

EE324 Control Systems Lab

Problem Sheet 8

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1 Question 1

Code

```
s = poly(0, 's')
poles = [0.01, 0.05, 0.1, 0.5]
t = 0:0.01:20
i = 1
for pole = poles
    G = syslin('c', (s + 5*pole) / (s + pole))
    tf = (G) / (1 + G)
    resp = csim("step", t, tf)
    plot2d(t, resp, i)
    i = i + 1
end
legend(string(poles))
```

```

scf()

i = 1

for pole = poles

    G = syslin('c', (s + 5*pole) / (s + pole))

    tf = (G) / (1 + G)

    resp = csim("impuls", t, tf)

    plot2d(t, resp, i)

    i = i + 1

end

legend(string(poles))

```

1.1 Part A

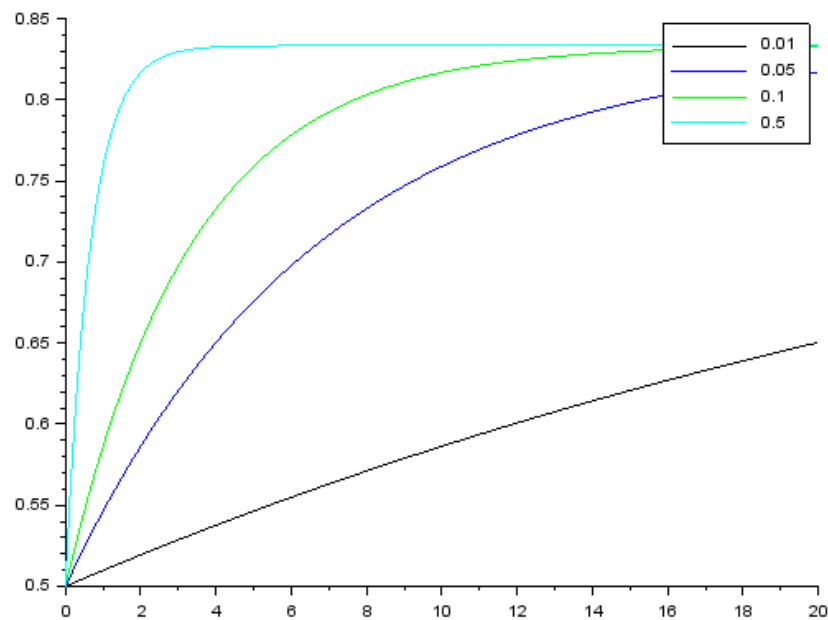


Figure 1: For step response, we see that as the pole moves farther away from origin, settling time decreases

1.2 Part B

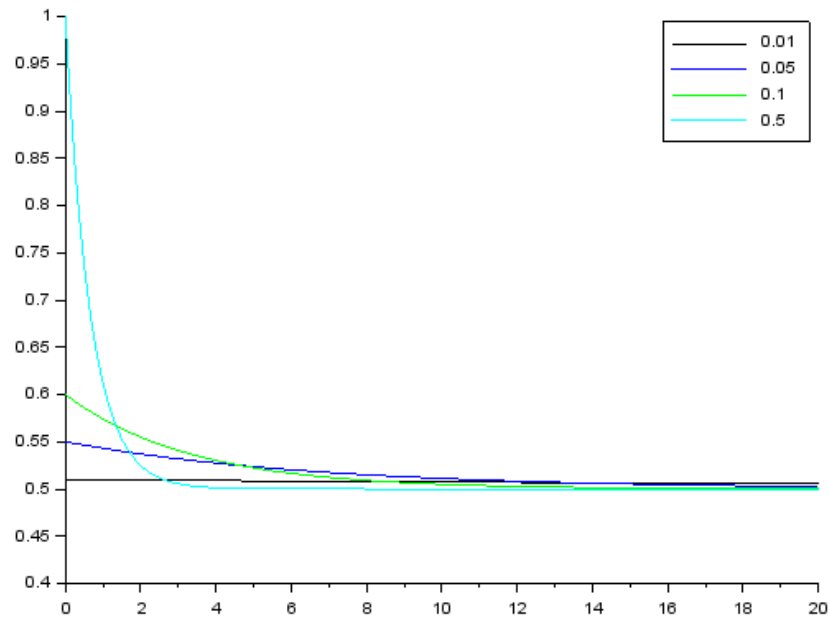


Figure 2: We see that as the pole moves farther away from origin, impulse response starts higher, and ends lower

2 Question 2

Code for all parts

```
s = poly(0, 's')
```

```
// part A
```

```
g = 1 / ((s + 1) * (s^2 + 1) * (s^2 + 4))
```

```
G = syslin("c", g)
```

```
evans(G)
```

```
// part B
```

```
scf()
```

```
s_ = s + 1
```

```
g = 1 / ((s_ + 1) * (s_^2 + 1) * (s_^2 + 4))
```

```
G = syslin("c", g)
```

```
bode(G)
```

```
// part C
```

```
// phase becomes -180 at  $w \sim 2$ 
```

```
// so we add zeros after  $w = 2$ , say at  $w \sim 10$ 
```

```
// now final phase is -450 deg
```

```
// we need to get it back upto -180 deg
```

```
/// so we need 4 zeros (since each zero contributes +90 deg)
```

```
scf()
```

```
G = G * (1 + s/10)^4
```

```
bode(G)
```

scf()

evans(G)

2.1 Part A

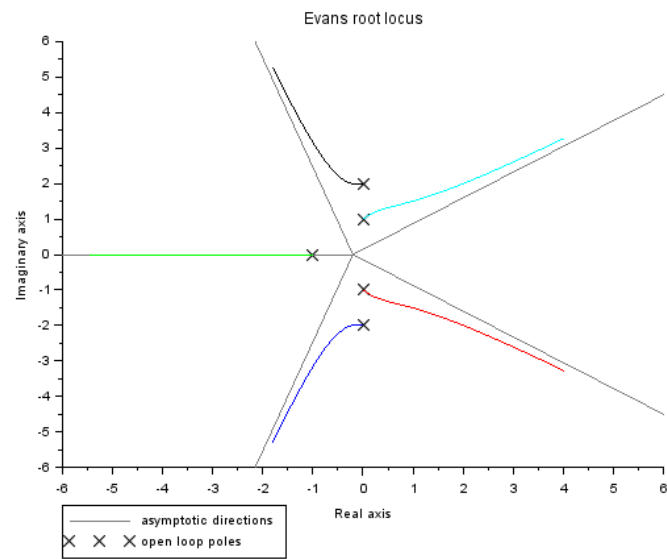


Figure 3: Root locus

2.2 Parts B, C, D

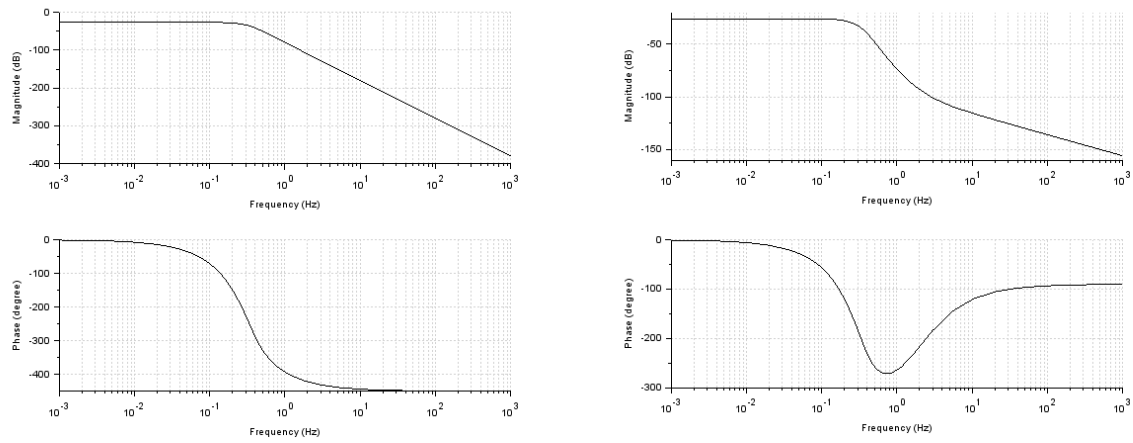


Figure 4: Bode plot without zeros, and with zeros

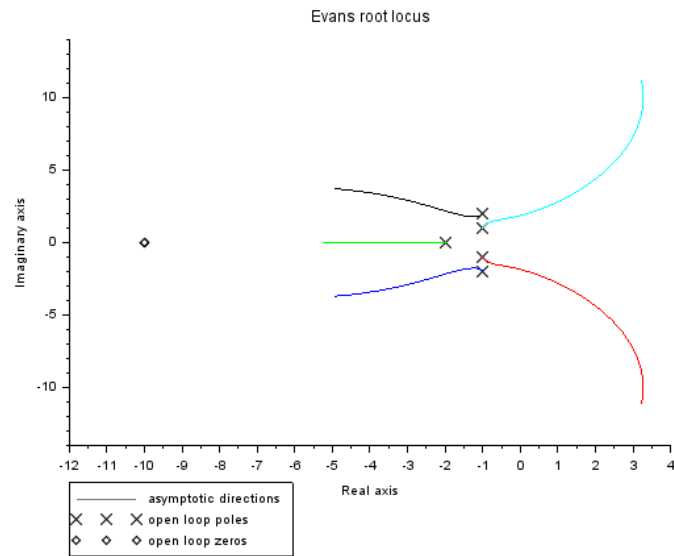


Figure 5: Final root locus

Calculation of the zeros is included in the code.

3 Question 3

3.1 Code and calculation

```
s = poly(0, 's')  
  
// there is +40dB/dec slope starting at w=1 => single zero  
// slope becomes 0 at w=5 => single pole  
// slope becomes -20dB/dec at w=10 => single pole  
// slope becomes -40dB/dec at w=100 => single pole  
// initial value is -75dB = 0.00017782794100389227  
  
g = 0.00017782794100389227 * (1 + s) / ((1 + s/5) * (1 + s/10) * (1 + s/100))  
  
G = syslin("c", g)  
  
bode(G)
```

3.2 Phase plot

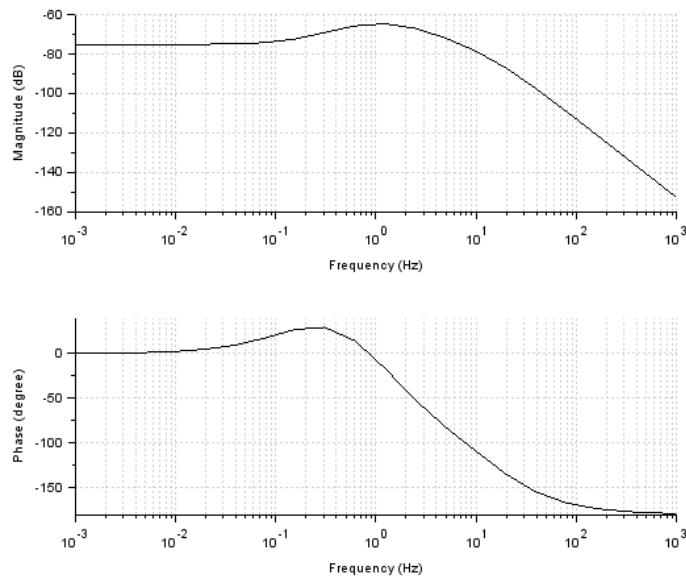


Figure 6: Magnitude and phase bode plot of the system