Homework 11 - Karhunen-Loève transform

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Karhunen-Loève Transform Implementation

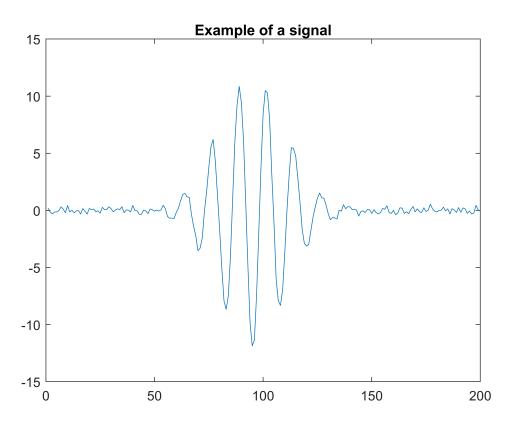
Consider the following piece of Matlab code:

```
%% Settings
n=200; % segment length

t=0:n-1; % time axis (a column vector 1xn)
t=t(:); % time axis (as row vector nx1)

amplitudeNoise=10; % noise parameters
sigmaNoise=20;
t0Noise=20;
whiteNoise=0.2;

A=5+amplitudeNoise*rand(1);
sigma=10+sigmaNoise*rand(1);
t0=100+t0Noise*rand(1);
s=A*exp( -(t-t0).^2 / (2*sigma^2)).*cos(0.5*t);
s=s+whiteNoise*randn(n,1);
plot(s);
title('Example of a signal')
```



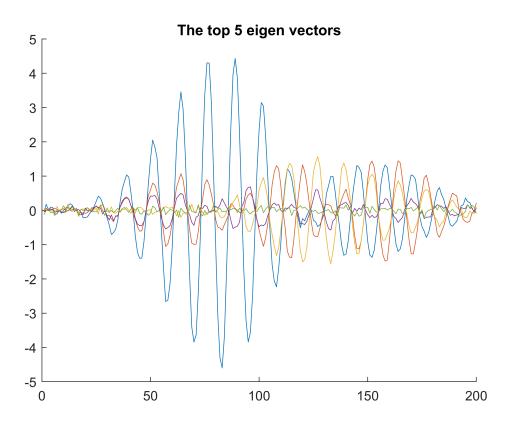
```
N=10; % Number of signals to generate
X=zeros(n,N);

%% build up an 'observed' data set
for q=1:N
    A=5+amplitudeNoise*rand(1); % The highest peak
    sigma=10+sigmaNoise*rand(1); % The "width" of pulse
    t0=100+t0Noise*randn(1); % The center of the highest peak
    s=A*exp( -(t-t0).^2 / (2*sigma^2)).*cos(0.5*t);
    X(:,q)=s+whiteNoise*randn(n,1);
end

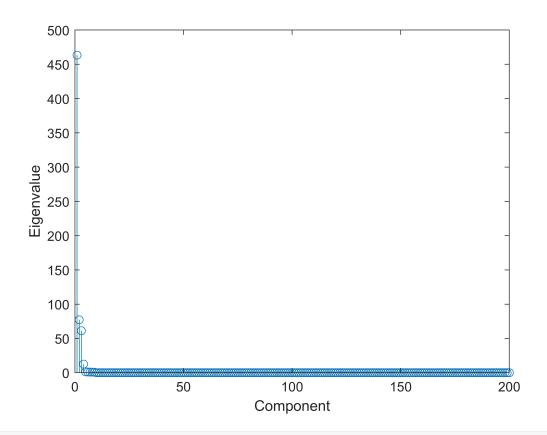
rankX = rank(X)
```

rankX = 10

```
figure(1)
clf(figure(1))
hold on
for q=1:5
  plot(A(:,q)*sqrt(lambda(q,q)))
end
title('The top 5 eigen vectors')
hold off
```



```
figure(2)
stem(diag(lambda))
xlabel('Component')
ylabel('Eigenvalue')
```



Work through the code and explain what it does.

Play around with the noise parameters and comment on how the plots are altered by the noise parameters.

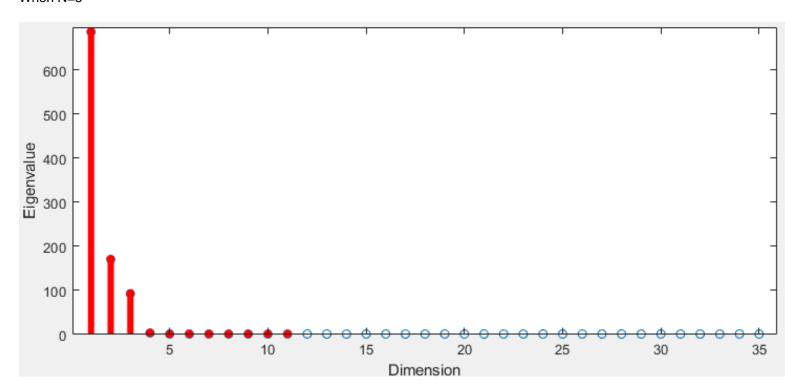
When the noise parameters are all set to zero, we are generating the same signal duplicated N times. So our X has N columns of the same $n \times 1$ vector. This means the rank of the matrix is 1.

Changing the amplitute noise parameter does not effect the rank of the matrix since changes in amplitude cause vectors to be scaled.

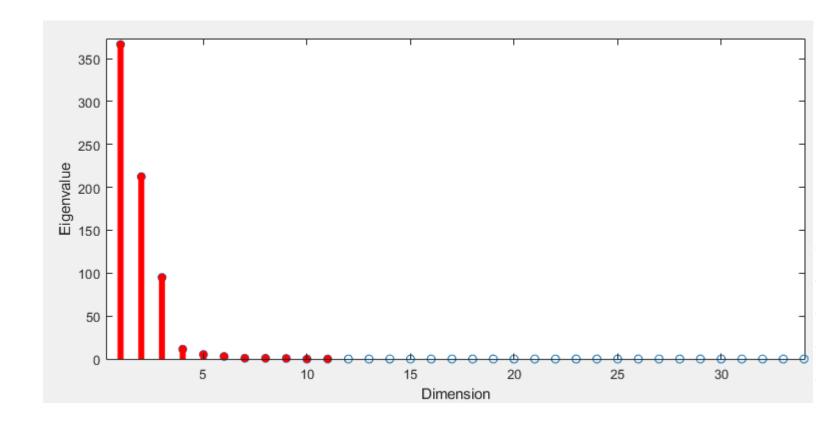
Changes in the other noise parameters causes the X matrix to be full rank (almost at every generation) since the signals are more likely to be shifted.

How are the results affected by N, the number of experiments?

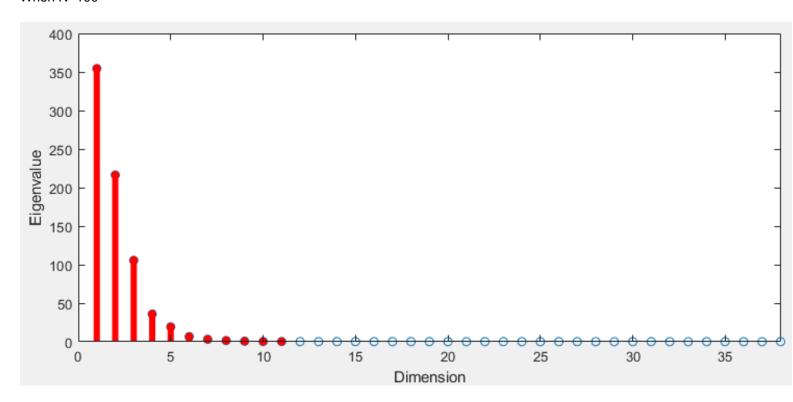
When N=5



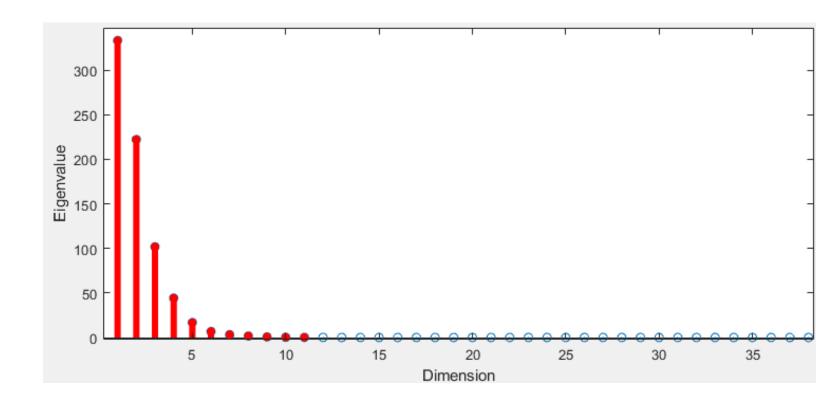
When N=10



When N=100

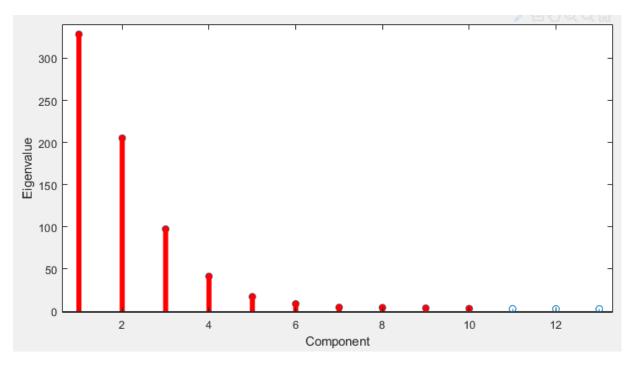


N=1000

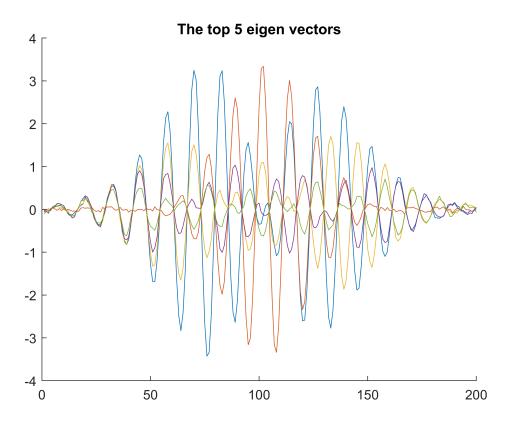


What happens if colored noise is used instead of white noise?

Even with coloured noise, it seems that the largest variance within the different signals can be explained by the top 5-10 components.



```
sigmaNoise=20;
t0Noise=20;
colouredNoise=0.3;
N=1000; % Number of signals to generate
X=zeros(n,N);
%% build up an 'observed' data set
for q=1:N
    A=5+amplitudeNoise*rand(1); % The highest peak
    sigma=10+sigmaNoise*rand(1); % The "width" of pulse
    t0=100+t0Noise*randn(1);
                               % The center of the highest peak
    s=A*exp(-(t-t0).^2 / (2*sigma^2)).*cos(0.5*t);
    X(:,q)=s+step(dsp.ColoredNoise('InverseFrequencyPower', colouredNoise, 'SamplesPerFrame', n));
end
%% Calculate C using 14.206 and perform a KLT
C=zeros(n,n);
mean vector = mean(X, 2); % Compute mean vector across all samples.
for q=1:N
    % x=X(:,q)-mean(X(:,q)); % Original code, seems wrong?
    x = X(:,q) - mean\_vector; % My code
    C = C + x*x';
end
C=C/N;
[U, lambda, A]=svd(C);
%% Plot results
figure(1)
clf(figure(1))
hold on
for q=1:5
  plot(A(:,q)*sqrt(lambda(q,q)))
title('The top 5 eigen vectors')
hold off
```



```
figure(2)
stem(diag(lambda))
xlabel('Component')
ylabel('Eigenvalue')
```

