

# Lecture 11

C pointers and Arrays /  
Event-based programming

# Agenda

- 01. Pointers/Arrays – continued –
- 02. Events and Services Framework
- 03. Finite State Machines

# Stuff

## Parts fabrication:

- Parts are being fabricated for you by the TA's:
  - Pros: you don't have to spend hours at the machines to do this
  - Cons: you aren't learning how to use these machines
- There may be limited opportunities for those submitting late or doing a 2<sup>nd</sup> iteration. Each iteration will count as 1 late day.
- It's easier if you submit one DWG file with multiple parts rather than many separate DWG files.
- 3D printing is slower than expected (not sure about our machine allocation)

# C can be an obscure language

```
int a[4<<9],i;main(){for(a[40]=1;i++<1620;
printf(i%80?"%c":"\n",".oO"
[a[i]&3]),a[i+79]+=a[i],
a[i+81]+=a[i])a[1304]=a[1336]=0;}
```

```
int a[4 << 9], i;
main() {
    for (a[40] = 1; i++ < 1620;
        printf(i % 80 ? "%c" : "\n", ".oO" [a[i] & 3]),
        a[i + 79] += a[i], a[i + 81] += a[i])
        a[1304] = a[1336] = 0;
}
```

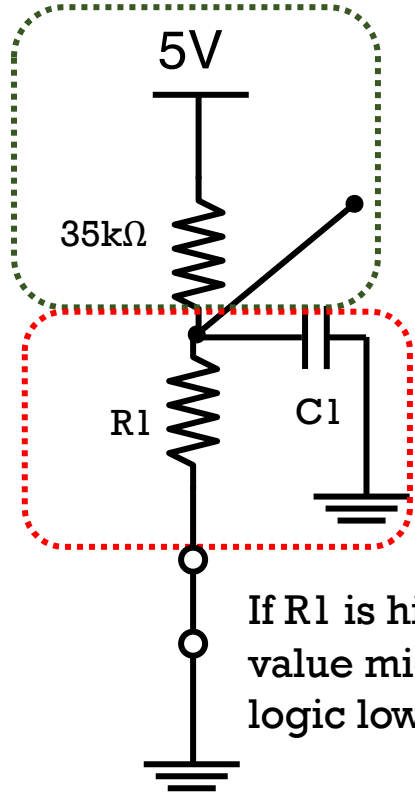
```

      .
    . .
  . o .
. o o .
    o
  . . o o .
. o o   o o .
. o . o o . o .
      o
    . .   o o   .
  . o .   o   . o .
. o o . o o o o . o o .
    o   o       o o .
  . . o o o o   o o o o .
. o o   . o o   o o .   o o .
. o . o . o . o o . o . o . o .
      o
      o o
    o   o
  o o o o
```

Output: Prints a christmas tree.

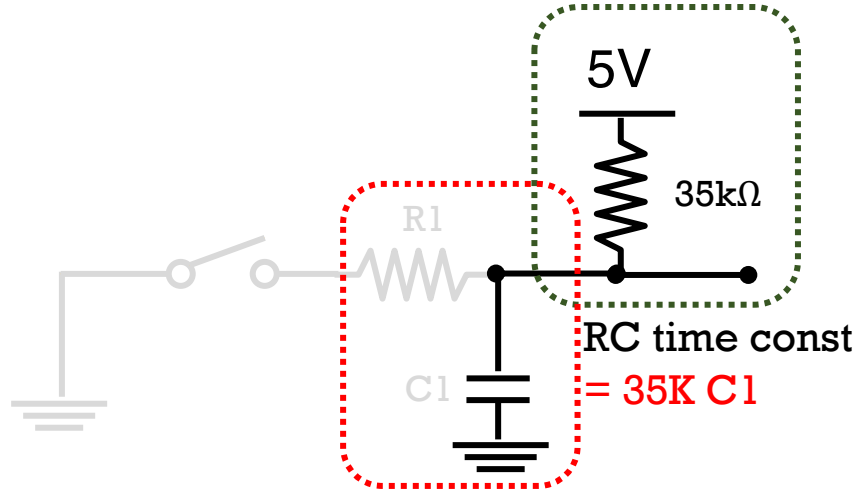
by Hannu Kankaanpää 2000

# Lab 1 Filters on Switches

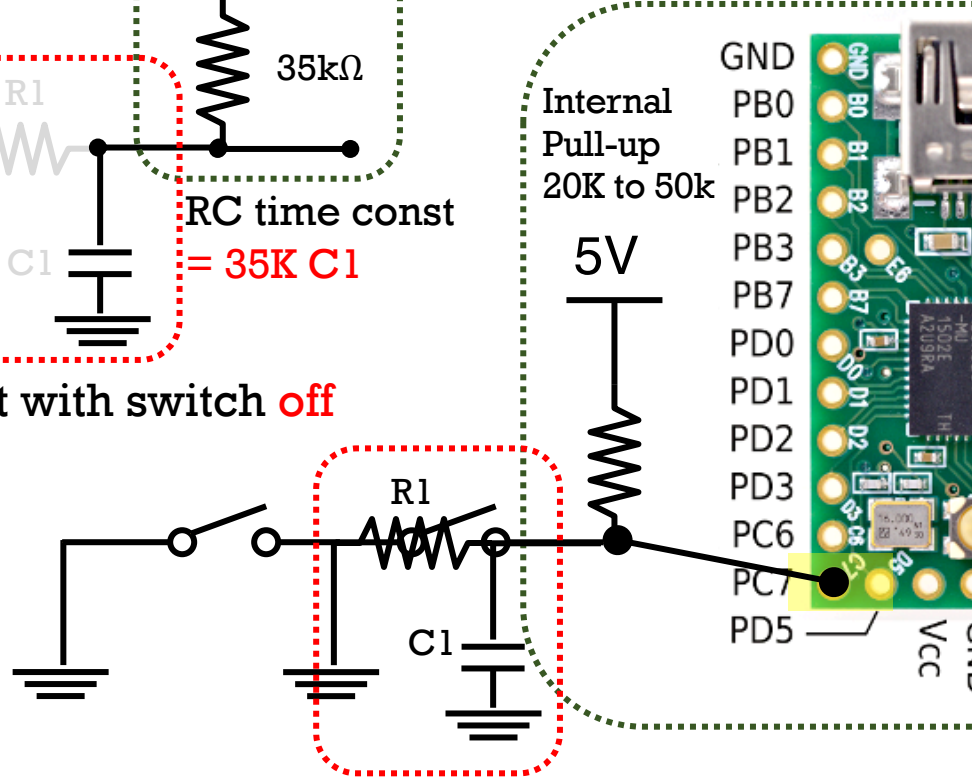


If R1 is higher than ~10K value might not be valid logic low.

Circuit with switch **on**



Circuit with switch **off**



Internal Pull-up 20K to 50k

01

# Pointers and Arrays – part 2

# Pointer declarations

- Declarations using \* operator combined with a variable type

```
int      *ip;      // pointer to an integer  (2 bytes)
```

```
double   *dp;      // pointer to a double    (8 bytes)
```

```
float     *fp;      // pointer to a float     (4 bytes)
```

```
char      *cp;      // pointer to a character (1 byte)
```

// Note: char\* cp; is the same as char \* cp; and char \*cp;

- Size of pointers are all the same (16bit for ATmega)
- Size of the things they are point to may vary (important for arrays)

# Using Pointers

```
#include "teensy_general.h"
#include "t_usb.h"
#define NLCR      m_usb_tx_char(10); m_usb_tx_char(13) // print newline
```

```
int main () {
    int  var = 20;    // actual variable declaration
    int  *ip;         // pointer variable declaration

    m_usb_init();

    ip = &var; // store address of var in pointer variable
    m_usb_tx_hex( &var ); NLCR; // print address of var variable
    m_usb_tx_hex( ip ); NLCR;   // address stored in pointer variable
    m_usb_tx_uint( *ip ); NLCR; // access the value using the pointer
    while (1) ;
}
```

**OAFA** random address  
location compiler finds

**Output:**

**0AFA**

**0AFA**

**20**



# Using Pointers

- Declaration

```
int *fooptr;
```

- Assignment

```
fooptr = 42;
```

Will generate a warning when compiling

- Dereferencing

```
*fooptr = 42;
```

Stores 42 into the location at fooptr

```
int bar = *fooptr;
```

Loads the contents in fooptr into bar

- Passing pointers

```
int subroutine1( int *fooptr) {  
    *fooptr = 20;    // changes content of pointer (like a global)  
    return 1;  
}
```

# Using Pointers

- Declaration

```
int *fooptr;
```

- Assignment

```
fooptr = 42;
```

Will generate a warning when compiling

- Dereferencing

```
*fooptr = 42;
```

Stores 42 into the location at fooptr

```
int bar = *fooptr;
```

Loads the contents in fooptr into bar

- Pointer arithmetic (4 operations)

- ++

Increment address by one word (sizeof variable)

- --

Decrement address by one word (sizeof variable)

- +

Add to address # of words (sizeof variable)

- -

Subtract from address # of words (sizeof variable)

# Pointers and Arrays

- Arrays can be treated as pointers almost always

```
int array[];  
array == &array[0] == &array  
int *iptr;  
*iptr == iptr[0]
```

- Some exceptions

```
int *arrayA, arrayB[8];  
arrayA = arrayB;  
arrayA[i] is the same as arrayB[i]  
*(++arrayA) is the same as arrayB[1]; but  
*(++arrayB) will give an error. You can't change the value of the address of an array.
```

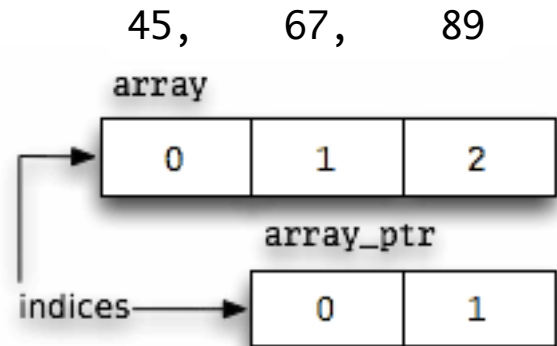
- Strings are arrays of characters that are NULL terminated, adding extra

```
char greeting[6] = {'H', 'e', 'l', 'l', 'o', '\0'};  
char greeting[] = "Hello";
```

# Pointers and Arrays

- Q1: What does the following print?

```
int array[] = { 45, 67, 89 };  
int *array_ptr = &array[1];  
printf("%i\n", array_ptr[1]);
```



# Pre-increment and post-increment

```
void somefunction()  
{  
    int x = 10, a;  
    a = ++x; // Value of x will change before assignment  
    x = x+1;  
    a = x;  
    m_usb_tx_uint( a); 11  
    m_usb_tx_uint( x); 11  
}
```

Output:

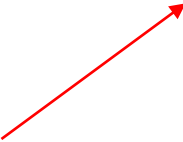
```
void somefunction()  
{  
    int x = 10, a;  
    a = x++; // Value of x will change after assignment  
    x = x+1;  
    a = x;  
    m_usb_tx_uint( a); 10  
    m_usb_tx_uint( x); 11  
}
```

Output:

## Q2: Pointer Arithmetic (what 4 numbers will print?)

- Indexing an array with pointer math

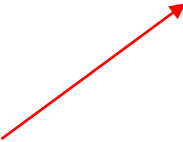
```
int array[] = { 45, 67, 89 };  
int *array_ptr = array;  
somecode() {  
    m_usb_tx_uint(*(array_ptr++));  
    m_usb_tx_uint(*(array_ptr++));  
    m_usb_tx_uint(*array_ptr);  
    m_usb_tx_uint(*(array+2));  
}
```

 `*array_ptr;`  
`array_ptr=array_ptr+1;`

## Q2: Pointer Arithmetic (what 4 numbers will print?)

- Indexing an array with pointer math

```
int array[] = { 45, 67, 89 };
int *array_ptr = array;
somecode() {
    m_usb_tx_uint(*(array_ptr++));
    m_usb_tx_uint(*(array_ptr++));
    m_usb_tx_uint(*array_ptr);
    m_usb_tx_uint(*(array+2));
}
```



The diagram shows a red arrow pointing from the first `*(array_ptr++)` expression in the `somecode()` function to the pointer increment logic. This logic is shown as two lines of code: `*array_ptr;` followed by `array_ptr=array_ptr+1;` on the next line.

parentheses has no effect in many post increment cases

# Extra stuff about pointers

- In general, you can probably get through this course without using pointers.
- Pointers which point to NULL or 0 are a special case. Usually NULL is an invalid address, often indicating uninitialized pointers or other special cases.
- Multiple indirection is valid (I don't recommend it...)

```
int    a = 3;
```

```
int    *b = &a;
```

```
int    **c = &b;
```

```
int    ***d = &c;
```

- Function pointers. You can treat functions as variables by passing pointers to functions. (advanced topic – not necessary in this course).

<http://boredzo.org/pointers/>



02

# Events and Services Framework

# Programming Embedded Systems

## Program Structure:

- often asynchronous
- “simultaneous” inputs & outputs
- sequences unknowable, re-orderable
- no “end” or “exit”

## Inputs:

- sensors (switches, light sensors, voltages, etc.)
- timers
- user inputs (keypad, push-buttons)

## Outputs:

- update a display
- move something
- switch something on or off
- in general → CHANGE SOMETHING

## Q3A Lab 1 Loop Exercise

- Assume you have set up a timer to use OCR1A as a 50 Hz PWM signal and hooked up an LED to the OC1A pin so that writing to OCR1A will set the pulse width of the LED.
  - OCR1A = 255; will be 100% on,
  - OCR1A = 0; will be 100% off
- Write a loop (or loops) that will cause the LED to take 255 steps to grow in intensity to 100% over and over.

```
while(1) {
```

## Q3B Loop Exercise

- Write code to have a second LED attached to OCR1B to grow in intensity in sync (50Hz) 255 steps.

```
while(1) {  
    for (int i=0; i<255; i++) {  
        OCR1A = i;  
        _delay_ms(20);  
    }  
}
```

# Q3C Tough exercise

- How can we have the second LED change it's frequency independent of the first?

```
while(1) {  
    for (int i=0; i<255; i++) {  
        OCR1A = i;  
        _delay_ms(20);  
    }  
    for (int i=0; i<255; i++) {  
        OCR1B = i;  
        _delay_ms(20);  
    }  
}
```

```
while(1) {  
    for (int i=0; i<255; i++) {  
        OCR1A = i;  
        OCR1B = i;  
        _delay_ms(20);  
    }  
}
```

# Events and Services Framework

- Conceptual framework
- An excellent method for *Event-Driven* programming
- Emphasizes design first

# Events and Services Framework

## RULE #1:

Recognize that tasks break down ONLY into  
two fundamental classes:

- a. Event Detectors
- b. Services

# Events and Services Framework

## CORROLARY TO RULE #1:

- Keep Event-Detector and Service routines as short as possible.
  - Try NOT to have too many (or long) delays()
- Must implement “Non-Blocking” routines

Blocking code has indefinite waits,  
e.g. `while (!something) wait;`

If you think you need this  
`while( )`, this is a hint  
to add another event

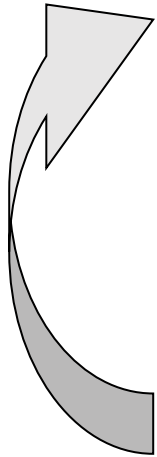


# Writing Events and Services Programs

## Complete program structure:

- Initialize hardware and software
- Continually test for Events
  - Round-robin scanning
  - “Non-blocking” code
- Perform Service(s) when Event detected
  - “Non-blocking” code
- Repeat

```
If (test1) dosomething()  
If (test2) dosomethingelse()  
Etc.
```

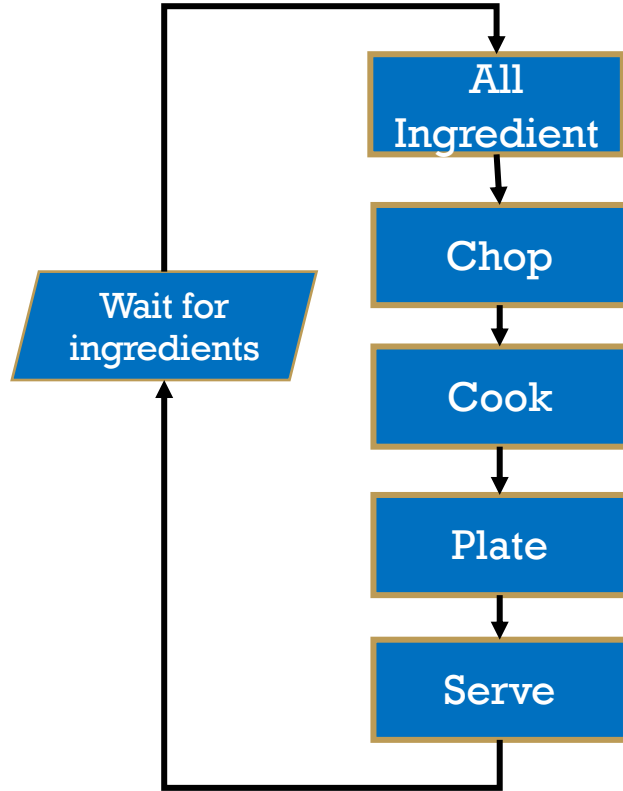


# Overcooked video game

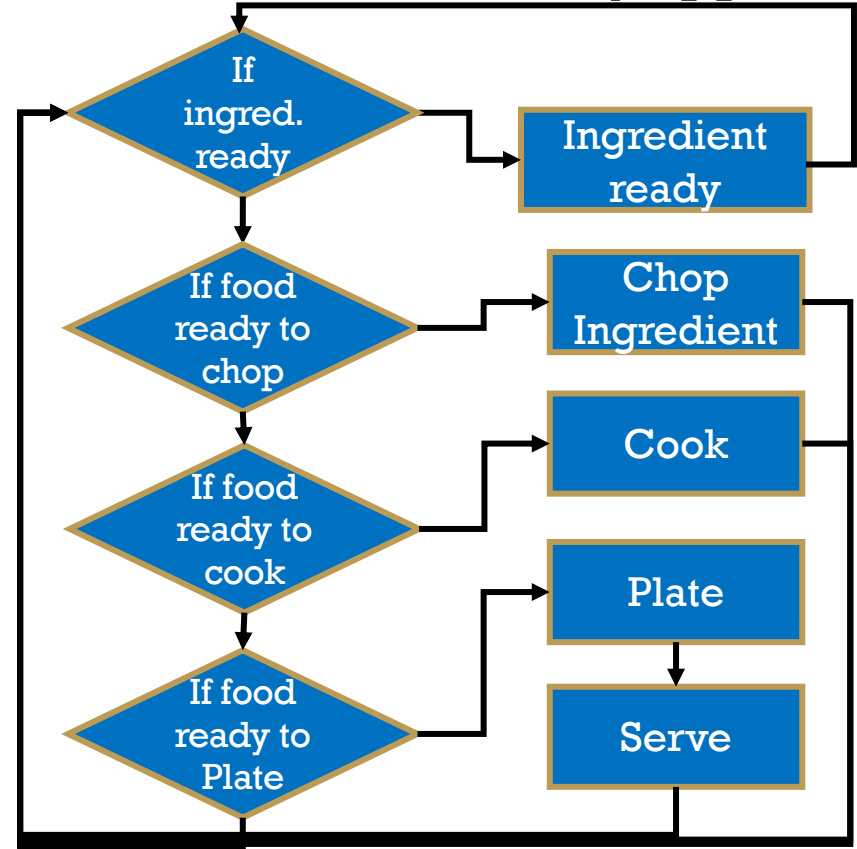


# Analysis of Server Client Process

- Process one dish at a time.

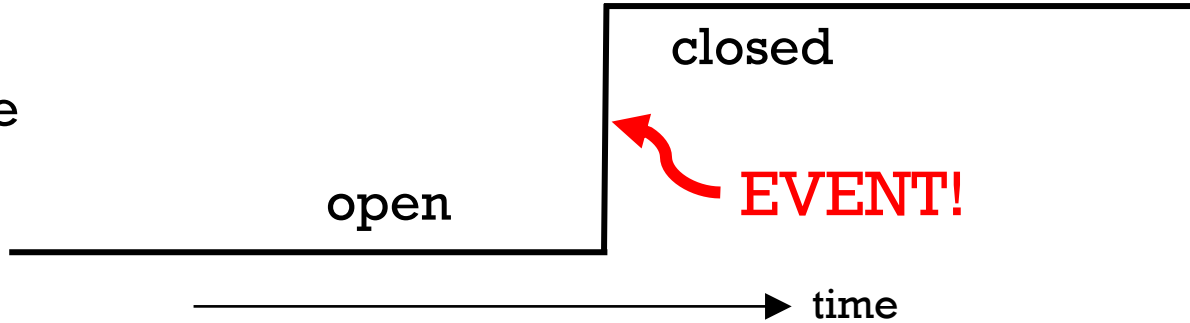


- Process tasks as they appear



# So, what is an event?

Example:  
Switch state



Instantaneous change  
(e.g a change in state)

It is NOT the  
value of a state

In subroutines, use `static` local variable  
to detect events changed between calls

# How to unblock blocking code?

- Break up long routines
- Add events
- Allow for “simultaneous” processes to occur as services triggered by events.

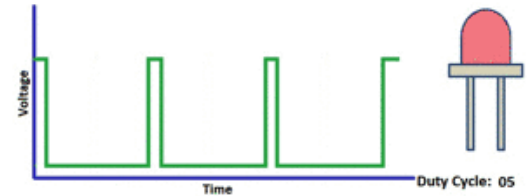
# Breaking up for loop

```
while(1) {  
    if (i++ < 255) {  
        ledPWMService();  
    }  
    else i=0;  
  
    _delay_ms(50);  
}
```

```
void ledPWMService() {  
    OCR1A = i;  
    m_usb_tx_uint(i);  
}
```

```
while(1) {  
    for (i=0; i<255; i++) {  
        OCR1A = i;  
        m_usb_tx_uint(i);  
        _delay_ms(50);  
    }  
}
```

Portion of an LED ramp  
function increasing duty  
cycle of PWM



What happens when we have  
two PWM channels

# Breaking up for loop

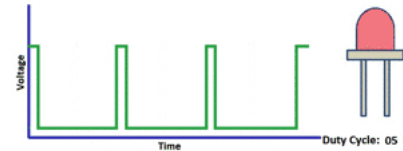
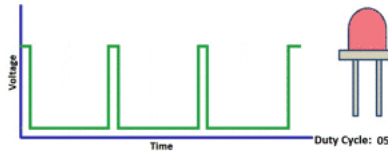
```
while(1) {  
    if (i++ < 255) {  
        ledPWMservice();  
    }  
    else i=0;  
    if (j++ < 180) {  
        ledPWMservice2();  
    }  
    else j=90;  
    _delay_ms(50); // share same delay(50)  
}  
return 0;
```

```
void ledPWMservice() {  
    OCR1A = i;  
    m_usb_tx_uint(i);  
}  
void ledPWMservice2() {  
    OCR1B = j;  
    m_usb_tx_uint(j);  
}
```

// i and j are globals

```
int i,j;  
while(1) {  
    for (i=0; i<255; i++) {  
        OCR1A = i;  
        m_usb_tx_uint(i);  
        _delay_ms(50);  
    }  
    for (j=90; j<180; j++) {  
        OCR1B = j;  
        m_usb_tx_uint(j);  
        _delay_ms(50);  
    }  
}
```

Two LEDs controlled by output capture  
PWM Timer1A and Timer1B



# Events and Services Framework

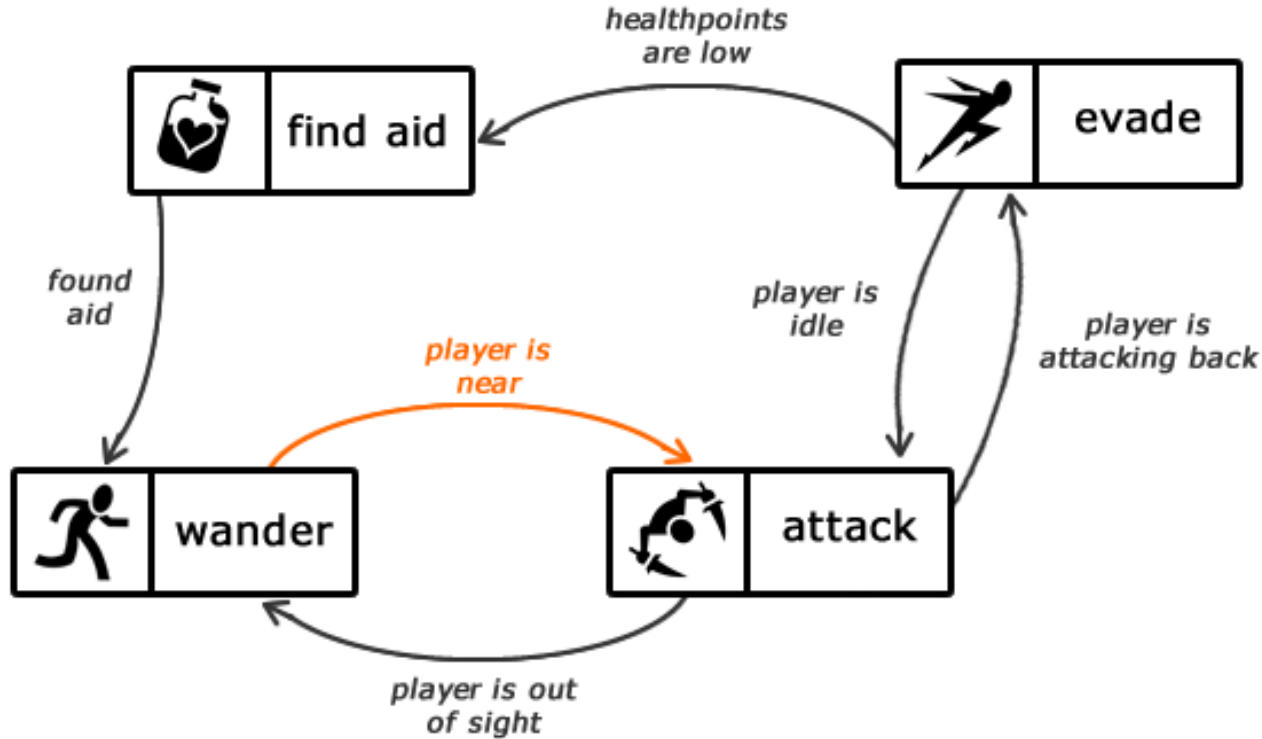
- Breaking into short services emphasizes design first
- Gets you to use structures that:
  - 1) make it clear how to define the low-level functions
  - 2) make debugging code simpler (even before coding!)



03

# Finite State Machines

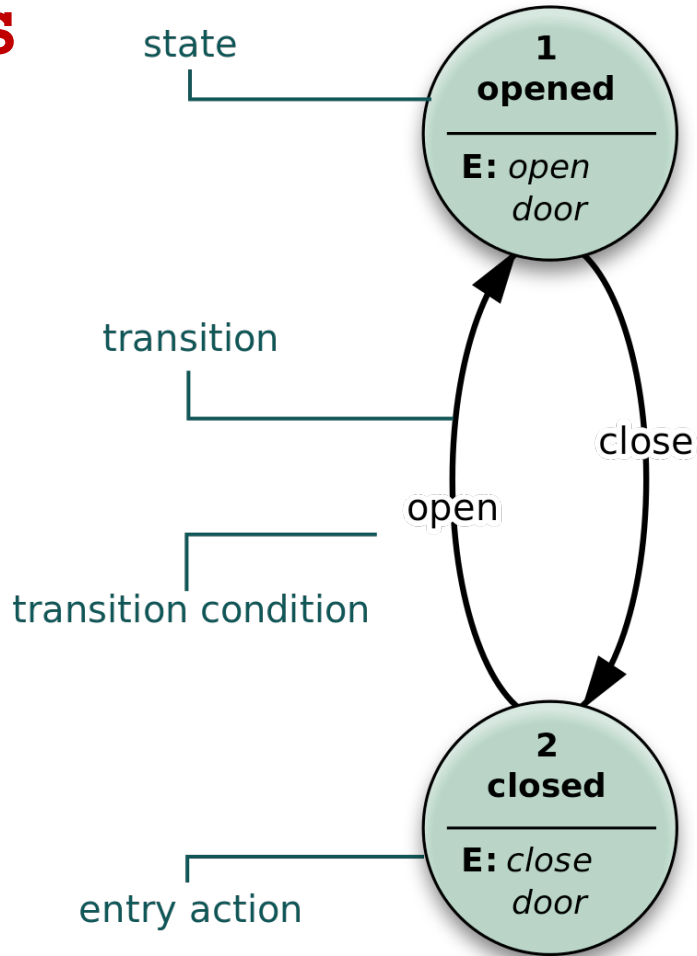
# Video Game AI using FSM



All icons made by Lorc, and available on <http://game-icons.net>.

# Finite State Diagrams

- Abstract description of system behavior.
- Sometimes well suited for embedded applications
- There are many different representations and implementations.

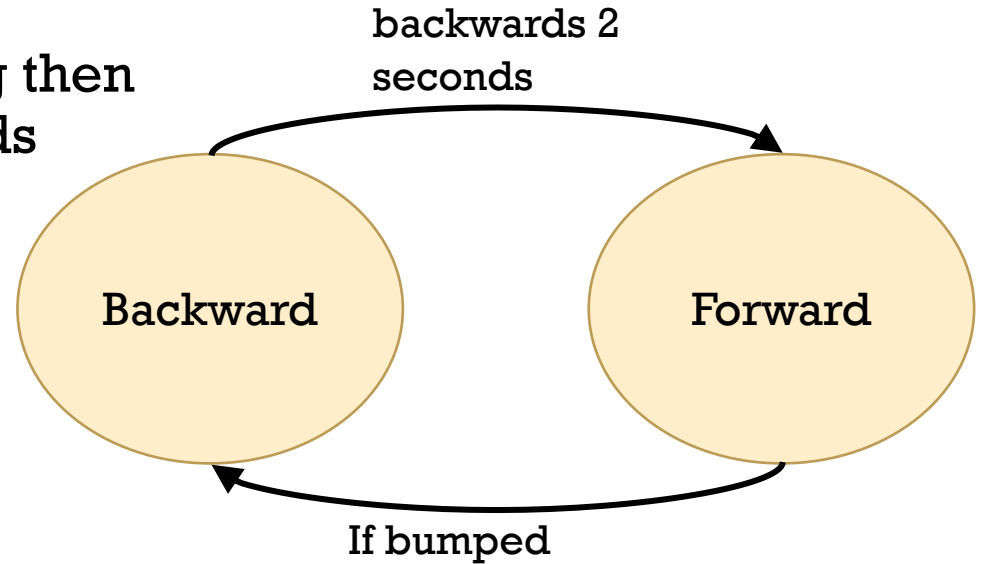


# Finite state machine example

Behavior:

Continuously moves forward

But if it bumps into something then  
move backwards for 2 seconds



Q4: Write pseudo-code for this program

# Pseudo Code Example

**Entry  
action**

Start state of moving forward  
set state FORWARD;  
Turn on motor forward direction

---

**While  
in state**

Loop Moving forward  
check if bumped to start backward

**Entry  
action**

Start state of moving backward  
set state BACKWARD;  
Turn on motor backward direction

---

**While  
in state**

Loop Moving backward  
if 2 secs passed start forward



# Pseudo Code Example (Events and Services)

Loop forever

Events	Services
if in FORWARD state, check if bumper	then start backwards
if in BACKWARD state, check if 2 seconds passed	then start forward

if in FORWARD state,	step forward
if in BACKWARD state,	step backwards

Start state of moving FORWARD  
set state FORWARD;  
Turn on motor forward direction  
Moving forward  
;

Start state of moving backward  
set state backward;  
Turn on motor backward direction  
Moving backward  
;



```

void startForward() { // Start state of moving forward
    state = FORWARD; // set state forward;
    setMotorDirection(1); // Turn on motor forward direction
}

void duringForward() { // Moving forward
    if (bumped()) startBackward(); // check if bumped to move backward
}

void startBackward() { // Start state of moving backward
    state = BACKWARD; // set state backward;
    setMotorDirection(-1); // backward direction
}

void duringBackward() { // Moving backward
    if (twosecondspassed()) startForward(); // if 2 secs passed move forward
}

...

int main() {
    ...
    while (1) {
        if (state == FORWARD) duringForward();
        if (state == BACKWARD) duringBackward();
    }
}

```

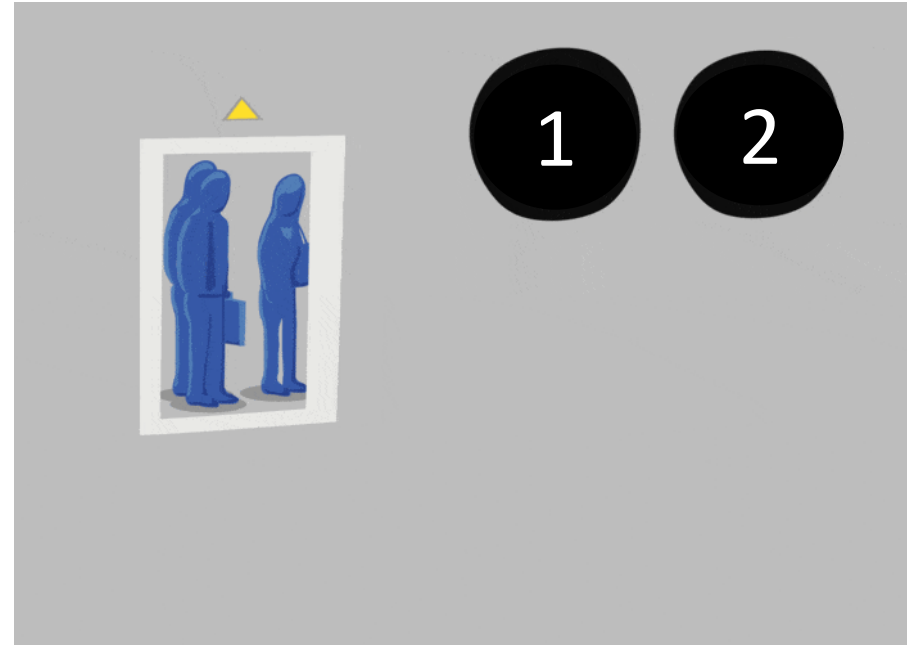
```

#define FORWARD 1
#define BACKWARD 2
int state; // global variable

```

# Two Floor Elevator FSM

- Car floor [1st, 2nd]
- Door state [open/close]
- Floor 1 button [on / off]
- Floor 2 button [on / off]
- 1<sup>st</sup>F call (going up) [on / off]
- 2<sup>nd</sup>F call (going down) [on / off]





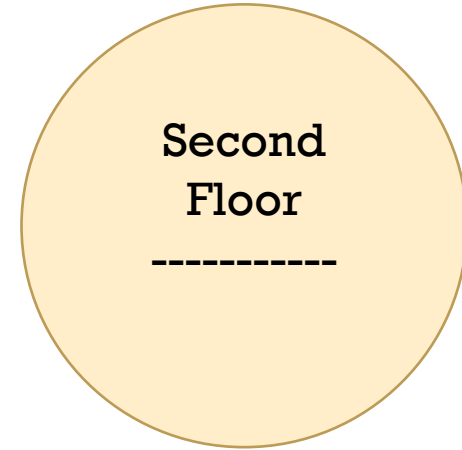
# Finite state machine for an elevator

- Highest level two states: based on which floor car is at

Q5 Draw (no hold) arrows for the transitions between states?

Call button (**Down** from 2<sup>nd</sup> floor)

(**2**) Button inside car



(**1**) Button inside car

Call button (**Up** from 1<sup>st</sup> floor)

# Labeling for Elevator States

## More States?

- On which floor
- Door state
- Floor 1 button
- Floor 2 button on

## Ignoring for now

- 1<sup>st</sup>F call button (going up) **U** on
- 2<sup>nd</sup>F button (going down) **D** on

1<sup>st</sup>

Opened

**1** on

**2** on

2<sup>nd</sup>

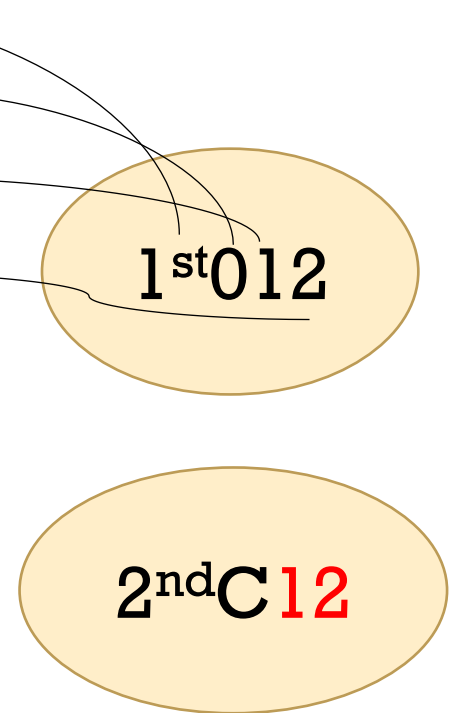
Closed

1 off

2 off

1<sup>st</sup>012

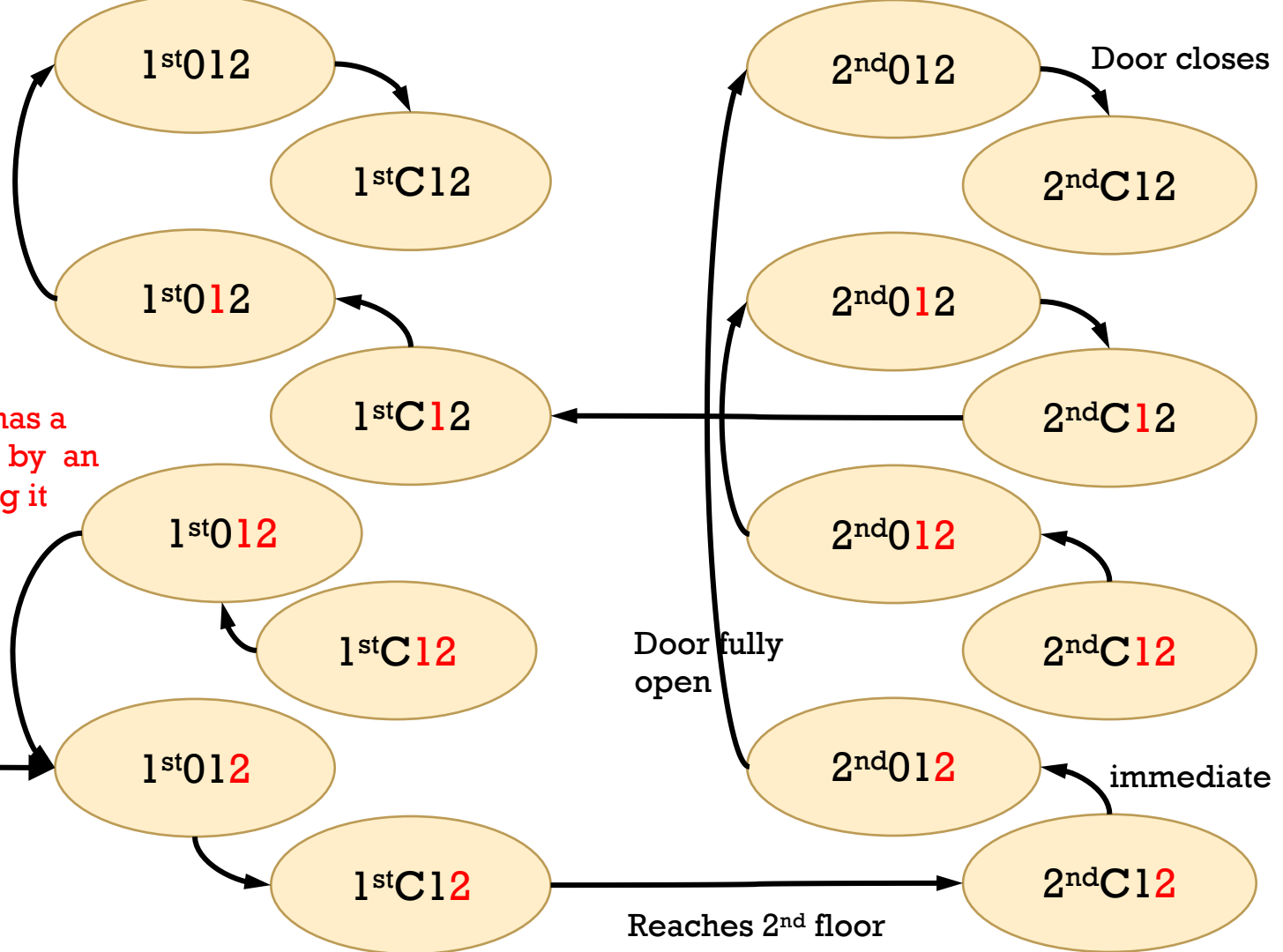
2<sup>nd</sup>C**1**2



# All 16 Possible states for selected 4 parameters

Every button ON state has a transition into that state by an external person pushing it

Someone inside presses (2) button



# Adding Up Down Elevator States

## More States?

- On which floor
- Door state
- Floor 1 button
- Floor 2 button on
- 1<sup>st</sup>F call button (going up) **U** on
- 2<sup>nd</sup>F button (going down) **D** on

1<sup>st</sup>  
Opened

**1** on

**2** on

**U** on

**D** on

2<sup>nd</sup>

Closed

1 off

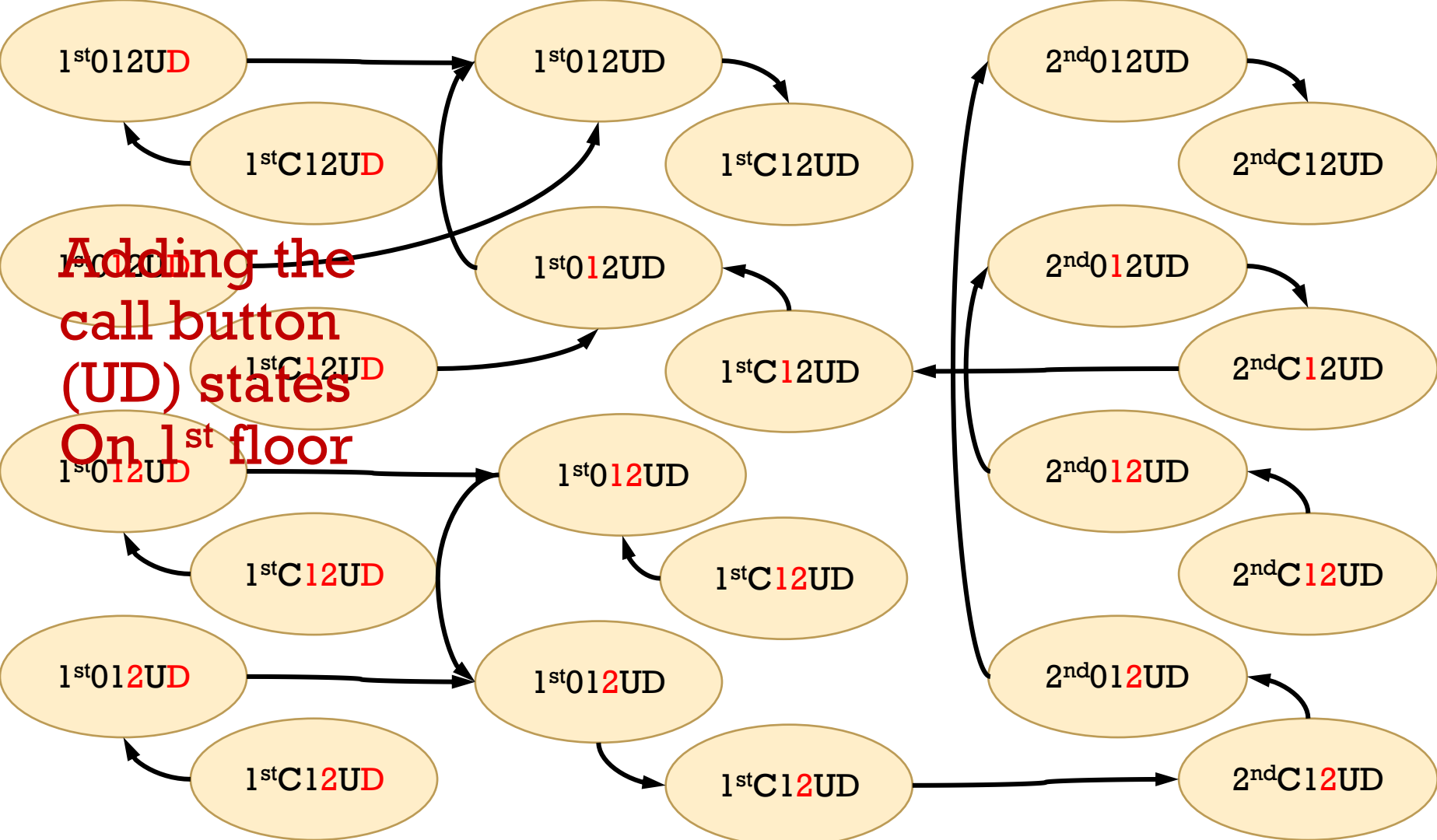
2 off

U off

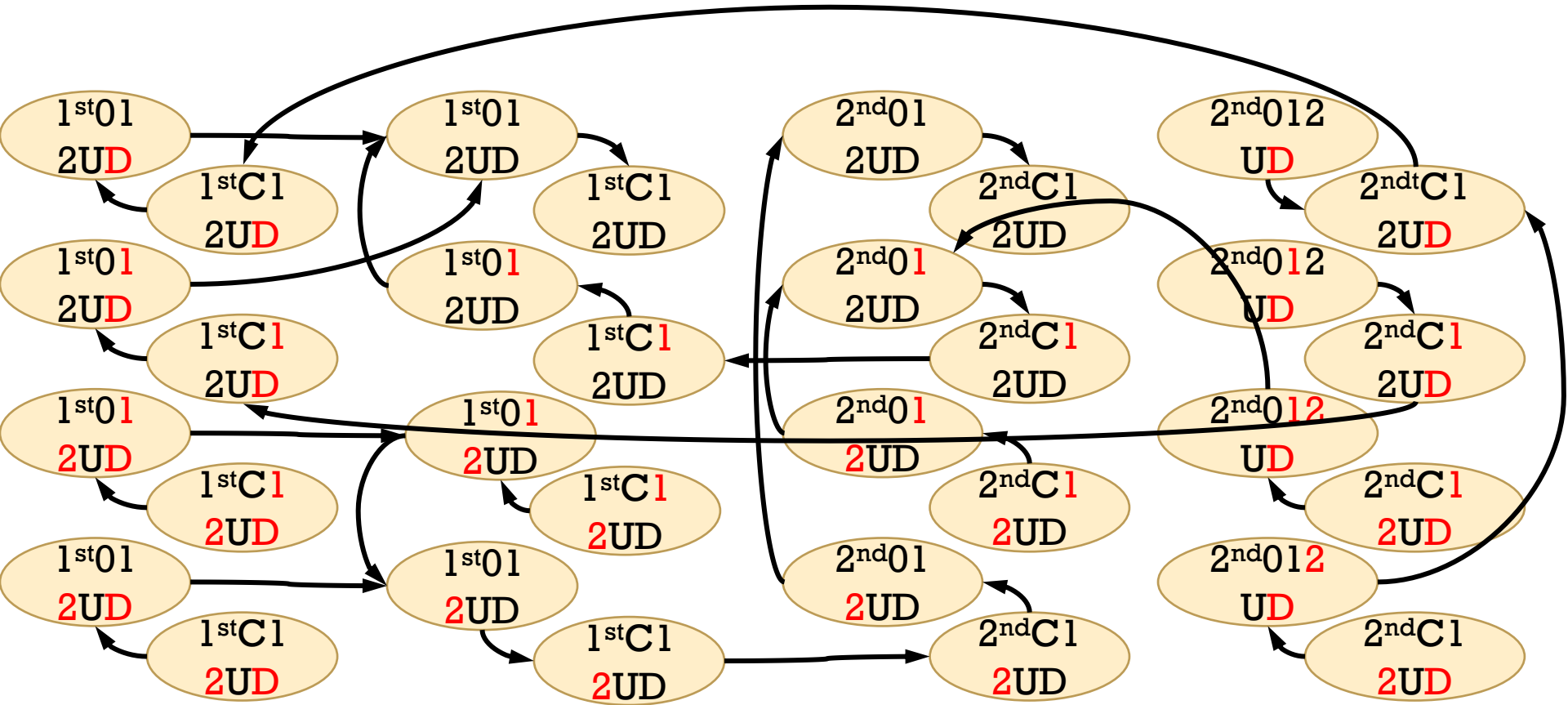
D off

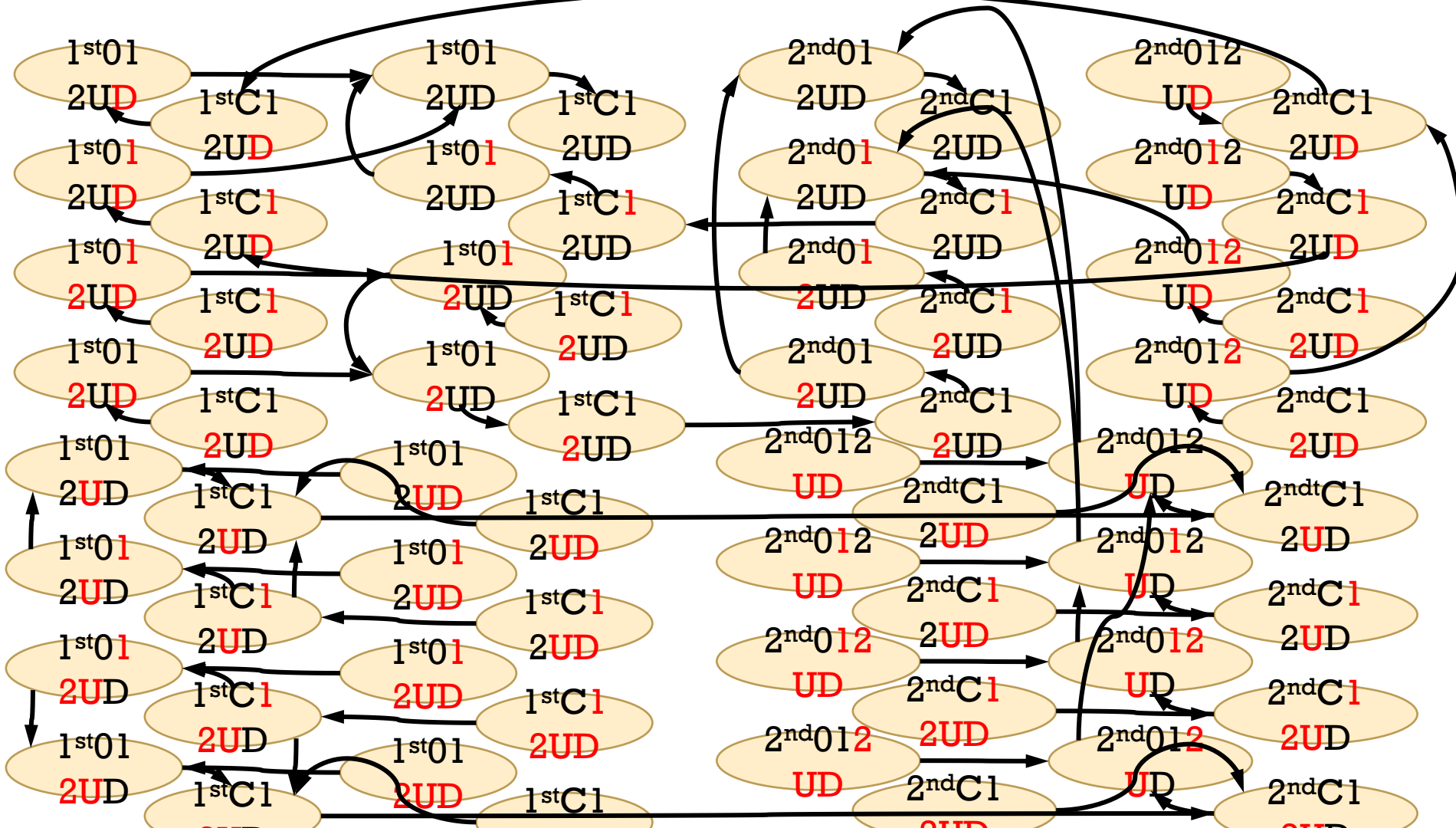
1<sup>st</sup>012

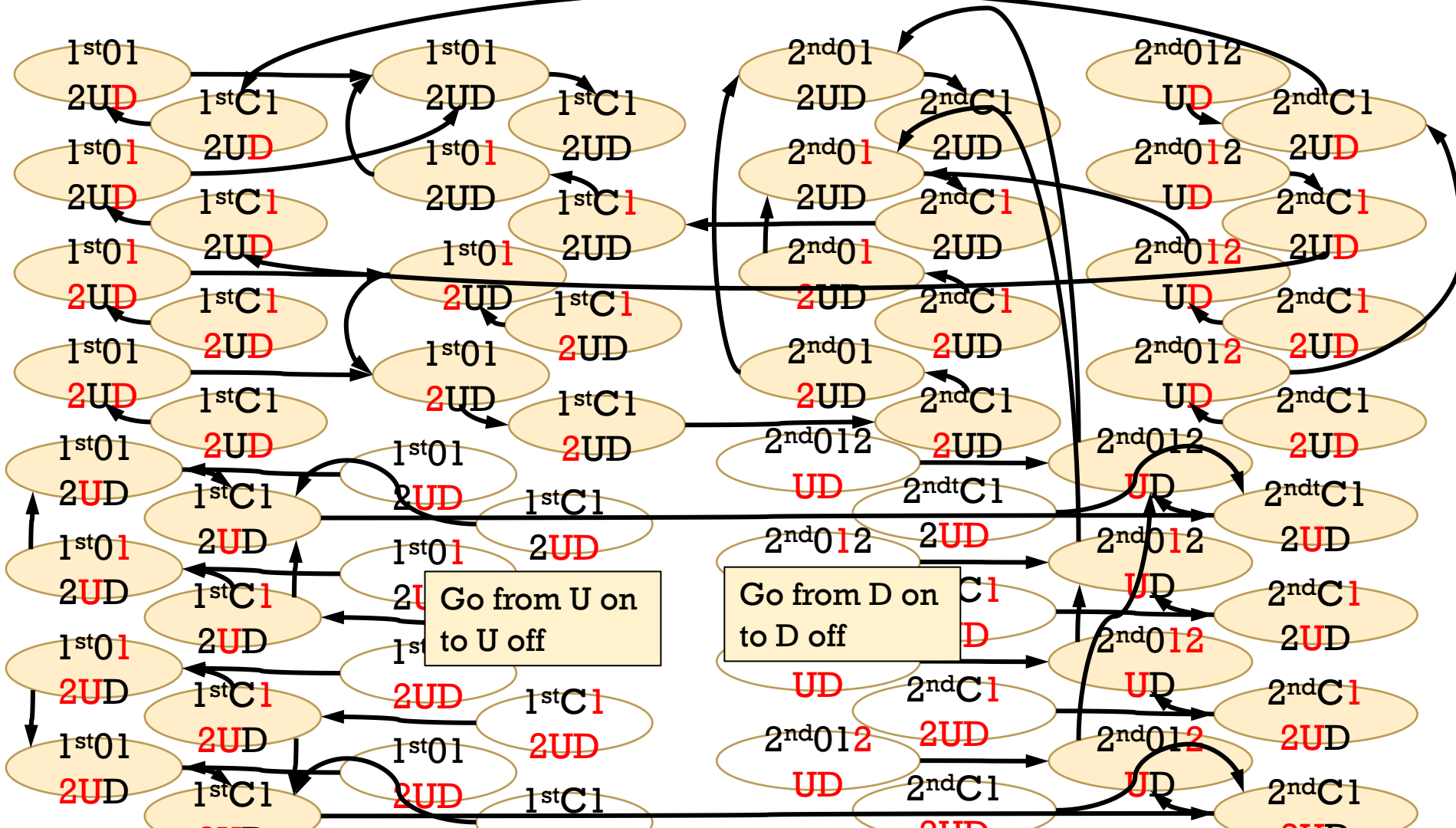
2<sup>nd</sup>C**1**2



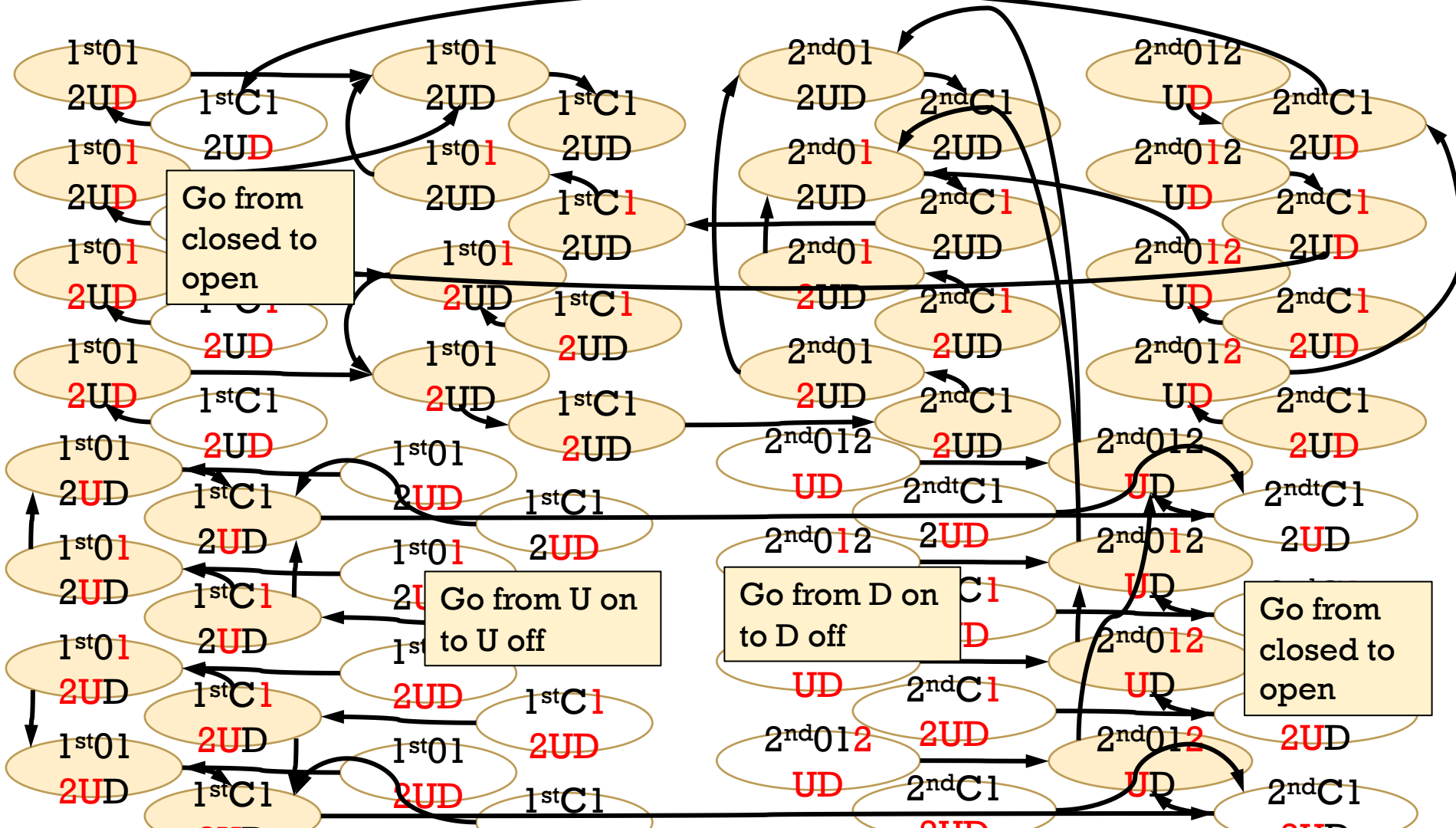
# Adding Down Call Button On (adds 16)

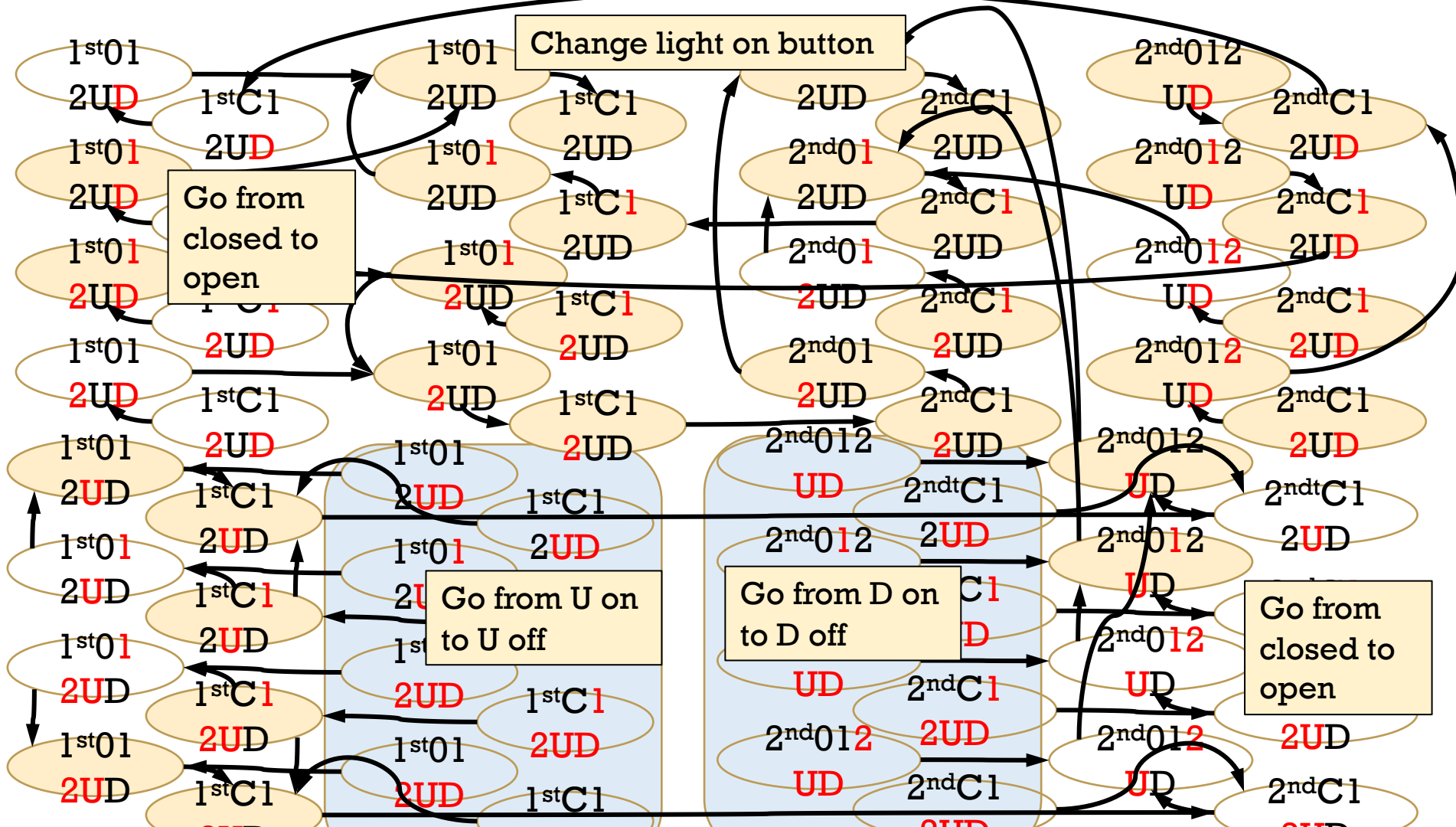












# Resources

- FSM using C code example (Dr.Dobbs article) on canvas
  - Files->Resources-> FSM-samek DrDobbs.pdf
- Google "finite state machine"
- Electrical engineering aspects: FSM with output (Mealy, Moore machines) -> creating FSM circuits
- Computer science aspects: properties of computer languages, grammars, etc.
- Automated FSM code generators.

# Summary

- Arrays are like pointers (variables that hold addresses)
- Pointers are used to at the lower level to access registers and often for more complex functions. For MEAM510, most functions can be achieved without pointers.
- Events and Services framework provides a structure for asynchronous, concurrent tasks in embedded systems. It makes writing larger complex of systems easier. It is highly recommended for when you write your final project code.
- FSM's can help to visually organize program flow