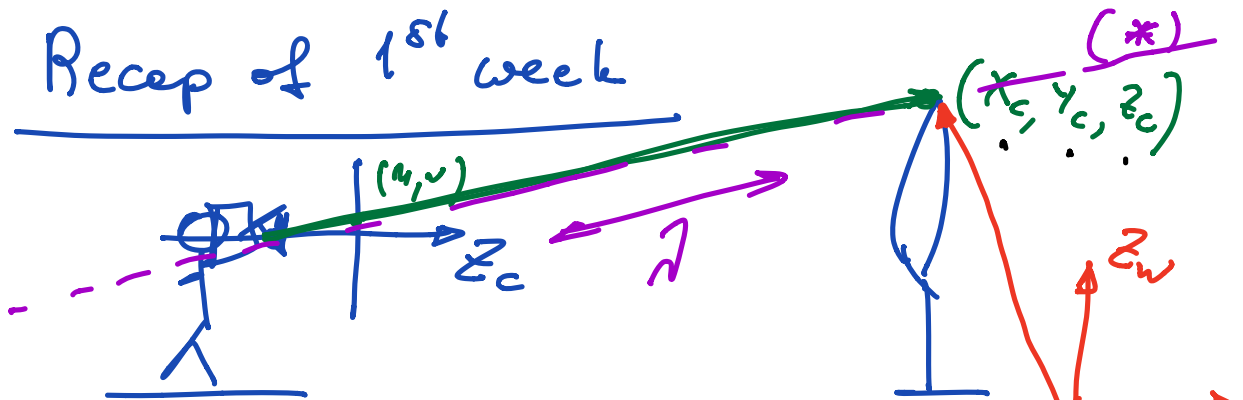


Recap of 1st week



$$\begin{aligned} u &= f \frac{x_c}{z_c} + u_0 \\ v &= f \frac{y_c}{z_c} + v_0 \end{aligned}$$

[pixels]

$${}^c P = {}^c R_w {}^w P + {}^c T_w$$

where ${}^c R_w$ is camera

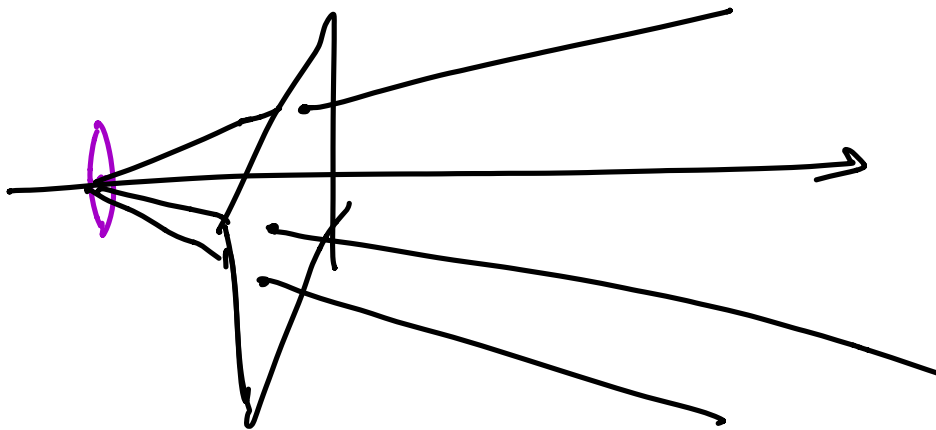
$$\lambda \begin{pmatrix} u \\ v \\ 1 \end{pmatrix} = \underbrace{\begin{pmatrix} f & 0 & u_0 \\ 0 & f & v_0 \\ 0 & 0 & 1 \end{pmatrix}}_{\substack{3 \times 3 \\ K \\ \text{intrinsic}}} \underbrace{\begin{pmatrix} {}^c R_w & {}^c T_w \end{pmatrix}}_{\substack{3 \times 4 \\ M \\ \text{extrinsic}}} \begin{pmatrix} x_w \\ y_w \\ z_w \\ 1 \end{pmatrix}$$

given (u, v)
where is $\begin{pmatrix} x_w \\ y_w \\ z_w \end{pmatrix}$?

$$\begin{pmatrix} x_w \\ y_w \\ z_w \end{pmatrix} = -{}^c R_w^{-1} {}^c T_w + \lambda {}^c R_w^{-1} K \begin{pmatrix} u \\ v \\ 1 \end{pmatrix}$$

(*) line equation

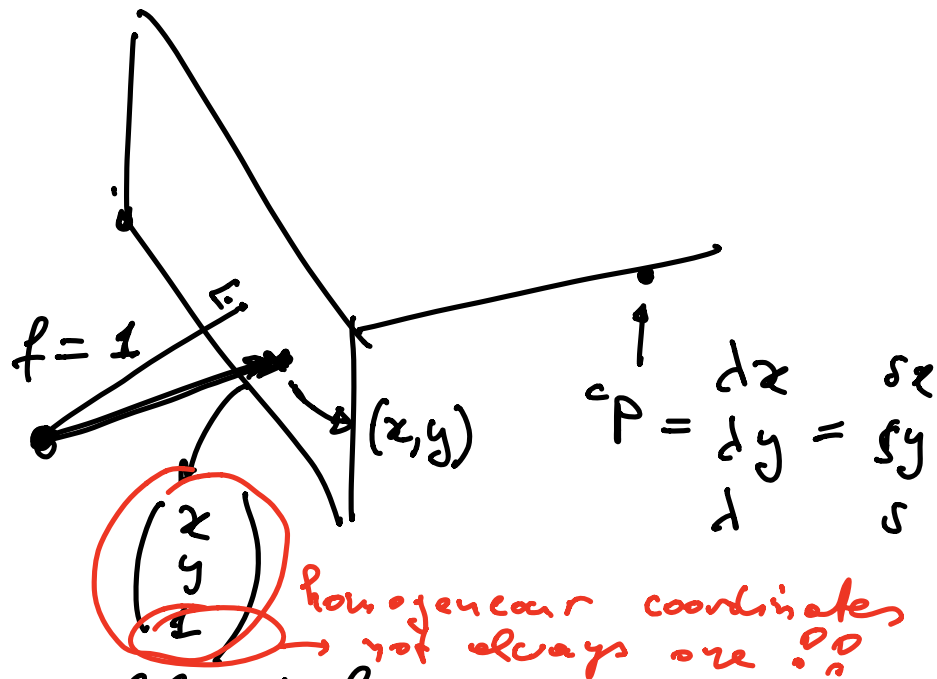
given $\begin{pmatrix} u \\ v \end{pmatrix}$ we know only the ray through $\begin{pmatrix} u \\ v \end{pmatrix}$ and the projection center (origin of cam. c.s.).



we need a new geometry
to deal with a set of rays
through one point (pencil of rays)
(old geometry : euclidean geometry)

Axiom : Parallel lines never
"Def" intersect.

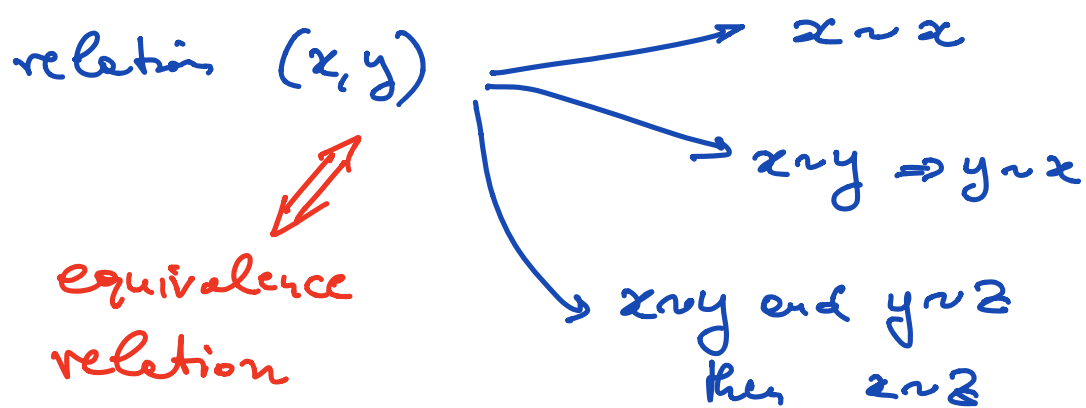
Picture taking (Perspective projection)
 can make parallel lines
 not parallel (intersect)!



We will define a new
 set where each ray is one element!

= set of rays

"all points along one ray
 are equivalent"

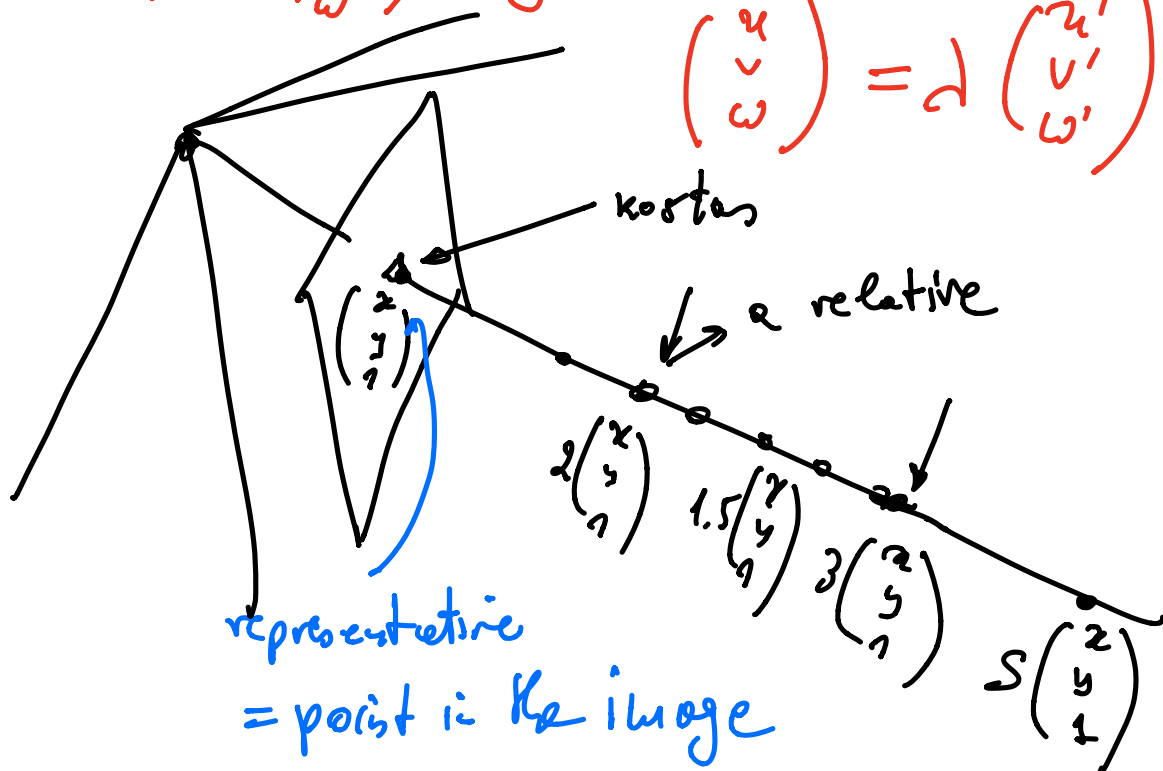


$$\text{equivalence class} = \left\{ x \in X : x \sim a \text{ for an } a \in X \right\}$$

projective equivalence

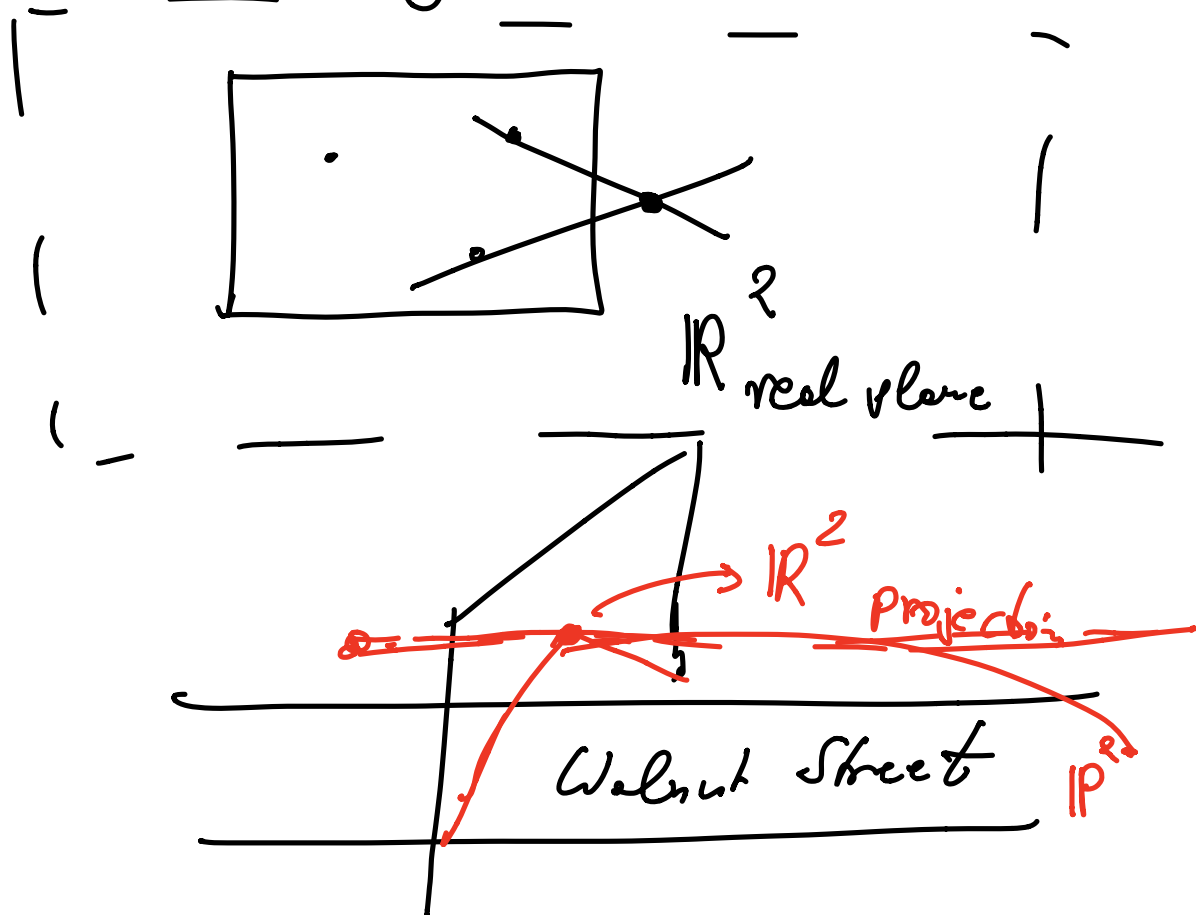
↑
representative

$$\begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \neq \begin{pmatrix} u \\ v \\ w \end{pmatrix} \sim \begin{pmatrix} u' \\ v' \\ w' \end{pmatrix} \neq \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \text{ iff } \exists \lambda \neq 0 : \begin{pmatrix} u \\ v \\ w \end{pmatrix} = \lambda \begin{pmatrix} u' \\ v' \\ w' \end{pmatrix}$$



projective plane \mathbb{P}^2 = set of all
 rays $s \begin{pmatrix} 2 \\ 4 \\ 2 \end{pmatrix}$ when $\begin{pmatrix} 2 \\ 4 \\ 2 \end{pmatrix} \neq 0$
 $s \in \mathbb{R} \setminus \{0\}$

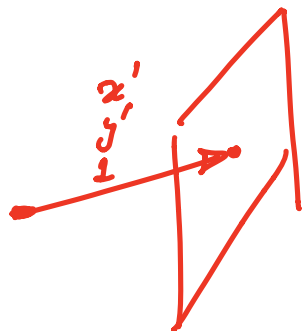
Why was the image plane
 not enough? \mathbb{R}^2



Main reason for introducing \mathbb{P}^2 is the projection of points at infinity!

$$\mathbb{P}^2 = \mathbb{R}^2 \cup \{\text{points at infinity}\}$$

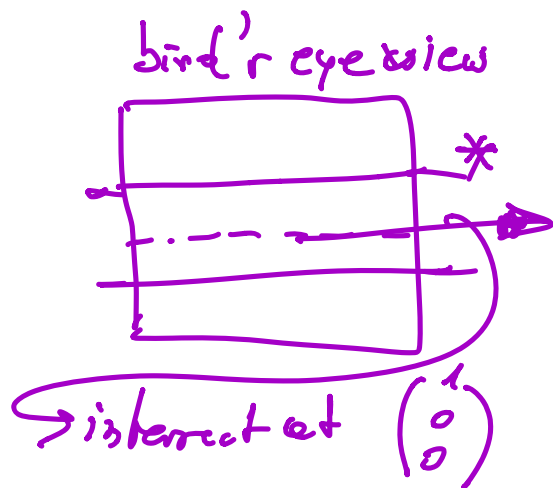
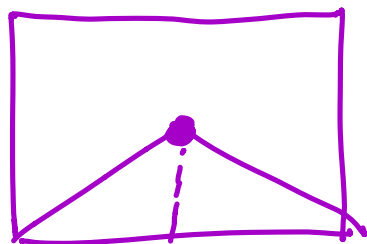
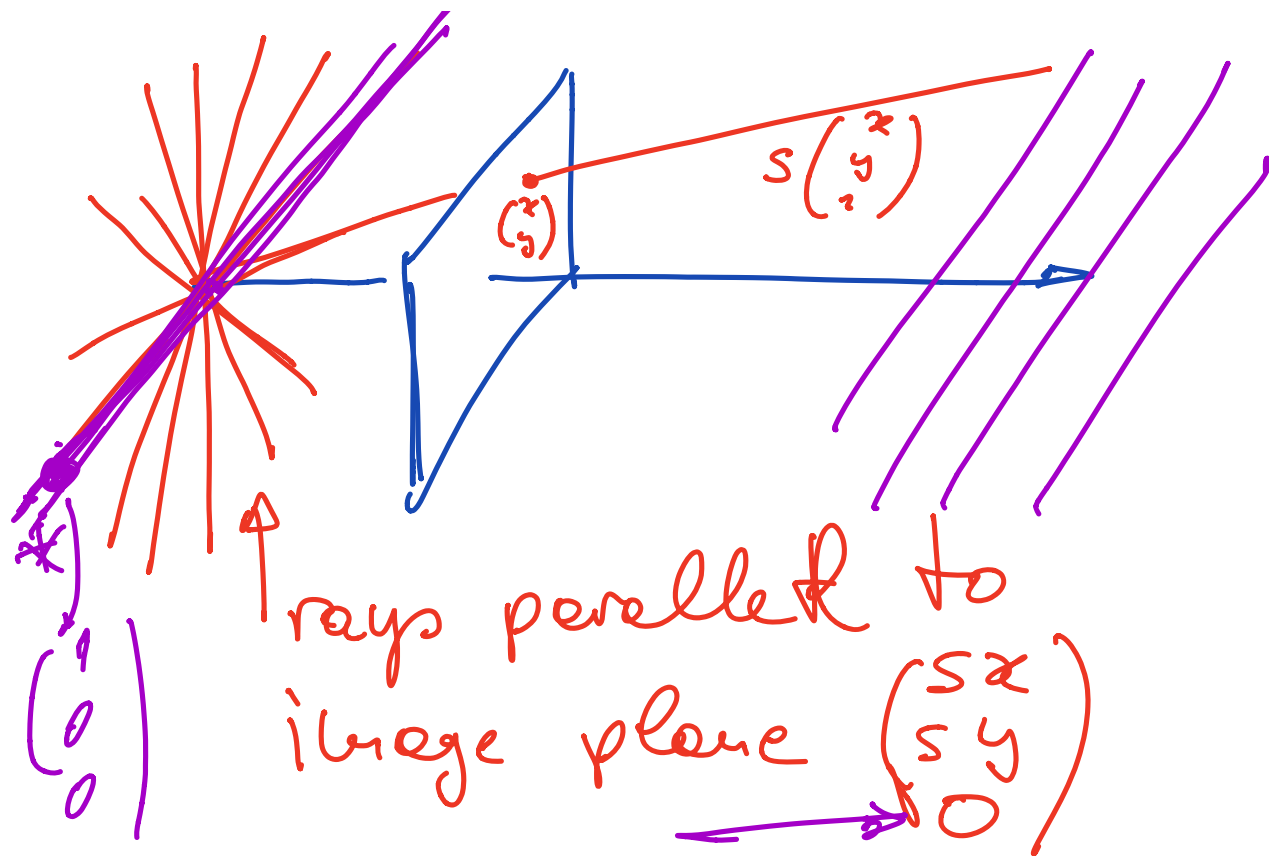
$$\begin{pmatrix} x' \\ y' \end{pmatrix} \in \mathbb{R}^2 \longrightarrow \mathbb{P}^2 \ni \begin{pmatrix} x' \\ y' \\ 1 \end{pmatrix}$$



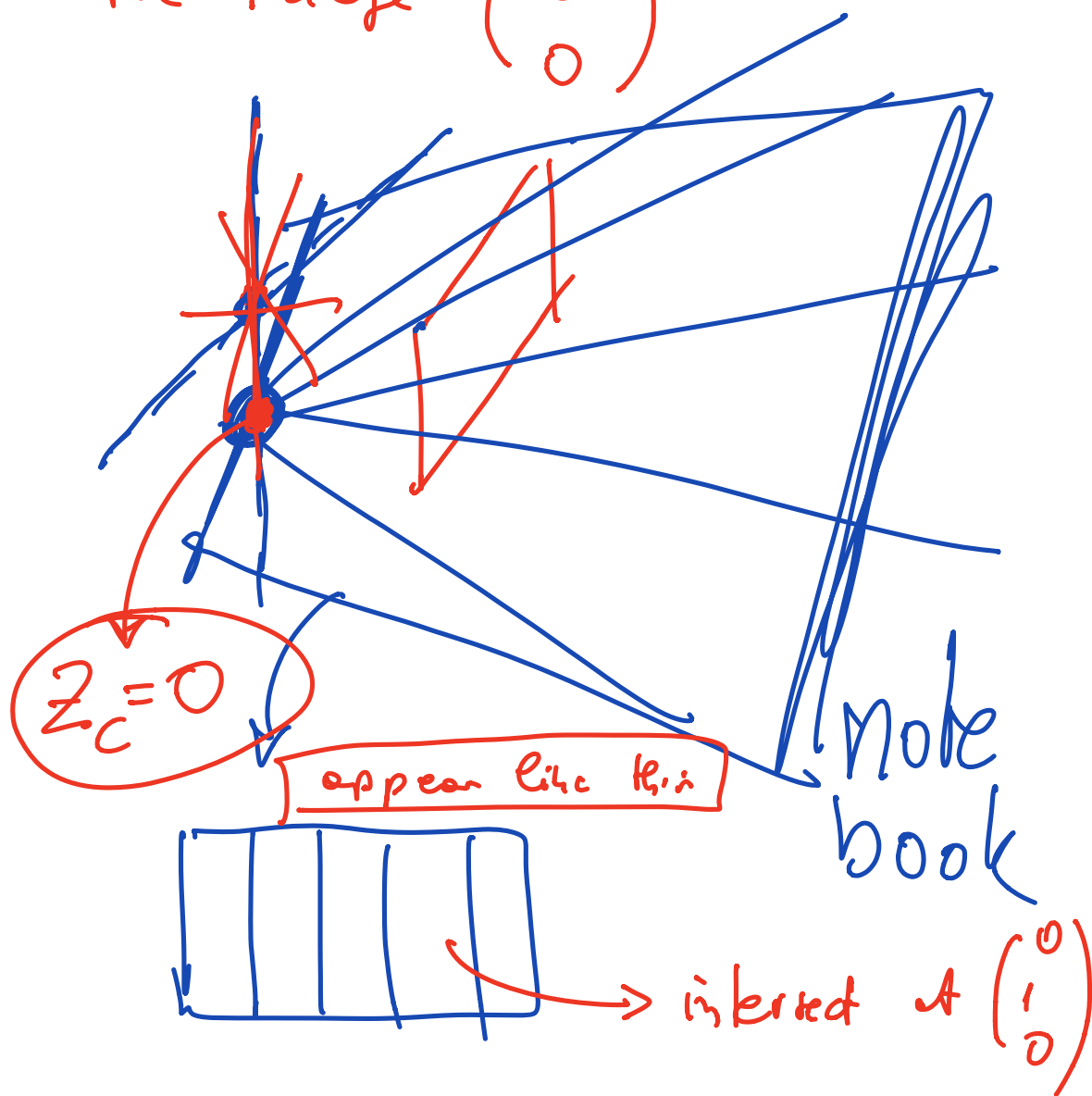
$$\begin{pmatrix} u \\ v \\ w \end{pmatrix} \in \mathbb{P}^2 \implies \mathbb{R}^2 \ni \begin{pmatrix} u/w \\ v/w \end{pmatrix}$$

if $w \neq 0$.

Points at infinity $w = 0$

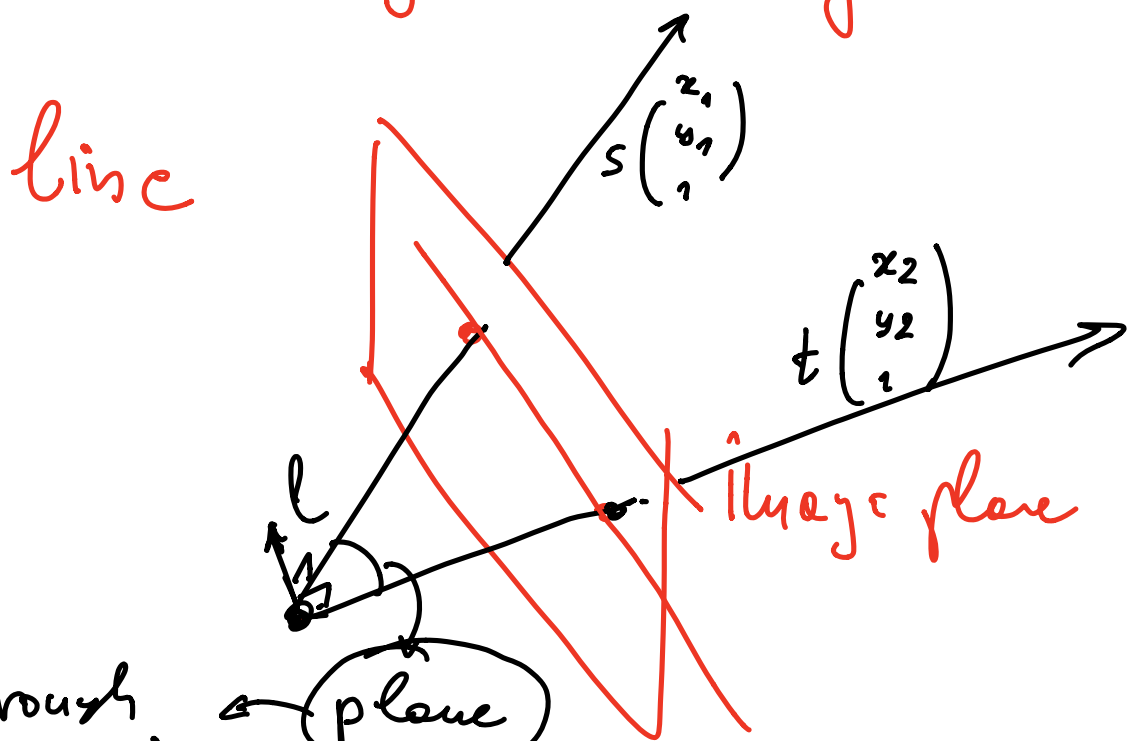


Can intersecting lines in the world appear parallel in the image? \rightarrow intersection in the image $\begin{pmatrix} \bullet \\ \bullet \\ 0 \end{pmatrix}$



$$\mathbb{P}^2 = \left\{ s \begin{pmatrix} x \\ y \\ 1 \end{pmatrix} \right\} \cup \left\{ t \begin{pmatrix} x \\ y \\ 0 \end{pmatrix} \right\}$$

$\underbrace{\hspace{10em}}_{\text{ray}} \quad \underbrace{\hspace{10em}}_{\text{ray}}$
 $\uparrow \text{representative} \quad \downarrow \mathbb{R}^2 \quad \uparrow \text{representative}$



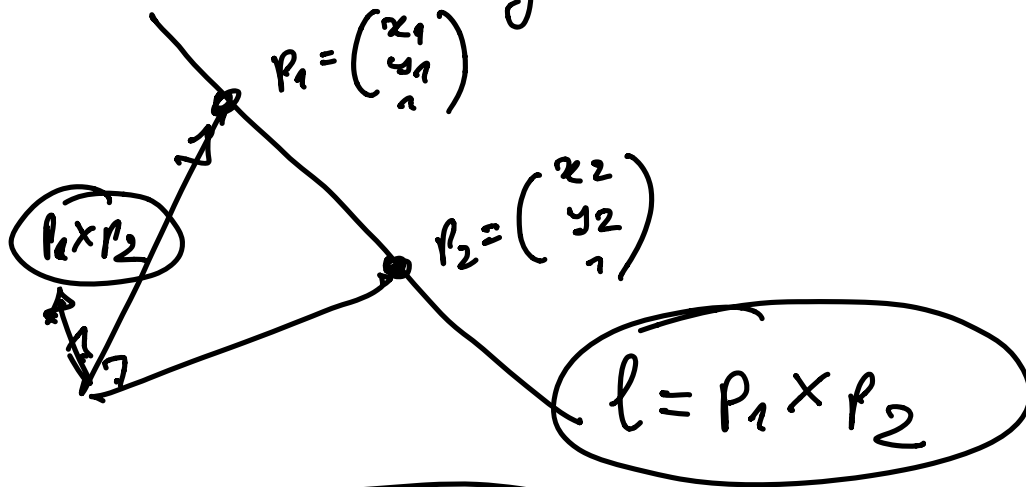
through
(0,0,0)

$$ax + by + cz = 0$$

$$(a \ b \ c) \begin{pmatrix} x \\ y \\ z \end{pmatrix} = 0$$

homogeneous
coordinates $\rightarrow l^T p = 0$

line is not that different then real
lines $ax + by + c = 0$



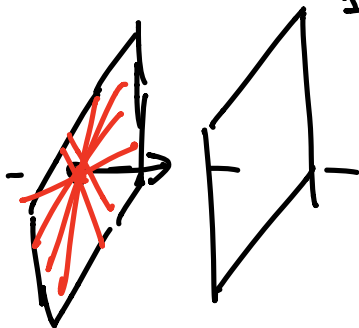
$$ax + by = 0$$

passing through
image origin
(not projection
center)

which line has the

form $\begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$? $0x + 0y + 1 \cdot z = 0$

this is the line
at infinity: l_∞



$$l_{\infty} = \left\{ \begin{pmatrix} x \\ y \\ 0 \end{pmatrix} \neq \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \right\}$$

$$l_{\infty} \text{ is } \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \notin \mathbb{R}^2$$

$$0x + 0y + 1 = 0$$

$$1 = 0$$

