

Shay McKim *Mechatronics Engineering - Varsity Athlete*

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Education

University of Waterloo, Mechatronics Engineering Sep 2024 – Current

- Varsity Men's Volleyball Team member balancing 30+ hours/week of high-performance training with engineering coursework. Built strong teamwork and communication skills through strategy meetings focused on KPIs and team performance.

Work Experience

CAD Electrical Technologist, Manitoba Liquor and Lotteries - Crown Corp. May 2025 – Aug 2025

- Independently updated AutoCAD electrical and fire alarm drawings for **2 multi-floor casinos** and **60+ retail stores**, improving drawing accuracy for maintenance and renovation firms.
- Interpreted handwritten electrician markups and collaborated with electricians and architects to resolve layout and circuiting discrepancies using layers and Xrefs, maintaining drawing standardization.
- Compiled **21 data points** across **60+ stores**, producing a tool that streamlined project prioritization for **senior management**.

Web Scheduling Application Developer, PolySense - Mechatronics Startup ⚡ Jun 2024 – Sep 2024

- Developed a web-based scheduling tool (JavaScript, FullCalendar.js, HTML, CSS) enabling clients to book equipment and track usage directly through PolySense's site.
- Improved equipment coordination by enabling clients to visualize usage trends and manage bookings, optimizing lab space and machine availability.

Utopian 3D, Founder Mar 2020 – Jan 2022

- Designed, iterated, and manufactured over **100 custom products** using Fusion 360 and FDM 3D printing.
- Managed printer maintenance, troubleshooting, design, customer service, and shipping, achieving 800% ROI and 5-star customer rating.

Selected Projects

Algorithm Controlled 4-Axis Robotic Arm, Unbeatable Game Opponent ⚡

- Designed a cost-constrained **4-axis** robotic arm **optimized for FDM printing** using Fusion 360; created 10+ custom components and C++ firmware to coordinate **5 servos** with **±5 mm** positioning accuracy.
- Built a Python **minimax algorithm** to compute optimal moves and transmit decisions over serial, interactive matches.

Automated Culinary Robot, Full-Stack Team Leadership ⚡

- Coordinated a 4-member team to deliver a fully integrated pudding-preparation robot, guiding task division and system integration; **recognized by professors as the most intricate project in the cohort**.
- Designed powder and water dispensing mechanisms and programmed DC motor control with LCD interface in C++, applying timing-based logic for reliable operation.

Award-Winning Water Filtration System, >100L/Day Output - Top Design in Division ⚡

- **Led a 5-member team** to design a water filtration system for isolated northern communities.
- Designed, programmed, and wired Arduino-based chlorination and agitation subsystems, sourcing components and ensuring reliable automation.
- Modeled and 3D-printed a custom water pump, reducing costs compared to off-the-shelf alternatives.

Spring-Loaded Net Launcher, Sub-500g Drone Capture System ⚡

- Designed 8 custom Fusion 360 components optimized for FDM printing, reducing system weight to <0.5kg for portable drone defense applications.
- Iterated trigger mechanism through **20+ CAD revisions** to improve trigger actuation smoothness and mechanical reliability.

200lb Trebuchet, 250ft Range Siege Engine ⚡

- Designed a fully functional, 12ft tall trebuchet with a 200lb counterweight, able to **launch stones over 200ft**.
- Built it start to finish independently in 48 hours with recycled wood and any materials I had on hand.

Skills

Software: C++, Python, VHDL, JavaScript, HTML/CSS, Java, LLM Integration, Arduino IDE, Git

Hardware: Arduino, Microcontrollers, Motor Control, Sensor Integration, PCB Design, UART, I2C, PWM, GPIO, PLC, FPGA

Design Tools: Fusion 360, SolidWorks, AutoCAD

Manufacturing: 3D Printing (FDM), CNC Machining, Design for Manufacturing

Certifications: Google Project Management Certificate, Lean Six Sigma Yellow Belt