

Signal Processing - 1 by One

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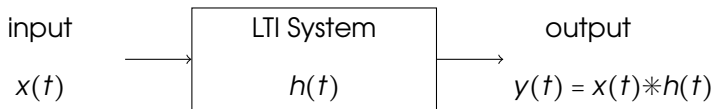
- So Far: Impulse, Sampling, Convolution and Interpolation
- Previous Week: Fourier Series
- Previous Class: Uniqueness of Fourier Series
- Today: Fourier Transform



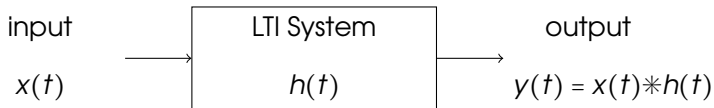
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Analog LTI Systems



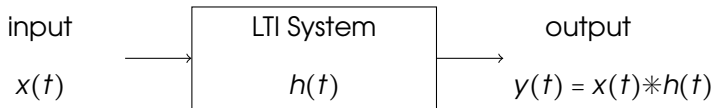
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$$y(t) = \int_{\tau \in \mathbb{R}} h(\tau) x(t - \tau) d\tau = \int_{\tau \in \mathbb{R}} x(\tau) h(t - \tau) d\tau.$$

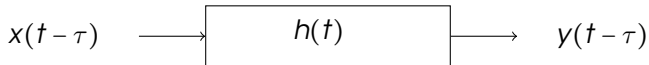


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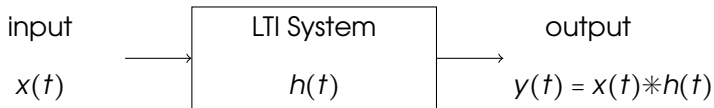


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Time Invariance:

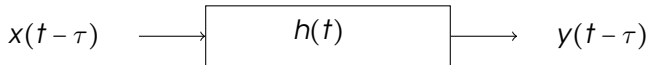


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Time Invariance:



Causal Systems $\Rightarrow h(t) = 0, \forall t < 0$.



Sinusoidal Inputs to LTI

Definition:

We say that a function $h(t)$ is integrable if $\int_{\mathbb{R}} |h(t)| dt < \infty$.

For $h(t)$ integrable, $x(t)*h(t)$ is well defined for **bounded** $x(t)$.

The second term depends only on f , denote it as $H(f)$.



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$$\begin{aligned} y(t) &= \int_{\tau \in \mathbb{R}} h(\tau) \exp(j2\pi f (t - \tau)) d\tau \\ &= \exp(j2\pi f t) \int_{\tau \in \mathbb{R}} h(\tau) \exp(-j2\pi f \tau) d\tau \\ &= x(t) \int_{\tau \in \mathbb{R}} h(\tau) \exp(-j2\pi f \tau) d\tau. \end{aligned}$$

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From Series to Transform

Fourier Transform:

$$H(f) := \int_{t \in \mathbb{R}} h(t) \exp(-j2\pi f t) dt.$$

$$H(f) = |H(f)| \exp[j\theta(f)].$$

Thus for a pure sinusoidal input $\exp(j2\pi f t)$ to the LTI system $h(t)$:

1. The amplitude will be scaled by $|H(f)|$.
2. Phase will be shifted by $\theta(f) \in [-\pi, \pi]$.
3. But frequency is unchanged, unless $H(f) = 0$.

Closely related to **Laplace Transform** for solving ODEs.



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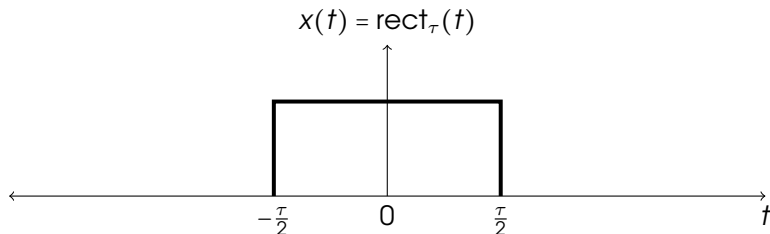
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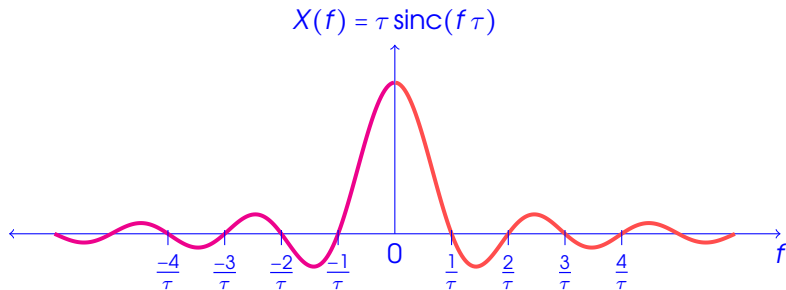
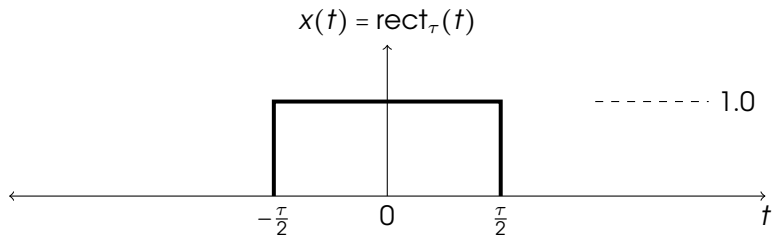
Example-1



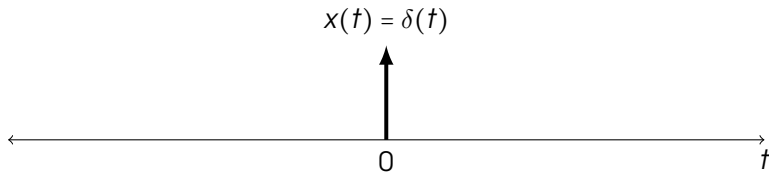
$$\begin{aligned} X(f) &= \int_{\mathbb{R}} x(t) \exp(-j2\pi f t) dt \\ &= \frac{1}{-j2\pi f} \left(\exp(-j2\pi f \frac{\tau}{2}) - \exp(j2\pi f \frac{\tau}{2}) \right) \\ &= \frac{\sin(\pi f \tau)}{\pi f} \\ &= \tau \text{sinc}(f \tau). \end{aligned}$$



Example-1: Plot



Example-2



$$\begin{aligned} X(f) &= \int_{\mathbb{R}} x(t) \exp(-j2\pi f t) dt \\ &= \int_{\mathbb{R}} \delta(t) \exp(-j2\pi f t) dt \\ &= \exp(-j2\pi f 0) = 1.0 \text{ everywhere} \end{aligned}$$

