

Homework 10

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[✓] ADSI Problem 6.2: Autocorrelation expression for an AR(1) process (proof)

Consider an AR(1) process given by $y(n) = -ay(n-1) + x(n)$
with $-1 < a < 1$ and $x(n) \sim WN(0, \sigma_x^2)$.

1. Show that the autocorrelation of the AR(1) process is given by

$$r_{yy}(l) = \frac{\sigma_x^2}{1-a^2}(-a)^{|l|}$$

Hint: Use equation (13.138) and (13.140).

The autocorrelation of an AR(p) process is given by Eq. 13.138:

$$r_{yy}[\ell] = - \sum_{k=1}^p a_k r_{yy}[\ell - k] + \sigma_x^2 b_0 h[-\ell]. \text{ all } \ell \quad (13.138)$$

where $h[n]$ is the impulse response of an all-pole system.

Equation 13.138 is an general expression for all ℓ . However, since $h[\ell] = 0$ for negative values of ℓ then we know that $h[-\ell] = 0$. Therefore, Eq. 13.138 can be reduced to:

$$r_{yy}[\ell] = - \sum_{k=1}^p a_k r_{yy}[\ell - k], \ell > 0 \quad (13.140)$$

For an AR(1) process, Eq. 13.138 simplifies to:

$$r_{yy}[\ell] = -a_1 r_{yy}[\ell - 1] + \sigma_x^2 b_0 h[-\ell] \text{ for all } \ell$$

For an AR(1) process, Eq. 13.140 simplifies to:

$$r_{yy}[\ell] = -a_1 r_{yy}[\ell - 1] \text{ for } \ell > 0$$

Setting $\ell = 0$ in the first equation, we get:

$$r_{yy}[0] = -a_1 r_{yy}[-1] + \sigma_x^2 b_0 h[0]$$

The book says that $h[0] = b_0 = 1$ so we are left with:

$$r_{yy}[0] = -a_1 r_{yy}[-1] + \sigma_x^2$$

We can use the symmetry property of autocorrelation function i.e., $r_{yy}[-\ell] = r_{yy}[\ell]$:

$$r_{yy}[0] = -a_1 r_{yy}[1] + \sigma_x^2$$

To find an expression for $r_{yy}[1]$, we set $\ell = 1$ in the second equation:

$$r_{yy}[1] = -a_1 r_{yy}[0]$$

We insert the second equation into the first equation:

$$r_{yy}[0] = -a_1 (-a_1 r_{yy}[0]) + \sigma_x^2$$

$$r_{yy}[0] = a_1^2 r_{yy}[0] + \sigma_x^2$$

$$\sigma_x^2 = r_{yy}[0] - a_1^2 r_{yy}[0]$$

$$\sigma_x^2 = r_{yy}[0] (1 - a_1^2)$$

$$r_{yy}[0] = \frac{\sigma_x^2}{1 - a_1^2}$$

Now, we need to find an expression for $\ell > 0$. We can do this by using the second equation.

First, we set $\ell = 1$ in the second equation:

$$r_{yy}[1] = -a_1 r_{yy}[0] \Leftrightarrow -a_1 \frac{\sigma_x^2}{1 - a_1^2}$$

$$r_{yy}[2] = -a_1 r_{yy}[1] \Leftrightarrow -a_1 \left(-a_1 \frac{\sigma_x^2}{1 - a_1^2} \right) \Leftrightarrow (-a_1)^2 \frac{\sigma_x^2}{1 - a_1^2}$$

$$r_{yy}[3] = -a_1 r_{yy}[2] \Leftrightarrow -a_1 \left((-a_1)^2 \frac{\sigma_x^2}{1 - a_1^2} \right) \Leftrightarrow (-a_1)^3 \frac{\sigma_x^2}{1 - a_1^2}$$

This means that in general, we have:

$$r_{yy}[\ell] = (-a_1)^\ell \frac{\sigma_x^2}{1 - a_1^2}$$

If we apply the symmetric property of the autocorrelation, we get:

$$r_{yy}[\ell] = (-a_1)^{|\ell|} \frac{\sigma_x^2}{1 - a_1^2}$$

ADSI Problem 6.3: Wiener FIR Filtering, minimum square error

Consider a signal $x(n) = s(n) + w(n)$ where $s(n)$ is an AR(1) process that satisfies the difference equation

$$s(n) = 0.8s(n-1) + v(n)$$

where $\{v(n)\}$ is a white noise sequence with variance $\sigma_v^2 = 0.49$ and $\{w(n)\}$ is a white noise sequence with variance $\sigma_w^2 = 1$. The processes $\{v(n)\}$ and $\{w(n)\}$ are uncorrelated.

1) Determine the autocorrelation sequences for $x(n)$ and $s(n)$

Determine the autocorrelation sequences $\{r_s(l)\}$ and $\{r_x(l)\}$.

2) Design a Wiener filter of length $M=2$ to estimate $s(n)$

Design a Wiener filter of length $M = 2$ to estimate $\{s(n)\}$.

3) Determine the minimum mean square error for M=2

ADSI Problem 6.4: Linear interpolation, estimate missing samples

Sometimes it happens that a datapoint is missing from some signal acquisition due to sensor failure, transmission errors etc. Assume that we have a long stationary sequence $\{x[n]\}_{n=0}^{N-1}$ where the j 'th sample is missing i.e.

$$\{x[n]\} = \{x[0], x[1], \dots, x[j-1], x[j+1], x[j+2], \dots, x[N-2], x[N-1]\}$$

We want estimate the missing datapoint as a linear combination of the two neighbouring samples

$$\hat{x}[j] = c_1 x[j-1] + c_2 x[j+1]$$

1. Use our standard mean square error approach to derive equations for c_1 and c_2 based on the autocorrelation $r_{xx}(l)$.

1) Use mean square error to derive coefficients based on the ACRS

ADSI Problem 6.5: Levinson-Durbin by Hand

The aim of this problem is to get a finger-tip feeling of the flow of the Levinson-Durbin recursion. Assume that the following autocorrelation function values have been determined from an unknown random process $\{x(n)\}$

l	$r_{xx}(l)$
0	5
1	4
2	3
3	2
4	1

Work through the Levinson-Durbin recursion by hand and find the optimum linear predictors for $m=1, 2$ and 3 as well as the corresponding minimum mean square errors J_m 's and reflection coefficients k_m 's.

1) Work through Levinson-Durbin by hand to find the optimum linear predictors for $m=1,2,3$

2) Find the corresponding minimum mean square errors

3) Find the corresponding reflection coefficients

ADSI Problem 6.6: Levinson-Durbin and linear prediction

The autocorrelation function of an AR(2) process with two complex conjugated poles at $p = r_p e^{\pm j\omega_p}$ can be calculated analytically and is given by

$$r_{xx}(l) = \frac{r_p^l (\sin((l+1)\omega_p) - r_p^2 \sin((l-1)\omega_p))}{(1 - r_p^2) \sin(\omega_p) (1 - 2r_p^2 \cos(2\omega_p) + r_p^4)} \quad \text{for } l \geq 0$$

Assume that $r_p = 0.9$ and $\omega_p = \pi/16$.

1) Plot the autocorrelation function.

2) Compute reflection coefficients for m 'th order optimum linear predictors

Use the above autocorrelation function and the Levinson-Durbin recursion to calculate reflection coefficients and minimum mean square errors for m 'th order optimum linear predictors for $m = 1$ to $m = 6$. Are the results in agreement with your anticipations and Eq. (14.149)?

$$J_{m+1} = J_m + \beta_{m+1} k_{m+1} = (1 - k_{m+1}^2) J_m. \quad (14.149)$$

ADSI Problem 6.7: Linear prediction

This problem addresses linear prediction on a simple harmonic signal where the results can be compared with our intuitive understanding.

Let a discrete time signal be given by

$$x(n) = \sqrt{2} \sin(\omega_0 n + \phi)$$

Where the phase ϕ is uniformly distributed between 0 and 2π .

1) Determine the autocorrelation function for $x(n)$

2) Determine the 2nd order forward linear prediction filter

Write down the normal equation for the forward linear prediction filter and determine the filter coefficients for a 2nd order filter. For mathematical convenience we set $\omega_0 = \frac{\pi}{3}$.

3) Find the system function for the filter and locate the zeros

Find the system function $H(z)$ for the filter and locate the zeros.

4) Determine the frequency response, plot it and comment on the result

Determine the frequency response $H(\omega)$. Plot it and comment on the result.

5) Calculate the prediction error

ADSI Problem 6.8: Autocorrelation function and linear prediction

Assume that for a given sequence of data $\{x(n)\}$ the autocorrelation function has been calculated and used to solve the normal equations so that the optimum p 'th order linear predictor was found. Now, an amplifier is placed in the signal chain so that the signal is $\{c \cdot x(n)\}$. How does the autocorrelation function and the linear predictor change?

Functions