

# Midterm feedback

- ◆ Welcome back!
- ◆ OSC: Don't copy HW!!!
- ◆ Midterm: returned today

# Survey results

- Consistent notation; correct quiz answers
- More depth (math and application); more intuition & derivation
  - Recitation as review; no new material
  - Too much math in HW; too little in lecture
- Slides and lecture notes more complete
- Too fast
- HW: too much; not clear enough; too many errors
  - Autograder; Output shape for programming problems
  - Ask for more explanation
- Faster piazza response time

# Unsupervised Learning

- ◆ **Spectral methods**

- Eigenvector/singular vector decomposition (SVD)
- PCA, CCA

- ◆ **Reconstruction methods**

- PCA, ICA, auto-encoders

- ◆ **Clustering and Probabilistic methods**

- K-means
- Gaussian mixtures
- Latent Dirichlet Allocation (LDA)

# SVD

**Learning objectives**  
*SVD and ‘thin SVD’*  
*Matrix norms*  
*Generalized inverses*

Lyle Ungar

# Eigenvectors (review)

- ◆  $\mathbf{A} \mathbf{v}_i = \lambda_i \mathbf{v}_i$
- ◆ Eigen-decomposition of a symmetric matrix  $\mathbf{A}$  ( $n \times n$ )
  - $\mathbf{A} = \mathbf{V}\mathbf{D}\mathbf{V}^T$
- ◆  $\mathbf{V}$ : orthogonal,  $\mathbf{V}^T\mathbf{V}=\mathbf{I}$  ( $n \times n$ )
  - Columns of  $\mathbf{V}$  are the *eigenvectors of A*
- ◆  $\mathbf{D}$ : diagonal ( $n \times n$ )
  - Diagonal elements of  $\mathbf{D}$  are the *eigenvalues of A*
  - All non-negative if  $\mathbf{A} = \mathbf{X}^T\mathbf{X}$
  - Reported in *decreasing* order of magnitude down the diagonal

# We don't compute eigenvectors

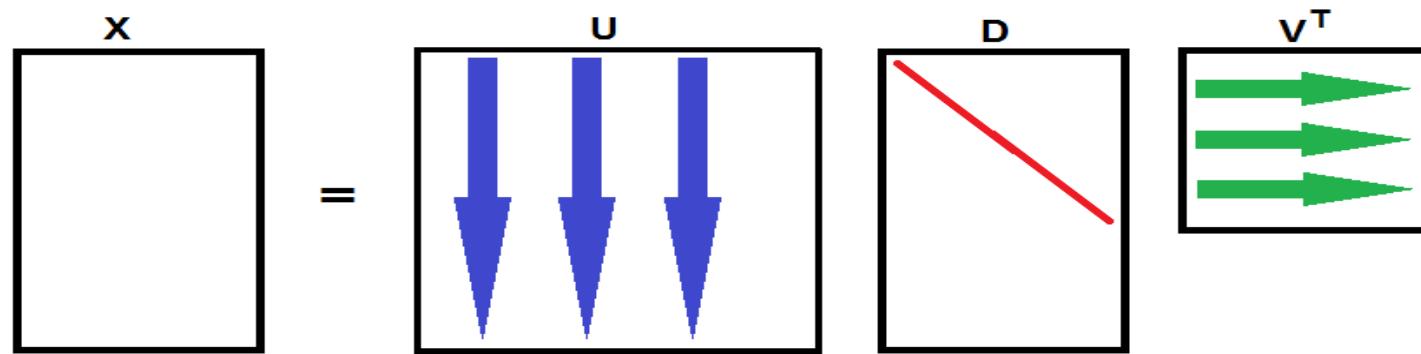
- ◆ What symmetric matrix have we seen?
- ◆ In practice we rarely compute eigenvectors
  - Why not?

# Singular Value Decomposition

- ◆ Singular value decomposition of matrix  $X$  ( $n \times p$ )
  - $X = UDV^T$
- ◆  $U$ : orthogonal,  $U^T U = I$  ( $n \times n$ )
  - Columns of  $U$  are the *left singular vectors of  $X$*
- ◆  $D$ : diagonal ( $n \times p$ )
  - Diagonal elements of  $D$  are the *singular values of  $X$*
- ◆  $V$ : orthogonal,  $V^T V = I$  ( $p \times p$ )
  - Columns of  $V$  are the *right singular vectors of  $X$*

# SVD

Singular value decomposition of  $\mathbf{X}$ :  $\mathbf{X} = \mathbf{U}\mathbf{D}\mathbf{V}^T$



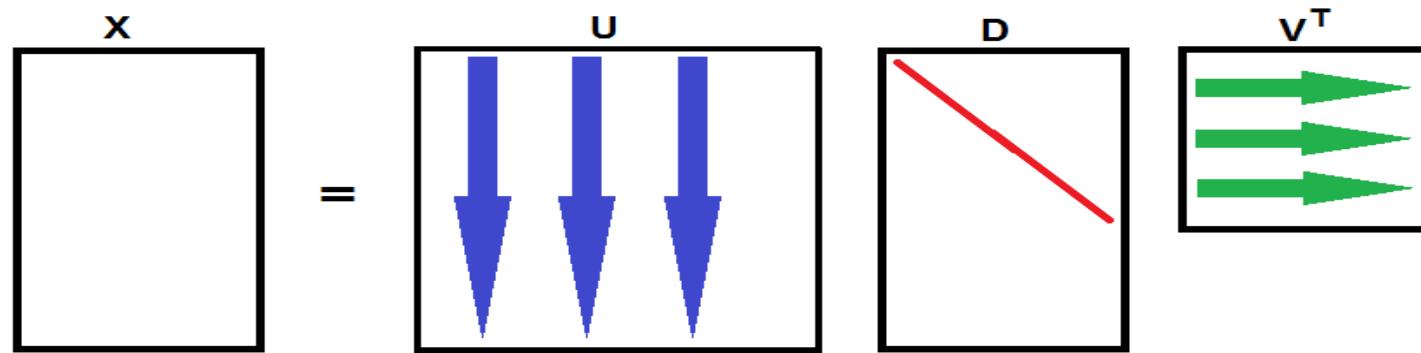
$$\text{Let } k = \min(n, p). \text{ Then: } \mathbf{X} = \sum_{i=1}^k D_{ii} \mathbf{u}_i \mathbf{v}_i^T$$

Since all  $\mathbf{u}_i, \mathbf{v}_i$  are unit vectors, the importance of the  $i$ 'th term in the sum is determined by the size of  $D_{ii}$ .

- ◆  $X_{n \times p} = U D V^T$
- ◆ What are the dimensions of  $U$   $D$  and  $V$ ?
- ◆ What are the eigenvectors of  $X^T X$ ?
- ◆ What are the eigenvalues of  $X^T X$ ?

# Thin SVD – pick a smaller k

Singular value decomposition of X:  $\mathbf{X} = \mathbf{UDV}^T$



Let  $k = \min(n,p)$ . Then:  $\mathbf{X} = \sum_{i=1}^k D_{ii} \mathbf{u}_i \mathbf{v}_i^T$

Since all  $\mathbf{u}_i, \mathbf{v}_i$  are unit vectors, the importance of the  $i$ 'th term in the sum is determined by the size of  $D_{ii}$ .

# SVD and eigenvalues/eigenvectors

$$\mathbf{X} = \mathbf{U}\mathbf{D}\mathbf{V}^T, \quad \mathbf{X}^T\mathbf{X} = \mathbf{V}(\mathbf{D}^T\mathbf{D})\mathbf{V}^T$$

The columns  $\mathbf{v}_1, \dots, \mathbf{v}_p$  of  $\mathbf{V}$  are the *eigenvectors* of the covariance matrix  $\mathbf{X}^T\mathbf{X}$ . Hence we can write

$$\mathbf{X}^T\mathbf{X} = \sum_{i=1}^p (D_{ii})^2 \mathbf{v}_i \mathbf{v}_i^T$$

From before:

$$\mathbf{X} = \sum_{i=1}^k D_{ii} \mathbf{u}_i \mathbf{v}_i^T$$

$k = \min(n, p)$ .

$D_{ii}$  are singular values of  $\mathbf{X}$ ,  $(D_{ii})^2$  are eigenvalues of  $\mathbf{X}^T\mathbf{X}$

# Frobenius norm

- ◆ How to measure the size of a matrix?

$$\|A\|_F = \sqrt{\sum_{i=1}^m \sum_{j=1}^n |a_{ij}|^2} = \sqrt{\text{trace}(A^\dagger A)} = \sqrt{\sum_{i=1}^{\min\{m,n\}} \sigma_i^2(A)}$$

- ◆ Where  $\sigma_i$  are the singular values.
- ◆ One can also use an  $L_1$  norm  $\|A\|_1 = \|\sigma\|_1$

# Generalized Inverses

- ◆ Linear regression estimates  $w$  in  $y = Xw$
- ◆ This uses a pseudo-inverse (“Moore-Penrose inverse”)  $X^+$  of  $X$ , so
  - $w = X^+y$
- ◆ Thus far, we have done this by
  - $X^+ = (X^T X)^{-1} X^T$

# Generalized Inverses

- ◆ We can also compute inverses using SVD
- ◆ The idea:

$$X^+ = (U\Lambda^{-1}V^T)^T = V\Lambda^{-1}U^T$$

- ◆ You can't take the inverse of a rectangular matrix, but we can approximate it using the thin SVD

$$X^+ = V_k \Lambda_k^{-1} U_k^T |$$

# Pseudo-inverse of $X = U D V^T$

- ◆ What are the dimensions of  $X^+ = V D^{-1} U^T$
- ◆ What is  $X X_k^+$ 
  - $X X^+ = U D V^T V D^{-1} U^T$

# Power Method

## ◆ Power method for a square matrix A

- Write any  $\mathbf{x} = \sum_i z_i \mathbf{v}_i$  where  $z_i = \mathbf{v}_i^T \mathbf{x}$
- Then  $A\mathbf{x} = A \sum_i z_i \mathbf{v}_i = \sum_i z_i A \mathbf{v}_i = \sum_i z_i \lambda_i \mathbf{v}_i$
- So  $A^4 \mathbf{x} = A^4 \sum_i z_i \lambda_i^4 \mathbf{v}_i$

## ◆ Find the largest eigenvalue/eigenvector

- Project it off from  $\mathbf{x}$  and repeat
  - $\mathbf{x} := \mathbf{x} - (\mathbf{v}_1^T \mathbf{x}) \mathbf{v}_1$

# Fast ‘Randomized’ SVD

- ◆ Generalizes the power method
- ◆ Input:
  - matrix  $A$  of size  $n \times p$ ,
  - the desired hidden state dimension  $k$ ,
  - the number of “extra” singular vectors,  $l$
- ◆ Simultaneously find all the largest singular values/vectors by alternately left and right multiplying by  $A$

# Randomized SVD

1. Generate a  $(k + l) \times n$  random matrix  $\Omega$
2. Find the SVD  $U_1 D_1 V_1^T$  of  $\Omega A$ , and keep the  $k + l$  components of  $V_1$  with the largest singular values
3. Find the SVD  $U_2 D_2 V_2^T$  of  $A V_1$ , and keep the ‘largest’  $k + l$  components of  $U_2$
4. Find the SVD  $U_3 D_3 V_{final}^T$  of  $U_2^T A$ , and keep the ‘largest’  $k$  components of  $V_{final}$
5. Find the SVD  $U_{final} D_4 V_4^T$  of  $A V_{final}$  and keep the ‘largest’  $k$  components of  $U_{final}$

**Output:** The left and right singular vectors  $U_{final}$ ,  $V_{final}^T$

You are not required to know this

# What you should know

- ◆ Eigenvalues/vectors & singular values/vectors
- ◆ Eigenvectors as a basis
- ◆ Thin SVD
- ◆ Frobenius norm
- ◆ Pseudo (“Moore-Penrose”) inverse
- ◆ Power method

## ◆ What is an efficient way to do linear regression?

- $w = (X^T X)^{-1} X^T y$
- How does it scale with n and p?