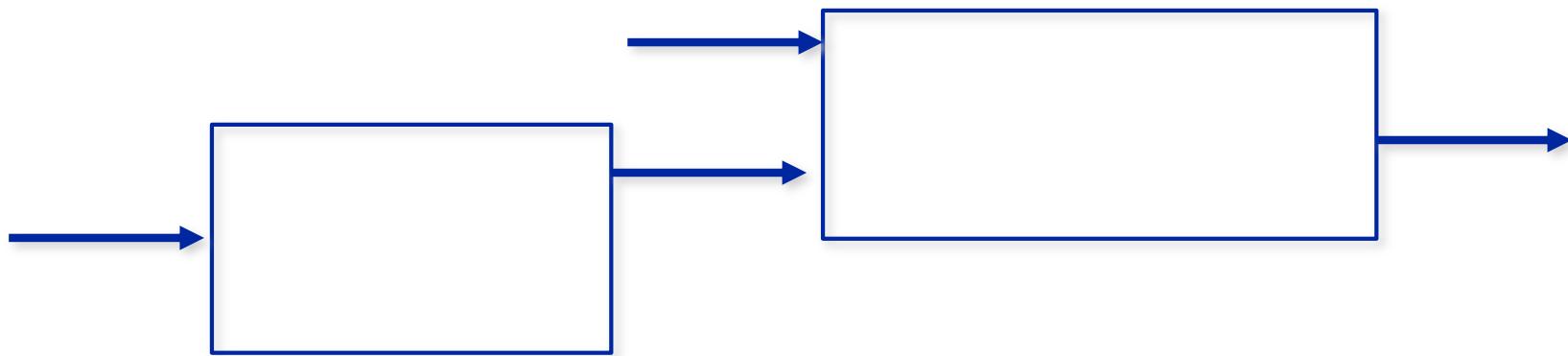


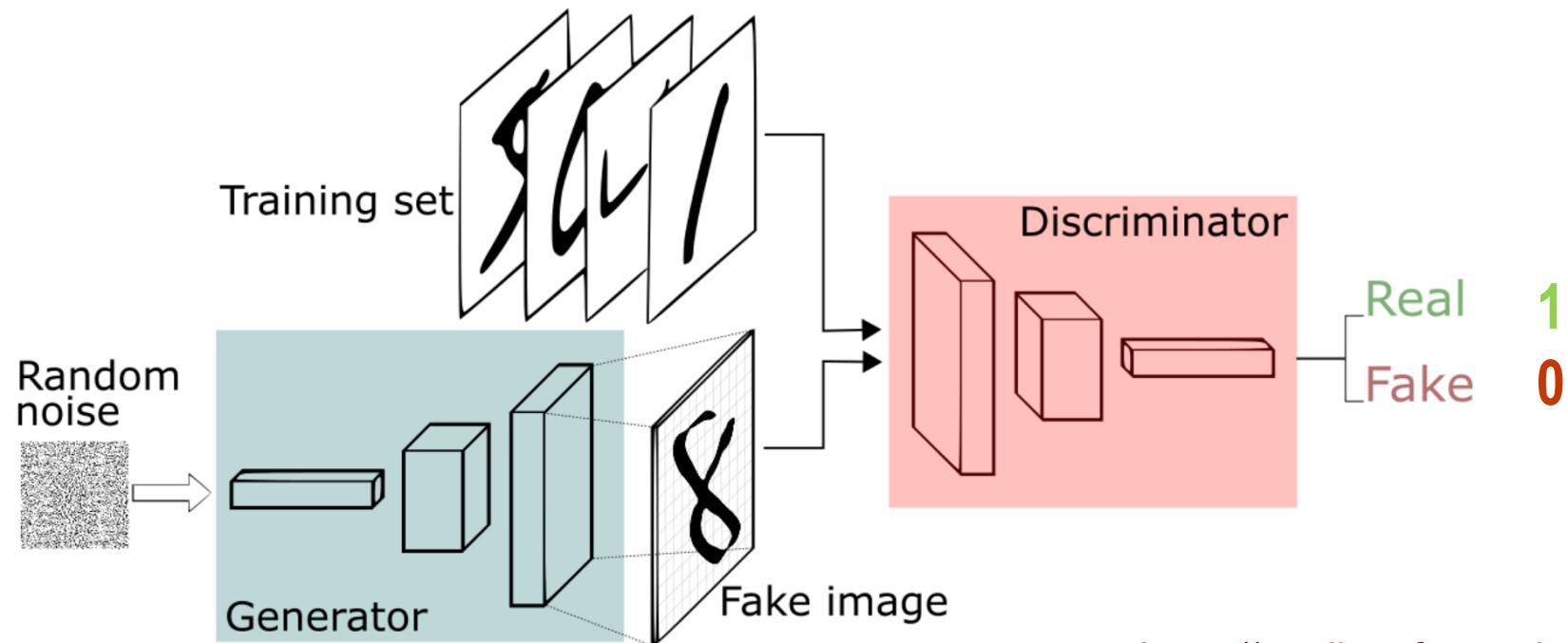
Midterm Review

2019

GANS



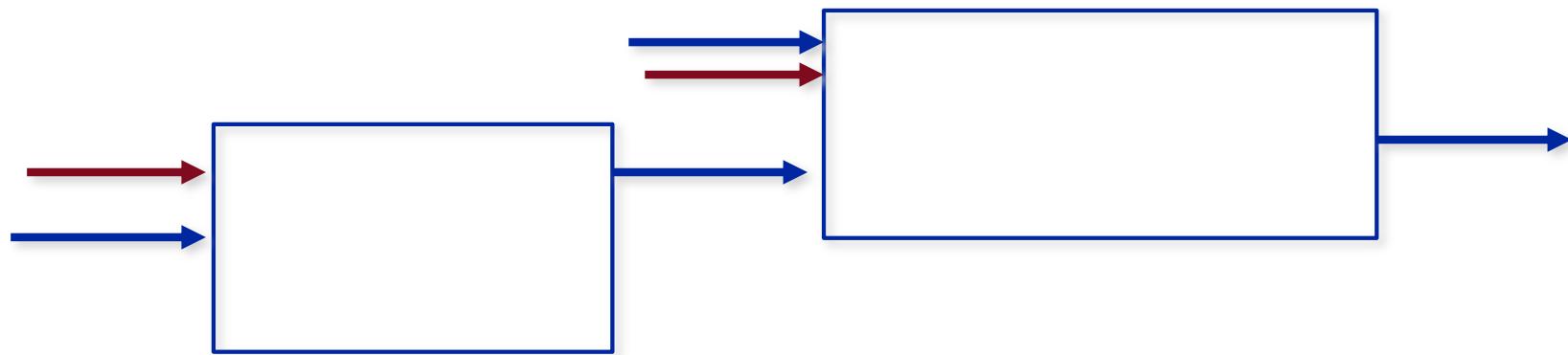
Generative Adversarial Networks: GANS



$$G: \operatorname{argmin} \log(1 - D(G(\text{noise})))$$

[https://medium.freecodecamp.org/
an-intuitive-introduction-to-
generative-adversarial-networks-
gans-7a2264a81394](https://medium.freecodecamp.org/an-intuitive-introduction-to-generative-adversarial-networks-gans-7a2264a81394)

Conditional GANS



CNN

Input Volume (+pad 1) (7x7x3)

| $x[:, :, 0]$ |
|---------------|
| 0 0 0 0 0 0 0 |
| 0 0 2 0 1 1 0 |
| 0 0 2 1 0 0 0 |
| 0 0 2 1 0 2 0 |
| 0 2 1 1 2 1 0 |
| 0 0 2 2 2 0 0 |
| 0 0 0 0 0 0 0 |

| $x[:, :, 1]$ |
|---------------|
| 0 0 0 0 0 0 0 |
| 0 1 0 1 0 1 0 |
| 0 0 2 0 1 2 0 |
| 0 1 1 2 2 2 0 |
| 0 1 0 2 0 1 0 |
| 0 0 0 0 0 2 0 |
| 0 0 0 0 0 0 0 |

Filter W0 (3x3x3)

| $w0[:, :, 0]$ |
|---------------|
| -1 1 0 |
| 1 0 1 |
| -1 -1 -1 |
| 1 -1 0 |
| 1 -1 1 |
| 1 1 -1 |

| $w0[:, :, 1]$ |
|---------------|
| 1 1 -1 |
| 1 -1 0 |
| -1 -1 -1 |

| $w0[:, :, 2]$ |
|---------------|
| 1 1 -1 |
| 1 -1 0 |
| 1 1 -1 |
| 1 1 -1 |

Bias b0 (1x1x1)

| $b0[:, :, 0]$ |
|---------------|
| 1 |

Filter W1 (3x3x3)

| $w1[:, :, 0]$ |
|---------------|
| -1 1 -1 |
| 1 1 0 |
| -1 0 -1 |
| 3 0 0 |

| $w1[:, :, 1]$ |
|---------------|
| 1 0 1 |
| -1 -1 0 |
| 1 -1 0 |

| $w1[:, :, 2]$ |
|---------------|
| -1 1 -1 |
| 0 -1 -1 |
| 1 1 -1 |

Bias b1 (1x1x1)

| $b1[:, :, 0]$ |
|---------------|
| 0 |

Output Volume (3x3x2)

| $o[:, :, 0]$ |
|--------------|
| -4 -6 -2 |
| -1 -5 -2 |
| 3 0 0 |
| -1 0 0 |
| -4 -6 0 |
| -2 -3 -2 |

| $o[:, :, 1]$ |
|--------------|
| -1 0 0 |
| -1 -1 0 |
| 1 -1 0 |



Information and friends

- ◆ Entropy of the expected value of _____
- ◆ KL divergence is the expected value of _____
- ◆ Information gain is the difference between _____

Kullback Leibler divergence

- ◆ P = true distribution;
- ◆ Q = alternative distribution that is used to encode data
- ◆ KL divergence is the expected extra message length per datum that must be transmitted using Q

$$\begin{aligned} D_{\text{KL}}(P \parallel Q) &= \sum_i P(x_i) \log (P(x_i)/Q(x_i)) \\ &= - \sum_i P(x_i) \log Q(x_i) + \sum_i P(x_i) \log P(x_i) \\ &= H(P, Q) && - H(P) \\ &= \text{Cross-entropy} && - \text{entropy} \end{aligned}$$

$$D(p(\theta | x, x') \parallel p(\theta | x))$$

- ◆ Measures how different the two distributions are

Scale invariance

- ◆ Decision tree?
- ◆ k-nn?
- ◆ OLS?
- ◆ Elastic net?
- ◆ L_0 penalized regression?
- ◆ SVM?

k-class logistic regression

$$P(Y = k | \mathbf{x}, \mathbf{w}) = \frac{\exp\{\mathbf{w}_k^\top \mathbf{x}\}}{\sum_{k'=1}^K \exp\{\mathbf{w}_{k'}^\top \mathbf{x}\}}, \quad \text{for } k = 1, \dots, K$$

Prediction: $y = \operatorname{argmax}_k (\mathbf{w}_k^\top \mathbf{x})$

Kernel functions $k(\mathbf{x}_1, \mathbf{x}_2)$

- ◆ Measure similarity or distance?
- ◆ How to check if something is a kernel function?
 - Compute a Kernel matrix with elements $k(\mathbf{x}_i, \mathbf{x}_j)$
 - Make sure its eigenvalues are non-negative
- ◆ Example: $k(\mathbf{x}_i, \mathbf{x}_j) = x_{i1} + x_{i2} + x_{j1} + x_{j2}$
 - Try the single point $\mathbf{x} = (1, -2)$
 - $K(\mathbf{x}, \mathbf{x}) = 1-2+1-2 = [-3]$ which is a matrix with eigenvalue -3