

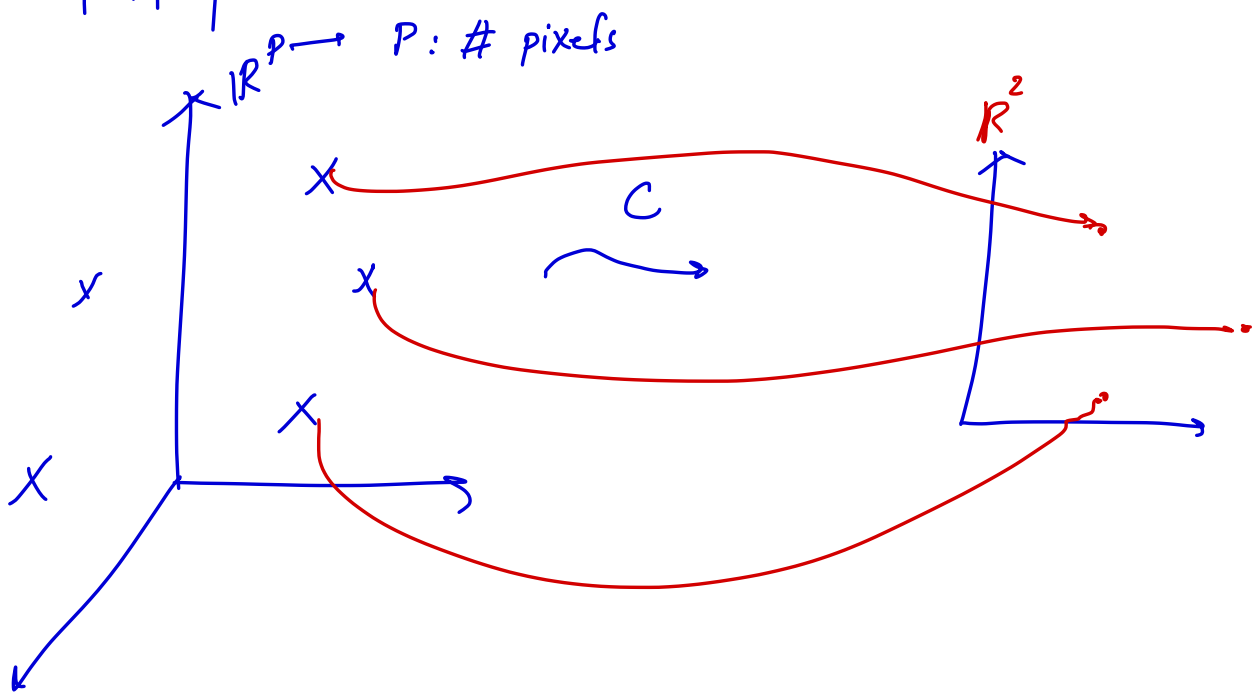
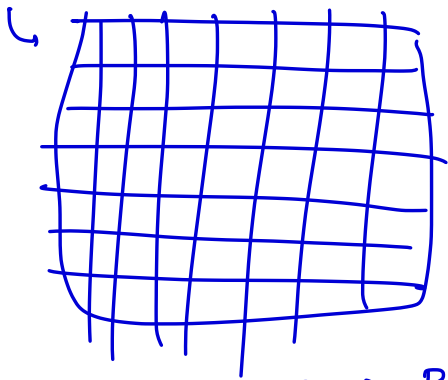
centers that have the best loss.

Lecture 20 :

unsupervised learning $\begin{cases} \text{clustering} \\ \text{dimensionality reduction} \end{cases}$
PCA

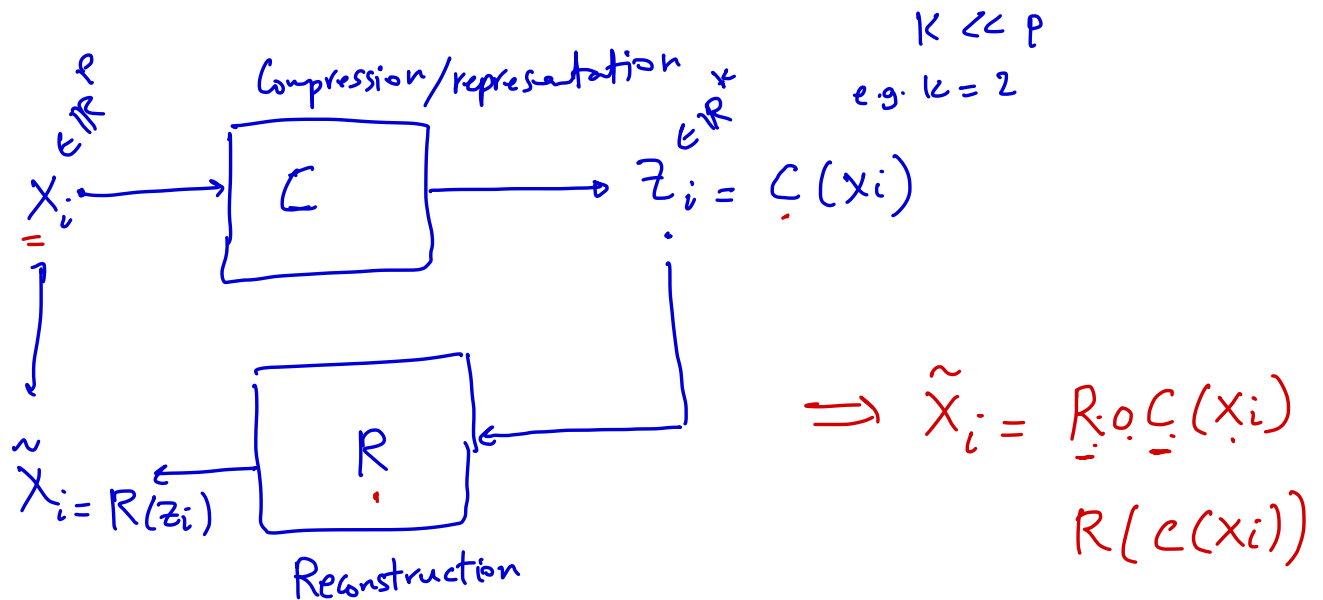
$\{x_1, x_2, \dots, x_n\}$

image



- $x_1, x_2, \dots, x_n \in \mathbb{R}^p$ (p is typically large)

- we'd like to represent the data in a low-dimensional space (e.g. \mathbb{R}^2)



Our goal is to design C, R such that x_i and \tilde{x}_i are as close as possible.

Objective:

$$\begin{aligned} & \text{Minimize}_{C, R} \sum_{i=1}^n \|x_i - \tilde{x}_i\|_2^2 \\ & = \text{Minimize}_{C, R} \sum_{i=1}^n \|x_i - R \circ C(x_i)\|_2^2 \end{aligned}$$

$$X_i = \begin{pmatrix} \vdots \end{pmatrix} \in \mathbb{R}^P \quad \xrightarrow{C} \quad z_i = C(X_i)$$

$$X_i \xrightarrow{C} \begin{pmatrix} 0 \\ 0 \end{pmatrix} = z_i$$

As usual, let's start with the simplest class of mappings which are linear mappings.

$$z_i = C(X_i) = \overset{\text{matrix}}{C} X_i \quad C = \begin{bmatrix} & \end{bmatrix}_{k \times P}$$

$$\text{e.g. } k=2 \rightarrow C = \begin{bmatrix} \text{---} \\ \text{---} \end{bmatrix}_{2 \times P}$$

$$= \begin{bmatrix} U_1^T \\ U_2^T \end{bmatrix}$$

$$\Rightarrow Z_i = C X_i = \begin{bmatrix} U_1^T X_i \\ U_2^T X_i \end{bmatrix}$$

Also, $R =$ linear mapping

$$\tilde{X}_i = R Z_i = \begin{bmatrix} R \cdot C \cdot X_i \end{bmatrix}$$

\downarrow \downarrow \downarrow
 $\in \mathbb{R}_{p \times k}$ $\in \mathbb{R}_{p \times k}$ $\in \mathbb{R}_{k \times p}$

objective: $\min \sum_{i=1}^n \|X_i - R \cdot C \cdot X_i\|_2^2$ (PCA)

R, C
 \downarrow \downarrow
 $\in \mathbb{R}_{p \times k}$ $\in \mathbb{R}_{k \times p}$

$C: \mathbb{R}^p \rightarrow \mathbb{R}^k$
 $C = (\text{matrix})_{k \times p}$

This problem is called the Principal Component Analysis (PCA)

In order to solve this problem, we need to review an important tool in linear algebra:

(this tool is important for many other branches of Data science)

The Singular Value Decomposition:

Theorem: Every symmetric matrix, A ,
can be written as

$$A = \underset{p \times p}{U}^T \underset{p \times p}{\Lambda} \underset{p \times p}{U}$$

- where $UU^T = I_{p \times p}$ identity matrix

$\Lambda = \text{diagonal:}$ $\begin{pmatrix} \lambda_1 & & 0 \\ & \lambda_2 & \\ 0 & & \ddots \\ & & & \lambda_n \end{pmatrix}$

- $A = U^T \cdot \begin{pmatrix} \lambda_1 & & 0 \\ & \lambda_2 & \\ 0 & & \ddots \\ & & & \lambda_n \end{pmatrix} U$

- $\lambda_1 \geq \lambda_2 \geq \lambda_3 \geq \dots \geq \lambda_n$

- $\lambda_i =$ eigenvalues of A .

- Each row of U is an "eigenvector" of the matrix A .

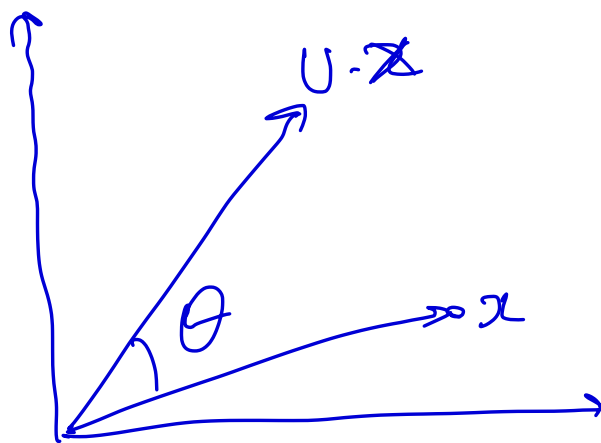
Example:

Assume A is 2×2 matrix.

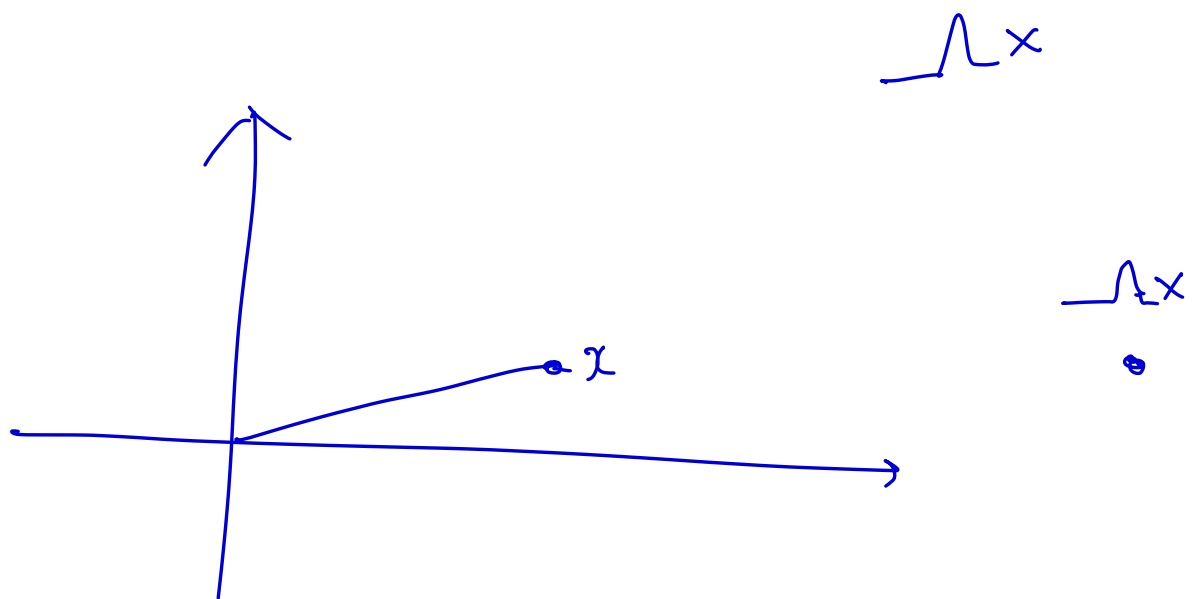
$$A = \begin{pmatrix} a & c \\ c & b \end{pmatrix} \quad \underbrace{\hspace{10em}}_{\text{rescaling}}$$

$$A = \underbrace{U}_{\text{Rotation}(\theta)} \cdot \underbrace{\begin{pmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{pmatrix}}_{\text{rescaling}} \cdot \underbrace{V^T}_{\text{Rotation}(-\theta)}$$

$$U \cdot U^T = I \rightarrow U = \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix}$$



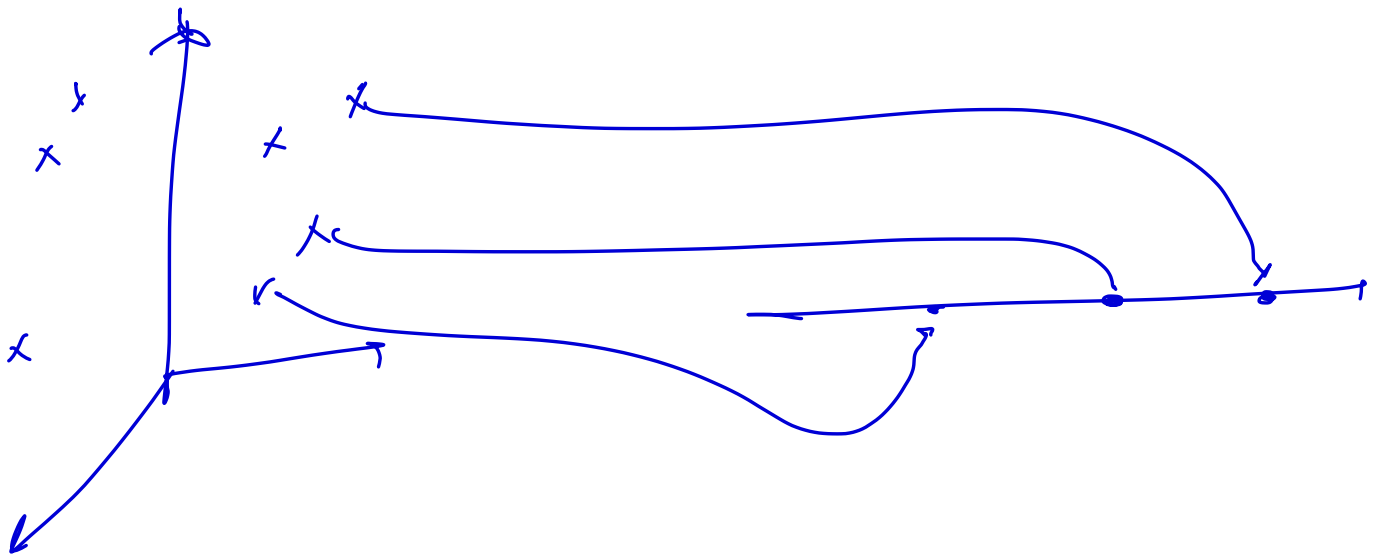
$$\Lambda = \begin{pmatrix} 4 = \lambda_1 \geq 0 & 0 \\ 0 & 1 = \lambda_2 \geq 0 \end{pmatrix} \quad \text{re Scaling}$$



$$A = \text{Rotation}(-\theta), \text{Rescaling}, \text{Rotation}(\theta)$$

let's go back to our problem.

let's assume for simplicity that $k=1$; we're looking for the best 1-dimensional representation of the data.

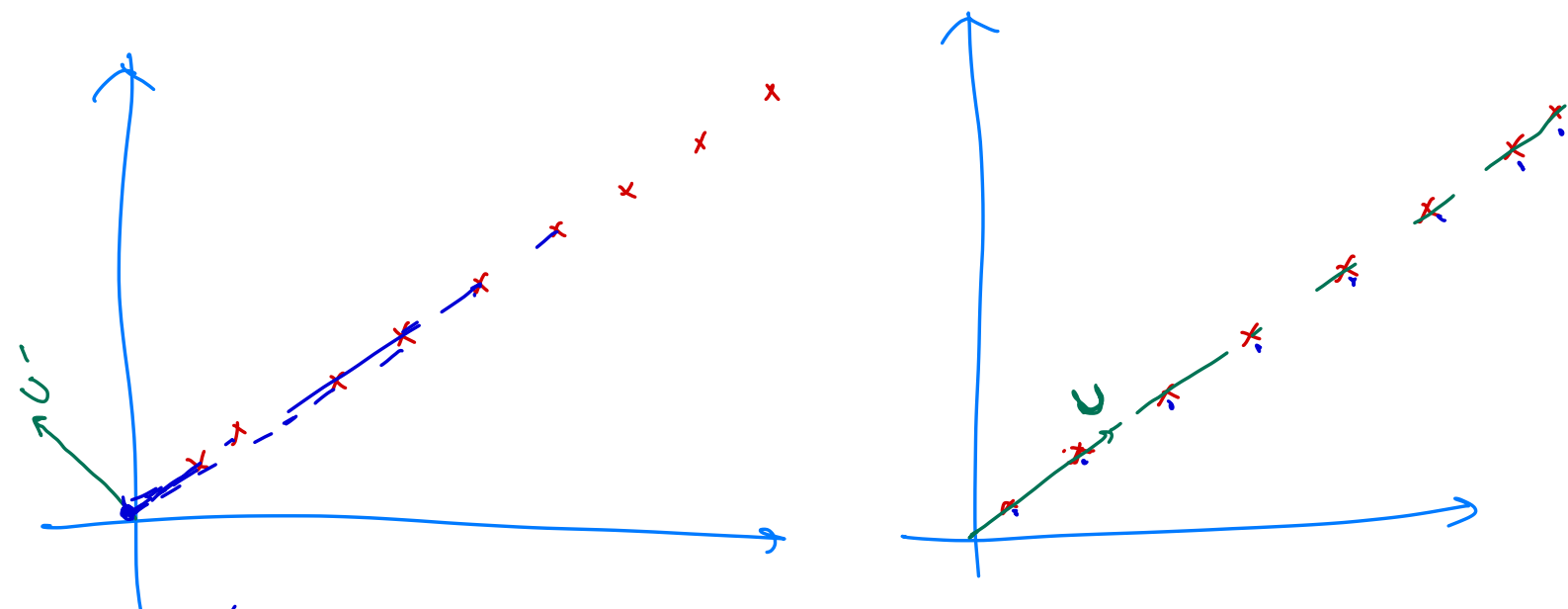


$$C = \begin{bmatrix} & \end{bmatrix}_{k \times p} \longrightarrow C = U^T$$

$$C \cdot X_i = \underbrace{U^T}_{\text{vector}} X_i$$

When $k=1$, our goal is to find a single vector U^T such that the representation $z_i = U^T X_i$ is "the most informative" representation.

Example:

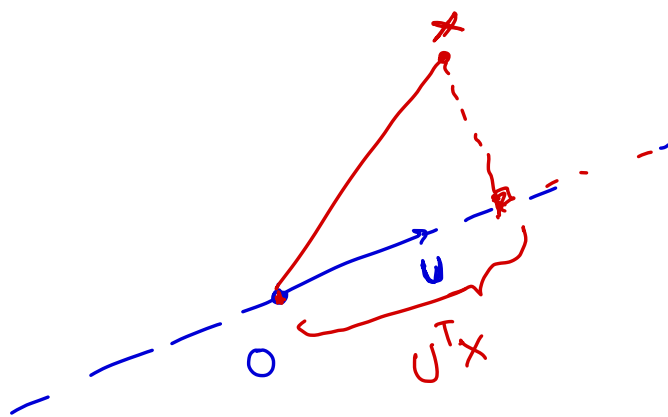


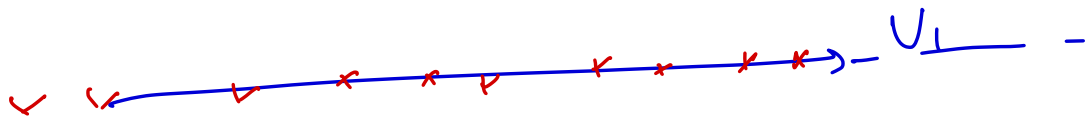
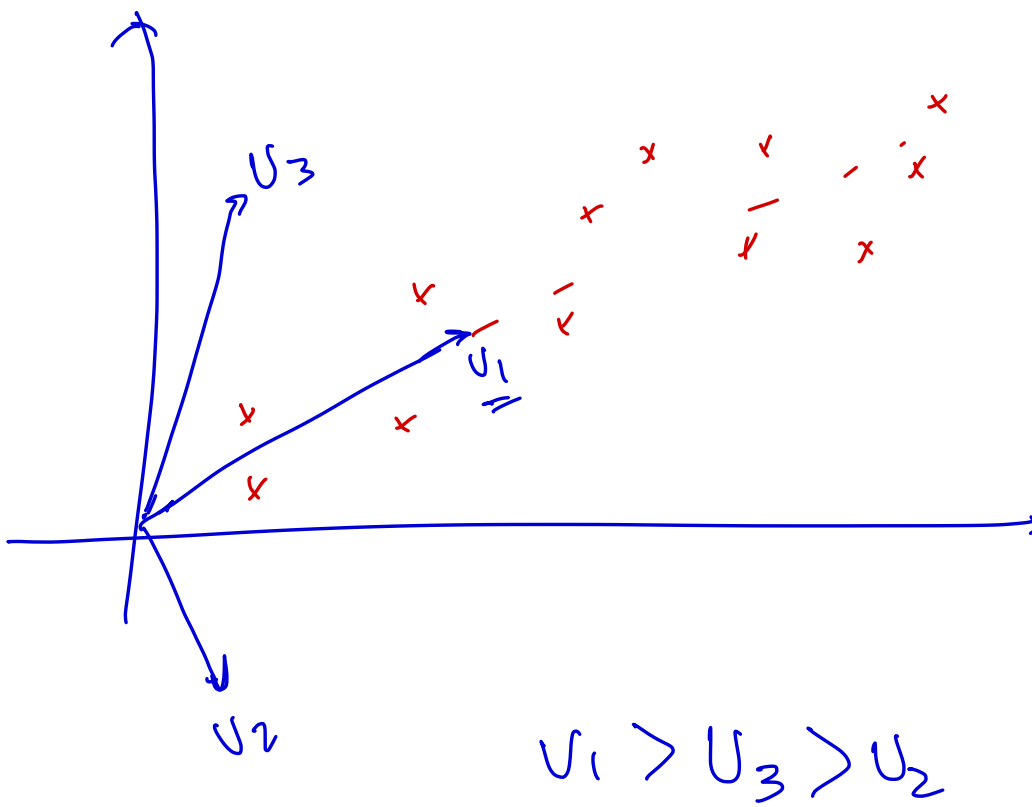
$$U'^T X_i \approx 0$$

$$U^T X_i$$

U is a better direction than U' in terms of capturing more information about the data

Assume $\|U\|_2 = 1$





We're looking for a direction U along which data has the most "variation".

- Mathematically, we're looking for a direction u such the "variance" of $u^T X$ is the most.
- Assume that the data comes from a distribution $X \sim P(X)$. Also assume for simplicity that $E[X] = 0$.

$$\begin{aligned}
 & \max_{\substack{u^T \in \mathbb{R}^{1 \times p} \\ \|u\|_2 = 1}} \text{Var}(u^T X) \\
 &= \max_{u: \|u\|_2 = 1} E[(u^T X)^2] \\
 &= \max_{u: \|u\|_2 = 1} E[u^T X^T X u] \\
 &= \max_{u: \|u\|_2 = 1} u^T \underbrace{E[XX^T]}_{\substack{\text{Covariance} \\ \text{matrix of} \\ \text{the data}}} u
 \end{aligned}$$

$$\left(\begin{array}{l} X \in \mathbb{R}^p \\ E[XX^T] \\ = \sum_{p \times p} \end{array} \right)$$

$$\text{Let } \Sigma \triangleq E[xx^T]$$

$$= \max_u u^T \Sigma u$$

$$u:$$

$$\|u\|_2 = 1$$

The solution of the problem above can be found from the singular value decomposition of Σ .

$$\Lambda = \begin{pmatrix} \lambda_1 & & 0 \\ & \lambda_2 & \\ 0 & & \ddots \\ & & & \lambda_p \\ & & & & 0 \end{pmatrix}$$

$$\lambda_1 \geq \lambda_2 \geq \dots \geq \lambda_p$$

$$\text{SVD} \rightarrow \underline{\Sigma} = \underline{U} \Lambda U$$

It can be shown the the first row of the matrix U , is the maximizer of the following problem:

$$\max_u u^T \Sigma u$$

$$u: \|u\|_2 = 1$$

$$U = \begin{pmatrix} \boxed{u_1^T} \\ u_2^T \\ \vdots \\ u_p^T \end{pmatrix}_{p \times p}$$

- u_1^T is the solution to the problem above.
- u_1^T is the principal component of the data

- v_i^T is the vector along which the data has the most "variation".

$$\Sigma = E[X X^T]$$

- We know that the data

$$X_1, X_2, \dots, X_n \stackrel{\text{iid}}{\sim} \text{distribution } X \sim P(X)$$

in practice:

- We cannot compute the matrix Σ because we do not know the distribution of the data

$$\Sigma \approx \underbrace{\frac{1}{n} \sum_{i=1}^n X_i X_i^T}_{\text{unbiased estimator}}$$

Algorithm (PCA) : ($k=1$)

- Input: $X_1, X_2, \dots, X_n \in \mathbb{R}^p$
- Compute the empirical covariance matrix of data:
$$\hat{\Sigma} = \frac{1}{n} \sum_{i=1}^n X_i X_i^T$$
- Compute the Singular value decomposition of $\hat{\Sigma}$:

$$\hat{\Sigma} = U \Lambda U^T$$

- Use the first row of U , u_1 , as the principal component of the data:

$$Z_i = u_1^T X_i.$$

* let's now find the best 2-dimensional representation of the data.

$$\rightarrow \max_{u_1, u_2} u_1^T \Sigma u_1 + u_2^T \Sigma u_2$$

$$\|u_1\|, \|u_2\| = 1$$

$$(\text{orthogonal}) \quad u_1^T u_2 = 0$$

It can be shown that u_1, u_2 are the first two rows of the matrix U .

* In general if we want to find a matrix $C = \begin{bmatrix} u_1^T \\ u_2^T \\ \vdots \\ u_k^T \end{bmatrix}_{k \times n}$ then

we need to solve the following optimization problem:

Cumulative variance of the data along the directions u_1, \dots, u_k \leftarrow

$$\sum_{i=1}^k u_i^T \Sigma u_i$$

s.t. $\|u_i\| = 1$
and $u_i^T u_j = 0$ for $i \neq j$

It can be shown that the solution to the above optimization problem is the first k rows of the matrix U .

Algorithm PCA for general k :

- Input : $X_1, \dots, X_n \in \mathbb{R}^p$

- Compute: $\hat{\Sigma} = \frac{1}{n} \sum_{i=1}^n X_i X_i^T$

- Compute: (SVD) $\hat{\Sigma} = U^T \Lambda U$

- $C = \begin{bmatrix} U_1^T \\ U_2^T \\ \vdots \\ U_k^T \end{bmatrix}$ where U_1, \dots, U_k are the first k rows of the matrix U .

It can be proven that PCA gives the optimal linear representation of the data (it solves equation (PCA) exactly).