

PCA

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Learning objectives

PCA as change of basis

PCA minimizes reconstruction error

PCA maximizes variance

PCA relation to eigenvalues/vectors

PCR: PCA for feature creation

Based in part on slides by Jia Li
(PSU) and Barry Slaff (Upenn)

PCA

- ◆ Express a vector x in terms of coefficients on an (orthogonal) basis vector (eigenvectors v_k)

$$x_i = \sum_k z_{ik} v_k$$

- We can describe how well we approximate x in terms of the eigenvalues

- ◆ PCA is used for dimensionality reduction

- visualization
- semi-supervised learning
- eigenfaces, eigenwords, eigengrasp

PCA

- ◆ PCA can be viewed as

- minimizing distortion $\|\mathbf{x}_i - \sum_k z_{ik} \mathbf{v}_k\|_2$
- A rotation to a new coordinate system to maximize the variance in the new coordinates

- ◆ Generally done by mean centering first

- You may or may not want to standardize

Nomenclature

$$X = ZV'$$

- ◆ **Z** (n x k)
 - principal component **scores**
- ◆ **V** (p x k)
 - **Loadings**
 - Principal component **coefficients**
 - Principal components

PCA minimizes Distortion

- ◆ First subtract off the average \bar{x} from all the x_i
 - From here, we'll assume this has been done
- ◆ Approximate x in terms of an orthonormal basis v
 - $\hat{x}_i = \sum_k z_{ik} v_k$ or $X = ZV^T$
- ◆ Distortion

$$\sum_{i=1}^n ||x^i - \hat{x}^i||_2^2 = \sum_{i=1}^n \sum_{j=1}^m (x_j^i - \hat{x}_j^i)^2.$$

PCA minimizes distortion

$$\begin{aligned}\text{Distortion}_k &: \sum_{i=1}^n \sum_{j=k+1}^m \mathbf{u}_j^\top (\mathbf{x}^i - \bar{\mathbf{x}})(\mathbf{x}^i - \bar{\mathbf{x}})^\top \mathbf{u}_j \\ &= \sum_{j=k+1}^m \mathbf{u}_j^\top \left(\sum_{i=1}^n (\mathbf{x}^i - \bar{\mathbf{x}})(\mathbf{x}^i - \bar{\mathbf{x}})^\top \right) \mathbf{u}_j \\ &= n \sum_{j=k+1}^m \mathbf{u}_j^\top \Sigma \mathbf{u}_j = n \sum_{j=k+1}^m \lambda_j\end{aligned}$$

See the course wiki!

PCA maximizes variance

$$\begin{aligned}\text{Variance}_k &: \sum_{i=1}^n \sum_{j=1}^k (\mathbf{u}_j^\top \mathbf{x}^i - \mathbf{u}_j^\top \bar{\mathbf{x}})^2 \\ &= \sum_{j=1}^k \mathbf{u}_j^\top \left(\sum_{i=1}^n (\mathbf{x}^i - \bar{\mathbf{x}})(\mathbf{x}^i - \bar{\mathbf{x}})^\top \right) \mathbf{u}_j \\ &= n \sum_{j=1}^k \mathbf{u}_j^\top \Sigma \mathbf{u}_j.\end{aligned}$$

See the course wiki!

PCA - Summary

$$\hat{\mathbf{x}}^i = \mathbf{x}^i = \bar{\mathbf{x}} + \sum_{j=1}^m z_j^i \mathbf{u}_j$$

$$\text{Variance}_k + \text{Distortion}_k = n \sum_{j=1}^m \lambda_j$$

See the course wiki!

Principal Component Analysis

$$\mathbf{X} \rightarrow \mathbf{X}_c = \mathbf{UDV}^T = \mathbf{ZV}^T$$

\mathbf{X}_c is $(n \times p)$, \mathbf{Z} is $(n \times p)$, \mathbf{V} is $(p \times p)$.

\mathbf{Z} is the transformation of \mathbf{X} into “PC space”

Column vector \mathbf{z}_i is the i 'th *PC score vector*.

Column vector \mathbf{v}_i is the i 'th *PC direction or loading*.

Since \mathbf{V} is orthogonal, $\mathbf{X}_c \mathbf{V} = \mathbf{ZV}^T \mathbf{V} = \mathbf{Z}$, and therefore:

$$\mathbf{z}_i = \mathbf{X}_c \mathbf{v}_i = \mathbf{u}_i D_{ii}$$

Hence \mathbf{z}_i is the projection of the row vectors of \mathbf{X}_c on the (unit) direction \mathbf{v}_i , scaled by D_{ii} .

Principal Component Analysis

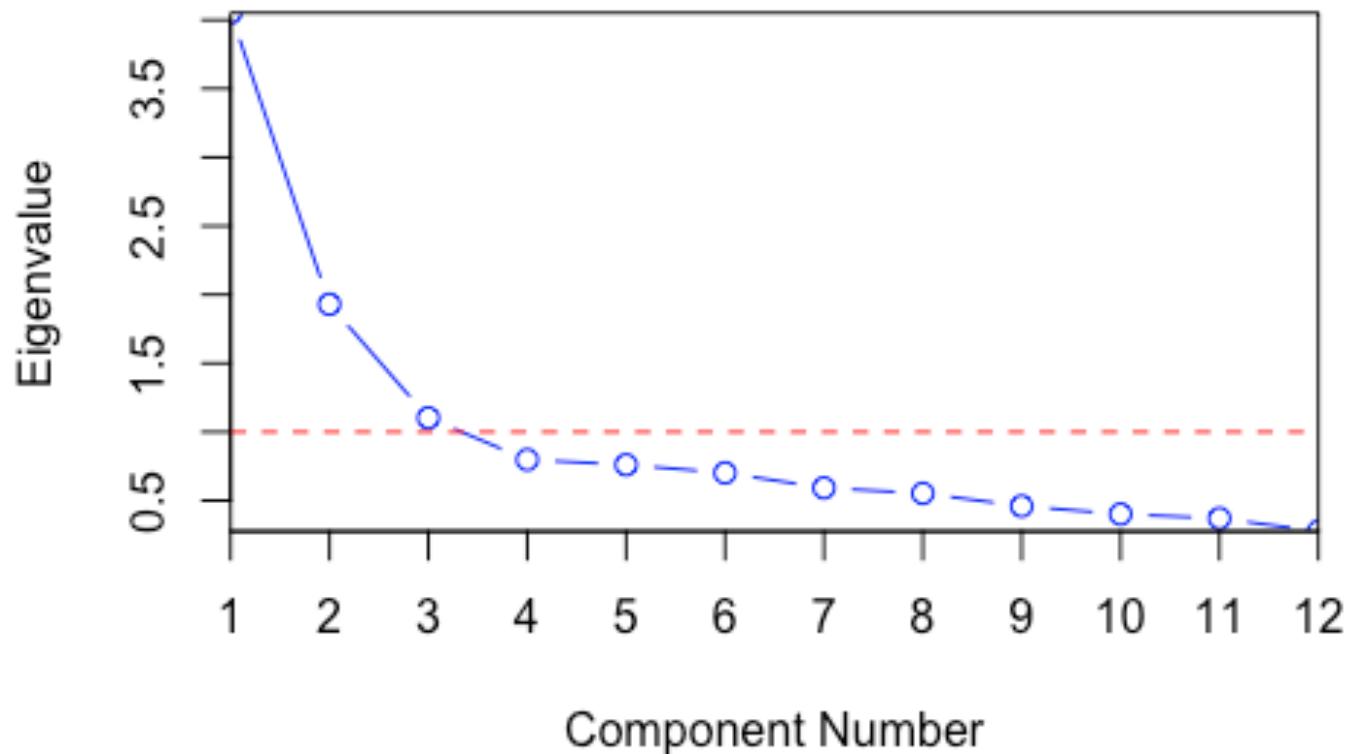
$$\mathbf{X} \rightarrow \mathbf{X}_c = \mathbf{UDV}^T = \mathbf{ZV}^T$$

$$\mathbf{X}_c^T \mathbf{X}_c = \sum_{i=1}^p (D_{ii})^2 \mathbf{v}_i \mathbf{v}_i^T$$

“% Variance explained by the i'th principal component:”

$$= 100 \cdot \frac{(D_{ii})^2}{\sum_{j=1}^p (D_{jj})^2} = 100 \lambda_i / \sum_i \lambda_i$$

Scree plot



Keep components
about the “elbow”

[https://en.wikipedia.org/
wiki/Scree_plot](https://en.wikipedia.org/wiki/Scree_plot)

PCA

True or false:

If X is any matrix, and X has singular value decomposition $X = UDV^T$
then the principal component scores for X are the columns of

$$Z = UD$$

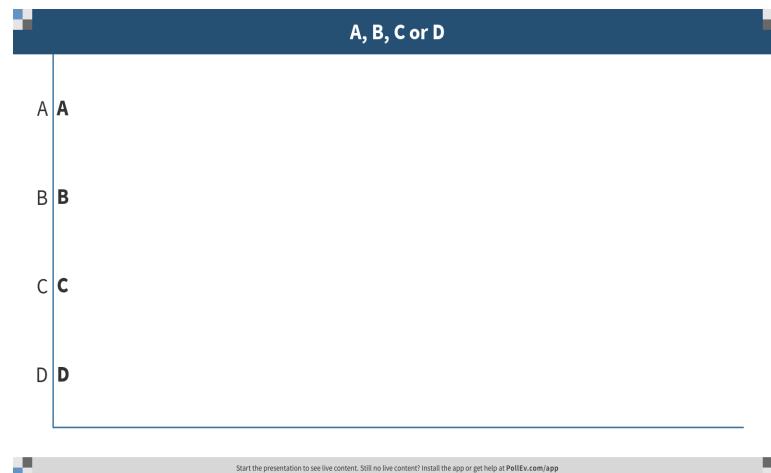
- a) True
- b) False



PCA

If X is mean-centered, then PCA finds...?

- (a) Eigenvectors of $X^T X$
- (b) Right singular vectors of X
- (c) Projection directions of maximum covariance of X
- (d) All of the above



PCA: Reconstruction Problem

PCA can be viewed as an L₂ optimization, minimizing distortion, the reconstruction error.

$$Z^*, V^* = \underset{\substack{Z \in \mathbb{R}^{n \times k}, V \in \mathbb{R}^{p \times k}, \\ v_i^T v_j = \delta_{ij}}}{\operatorname{argmin}} |X_c - ZV^T|_F$$

Here we have constrained Z , V by dimension:

X_c is still $(n \times p)$.

Z is $(n \times k)$, with $k \leq p$.

V is $(p \times k)$.

If $k=p$ then the reconstruction is perfect. $k < p$, not.

PCA via SVD

◆ $\mathbf{X} = \mathbf{ZV}' = \mathbf{UDV}'$

- \mathbf{X} n x p \mathbf{U} n x k \mathbf{D} k x k \mathbf{V}' k x p

◆ $\mathbf{Z} = \mathbf{UD}$ - component scores or "factor scores"

- the transformed variable values corresponding to a particular data point

◆ \mathbf{V}' - loadings

- the weight by which each standardized original variable should be multiplied to get the component score

PCA via SVD

- ◆ $x_i = \sum_k z_{ik} v_k$
- ◆ What is z_{ik} ?
 - $x_i = \sum_k u_{ik} d_{kk} v_k$

Sparse PCA

- ◆ $\operatorname{argmin}_{Z,V} \|X - ZV'\|_2$
 - $v_i'v_j = \delta_{ij}$ (orthonormality)
- ◆ with constraints
 - $\|v_i\|_1 < c_1$ for $i = 1 \dots k$
 - $\|z_i\|_1 < c_2$ for $i = 1 \dots k$
- ◆ or you can view this as a penalized regression – using Lagrange multipliers
- ◆ or you can use an L_1 penalty

PCR: Principal Component Regression

PCR has two steps:

1. Do a PCA on X to get component scores Z
2. Do OLS regression using Z as features

$$y = w'z$$

PCR

◆ How to find z for a new x?

- $X = ZV'$

◆ $xV = z$ $V'V = I$

$$\begin{matrix} V & p \times k \\ V'V = I & k \times k \end{matrix}$$

$$\begin{matrix} x & 1 \times p \\ z & 1 \times k \end{matrix}$$

PCR: Principal Component Regression

$$\mathbf{X} \rightarrow \mathbf{X}_c = \mathbf{ZV}^T$$

The columns $\mathbf{z}_1, \dots, \mathbf{z}_k$ can be used as features in supervised learning.

Ex: linear regression. Given training \mathbf{X} and \mathbf{Y} ,

$$w^* = \underset{w \in \mathbb{R}^p}{\operatorname{argmin}} \|Y - Zw\|_2^2$$

If $k=p$: result is the *same* as linear regression with \mathbf{X}, \mathbf{Y}

If $k < p$: this is a form of *regularized* linear regression

So is ridge regression! How are PCR and Ridge fundamentally different?

What you should know

- ◆ PCA as minimum reconstruction error ('distortion')
- ◆ PCA as finding direction of maximum covariance
- ◆ Sensitivity of PCA to standardizing
- ◆ Nomenclature: scores, coefficients/loadings
- ◆ Coming next: autoencoders, eigenfaces, eigenwords