

# Deep Learning Extensions

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Learning objectives

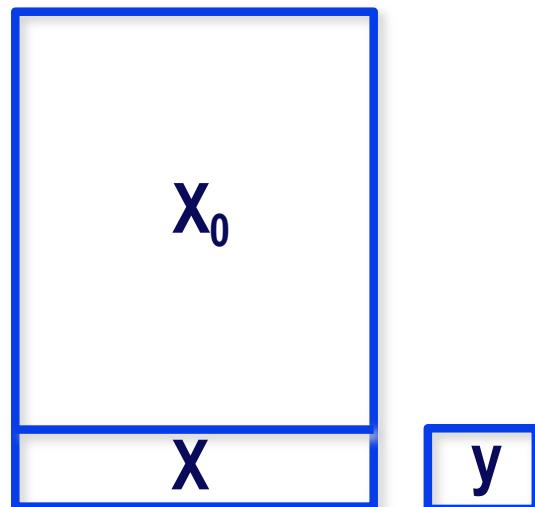
GANS

KL-divergence

CNNs for NLP

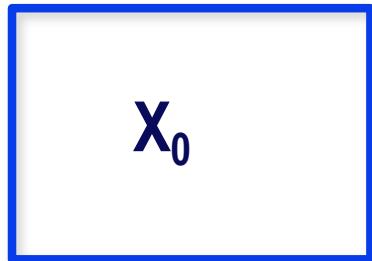
# Semi-supervised learning

- ◆ Use unlabeled data  $X_0$  to derive new features  $z = \phi(x)$
- ◆ Train  $y = f(\phi(x), w)$



# Transfer learning

- ◆ Use one data set ( $X_0, y_0$ ) to train a model
- ◆ Find feature transformations  $\phi(x)$
- ◆ Use those transformations  $\phi(x)$  on data from data set with a different label,  $y$ .

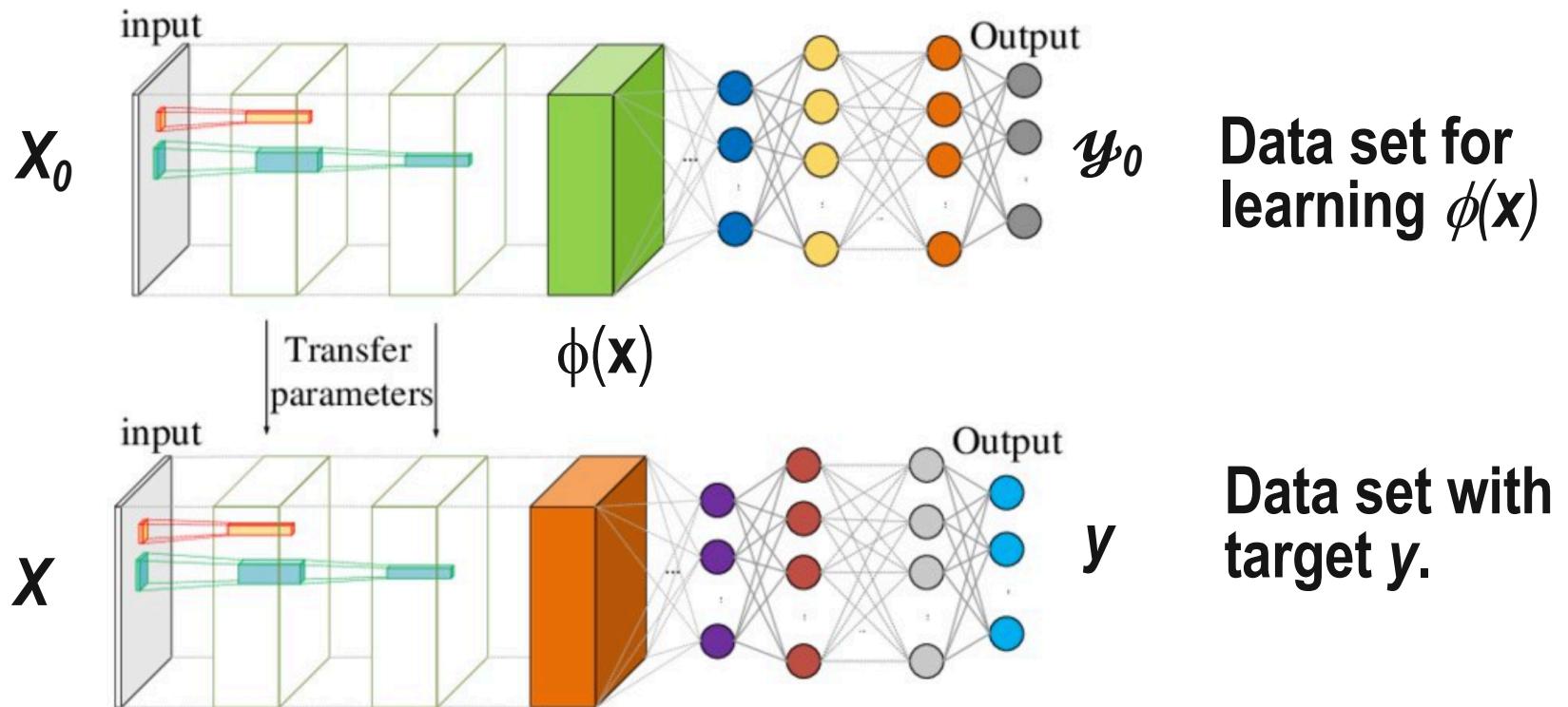


Data set for learning  $\phi(x)$



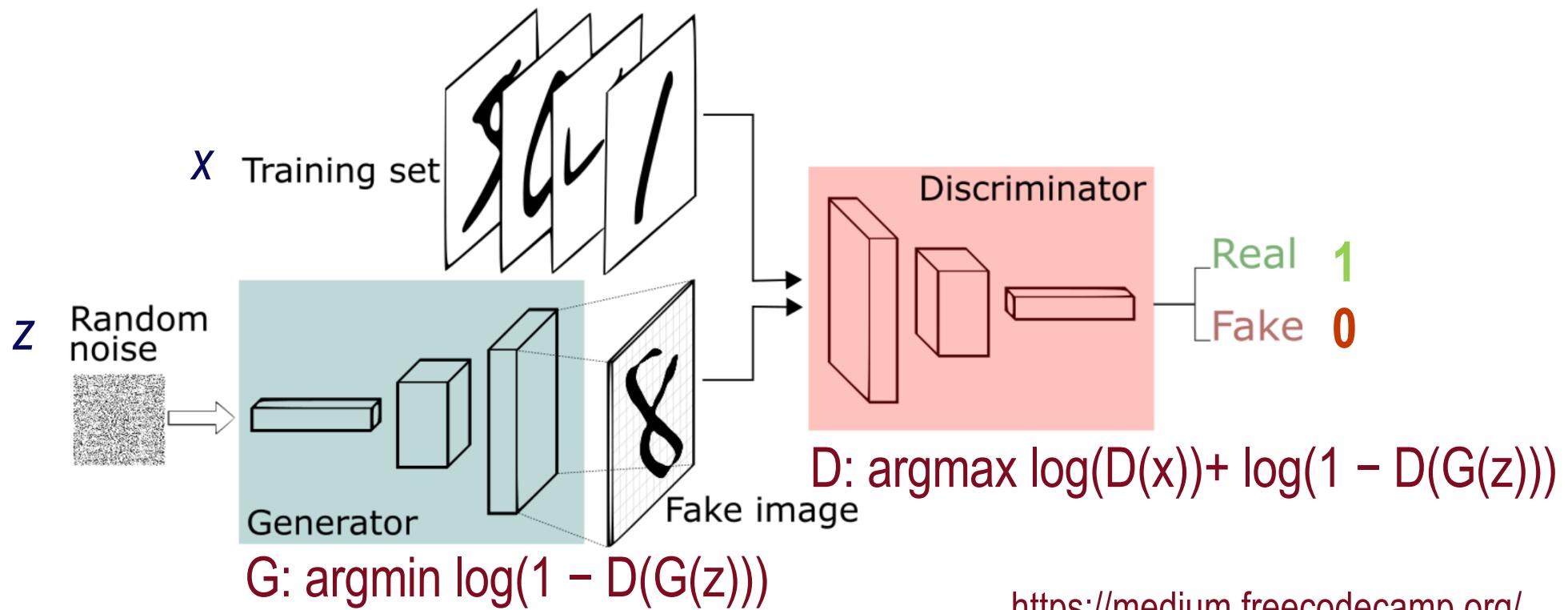
Data set with target  $y$ .

# Transfer learning for NNets



# Digression: KL-divergence

# Generative Adversarial Networks: GANS



[https://medium.freecodecamp.org/  
an-intuitive-introduction-to-](https://medium.freecodecamp.org/an-intuitive-introduction-to-gans-1a2d1f3a3a2)

$$\min_G \max_D V(D, G) = \mathbb{E}_{\mathbf{x} \sim p_{\text{data}}(\mathbf{x})} [\log D(\mathbf{x})] + \mathbb{E}_{\mathbf{z} \sim p_{\mathbf{z}}(\mathbf{z})} [\log(1 - D(G(\mathbf{z})))]$$

# GANs

- ◆ Make generative model,  $G$ , close to data PDF

$$\theta^* = \arg \min_{\theta} D_{\text{KL}}(p_{\text{data}}(\mathbf{x}) \| p_{\text{model}}(\mathbf{x}; \theta)) = E(\sum p_{\text{data}} \log(p_{\text{model}}/p_{\text{data}}))$$

- ◆ For actual data this is the MLE:

$$\theta^* = \arg \max_{\theta} \prod_{i=1}^m p_{\text{model}}(\mathbf{x}^{(i)}; \theta)$$

$$= \arg \max_{\theta} \log \prod_{i=1}^m p_{\text{model}}(\mathbf{x}^{(i)}; \theta)$$

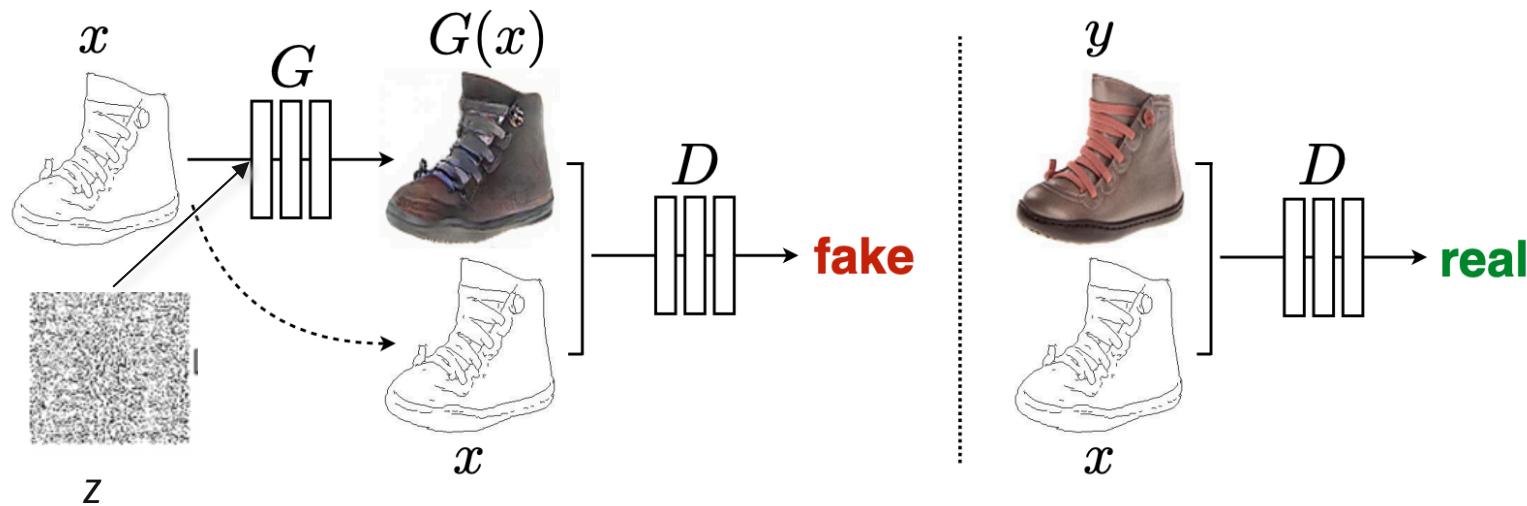
$$= \arg \max_{\theta} \sum_{i=1}^m \log p_{\text{model}}(\mathbf{x}^{(i)}; \theta) . \quad E(\sum p_{\text{data}} \log(p_{\text{model}}/p_{\text{data}}))$$

# GANs Training

## ◆ Training can be slow and unstable

- Better convergence if you alternately train discriminator and generator

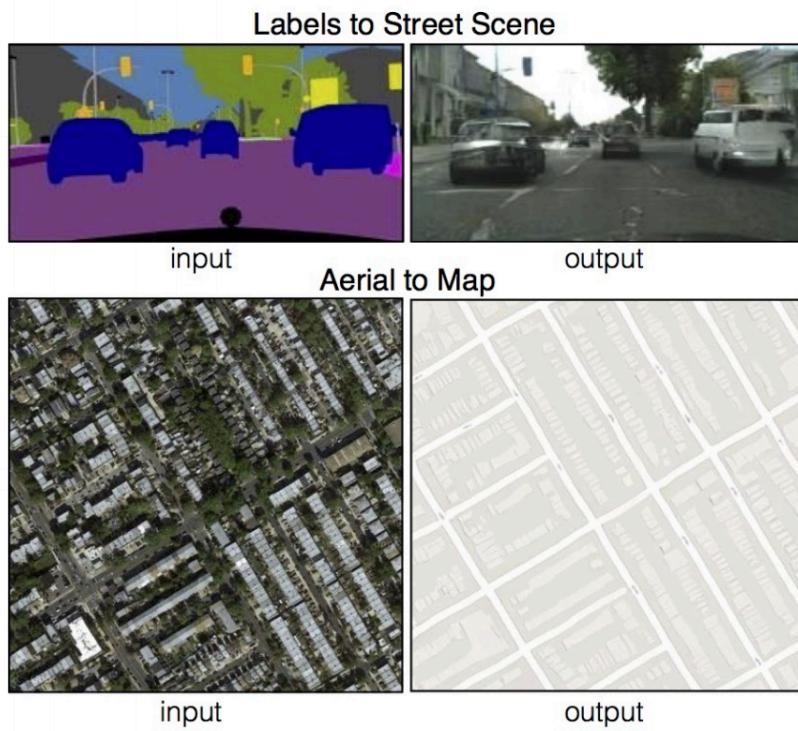
# Conditional GANs for Image Translation (outline to photo)



$$\min_G \max_D V(D, G) = \mathbb{E}_{x,y}[\log D(x, y)] + \\ \mathbb{E}_{x,z}[\log(1 - D(x, G(x, z)))]$$

<https://arxiv.org/pdf/1611.07004.pdf>

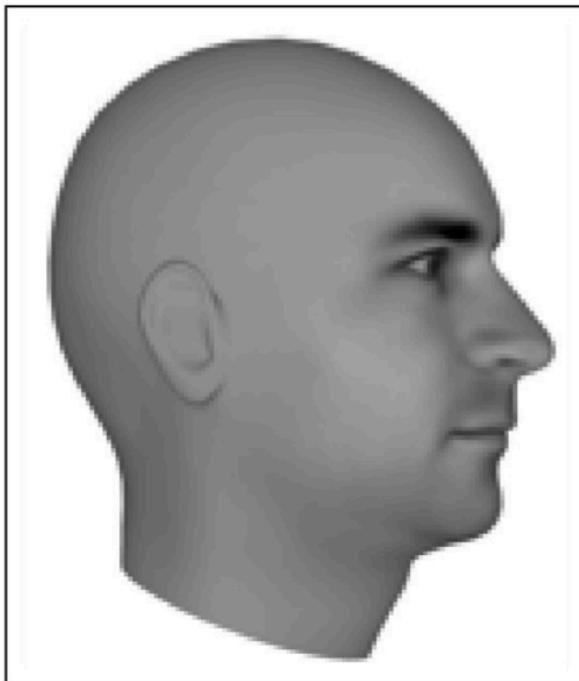
# GANs: Image translation



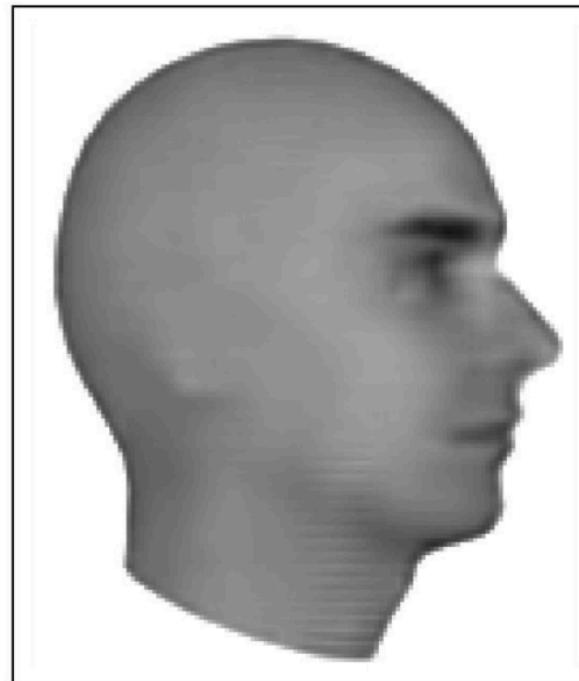
<https://arxiv.org/pdf/1701.00160.pdf>  
Isola et al. (2016)

# GANs: Predict next video frame

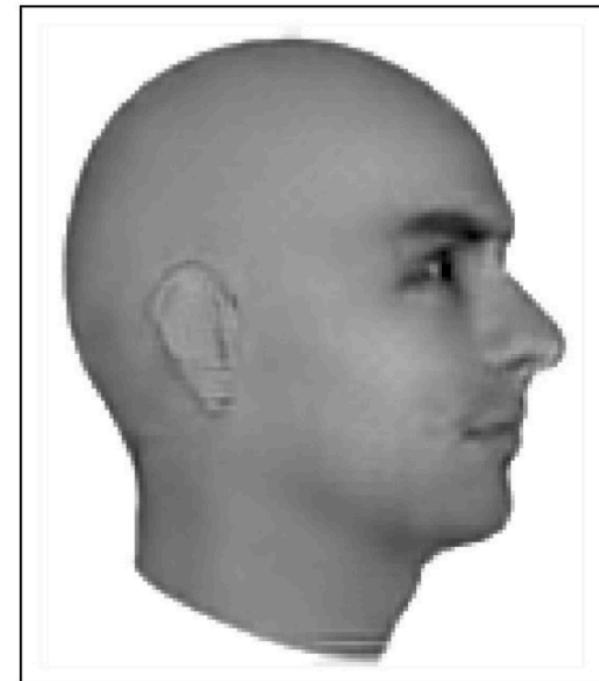
Ground Truth



MSE



Adversarial



<https://arxiv.org/pdf/1701.00160.pdf>  
Lotter et al. 2015

# GANs: Image translation

- ◆ Summer to winter
- ◆ Sketch to photo
- ◆ low resolution to high resolution photo
- ◆ Young to old
- ◆ Photo to impressionist painting



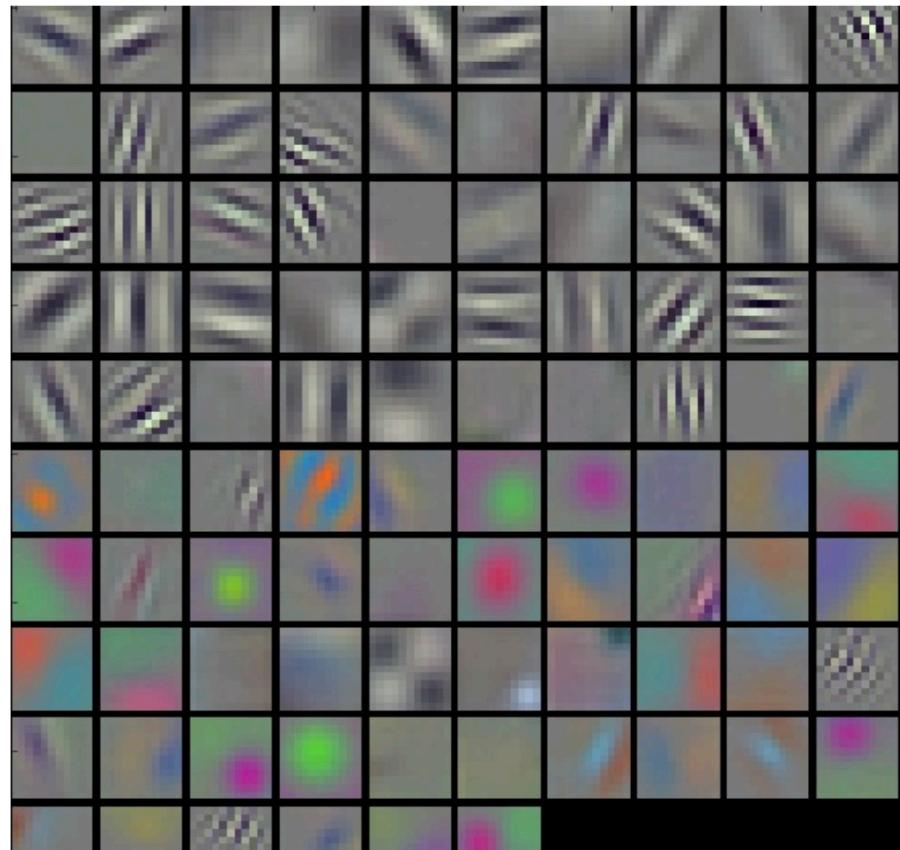
[https://www.youtube.com/watch?time\\_continue=3704&v=AJJRWFVfNPg](https://www.youtube.com/watch?time_continue=3704&v=AJJRWFVfNPg)

# Visualizing networks

- ◆ **Display pattern of hidden unit activations**
  - Just shows they are sparse
- ◆ **Show input that maximizes a node's output**
  - Over all inputs in the training set
  - Over the entire range of possible inputs
  - Early layers do feature detection
  - Later layers do object detection
- ◆ **Show how occluding parts of an image affect classification accuracy**

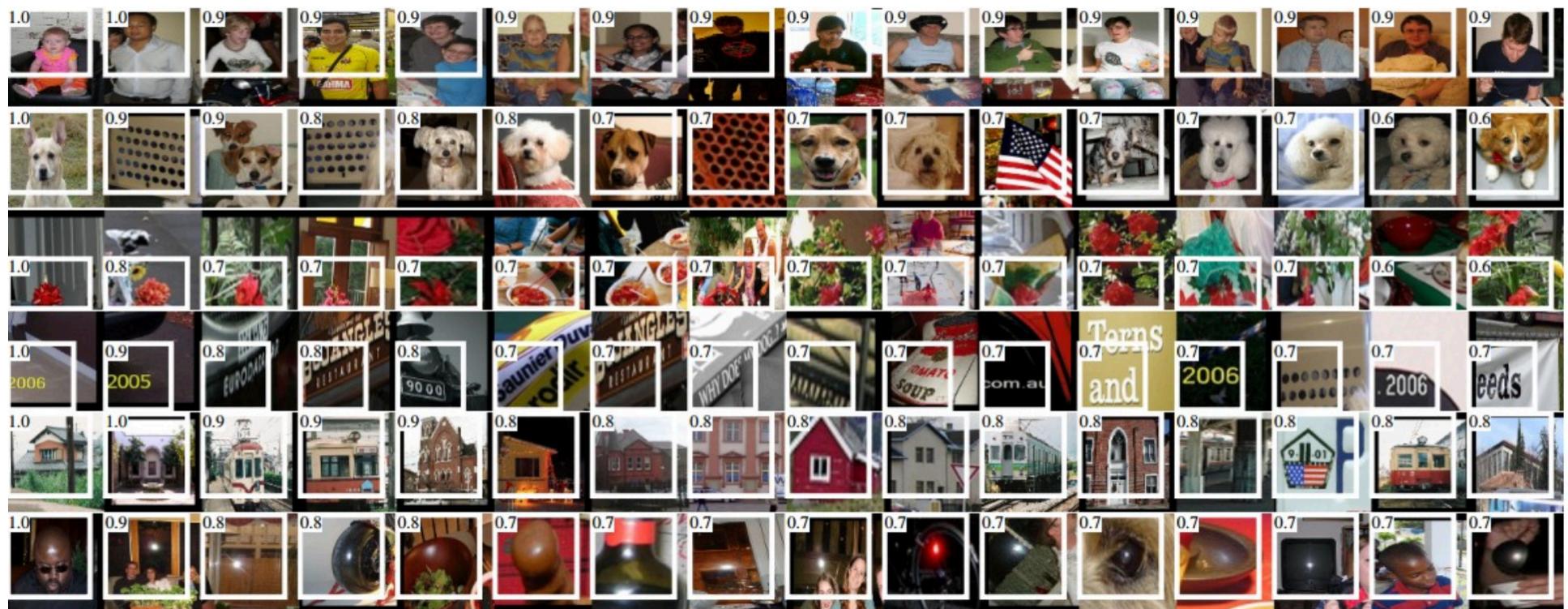
<http://cs231n.github.io/understanding-cnn/>

# Maximally activating inputs for the first CONV layer of an AlexNet

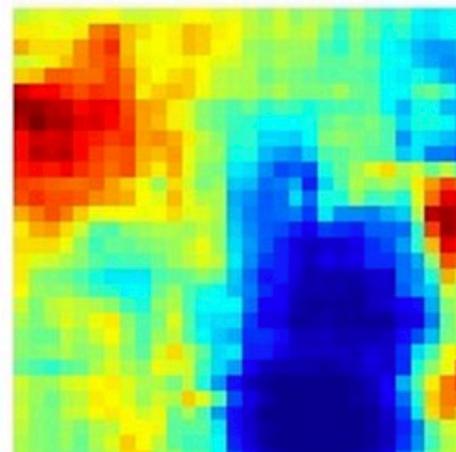
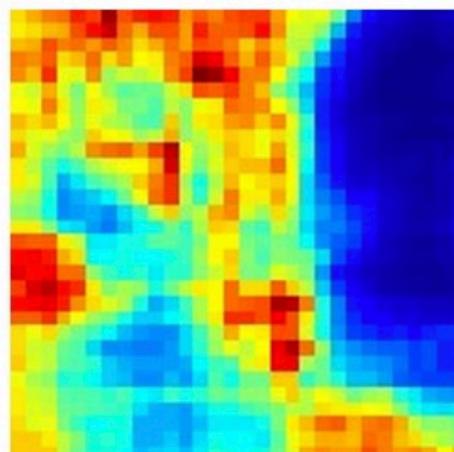
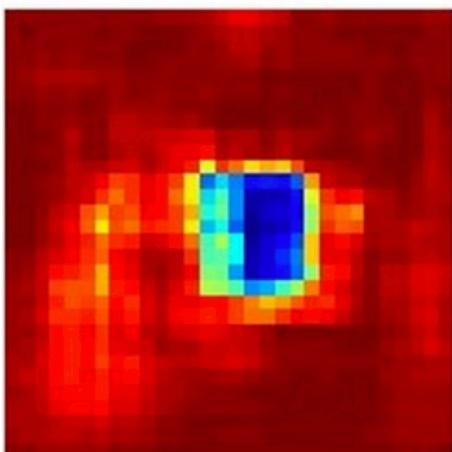
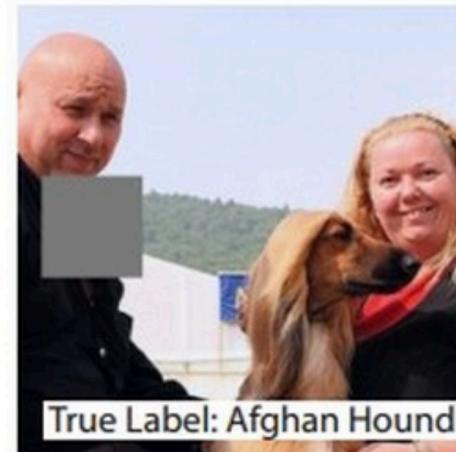


<http://cs231n.github.io/understanding-cnn/>

# Maximally activating images for some 5th maxpool layer neurons of an AlexNet.



# P(correct label) after occlusion



Matthew Zeiler's  
Visualizing and  
Understanding  
Convolutional  
Networks: