

# Homework 10

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## [✓] ADSI Problem 6.2: Autocorrelation expression for an AR(1) process (proof)

Consider an AR(1) process given by  $y(n) = -ay(n-1) + x(n)$   
with  $-1 < a < 1$  and  $x(n) \sim WN(0, \sigma_x^2)$ .

1. Show that the autocorrelation of the AR(1) process is given by

$$r_{yy}(l) = \frac{\sigma_x^2}{1-a^2}(-a)^{|l|}$$

Hint: Use equation (13.138) and (13.140).

The autocorrelation of an AR(p) process is given by Eq. 13.138:

$$r_{yy}[\ell] = - \sum_{k=1}^P a_k r_{yy}[\ell - k] + \sigma_x^2 b_0 h[-\ell]. \text{ all } \ell \quad (13.138)$$

where  $h[n]$  is the impulse response of an all-pole system.

Equation 13.138 is an general expression for all  $\ell$ . However, since  $h[\ell] = 0$  for negative values of  $\ell$  then we know that  $h[-\ell] = 0$ . Therefore, Eq. 13.138 can be reduced to:

$$r_{yy}[\ell] = - \sum_{k=1}^P a_k r_{yy}[\ell - k], \ell > 0 \quad (13.140)$$

For an AR(1) process, Eq. 13.138 simplifies to:

$$r_{yy}[\ell] = -a_1 r_{yy}[\ell - 1] + \sigma_x^2 b_0 h[-\ell] \text{ for all } \ell$$

For an AR(1) process, Eq. 13.140 simplifies to:

$$r_{yy}[\ell] = -a_1 r_{yy}[\ell - 1] \text{ for } \ell > 0$$

Setting  $\ell = 0$  in the first equation, we get:

$$r_{yy}[0] = -a_1 r_{yy}[-1] + \sigma_x^2 b_0 h[0]$$

The book says that  $h[0] = b_0 = 1$  so we are left with:

$$r_{yy}[0] = -a_1 r_{yy}[-1] + \sigma_x^2$$

We can use the symmetry property of autocorrelation function i.e.,  $r_{yy}[-\ell] = r_{yy}[\ell]$ :

$$r_{yy}[0] = -a_1 r_{yy}[1] + \sigma_x^2$$

To find an expression for  $r_{yy}[1]$ , we set  $\ell = 1$  in the second equation:

$$r_{yy}[1] = -a_1 r_{yy}[0]$$

We insert the second equation into the first equation:

$$r_{yy}[0] = -a_1 (-a_1 r_{yy}[0]) + \sigma_x^2$$

$$r_{yy}[0] = a_1^2 r_{yy}[0] + \sigma_x^2$$

$$\sigma_x^2 = r_{yy}[0] - a_1^2 r_{yy}[0]$$

$$\sigma_x^2 = r_{yy}[0] (1 - a_1^2)$$

$$r_{yy}[0] = \frac{\sigma_x^2}{1 - a_1^2}$$

Now, we need to find an expression for  $\ell > 0$ . We can do this by using the second equation.

First, we set  $\ell = 1$  in the second equation:

$$r_{yy}[1] = -a_1 r_{yy}[0] \Leftrightarrow -a_1 \frac{\sigma_x^2}{1 - a_1^2}$$

$$r_{yy}[2] = -a_1 r_{yy}[1] \Leftrightarrow -a_1 \left( -a_1 \frac{\sigma_x^2}{1 - a_1^2} \right) \Leftrightarrow (-a_1)^2 \frac{\sigma_x^2}{1 - a_1^2}$$

$$r_{yy}[3] = -a_1 r_{yy}[2] \Leftrightarrow -a_1 \left( (-a_1)^2 \frac{\sigma_x^2}{1 - a_1^2} \right) \Leftrightarrow (-a_1)^3 \frac{\sigma_x^2}{1 - a_1^2}$$

This means that in general, we have:

$$r_{yy}[\ell] = (-a_1)^\ell \frac{\sigma_x^2}{1 - a_1^2}$$

If we apply the symmetric property of the autocorrelation, we get:

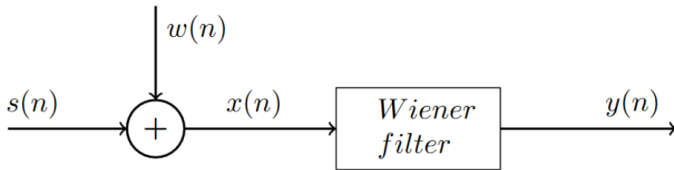
$$r_{yy}[\ell] = (-a_1)^{|\ell|} \frac{\sigma_x^2}{1 - a_1^2}$$

### ADSI Problem 6.3: Wiener FIR Filtering, minimum square error

Consider a signal  $x(n) = s(n) + w(n)$  where  $s(n)$  is an AR(1) process that satisfies the difference equation

$$s(n) = 0.8s(n-1) + v(n)$$

where  $\{v(n)\}$  is a white noise sequence with variance  $\sigma_v^2 = 0.49$  and  $\{w(n)\}$  is a white noise sequence with variance  $\sigma_w^2 = 1$ . The processes  $\{v(n)\}$  and  $\{w(n)\}$  are uncorrelated.



```
clear variables;
```

## [✓] 1) Determine the autocorrelation sequence for a signal with two noise processes

Determine the autocorrelation sequences  $\{r_s(l)\}$  and  $\{r_x(l)\}$ .

In Problem 6.2, we found that the autocorrelation function of an AR(1) is:

$$r_{yy}^{\text{AR}(1)}(\ell) = (-a_1)^{|\ell|} \frac{\sigma_x^2}{1 - a_1^2}$$

For the AR(1) process, we are given  $a_1 = -0.8$  and  $\sigma_v^2 = 0.49$ . So the autocorrelation sequence for  $s(n)$  is:

$$r_{ss}(\ell) = 0.8^{|\ell|} \frac{0.49}{1 - (-0.8)^2} = 0.8^{|\ell|} \frac{0.49}{0.36}$$

Next, we need to find the autocorrelation sequence for  $w(n)$ . The autocorrelation of white Gaussian noise is  $\sigma_w^2 \delta(\ell)$  so since white noise has unit variance i.e.  $\sigma_w^2 = 1$  we have:

$$r_{ww}(\ell) = \delta(\ell)$$

Since the two noise processes are uncorrelated, the ACRS of  $\{x(n)\}$  process is:

$$r_{xx}(\ell) = 0.8^{|\ell|} \frac{0.49}{0.36} + \delta(\ell)$$

## [♦] 2) Design a Wiener filter of length M=2 to estimate an AR(1) process

Design a Wiener filter of length  $M = 2$  to estimate  $\{s(n)\}$ .

The optimum Wiener filter to estimate a random process is given by Eq. 14.109:

$$\mathbf{h}_0 = \mathbf{R}_x^{-1} \mathbf{g}, \quad (14.109)$$

where  $\mathbf{R}_x$  is the correlation matrix of a random vector  $\mathbf{x}$  and  $\mathbf{g}$  is the cross-correlation vector between  $\mathbf{x}$  and  $\mathbf{y}$  (the signal that we want to recover which in this problem is  $s[n]$ ).

Basically, to design a  $p$ th order Wiener filter, we have to solve following equation with respect to  $\mathbf{h}$ :

$$\begin{bmatrix} r_x[0] & r_x[1] & \dots & r_x[p-1] \\ r_x[1] & r_x[0] & \dots & r_x[p-2] \\ \vdots & \vdots & \ddots & \vdots \\ r_x[p-1] & r_x[p-2] & \dots & r_x[0] \end{bmatrix} \begin{bmatrix} h_1 \\ h_2 \\ \vdots \\ h_p \end{bmatrix} = \begin{bmatrix} r_{yx}[0] \\ r_{yx}[1] \\ \vdots \\ r_{yx}[p-1] \end{bmatrix}, \quad (14.113)$$

Computing the autocorrelation matrix is straightforward since we have computed the autocorrelation  $r_{xx}(\ell)$  in part 1).

```
M = 2;
ell = 0:M-1;

r_ss = 0.8.^abs(ell) * (0.49/0.36);
r_ww = (ell == 0); % Simulate the delta function
r_xx = r_ss + r_ww;
R_xx = toeplitz(r_xx)
```

```
R_xx = 2x2
    2.3611    1.0889
    1.0889    2.3611
```

We have to come up with an expression for the cross-correlation  $r_{sx}(\ell)$ :

$$r_{sx}(\ell) = E[s(n)x(n-\ell)]$$

$$r_{sx}(\ell) = E[s(n)(s(n-\ell) + w(n-\ell))]$$

$$r_{sx}(\ell) = E[s(n)s(n-\ell) + s(n)w(n-\ell)]$$

$$r_{sx}(\ell) = E[s(n)s(n-\ell)] + E[s(n)w(n-\ell)]$$

Since the processes  $s(n)$  and  $w(n)$  are uncorrelated:

$$r_{sx}(\ell) = E[s(n)s(n-\ell)] + E[s(n)] \cdot E[w(n-\ell)]$$

❖ **Is it okay to make this assumption?**

We assume that  $w(n)$  is a zero-mean WGN, we know that  $E[w(n)] = 0$ , so we are left with

$$r_{sx}(\ell) = r_{ss}(\ell) + 0$$

From 1), we know the that:

$$r_{ss}(\ell) = 0.8^{|\ell|} \frac{0.49}{0.36}$$

```
g = r_ss';

h_opt = R_xx \ g % Same as `inv(R_xx)*g` but better
```

```
h_opt = 2x1
    0.4621
    0.2481
```

[✓] 3) Determine the minimum mean square error for  $M=2$

The minimum square error for an optimum  $p$ th Wiener (FIR) filter is given by Eq. 14.115:

$$J_o = r_y[0] - \mathbf{h}_o^T \mathbf{g} = r_y[0] - \sum_{k=0}^{p-1} h_o[k] r_{yx}[k]. \quad (14.115)$$

```
mse = r_ss(1) - h_opt'*g
```

```
mse = 0.4621
```

## ADSI Problem 6.4: Linear interpolation, estimate missing samples

Sometimes it happens that a datapoint is missing from some signal acquisition due to sensor failure, transmission errors etc. Assume that we have a long stationary sequence  $\{x[n]\}_{n=0}^{N-1}$  where the  $j$ 'th sample is missing i.e.

$$\{x[n]\} = \{x[0], x[1], \dots, x[j-1], x[j+1], x[j+2], \dots, x[N-2], x[N-1]\}$$

We want estimate the missing datapoint as a linear combination of the two neighbouring samples

$$\hat{x}[j] = c_1 x[j-1] + c_2 x[j+1]$$

1. Use our standard mean square error approach to derive equations for  $c_1$  and  $c_2$  based on the autocorrelation  $r_{xx}(l)$ .

### 1) Use mean square error to derive coefficients based on the ACRS

## ADSI Problem 6.5: Levinson-Durbin by Hand

*The aim of this problem is to get a finger-tip feeling of the flow of the Levinson-Durbin recursion. Assume that the following autocorrelation function values have been determined from an unknown random process  $\{x(n)\}$*

$l$	$r_{xx}(l)$
0	5
1	4
2	3
3	2
4	1

Work through the Levinson-Durbin recursion by hand and find the optimum linear predictors for  $m=1, 2$  and  $3$  as well as the corresponding minimum mean square errors  $J_m$ 's and reflection coefficients  $k_m$ 's.

**1) Work through Levinson-Durbin by hand to find the optimum linear predictors for  $m=1,2,3$**

**2) Find the corresponding minimum mean square errors**

**3) Find the corresponding reflection coefficients**

## ADSI Problem 6.6: Levinson-Durbin and linear prediction

The autocorrelation function of an AR(2) process with two complex conjugated poles at  $p = r_p e^{\pm j\omega_p}$  can be calculated analytically and is given by

$$r_{xx}(l) = \frac{r_p^l (\sin((l+1)\omega_p) - r_p^2 \sin((l-1)\omega_p))}{(1 - r_p^2) \sin(\omega_p) (1 - 2r_p^2 \cos(2\omega_p) + r_p^4)} \quad \text{for } l \geq 0$$

Assume that  $r_p = 0.9$  and  $\omega_p = \pi/16$ .

**1) Plot the autocorrelation function.**

**2) Compute reflection coefficients for  $m$ 'th order optimum linear predictors**

Use the above autocorrelation function and the Levinson-Durbin recursion to calculate reflection coefficients and minimum mean square errors for  $m$ 'th order optimum linear predictors for  $m = 1$  to  $m = 6$ . Are the results in agreement with your anticipations and Eq. (14.149)?

$$J_{m+1} = J_m + \beta_{m+1}k_{m+1} = (1 - k_{m+1}^2)J_m. \quad (14.149)$$

## ADSI Problem 6.7: Linear prediction

This problem addresses linear prediction on a simple harmonic signal where the results can be compared with our intuitive understanding.

Let a discrete time signal be given by

$$x(n) = \sqrt{2} \sin(\omega_0 n + \phi)$$

Where the phase  $\phi$  is uniformly distributed between 0 and  $2\pi$ .

### 1) Determine the autocorrelation function for $x(n)$

### 2) Determine the 2nd order forward linear prediction filter

Write down the normal equation for the forward linear prediction filter and determine the filter coefficients for a 2nd order filter. For mathematical convenience we set  $\omega_0 = \frac{\pi}{3}$ .

### 3) Find the system function for the filter and locate the zeros

Find the system function  $H(z)$  for the filter and locate the zeros.

### 4) Determine the frequency response, plot it and comment on the result

Determine the frequency response  $H(\omega)$ . Plot it and comment on the result.



## 5) Calculate the prediction error

### ADSI Problem 6.8: Autocorrelation function and linear prediction

*Assume that for a given sequence of data  $\{x(n)\}$  the autocorrelation function has been calculated and used to solve the normal equations so that the optimum  $p$ 'th order linear predictor was found. Now, an amplifier is placed in the signal chain so that the signal is  $\{c \cdot x(n)\}$ . How does the autocorrelation function and the linear predictor change?*

## Functions

