

# CURRICULUM VITAE

## Seung Hyeon Bang

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### EDUCATION

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- Aug. 2018 – present      **The University of Texas at Austin, Austin, TX**  
Doctor of Philosophy in Aerospace Engineering
- Advisor: Luis Sentis
- Aug. 2018 – Aug. 2022      **The University of Texas at Austin, Austin, TX**  
Master of Science in Aerospace Engineering
- Thesis topic: Operational Space Control of Compliant Isoelastic Robots and Their Interaction with an DIARC Cognitive Architecture
  - Advisor: Luis Sentis
- Aug. 2014 – May. 2018      **Stonybrook University, Stonybrook, NY**  
Bachelor of Engineering in Mechanical Engineering
- *Summa Cum Laude*

### WORK AND RESEARCH EXPERIENCE

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- Jan. 2019 – present      **Graduate Research Assistant**  
The University of Texas at Austin, Austin, TX
- Planning, control, and optimization algorithms for humanoid robots
  - Control and optimization algorithms for an isoelastic manipulator
- June. 2023 – August. 2023      **Robotics Software Engineer Intern**  
Apptronik Inc, Austin, TX
- Development of inertia-aware model predictive control (MPC) algorithms for humanoid robots
  - Trajectory generation support for the Apollo humanoid robot bringup

### PUBLICATIONS

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1. L. Rossini, E. Hoffman, **SH. Bang**, L. Sentis, and N. Tsagarakis, “A Real-Time Approach for Humanoid Robot Walking including Dynamic Obstacles Avoidance,” *2023 IEEE-RAS 23th International Conference on Humanoid Robots (Humanoids)*, 2023
2. M. Seo, S. Han, K. Sim, **SH. Bang**, C. Gonzalez, L. Sentis, and Y. Zhu, “Deep Imitation Learning for Humanoid Loco-manipulation through Human Teleoperation,” *2023 IEEE-RAS 23th International Conference on Humanoid Robots (Humanoids)*, 2023
3. **SH. Bang**, C. Gonzalez, J. Ahn, N. Paine, and L. Sentis, “Control and Evaluation of a Humanoid Robot with Rolling Contact Joints on its Lower Body,” *Frontiers in Robotics and AI*, 2023
4. C. Gonzalez, **SH. Bang**, P. Li, S. Chinchali, and L. Sentis, “Learning Adaptive Horizon Maps Based on Error Forecast for Model Predictive Control”, *2023 IEEE Conference on Decision and Control*, 2023
5. J. Ahn, **SH. Bang**, C. Gonzalez, Y. Yuan, and L. Sentis, “Data-driven safety verification for legged robots,” *2022 IEEE-RAS 22th International Conference on Humanoid Robots (Humanoids)*, 2022
6. J. Lee, J. Ahn, D. Kim, **SH. Bang**, and L. Sentis, “Online gain adaptation of whole-body control for legged robots with unknown disturbances,” *Frontiers in Robotics and AI*, vol. 8, 2022.
7. J. Ahn, S. J. Jorgensen, **SH. Bang**, and L. Sentis, “Versatile locomotion planning and control for humanoid robots,” *Frontiers in Robotics and AI*, vol. 8, 2021.

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8. J. Lee, **SH. Bang**, E. Bakolas, and L. Sentis, “MPC-Based Hierarchical Task Space Control of Underactuated and Constrained Robots for Execution of Multiple Tasks”, *In proceedings, IEEE International Conference on Decision and Control (CDC)* 2020
  9. J. Ahn, D. Kim, **SH. Bang**, N. Paine, and L. Sentis, “Control of a high performance bipedal robot using viscoelastic liquid cooled actuators,” in *2019 IEEE-RAS 19th International Conference on Humanoid Robots (Humanoids)*, 2019, pp. 146–153.

## UNDER REVIEW

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1. **SH. Bang**, J. Lee, C. Gonzalez, and L. Sentis, “Variable Inertia Model Predictive Control for Fast Bipedal Maneuvers,”
2. **SH. Bang**, C. Jové, and L. Sentis, “RL-augmented MPC Framework for Agile and Robust Bipedal Footstep Locomotion Planning and Control,”

## TEACHING EXPERIENCE

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| Jan. 2022 – May. 2022 | <b>Graduate Teaching Assistant</b><br>The University of Texas at Austin, Aerospace Engineering & Engineering Mechanics, <i>Austin, TX</i> <ul style="list-style-type: none"><li>• Decision and Control of Human-Centered Robots (ASE389)</li></ul> |
| Jan. 2021 – May. 2021 | <b>Graduate Teaching Assistant</b><br>The University of Texas at Austin, Aerospace Engineering & Engineering Mechanics, <i>Austin, TX</i> <ul style="list-style-type: none"><li>• Flight Dynamics (ASE367K)</li></ul>                              |
| Sep. 2018 – Dec. 2018 | <b>Graduate Teaching Assistant</b><br>The University of Texas at Austin, Mechanical Engineering, <i>Austin, TX</i> <ul style="list-style-type: none"><li>• Experimental Fluids Mechanics (ME 130L)</li></ul>                                       |

## SKILLS

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| Program Language | Python, C++, Matlab                  |
| Library          | Pinocchio, PyTorch, Protobuf, ZeroMQ |
| Simulator        | Dart, Pybullet, Mujoco               |
| Language         | English (fluent), Korean (native)    |