



# Shehzaman Salim Khatib ME09B130

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## EDUCATION

Year	Degree	Institute	CGPA/%
2009-Present	B.Tech-M.Tech Dual(Mechanical Engineering)	IIT Madras	9.17/10
2009	Pre-University Board, Karnataka(XII)	SRN Adarsh College, Bangalore	85%
2007	ICSE(X)	Frank Anthony Public School, Bangalore	92%

## PROFESSIONAL AND RESEARCH WORK

### • Dual-Degree project at IIT Madras

Research project guided by [Professor C. Balaji](#) and [Professor P. Rajagopal](#).

From March, 2013

- Currently working on developing a remote structural health monitoring machine which uses thermal images (IR band) to autonomously scan for defects.

### • MITACS Globalink Scholar, 2013 at University of British Columbia, Kelowna

Visiting Undergraduate Research Assistant at the ACIS lab working under the guidance of [Professor Homayoun Najjaran](#).

May-July, 2013

- Project 1: Built a multi-robot simulator for evaluating planning algorithms, in Linux environment by linking Matlab with ROS and Gazebo-3D simulator.
- Project 2: Developed a low cost (~\$10) high voltage DC-DC and DC-AC converter for Digital Microfluidic Systems (aka Lab on Chip devices).

### • Summer Internship at GE John F Welch Technology Center, Bangalore

Summer Intern at non-destructive testing lab, GE Global Research

June-July, 2012

- Developed scripts in python using Abaqus 6.11 (finite element software) API's to simulate ultrasonic waves for different material boundaries, especially steel and water for the purpose of studying beam deviation in non-destructive testing.

### • ABU Robocon, 2011

Member of Robocon team representing IIT Madras at the nationals of ABU Robocon, 2011 Pune

September, 2010 - March, 2011

- Designed and programmed the electronic control for locomotion and mechanisms of the 4-wheeled transwheel manual robot. [YouTube Link](#)
- In the following year mentored the Robocon 2012 team and improved on electrical system design. [YouTube Link](#)
- Robocon 2013 was another major improvement as we added pneumatic systems. This year we won the distinction of being the team to solve the problem statement in least time. [YouTube Link](#)

### • Summer Internship at Indigo Quotient Labs, Bangalore

Summer Intern for a technology start-up [Indiango Quotient labs](#), Bangalore

June-July, 2011

- Designed and prototyped an accelerometer based gesture controlled robot.

## PUBLICATIONS

### • Farrokhsiar, M., **Shehzaman, S.K.**, and Najjaran, H, 'Robust Active SLAM: A Tube-based Approach.'

*Journal of Intelligent and Robotic Systems*

*This paper analyses the robustness of the conventional active SLAM methods and propose integration of the set-theoretic and information theoretic frameworks to increase the robustness of the information theoretic active SLAM methods. Matlab simulations and ROS/Gazebo experiments indicate the effectiveness of the proposed method.*

Submitted

### • Farrokhsiar, M., **Shehzaman, S.K.**, and Najjaran, H, 'A Robust Market-based Motion Planning and Control Scheme for Multi-robot Active SLAM.'

*This paper presents an auction based multi-robot motion planning based on the tube-based nonlinear MPC for the exploration purposes. Draft*

## SCHOLASTIC ACHIEVEMENTS

- Kishore Vaigyanic Protsahan Yojana (KVPY) 2008, awarded by Indian Institute of Science (IISc), Bangalore - 140 students were awarded this fellowship in India.
- Fellow of National Talent Search Examination (NTSE) 2006, awarded by NCERT board, India.
- Selected to the National Level of Indian National Chemistry Olympiad (INChO) and Indian National Astronomy Olympiad (INAO), 2009 the top 300 students from the country are selected for this stage.

## SKILLS

- Engineering Software: MATLAB, ROS, Gazebo-3D simulator, LTSpice, COMSOL-Multiphysics, Python, Autodesk Inventor, Pro-E, SolidWorks, Abaqus6.11
- Programming Languages: C, C++ and Java
- Micro-Controllers: AVR family(AtMega16, AtMega128), Arduino
- Embedded Modules: GSM/GPRS, GPS, Bluetooth, Motor Drivers, Encoders, Xbee, Magnetic Compass, Accelerometers, PS2 joystick

## THEORY and LABORATORY COURSES

- |   |                                  |
|---|----------------------------------|
| • Mechatronic Systems                             | • Radiative Heat Transfer        |
| • Advanced Non-Destructive Testing and Evaluation | • Design Synthesis               |
| • Advanced Energy Conversion                      | • Applied Mechanics Lab          |
| • Turbo Machines                                  | • Heat Transfer                  |
| • Design and Optimization of Energy Systems       | • IC Engines                     |
| • Refrigeration and Air Conditioning              | • Computational Fluid Dynamics   |
| • Instrumentation and Control                     | • Machine Drawing Practice - CAD |
| • Design of Machine Elements                      | • Electrical Sciences Lab        |
| • Introduction to Machine Learning                | • Basic Electrical Engineering   |
| • Linear Algebra and Numerical Methods            | • Differential Equations         |
| • Calculus 1                                      | • Calculus 2                     |

## EXTRA-CURRICULAR ACHIEVEMENTS

- One of the top 5 teams in India selected for the GE-Edison Challenge, 2012 held at JFWTC-GE, Bangalore.
- Runner-up of Ericsson-Industry Defined Problem Statement at Shaastra 2013, annual technical fest of IIT Madras.
- Participated at the Student Design competition as part of ASME, Student professional development conference 2013.
- Winner of Fix The android, Traffic Rush and Image Processing autonomous robotic events at Pragyan 2012, technical festival of National Institute of Technology, Trichy.
- Coordinator for Fire and ICe an RC car Design and Build event at Shaastra, 2011.
- Winner of Intra-Hostel Autonomous Robotics at IIT Madras, 2011.
- Volunteer for the National Service Scheme (NSS) as part of the Environmental Conscious group, 2009-2010.
- Second Runner-up for demonstrating a solar powered lift at Energizing Ideas conducted by Tata BP solar and The Energy Resource Institute (teri) in Bangalore, 2006.