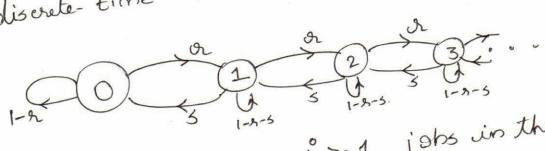
## Lyapunov stability analysis

For an irreducible DTMC, we know that if we Can find a ostationary distribution, then the chain is positive recurrent. However, often, we come across chains for which the atationary equations are intractable.

In such cases, one can still establish recurrence via a drift analysis. This involves guessing a Lyapunov function such that the DTMC Thas a nigative drift on the function.

To motivate this, let us return to our diserte-time M/M/1 queue.



Q: Given there are i > 1 jobs in the system, what is the average change in the number of jobs over 1 time step?

A: E[XR+1-XR | XIZ=i] = 91-S

=> When OrKS, the DTMC tends to reduce the # in system, on average.

(2) Turns out this implies positive recurrence of the chain.

Theorem: Considus an irreducible DTMC over Countable state space S. Suppose V: S -> TR+ and Countable state space S. Tf there exists C is a finite countset of S. If there exists & 8.70, b<00 s.t.

Vies-c, i) E [V(XR+1) - V(XR) | XR = i] <- 8

then the DTMC is positive recurrent. ii) E[V(XR+1) - V(XR) | XR = E] < b

Lattributed to Foster; also called

Foster's / Foster Foster Lyapunor theorem.

Proof or generalizations: Hajek motes.

Proof of Mote: In our M/M/1 example, out V(i)=i.

=> E[V(XR+1)-V(XR)|XR=i]

 $E[V(X_{R+1})-V(X_R)|X_R=i] = \begin{cases} -(S-92) & \text{if } i>1\\ = E[X_{R+1}-X_R|X_R=i] = \end{cases}$   $= E[X_{R+1}-X_R|X_R=i] = \begin{cases} -(S-92) & \text{if } i>1\\ 0 & \text{if } i=0 \end{cases}$ 

Dux X Satisfies For 925 (E) pcq), our the choice of V Satisfies, Foster's Theorem, with C= {0}, E=(5-7)/2, b=1.

=> The DTMC is positive recurrent. Example 2: Routing to multiple queues. Queue 1 Two queues are fed by a single arrival Otream BP(a) of jobs/ packets/files. When a job arrives, we have to route it immediately to one of Each queue, when mon-empty, completes a job with probability di. This might model: . Johns Yfiles with Quenice time Greenetric (di) · Wireless outup where each queue ses sus a good channel in a old with some probability.

De allow an assiving packet/196 to depart

We allow an assiving Suppose a < d1+d2. Intuitively, this is a necessary condition for stability.

D: How can you soute so that the objection is A: Find pe (0,1) s.t. ab <d1, a(1-1) < d2. Route each arrival to Queue 1 w.p. p. and to Queue 2 w.p. (1-b). Q: But this assumes you know a, d1, d2. What if you don't? A: As we will show, nouting to the shortest queue will stabilize the system.

Policy: Let (101, 102) be the victor of queue lengths. We havte to Queue 1 if re1 < re2, and to Queue 2 if rea < re1.

Given the policy, evolution of (nc1, nc2) is a DTM C over  $\mathbb{Z}_{+}^{2}$ .

Stationary equations would be a mess!

het 
$$V(x) = \frac{x_i^2 + x_i^2}{2}$$
.

Note:

$$\mathcal{R}_{i}(t+1) = \mathcal{R}_{i}(t) + A_{i}(t) - D_{i}(t) + L_{i}(t)$$
where:
$$A_{1}(t) = A(t) \cdot \frac{1}{2} \mathcal{R}_{i}(t) + \mathcal{R}_{i}(t)$$

$$A_{1}(t) = A(t) \cdot \frac{1}{2} \mathcal{R}_{i}(t) + \mathcal{R}_{i}(t)$$

$$D_{i}(t) \sim \mathcal{B} \mathcal{P}(d_{i})$$

$$L_{i}(t) = \frac{1}{2} \mathcal{R}_{i}(t) + A_{i}(t) - D_{i}(t) = -1\frac{1}{2}$$
Where the queue length mon-negative when  $D_{i}(t) = 1$ .

$$empty queue was no assival * Define 1.$$

$$empty queue was no assival * Define 2.$$

$$empty queue was no assival * Define 3.$$

$$empty queue was no assival * Define 4.$$

$$empty queue was$$

$$= \frac{1}{2} \sum_{i=1}^{2} E \left[ \frac{\gamma c_{i}^{2}(t+i) - \gamma c_{i}(t)}{\gamma c(t) + \alpha c(t)} \right]$$

$$= \frac{1}{2} \sum_{i=1}^{2} E \left[ \frac{\gamma c_{i}(t) + A_{i}(t) - D_{i}(t) + L_{i}(t)}{\gamma c(t) + \alpha c(t)} \right]$$

$$= \frac{1}{2} \sum_{i=1}^{2} E \left[ \frac{\gamma c_{i}(t) + A_{i}(t) - D_{i}(t) + L_{i}(t)}{\gamma c(t) + \alpha c(t)} \right]$$

(b) 
$$\Delta \leq \frac{1}{2} \sum_{i} \mathbb{E} \left[ \left( \mathcal{R}_{i}(t) + \mathcal{A}_{i}(t) + \mathcal{D}_{i}(t) \right)^{2} - \mathcal{R}_{i}^{2}(t) \right] \mathcal{R}_{i}(t) = \mathcal{R}$$

$$\leq \sum_{i} \mathbb{E} \left[ \mathcal{R}_{i}(t) \left( \mathcal{A}_{i}(t) - \mathcal{D}_{i}(t) \right) \right] \mathcal{R}_{i}(t) = \mathcal{R}$$

$$+ \frac{1}{2} \sum_{i} \mathbb{E} \left[ \left( \mathcal{A}_{i}(t) - \mathcal{D}_{i}(t) \right)^{2} \right] \mathcal{R}_{i}(t) = \mathcal{R} \right]$$

$$\leq \mathcal{R}_{2} \left( \mathcal{A}_{1} \mathcal{A}_{i}(t) + \mathcal{R}_{2} \mathcal{A}_{1} \right) + \mathcal{R}_{2} \left( \mathcal{A}_{1} \mathcal{A}_{i}(t) - \mathcal{R}_{2} \mathcal{A}_{2} \right) - \mathcal{A}_{2} + 1$$

$$= \mathcal{A} \left( \mathcal{R}_{1} \mathcal{A}_{1}(t) + \mathcal{R}_{2} \mathcal{A}_{1} \right) + \mathcal{R}_{2} \left( \mathcal{A}_{1} \mathcal{A}_{1}(t) - \mathcal{R}_{2} \mathcal{A}_{2} \right) - \mathcal{R}_{1} \mathcal{A}_{1} - \mathcal{R}_{2} \mathcal{A}_{2} + 1$$

$$= \mathcal{A} \left( \mathcal{R}_{1} \mathcal{A}_{1}(t) + \mathcal{R}_{2}(t) + \mathcal{R}_{2} \mathcal{A}_{1}(t) - \mathcal{R}_{2} \mathcal{A}_{2} \right) - \mathcal{R}_{1} \mathcal{A}_{1} - \mathcal{R}_{2} \mathcal{A}_{2} + 1$$

$$= \mathcal{A} \left( \mathcal{R}_{1} \mathcal{A}_{1}(t) + \mathcal{R}_{2}(t) - \mathcal{R}_{2}(t) - \mathcal{R}_{2}(t) - \mathcal{R}_{2}(t) + 1$$

$$= \mathcal{R}_{1} \left( \mathcal{A}_{1} - \mathcal{A}_{2} \right) - \mathcal{R}_{2} \left( \mathcal{A}_{1} - \mathcal{A}_{2} \right) + 1$$

$$\leq -\mathcal{E} \left( \mathcal{R}_{2} \mathcal{A}_{1} - \mathcal{R}_{2} \right) - \mathcal{R}_{2} \left( \mathcal{A}_{1} - \mathcal{A}_{2} \right) + 1$$

$$\leq -\mathcal{E} \left( \mathcal{R}_{2} \mathcal{A}_{1} - \mathcal{R}_{2} \right) - \mathcal{R}_{2} \mathcal{A}_{1} - \mathcal{R}_{2} + 1$$

$$= \mathcal{R}_{1} \mathcal{R}_{2} \mathcal{R}_{2$$

Note: Our nouting policy keeps saystem stable as long as this is possible, with no knowledge of system parameters!