUs
  - SuperH (SH2A-FPU, SH4A)
  - RX Family (RX600)
    - MCU/DSP Hybrid (FPU, MAC, Barrel Shifter)
    - “Digital Signal Controllers”
  - M16C Family (R32C / 100)
- Renesas Signal Processing Library
  - Collection of the most useful routines
  - Abstract away complexities of underlying implementation
    - Focus on algorithms & system-level design
  - Fine-tuned and highly-optimized for Renesas CPUs
  - Floating point and fixed point
  - Callable from C and C++



# Test-driven development

# Test Driven Development (TDD) – what is it?

- A development methodology
  - Not a test methodology...
  - ... although when done properly, resulting code is well-tested
- Development is driven (guided) by tests
  - Not the other way around
- Tests are written before the code
  - Forces the question: “How will I test this?”
  - Emphasizes importance of separating interface from implementation

# Test Driven Development (TDD) in one slide

- Short, iterative development cycles
  - Write test(s)
  - Run test(s) – FAIL (no logic in code)
  - Write code to make tests pass
  - Run tests – PASS
- Emphasis on writing the minimum code to pass tests
  - Tends to reduce YAGNI situations
- Emphasis on automation
  - Essential if battery of tests is to be run over & over again
- Refactoring done at end
  - Take a step back, improve internal structure without breaking anything



# Test Driven Development benefits

Assuming the process is followed properly

## 1. All code is unit tested

or at least what is feasible

## 2. Regression test suite is already developed

Did we break anything?

## 3. Tests are automated

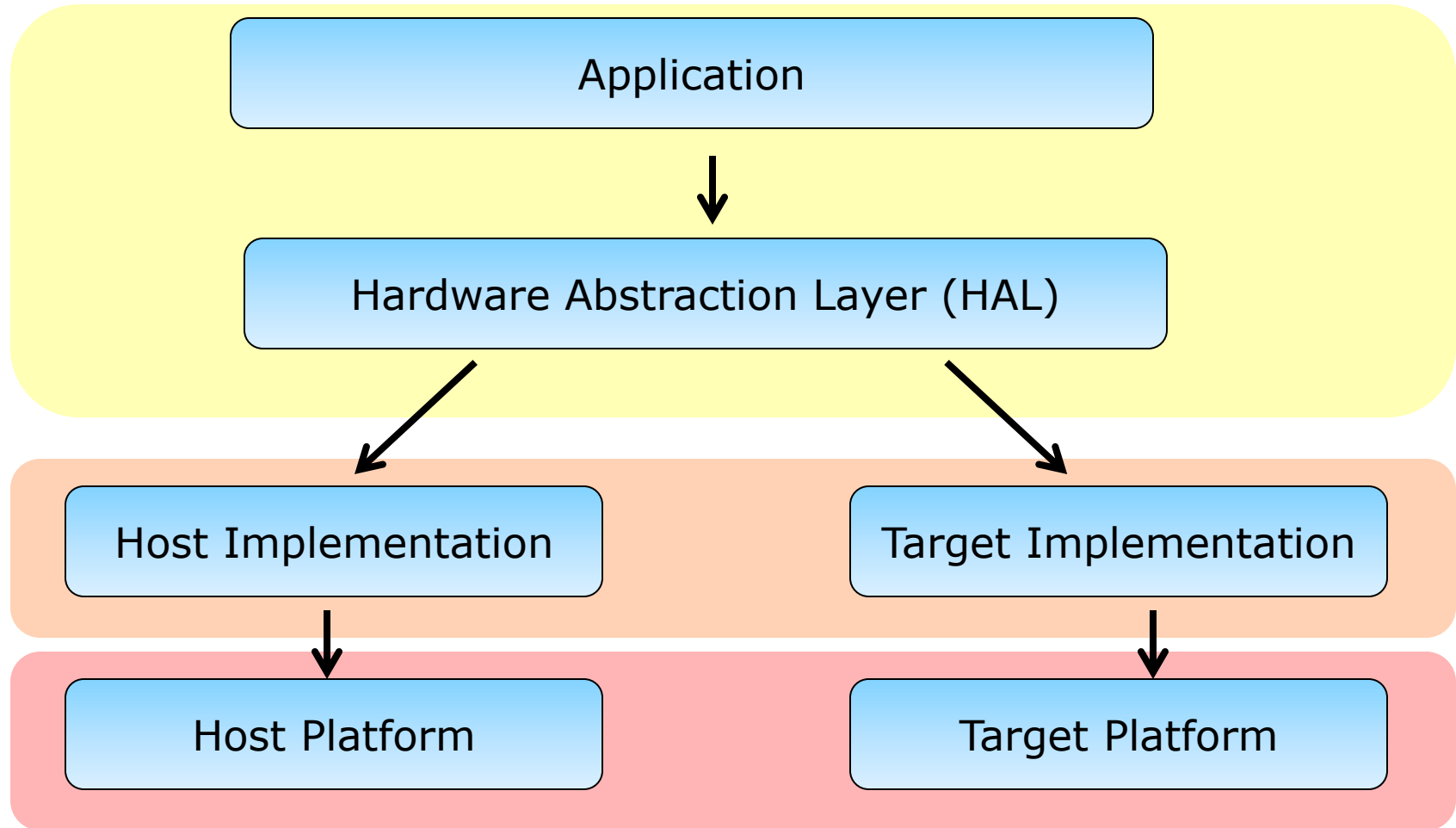
No barrier to running a “health test” on current build

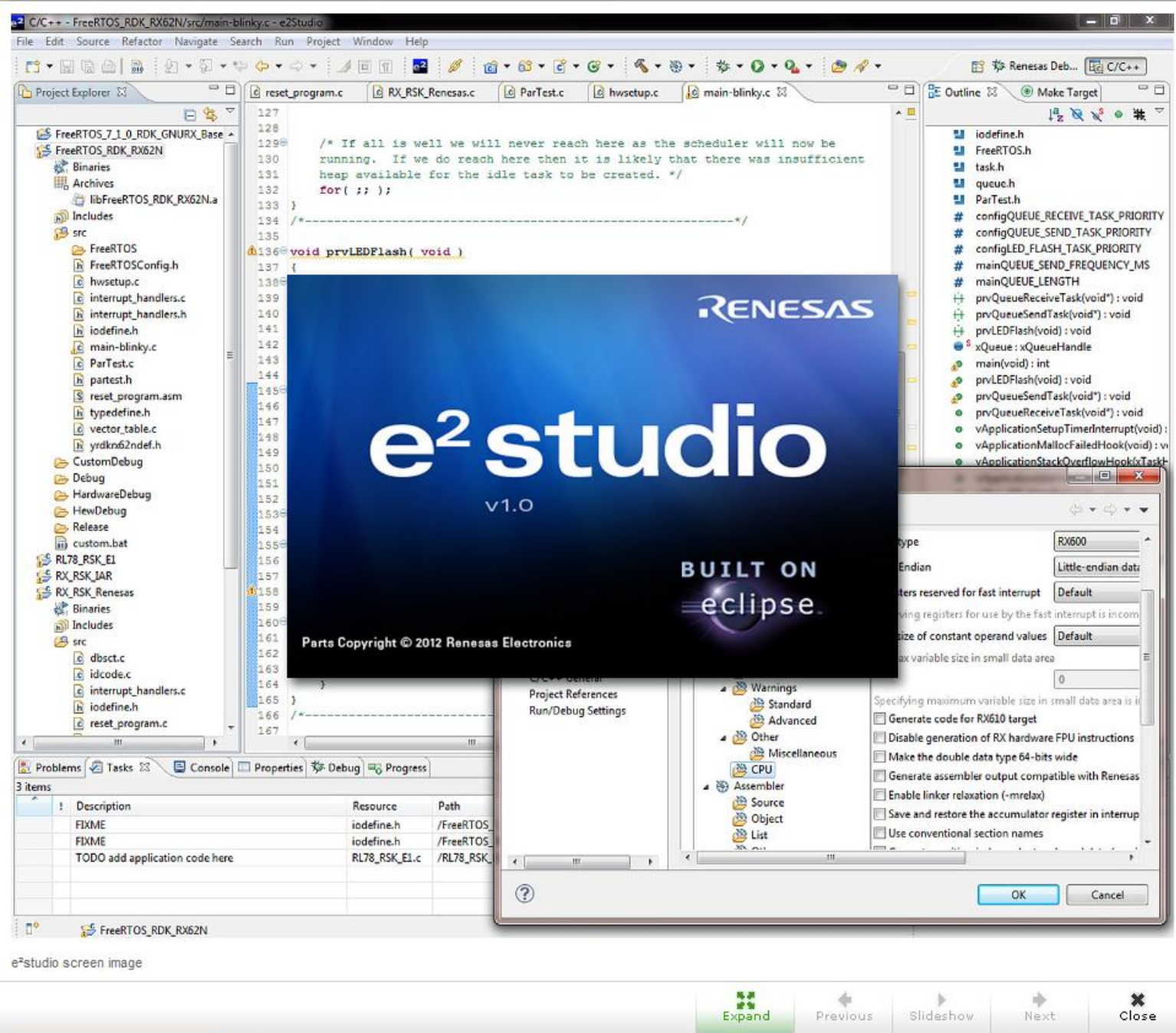
Lack of automation is the single biggest obstacle

## 4. Write code and run tests before target HW available

Test harness + removal of global state – simplifies testing

# Decoupling software from target platform





e2studio screen image

## Middleware and 3<sup>rd</sup> party firmware

# Increasing use of middleware

- Products are becoming more complex and capable
- Many capabilities are “enablers”
  - Network connectivity
  - Plugins / User Applications
  - Graphical User Interfaces
- Most companies aren’t in the business of developing user interface toolkits, network stacks and frameworks
  - But they want to use them
- Development -- more ***integration*** activities than ever
  - Final product - combination of company’s differentiating technology & 3<sup>rd</sup>-party enabling middleware

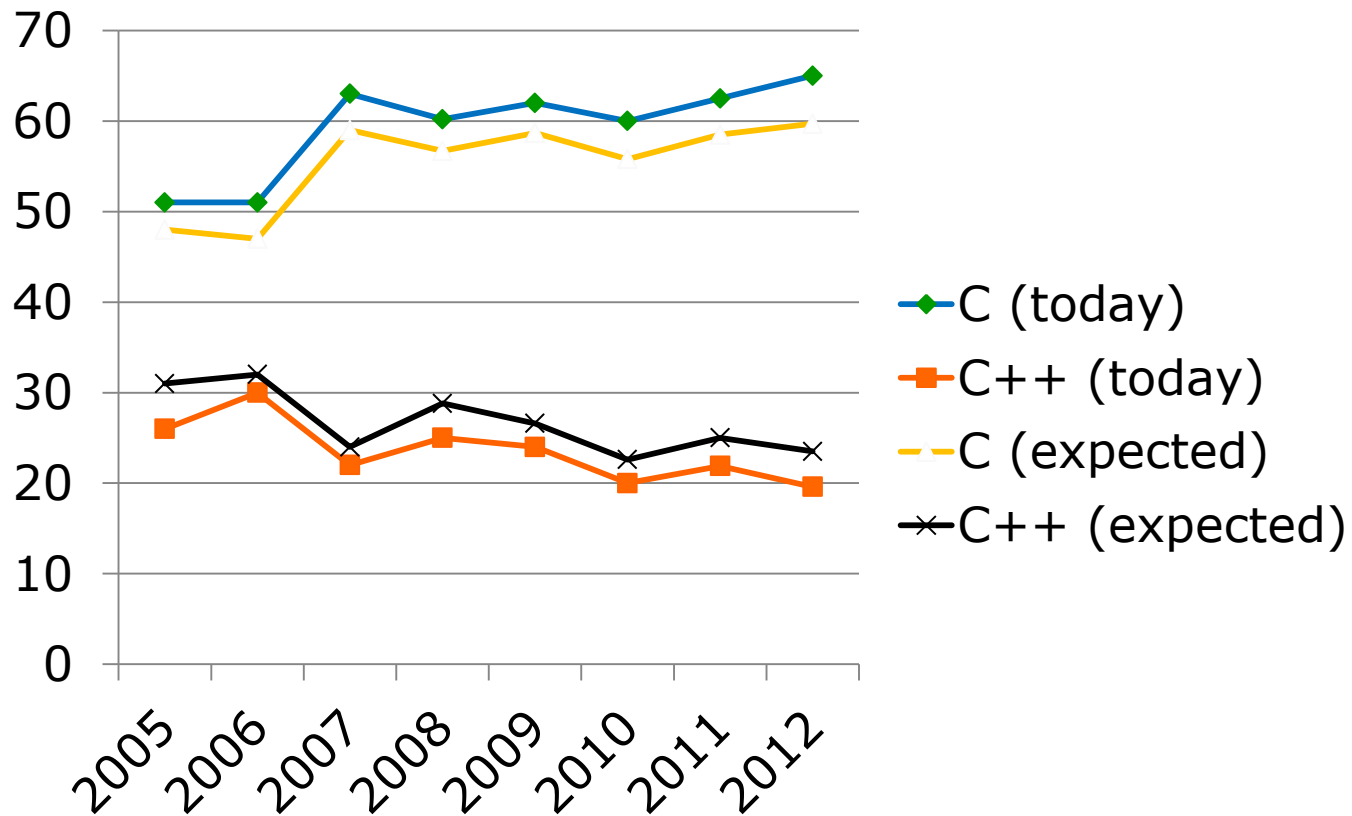
# Rich set of middleware and 3<sup>rd</sup>-party firmware



# Use of C and C++



# Trends in Programming Languages



# C & Embedded Systems

- A natural fit...
  - Ability to access & address memory directly
  - “volatile” keyword
  - Sometimes referred to as a “high level assembly language”
  - Gives you “enough rope to hang yourself”
- ... but fewer graduates than ever are being taught C!
  - And even fewer how write robust real-time firmware in C
  - Is this a good thing or a bad thing for veteran C developers?
- New C standard – C11
  - Most features not specifically targeted at firmware
    - ... but still useful
  - Toolset support still lagging

# Use of C++ in firmware development

- Usage of C++ increases with project complexity
  - 32 kilobytes or less: 8%
  - Up to 256 kilobytes : 24%
  - Up to 1MB: 56%
  - Greater than 1MB: 71%
  
- Usage of C++ increases with processor architecture
  - 8-bit: 6%
  - 16-bit: 18%
  - 32-bit: 52%
  
- A couple of important notes
  - Numbers reflect percentage of projects using **any** C++
    - Virtually all of the projects above reported use of C as well
  - Much embedded C++ in use is very “C like”

# Use of C++ going forward (2012 and beyond)

- New C++ standard (C++11)
  - Finalized in late 2011
  - Compiler support just rolling out now
  
- Now you can write firmware in C++ that is:
  - Safer (*e.g.* static (compile-time) assertions)
  - Faster (*e.g.* rvalue references / move semantics)
  - Smaller (*e.g.* constant expressions)
  - Simpler (*e.g.* type inference ("auto"), range-based for, lambda)
  
- Change in CPU, change in programming language
  - Move from 8/16 bit to 32-bit
    - "Now we can use C++"
  - Typically involves change in hardware, tools, etc.
    - Good time to consider change in implementation language

# IDEs/toolsets and programming languages

- Use of both C and C++ supported
  - Possible to migrate from C to C++
  - Also possible to mix C & C++ in same application
- Major IDEs support both programming languages
  - e<sup>2</sup> Studio (Eclipse)
  - Renesas High-Performance Embedded Workshop (HEW)
  - IAR Embedded Workbench
  - Green Hills MULTI
- Not locked in to any particular toolset or language
  - Relatively easy to migrate to different IDE
  - C and C++ compilers mostly standards-compliant

# Use of open-source software

# Increased use of open-source software

- More and more projects using open source software
- Motivations:
  - Source code availability
  - Licensing cost
  - Control / freedom
- Often not considered:
  - Stability / maturity of software
  - Cost / value of engineer's time
  - License requirements
- Most often cited reason for using open-source:
  - Not being dependent on software vendor for bug fixes / updates



# A few examples: Open-source & embedded

## ■ Host Side

- Host operating system
  - Linux (also on target side for larger systems)
- Build tools
  - GCC / G++ / LLVM
- IDE
  - Eclipse

## ■ Target Side

- Bootloader
  - U-Boot Bootloader
- RTOS
  - FreeRTOS
- Filesystem
  - FatFs (ElmChan)
- TCP/IP
  - lwIP, uIP

# Migration from 8/16 bit to 16/32 bit

# 8/16 bit CPUs

## ■ Not going away

- Extremely simple, high-volume, cost sensitive
- But the cost difference is decreasing
  - Especially when considering roadmap

## ■ The “hidden cost”

- Extra effort spent on optimizing memory & CPU cycles

## ■ CPU’s architecture is often exposed to programmer

- Code is typically not portable
- More time working around architecture (e.g. bank switching)

## ■ Development tools often limited

- Legacy compilers
- Often no support for C++
  - or even updated C (C99, C11)!

# The move to 32-bits

## ■ Key drivers

- Cost of 32-bit CPUs going down
  - Furthermore, CPU becoming smaller percentage of B.O.M.
  - Companies now consider indirect cost (development time)
- Products becoming software-intensive
  - Inexpensive, fast, integrated flash memory
  - Focus is on productivity, cycle time, debugging
  - More sophisticated development tools
  - Ability to program in higher-level languages
  - Less concern about memory and processing speed

## ■ 8/16 bit MCUs not going away

- Extremely simple, high-volume, cost sensitive
- Larger memories, faster clock speeds

# Renesas – 8/16/32 bit CPUs

## ■ Renesas – rich MCU portfolio under one umbrella

- One size does not fit all

## ■ 8/16 bit CPU offerings

- RL78, 78K, R8C
- M16C, H8 / H8x, 720/740



## ■ 32 bit offerings

- RISC: RX Family (RX600, RX200, ...)
- CISC: V850, SuperH



## ■ Roadmap / migration path

- Offerings for almost any power / performance requirement
- Commonality in IDEs and peripherals reduces learning curve

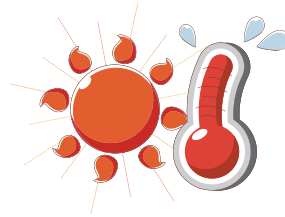
# Low Power Designs: The Firmware Aspect

# Motivation for low-power design

- Entire track at this conference on low power design

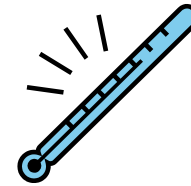
- What is heat?

- Wasted energy!



- Reduced heat

- Reduced cooling costs and complexity
  - Better reliability



- Battery-powered devices

- Longer run time
  - Smaller package



- Happier customers

- Better for environment
  - Less expensive to operate

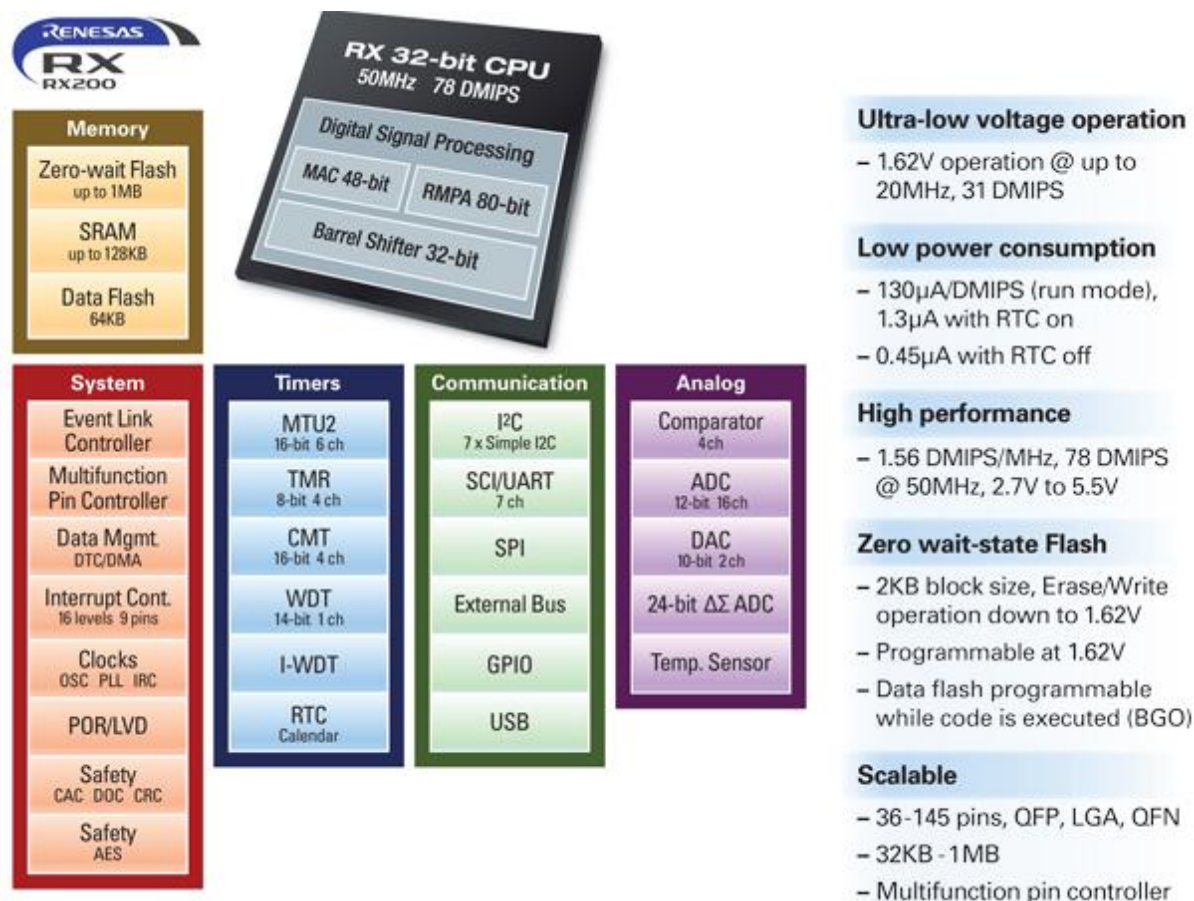




# Evolving role of firmware in low power devices

- Certainly, hardware design plays a large role
  - Often overlooked: role of software!
- Software is much easier to:
  - Patch / Change / Reprogram
  - Adapt & Evolve
  - Optimize
- Earlier: design hardware, write firmware, measure, panic!
- Today: design low-power firmware from outset
  - Emphasis on Hardware / Software co-design
  - Component selection – power down modes
  - Also important – internal MCU peripherals and clocks

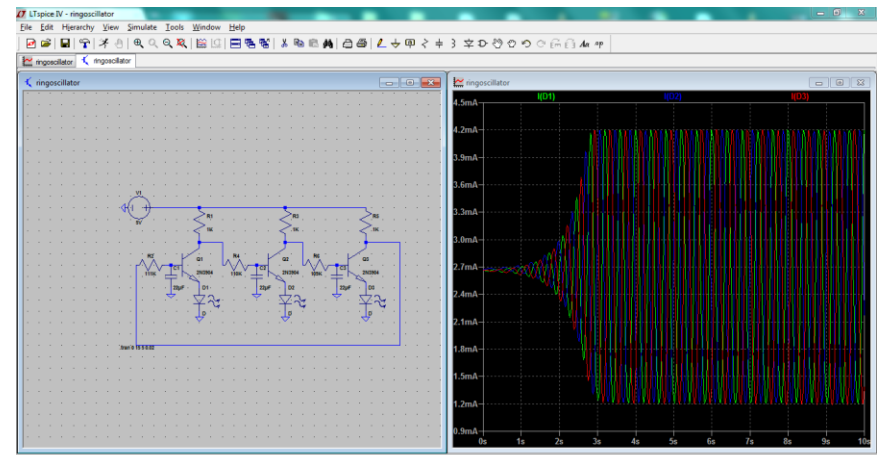
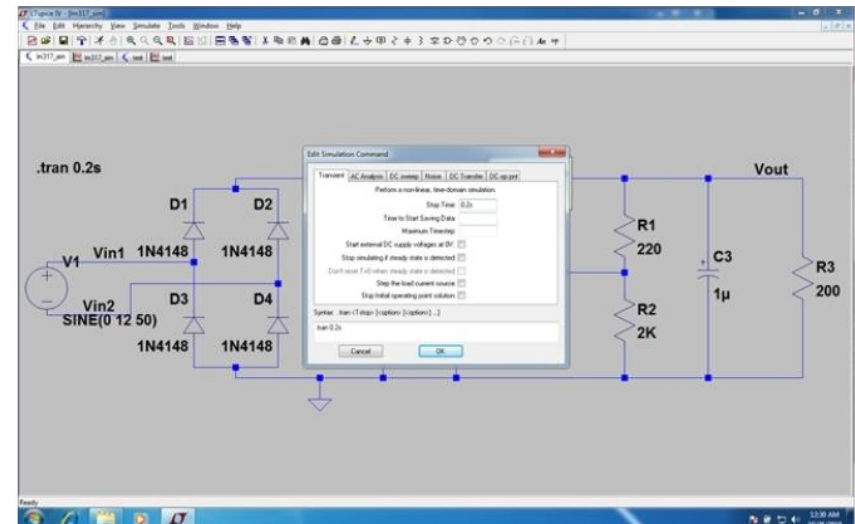
# Renesas – high performance, low power



# Modeling, Simulation, Code Generation, Frameworks

# Modeling & Simulation - Hardware

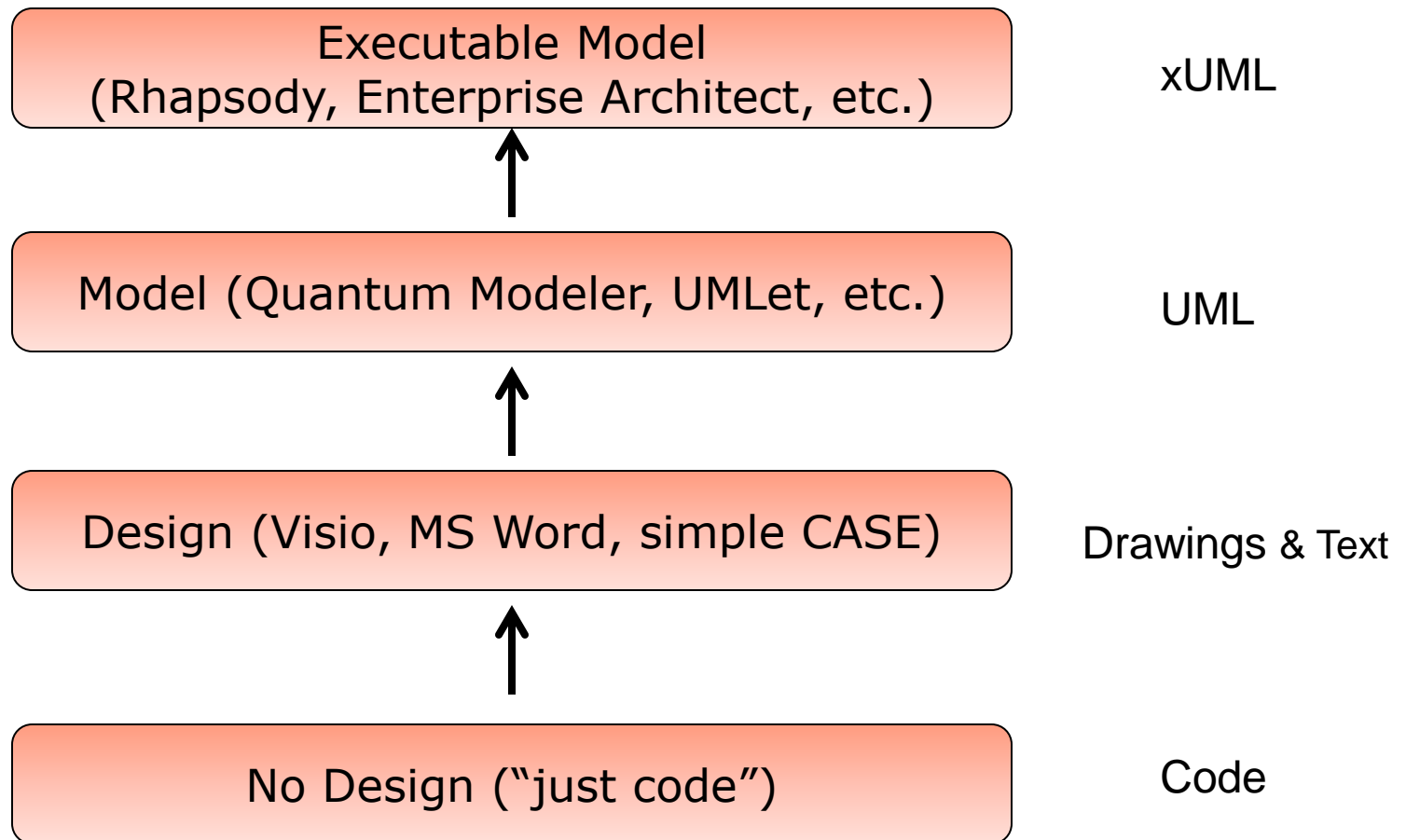
- Even important for simple circuits and hardware
- The interfaces & behavior of individual components are well-defined
  - Perfect for simulation
- Answers the question: "When I put this all together, will things behave the way I expect?"
- Faster & easier to test and debug than a real circuit



# Modeling & Simulation - Software

- Easier to get started
  - Not battling with nuances and quirks of new hardware
  - Friendly, robust, powerful environment
  - CPU & memory are essentially “unlimited”
  - Less intimidating
- Initial focus is not concerned with final target hardware
  - Task partitioning
  - Algorithm correctness
  - Data flow throughout system
- Getting these things right up front makes integration with new hardware easier (already proven correct on known HW)

# Development / modeling sophistication





# UML & Embedded Systems

- UML used increasingly for modeling embedded systems
  - Myth: UML only useful for OO / C++ systems
- UML statecharts : powerful, widely-used
  - Most embedded systems are event-driven at their core
  - Support for hierarchy in states
    - Reduce complexity and code size
  - Entry & exit actions
    - Enforce invariants
  - Guard conditions
    - Evaluate extended state variables at run time
- UML sequence diagrams
  - Show interactions between objects / tasks / threads
  - Describe data exchange (and often timing) between actors



# One size does not fit all

- Wide range of tools (from Visio to Rhapsody)
  - Visio: pure drawing tool
    - Not even UML aware
    - Better than nothing, but not by much!
  - Rhapsody: full-blown modeling tool
    - And all the complexity and “ceremony” that comes with it
- Different tools have different capabilities and features
- Consider the Costs
  - Financial
  - Learning Curve
  - Maintenance

# Modeling & Design Tools

## ■ Heavyweight tools

- Typically support round-trip engineering and executable UML
- Examples:
  - Rhapsody (IBM)
  - Enterprise Architect (Sparx Systems)
  - Visual Paradigm (only C++)
- These tools usually supply (or require) a framework

## ■ Lighter weight tools

- Quantum Modeler (Quantum Leaps)
- VisualState (IAR)
- Focused more on creating correct, robust hierarchical state machines than full-blown UML system engineering
- Code generation in C as well as C++
  - Targeted more at embedded systems

# Simulation and Modeling – Hidden Costs

## ■ False sense of security

- Not shaking out hardware
- Timing issues are largely undiscovered
- Memory/CPU limitations often not exposed
- Less intimidating development & debugging

## ■ Learning Curve

- Complex tools impose a serious learning curve
- Easy to become bogged down in options & drawing / layout
- Beware of analysis paralysis!

## ■ Move to target

- Use architecture-independent data types (e.g. `uint32_t`)
- Abstract away underlying hardware

# Code Generation

- One of the biggest motivations for modeling
  - UML-aware drawing tools are far better than Visio...
    - ...but code generation is even better!
- With code generation, the design is the code
  - “Design Rot” not possible with majority of application logic
    - Fix/enhance code by modifying design & re-generating
- Testing burden doesn’t disappear...
  - ... but at least the tedium of coding up diagrams does
  - Just because a model simulation works, there is no guarantee that the target code will
    - Code generation can have flaws just like compilers
    - Integration issues with marginal hardware

# Code Generation Example (Quantum Modeler)

The image displays two windows from the Quantum Modeler IDE. The left window shows the project explorer and a statechart for a ship object. The right window shows the generated C++ code for the ship object.

**Left Window: Project Explorer and Statechart**

- Project Explorer:** Shows the project structure with files like `game.h`, `missile.c`, `ship.c`, `tunnel.c`, `mine1.c`, and `mine2.c`.
- Statechart of Ship:** A statechart diagram showing three states: `active`, `flying`, and `exploding`.
  - active state:** Contains a `PLAYER_SHIP_MOVE` event and a `TAKE_OFF` event.
  - flying state:** Contains `TIME_TICK`, `PLAYER_TRIGGER`, `HIT_WALL`, and `HIT_MINE` events.
  - exploding state:** Contains a `TIME_TICK` event and a condition `[me->exp_ctr < 15]`.

**Right Window: C++ Code**

```
case TAKE_OFF_SIG: {
    return Q_TRAN(&ship_flying);
}
return Q_SUPER(&ship_active);
}
/* (AOS::Ship::Statechart::active::flying) ..... */
QState ship_flying(Ship *me, QEvent const *e) {
    switch (e->sig) {
        /* 0(2/1/5/1/3) */
        case Q_ENTRY_SIG: {
            scoreEvt *sev;
            me->score = 0; /* reset the score */
            sev = Q_NEW(ScoreEvt, SCORE_SIG);
            sev->score = me->score;
            QActive_postFIFO(AO_Tunnel, (QEvent *)sev);
            return Q_HANDLED();
        }
        /* 0(2/1/5/1/3/0) */
        case TIME_TICK_SIG: {
            /* tell the Tunnel to draw the Ship and test for hits */
            ObjectImageEvt *oie = Q_NEW(ObjectImageEvt, SHIP_IMG_SIG);
            oie->x = me->x;
            oie->y = me->y;
            oie->bmp = SHIP_BMP;
            QActive_postFIFO(AO_Tunnel, (QEvent *)oie);
            ++me->score; /* increment the score for surviving another tick */
            if ((me->score % 10) == 0) { /* is the score "round"? */
                ScoreEvt *sev = Q_NEW(ScoreEvt, SCORE_SIG);
                sev->score = me->score;
                QActive_postFIFO(AO_Tunnel, (QEvent *)sev);
            }
            return Q_HANDLED();
        }
        /* 0(2/1/5/1/3/1) */
        case PLAYER_TRIGGER_SIG: {
            ObjectPosEvt *ope = Q_NEW(ObjectPosEvt, MISSILE_FIRE_SIG);
            ope->x = me->x;
            ope->y = me->y + SHIP_HEIGHT - 1;
            QActive_postFIFO(AO_Missile, (QEvent *)ope);
            return Q_HANDLED();
        }
        /* 0(2/1/5/1/3/2) */
        case DESTROYED_MINE_SIG: {
            me->score += ((ScoreEvt const *)e)->score;
            /* the score will be sent to the Tunnel by the next TIME_TICK */
            return Q_HANDLED();
        }
        /* 0(2/1/5/1/3/3) */
        case HIT_WALL_SIG: {
            return Q_TRAN(&ship_exploding);
        }
        /* 0(2/1/5/1/3/4) */
        case HIT_MINE_SIG: {
            return Q_TRAN(&ship_exploding);
        }
    }
    return Q_SUPER(&ship_active);
}
/* (AOS::Ship::Statechart::active::exploding) ..... */
QState ship_exploding(Ship *me, QEvent const *e) {
    switch (e->sig) {
        /* 0(2/1/5/1/4) */
        case Q_ENTRY_SIG: {
            me->exp_ctr = 0;
            return Q_HANDLED();
        }
        /* 0(2/1/5/1/4/0) */
        case TIME_TICK_SIG: {
            if ([me->exp_ctr < 15]) {
                return Q_HANDLED();
            } else {
                return Q_TRAN(&ship_active);
            }
        }
    }
    return Q_SUPER(&ship_active);
}
```

# Security and Reliability

# Greater Need For Reliability And Security

- More embedded systems than ever impact safety
  - Medical Devices (defibrillators, insulin pumps, radiation)
  - Transportation (avionics, rail, road vehicles)
  - Industrial Control (food processing, robotics, smelting)
  - Energy (electric grid, nuclear power plants)
- But the question is:
  - Are these industries and products as safe as they could be?
    - And safe as they ***should*** be?
- Reliability and security are the cornerstones of safety
  - And they have to be considered from the outset
- Yet systems are becoming **larger** and **more complex**
  - What can be done to make and keep products safe and secure?

# Reliability & its role in embedded systems

- Reliability – one definition
  - A product's resistance to malfunction or failure in the presence of any single failure
- Statistical analysis must demonstrate that a **double fault is infinitesimally small and improbable**
  - Not all faults are independent and unrelated!
  - Some industries even require mitigation of double faults
- A **reliable system** starts with **reliable hardware**
  - But how software handles hardware problems is key
- **An unreliable system can never be a safe system**
  - Is your system reliable? Does it need to be?



# Failure Mode and Effects Analysis (FMEA)

- Identify and understand failures and their consequences
- Risk = Likelihood x Consequences
- FMEA: Assign values for failure likelihoods and consequences
  - Identify most cost-effective areas for improving reliability
  - Highlight areas of greatest likelihood / consequences
- Minimize impact of failure on system
  - Redundancy
  - Fault Identification & Isolation
- Firmware must be robust in the face of uncertainty
  - Hardware faults, user input, harsh environments, etc.

# Renesas & Safety: IEC 60730

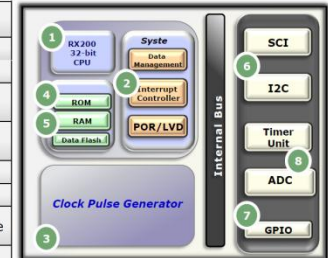
## ■ IEC 60730 (International Standard)

- Intended to increase quality & robustness of devices
- Defines classifications for automatic electronic controls
  - Class A – not intended ... for equipment safety
  - Class B – prevent unsafe operation of controlled equipment

IEC 60730-1 Class B<sup>1</sup> Requirements

|   | Controller's Module                 | Fault / Error                             |
|---|-------------------------------------|---|
| 1 | CPU Registers<br>CPU Program count  | Stuck                                     |
| 2 | Interrupt handling<br>and execution | No interrupt or too<br>frequent interrupt |
| 3 | Clock                               | Failure or Wrong<br>frequency             |
| 4 | ROM/Flash                           | All single bit faults                     |
| 5 | RAM                                 | DC Fault                                  |
| 6 | External<br>Communication           | Failure or not accurate                   |
| 7 | Input/output<br>peripheral          | Stuck or not accurate                     |
| 8 | Analog Circuits                     | Failure or not accurate                   |

Note 1: IEC60730-1 Specification Annex H- Table H.11.12.7



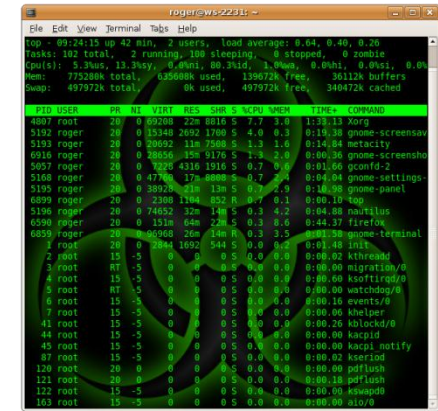
## ■ Renesas RX200 family

- Surpass requirements for Class B
- Built in functions to ensure safe automatic electronic control of class B appliances
- Examples: CPU registers, interrupt handling, memory tests, communication, I/O peripherals, A/D tests

# Security - The Risk

## ■ Why?

- Corporate espionage
- Blackmail
- Hackers (misuse leads to flakey or dangerous product)



The screenshot shows a Linux terminal window with the following output:

```
top - 09:24:15 up 42 min, 2 users, load average: 0.04, 0.40, 0.26
Tasks: 182 total, 2 running, 180 sleeping, 0 stopped, 0 zombie
Cpu(s): 3.3%us, 12.3%sy, 0.0%ni, 80.3%id, 3.0%wa, 0.0%st, 0.0%hi, 0.0%si
Mem: 775280k total, 435680k used, 139672k free, 340472k buffers
Swap: 497972k total, 0k used, 497972k free, 340472k cached
```

| PID  | USER  | PR | NI | VIRT  | RES  | SHR  | S | PCPU | MEM | TIME    | COMMAND         |
|------|-------|----|----|-------|------|------|---|------|-----|---------|-----------------|
| 4807 | root  | 20 | 0  | 60200 | 22k  | 8016 | S | 7.7  | 1.0 | 1:13.13 | xorg            |
| 5192 | roger | 20 | 0  | 15340 | 200k | 1700 | S | 4.0  | 0.3 | 0:14.38 | gnome-screensav |
| 5193 | roger | 20 | 0  | 20092 | 11k  | 2000 | S | 1.3  | 1.6 | 0:14.04 | metacity        |
| 6916 | roger | 20 | 0  | 26856 | 15k  | 5176 | S | 1.9  | 2.0 | 0:00.36 | gnome-screensho |
| 6957 | roger | 20 | 0  | 7220  | 4316 | 1916 | S | 0.7  | 0.0 | 0:01.66 | gconfd-2        |
| 7168 | roger | 20 | 0  | 4776  | 17k  | 4000 | S | 0.7  | 2.4 | 0:01.64 | gnome-settings  |
| 7195 | roger | 20 | 0  | 38920 | 21k  | 13k  | S | 0.0  | 2.9 | 0:16.58 | gnome-panel     |
| 6899 | roger | 20 | 0  | 2380  | 1704 | 852  | R | 0.7  | 0.1 | 0:00.19 | top             |
| 5196 | roger | 20 | 0  | 74652 | 32k  | 14k  | S | 0.3  | 4.2 | 0:04.04 | nautilus        |
| 6296 | roger | 20 | 0  | 151k  | 64k  | 22k  | S | 0.3  | 0.5 | 0:44.37 | firefox         |
| 6859 | roger | 20 | 0  | 60960 | 26k  | 14k  | R | 0.3  | 3.5 | 0:01.58 | gnome-terminal  |
| 1    | root  | 20 | 0  | 264k  | 1692 | 544  | S | 0.0  | 0.0 | 0:01.48 | init            |
| 2    | root  | 15 | -5 | 0     | 0    | 0    | S | 0.0  | 0.0 | 0:00.00 | kthreadd        |
| 3    | root  | RT | -5 | 0     | 0    | 0    | S | 0.0  | 0.0 | 0:00.00 | migration/0     |
| 4    | root  | 15 | -5 | 0     | 0    | 0    | S | 0.0  | 0.0 | 0:00.00 | ksoftirqd/0     |
| 5    | root  | RT | -5 | 0     | 0    | 0    | S | 0.0  | 0.0 | 0:00.00 | watchdog/0      |
| 6    | root  | 15 | -5 | 0     | 0    | 0    | S | 0.0  | 0.0 | 0:00.16 | events/0        |
| 7    | root  | 15 | -5 | 0     | 0    | 0    | S | 0.0  | 0.0 | 0:00.00 | khelper         |
| 41   | root  | 15 | -5 | 0     | 0    | 0    | S | 0.0  | 0.0 | 0:00.26 | kblockd/0       |
| 44   | root  | 15 | -5 | 0     | 0    | 0    | S | 0.0  | 0.0 | 0:00.00 | kswapd          |
| 45   | root  | 15 | -5 | 0     | 0    | 0    | S | 0.0  | 0.0 | 0:00.00 | kacpi_notify    |
| 87   | root  | 15 | -5 | 0     | 0    | 0    | S | 0.0  | 0.0 | 0:00.02 | kseriod         |
| 120  | root  | 20 | 0  | 0     | 0    | 0    | S | 0.0  | 0.0 | 0:00.00 | pdflush         |
| 121  | root  | 20 | 0  | 0     | 0    | 0    | S | 0.0  | 0.0 | 0:00.18 | pdflush         |
| 122  | root  | 15 | -5 | 0     | 0    | 0    | S | 0.0  | 0.0 | 0:00.00 | kswapd0         |
| 162  | root  | 15 | -5 | 0     | 0    | 0    | S | 0.0  | 0.0 | 0:00.00 | slopd           |

## ■ Security often an afterthought

- "Closing the barn door after the horses have escaped"

## ■ Difficult to retrofit security and patch holes

- But the alternative requires more time up front

## ■ Do you want to pay now?

- Or 10x as much later?



# Increased Connectivity = Increased Vulnerability

- Connectivity everywhere in embedded devices
  - Wireless
    - WiFi, 3G/4G, Bluetooth, Zigbee, Satellite, etc.
  - Wired
    - Ethernet, CANbus, DeviceNET, USB, etc.
- Each of these is a potential attack vector
  - Medical devices (wireless attack on ICDs and insulin pumps)
  - Industrial control & automation (Stuxnet, Duqu, Flame,...)
  - Vehicles (OBD-II exploit)
- Don't forget about physical access
  - JTAG port, soldered memory
  - Other attacks: side channel, brownout/glitch, thermal...
  - ***But we're talking about software right now...***

# What can be done?

- Embedded Devices have an advantage
  - Don't typically run arbitrary code
- Don't write encryption software yourself
  - What business are you in?
  - Focus and competence
  - Keeping up-to-date
- Use a coding standard that prioritizes correctness over form
- Don't do in software what can be done in hardware
- Renesas addresses security in multiple ways
  - Renesas middleware library (DES, AES, RSA, key exchange)
  - Secure MCUs – AE-x series and RS-4 series

# Wrap Up & Parting Thoughts

- Importance of firmware has never been greater
  - Develop more in less time without compromising correctness
- Modeling, code generation, frameworks
  - Design becomes code, no need to “re-invent the wheel”
- Security and reliability have never been more important
  - Difficult / impossible to retrofit
- Renesas is well-positioned to address all of these trends
  - Wide offering of MCUs and hardware platforms
  - Extremely broad “ecosystem”
    - Compilers, IDEs, middleware, RTOS, etc.
  - Be sure to work with FAEs, Salespeople, Distributors

# Reading and references

## ■ Available for download:

- [www.vdcresearch.com/documents/11\\_esdt\\_survey\\_hl.pdf](http://www.vdcresearch.com/documents/11_esdt_survey_hl.pdf)

## ■ Books:

- "Embedded C Coding Standard", Michael Barr
- "The CERT C Secure Coding Standard", Robert Seacord
- "Practical UML Statecharts in C/C++, 2nd Edition: Event-Driven Programming for Embedded Systems", Miro Samek
- "Test Driven Development for Embedded C", James Grenning
- "C++ Primer, 5th Ed.", Lippman, Moo, LaJoie

# Questions?



# Please provide your feedback...

- Please utilize the “Guidebook” application to leave feedback



**or**

- Ask me for the paper form for you to use

# Thank you!



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