Signal Processing - | by One

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Outline

- So Far: Sampling, Convolution, Fourier Transform
- Previous Week: Shannon Sampling Theorem
- Previous Class: Systems and Circuits
- Today: Laplace Transform



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$$\cos(2\pi f t + \theta) = \cos(2\pi f t)\cos(\theta) - \sin(2\pi f t)\sin(\theta).$$

Notice that

$$\int_{k\frac{T}{2}}^{(k+1)\frac{T}{2}}\cos(2\pi ft)\sin(2\pi ft)dt=0 \text{ for } T=\frac{1}{f}, k\in\mathbb{Z}.$$

Furthermore

$$\lim_{T_s \to \infty} \int_{-T_s}^{T_s} \cos(2\pi f t) \sin(2\pi f t) dt = 0 \text{ (In a generalized sense)}$$

$$\lim_{T_s\to\infty}\int_{-T_s}^{T_s}\cos(2\pi f_1t)\sin(2\pi f_2t)dt=0 \ (\text{as a generalized integral}) \ .$$

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For a real x(t), the 2 frequency components at t is represented by

$$\alpha + jb = \int_{\mathbb{R}} x(t) (\cos 2\pi f t - j \sin 2\pi f t) dt = X(f).$$

Notice that since

$$\cos(2\pi f t) = \frac{1}{2} \left(\exp(j2\pi f t) + \exp(-j2\pi f t) \right),$$

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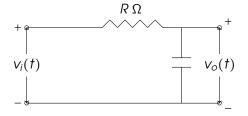
For f > 0, if the component $\exp(-j2\pi ft)$ corresponds to positive frequency, then $\exp(j2\pi ft)$ corresponds to negative frequency

Notice that $\exp(-j2\pi f t)$ and $\exp(j2\pi f t)$ are orthogonal for f > 0.



Complex Circuits

Complex numbers in electrical circuits suggest the presence of both $\cos(2\pi ft)$ and $\sin(2\pi ft)$ inside, even when $\cos(2\pi ft)$ is input.



Generalizing the Fourier Transform: For $s = \sigma + j2\pi f$,

$$X(s) = \int_{\mathbb{R}} x(t) \exp(-st) dt$$
 (Two-sided Laplace Transform).

Region of Convergence (ROC) : $\{Real(s)\}\$ s.t. Integral exists.

$$\lim_{\sigma\to 0}X(s)=X(f).$$



Kirchoff's Voltage Law:

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 and $V_o(s) = \frac{1}{C}\frac{I(s)}{s}$.

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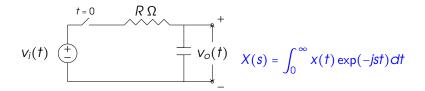
$$V_o(s) = V_i(s) \frac{1}{1 + sRC}.$$

At $s = j2\pi f$,

$$V_{o}(f) = H(f)V_{i}(f)$$
 where $H(f) = \frac{1}{1 + j2\pi fRC}$
 $V_{o}(t) = h(t) * V_{i}(t)$ where $h(t) = \frac{1}{RC} \exp(-\frac{t}{RC}), t \ge 0$.



Laplace with Initial Conditions



$$v_i(t) = i(t)R + \frac{1}{C} \int_{-\infty}^{t} i(\tau) d\tau.$$

Tool: One-sided or Unilateral Laplace Transform for $t \ge 0$.

$$C = \frac{1}{C} \int_{-\infty}^{t} i_c(\tau) d\tau.$$

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$$V_{c}(s) = \int V_{c}(t) \exp(-st) dt$$

$$= \frac{1}{C} \int_{t \in \mathbb{R}^{+}} \left[\int_{-\infty}^{0} i_{c}(\tau) d\tau + \int_{0}^{t} i_{c}(\tau) d\tau \right] \exp(-st) dt$$

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$$\begin{aligned} V_{C}(s) &= \int V_{C}(t) \exp(-st) dt \\ &= \frac{1}{C} \int_{t \in \mathbb{R}^{+}} \left[\int_{-\infty}^{0} i_{C}(\tau) d\tau + \int_{0}^{t} i_{C}(\tau) d\tau \right] \exp(-st) dt \\ &= V_{C}(0^{-}) \int_{t \in \mathbb{R}^{+}} \exp(-st) dt + \frac{1}{C} \int_{t \in \mathbb{R}^{+}} \int_{0}^{t} i_{C}(\tau) d\tau \exp(-st) dt \end{aligned}$$

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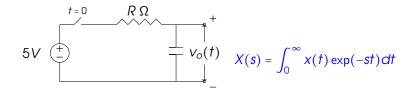
$$C = \frac{1}{C} V_c(t)$$

$$V_c(t) = \frac{1}{C} \int_{-\infty}^{t} i_c(\tau) d\tau.$$

$$\frac{1}{sC} \xrightarrow{\frac{1}{s}} \frac{1}{s} V_c(0^-)$$

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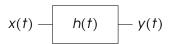
RC Circuit Example



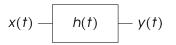
$$V_{i}(s) = I(s)R + \frac{V_{C}(0^{-})}{s} + \frac{1}{sC}I(s).$$

$$I(s) = \frac{\frac{5}{s} - \frac{V_{C}(0^{-})}{s}}{R + \frac{1}{sC}}$$

$$V_c(t) = V_c(0^-)u(t) + [5 - V_c(0^-)](1 - e^{-\frac{t}{RC}})u(t), t \ge 0.$$

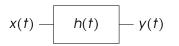


Q1) With unit step as the input x(t), it is given that $Y(s) = \frac{1}{s(s+\alpha)}$, where $\alpha \in \mathbb{R}^+$. Find the impulse response h(t).



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$$h(t) = \exp(-at)u(t)$$
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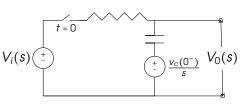
$$h(t) = \exp(-at)u(t).$$

GNURADIO: Showing the step response and identify the RC ckt.



Superposition

Q2) Apply super-position theorem and Laplace Transform to find the output voltage $v_0(t)$, if the input is 5u(t). The resistor is R ohms and capacitor is C

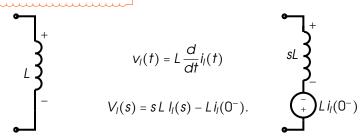


Output to Bounded Inputs

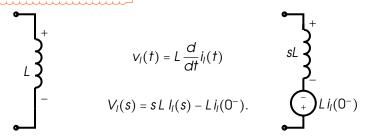
Q3) Consider an LTI system with impulse response h(t), which is integrable, i.e. $\int_{\mathbb{R}} |h(t)| dt < \infty$. If the input is bounded, i.e. $\max_{t \in \mathbb{R}} |x(t)| = v_m < \infty$, show that the output is also bounded (this is called **BIBO** stability).



Inertial Inductor



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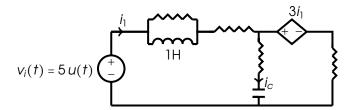
$$I_{l}(s) = \frac{V_{i}(s) + Li_{l}(0^{-})}{sL + R} = \frac{V_{m}}{sL + R} + Li_{l}(0^{-})$$

$$= \frac{V_{m}}{Ls(s + \frac{R}{L})} + \frac{i_{l}(0^{-})}{s + \frac{R}{L}}$$

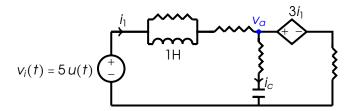
$$V_{i}(s) = RI_{i}(s) + sLI_{i}(s) - Li_{i}(0^{-})$$

$$i_{i}(t) = i_{dc} - [i_{dc} - i_{l}(0^{-})]e^{-\frac{R}{L}t}, t \ge 0.$$

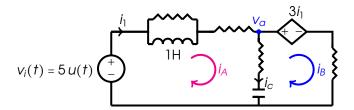
Mesh Analysis



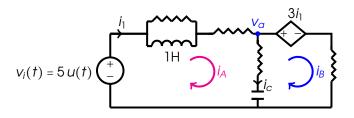




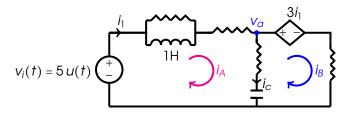








$$V_{i}(s) = \frac{s}{1+s}I_{A}(s) + I_{A}(s) + \left[I_{A}(s) - I_{B}(s)\right]\left(1 + \frac{1}{s}\right)$$
$$3I_{A}(s) = \left[I_{A}(s) - I_{B}(s)\right]\left(1 + \frac{1}{s}\right) - I_{B}(s)$$



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$$\begin{bmatrix} \frac{s}{s+1} + 2 + \frac{1}{s} & 1 + \frac{1}{s} \\ -2 + \frac{1}{s} & 2 + \frac{1}{s} \end{bmatrix} \begin{bmatrix} I_A \\ -I_B \end{bmatrix} = \begin{bmatrix} V_i(s) \\ 0 \end{bmatrix} \qquad Det = \frac{8s^2 + 12s + 5}{s(s+1)}$$

Matrix Inversion

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix}^{-1} = \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}^{-1} \frac{1}{ad - bc}.$$

$$A = \begin{bmatrix} \frac{s}{s+1} + 2 + \frac{1}{s} & 1 + \frac{1}{s} \\ -2 + \frac{1}{s} & 2 + \frac{1}{s} \end{bmatrix} \Rightarrow A^{-1} = \frac{1}{Det} \begin{bmatrix} 2 + \frac{1}{s} & -1 - \frac{1}{s} \\ 2 - \frac{1}{s} & \frac{s}{s+1} + 2 + \frac{1}{s} \end{bmatrix}.$$

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$$I_{A} - I_{B} = \begin{bmatrix} 1 & 1 \end{bmatrix} \begin{bmatrix} I_{A} \\ I_{B} \end{bmatrix} = \frac{4}{Det} \times \frac{5}{s} \Rightarrow V_{C}(s) = \frac{1}{s} (I_{A} - I_{B}) = \frac{20}{8} \frac{s+1}{s(s^{2} + \frac{3}{2}s + \frac{5}{8})}$$

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Find the inverse Laplace Transform of this rational function



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$$\frac{s+1}{s(s^2+\frac{3}{2}s+\frac{5}{8})} = \frac{1+\frac{1}{s}}{s^2+\frac{3}{2}s+\frac{5}{8}} = \frac{1}{s^2+\frac{3}{2}s+\frac{5}{8}} + \frac{1}{s(s^2+\frac{3}{2}s+\frac{5}{8})}$$
$$= \frac{1}{s^2+\frac{3}{2}s+\frac{5}{8}} + \left[\frac{1}{s} - \frac{s+\frac{3}{2}}{(s^2+\frac{3}{2}s+\frac{5}{8})}\right] \frac{8}{5}.$$

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$$= \frac{1}{s^2+\frac{3}{2}s+\frac{5}{8}} + \left[\frac{1}{s} - \frac{s+\frac{3}{2}}{(s^2+\frac{3}{2}s+\frac{5}{8})}\right] \frac{8}{5}.$$

Let us invert the first term



$$\exp(-at)u(t) \stackrel{L.T.}{\Longrightarrow} \frac{1}{s+a}$$
, Real $(s+a) \ge 0$. (*)

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Given any rational Laplace Transform H(s) s.t. for m > n

$$H(s) = \frac{b_0 + b_1 s + b_2 s^2 + \dots + b_n s^n}{a_0 + a_1 s_1 + \dots + s^m}$$

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$$H(s) = \frac{b_0 + b_1 s + b_2 s^2 + \dots + b_n s^n}{a_0 + a_1 s_1 + \dots + s^m} = \frac{A_1}{s - a_1} + \frac{A_2}{s - a_2} + \dots + \frac{A_m}{s - a_m}.$$

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, Real $(s+a) \ge 0$.

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$$H(s) = \frac{b_0 + b_1 s + b_2 s^2 + \dots + b_n s^n}{\alpha_0 + \alpha_1 s_1 + \dots + s^m} = \frac{A_1}{s - \alpha_1} + \frac{A_2}{s - \alpha_2} + \dots + \frac{A_m}{s - \alpha_m}.$$

Thus, (*) under suitable conditions sufice to find the inverse.



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Thus, $\alpha_i < 0$, $\forall i$ will imply BIBO stability.



Oscillatory Responses

Second order circuits may have poles α_i complex

$$\int_0^\infty \exp(-at)\cos(\omega t)dt = \frac{s+\alpha}{(s+\alpha)^2+\omega^2}, \text{ Real}(s+\alpha) > 0$$

$$\int_0^\infty \exp(-at)\sin(\omega t)dt = \frac{\omega}{(s+\alpha)^2+\omega^2}, \text{ Real}(s+\alpha) > 0$$

RLC Solution

$$V_{c}(s) = \frac{5}{2} \frac{1}{s^{2} + \frac{3}{2}s + \frac{5}{8}} + \frac{5}{2} \frac{1}{s(s^{2} + \frac{3}{2}s + \frac{5}{8})}$$



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$$V_{c}(s) = \frac{20}{2} \frac{\frac{1}{4}}{(s + \frac{3}{4})^{2} + \frac{1}{4^{2}}} + \frac{5}{2} \left(\frac{1}{s} - \frac{s + \frac{3}{2}}{(s + \frac{3}{4})^{2} + \frac{1}{4^{2}}} \right) \frac{8}{5}$$

RLC Solution

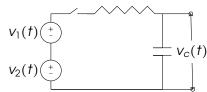
$$V_c(s) = \frac{5}{2} \frac{1}{s^2 + \frac{3}{2}s + \frac{5}{8}} + \frac{5}{2} \frac{1}{s(s^2 + \frac{3}{2}s + \frac{5}{8})}$$

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$$V_c(t) = 4u(t) - 4e^{-\frac{3}{4}t}\cos(\frac{t}{4}) - 2e^{-\frac{3}{4}t}\sin(\frac{t}{4}), \ t \ge 0.$$

Not-So Linear Initial Conditions

Q4) Can you apply superposition theorem on the two voltage sources to find $v_c(t)$. The resistor is R ohms and capacitor is C Farads, which has an $v_2(t)$ 0 initial charge of 0.3V.





RLC Circuit

Q5) For the serial RLC circuit find the voltage across C.

