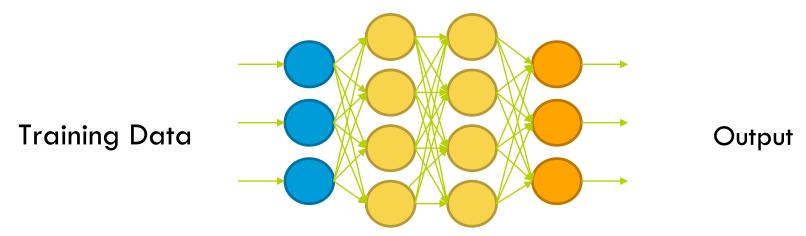


Nets

### How to Train a Neural Net?



- Put in Training inputs, get the output
- Compare output to correct answers: Look at loss function J
- - calculus.

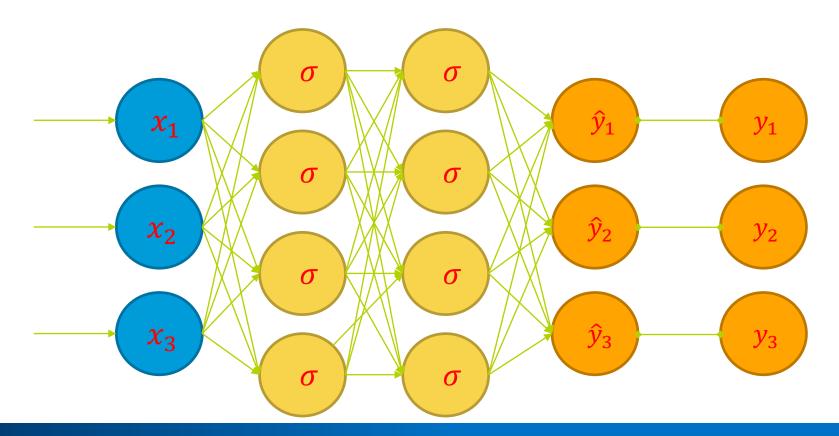
#### How have we trained before?

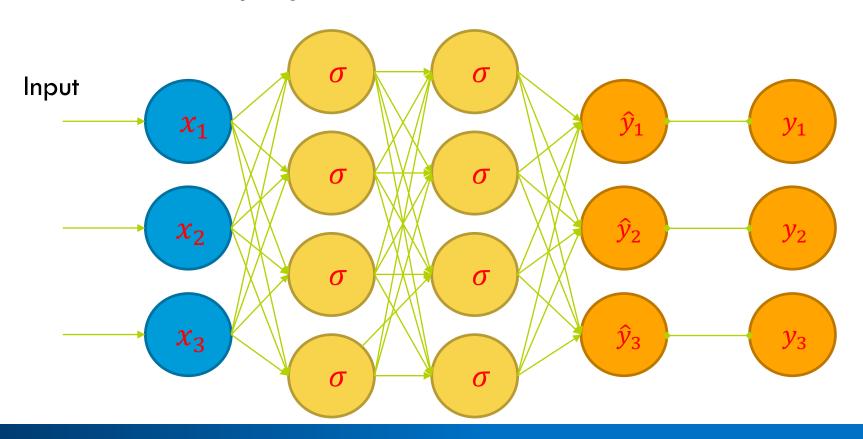
- Gradient Descent!
- 1. Make prediction
- 2. Calculate Loss
- 3. Calculate gradient of the loss function w.r.t. parameters
- 4. Update parameters by taking a step in the opposite direction
- 5. Iterate

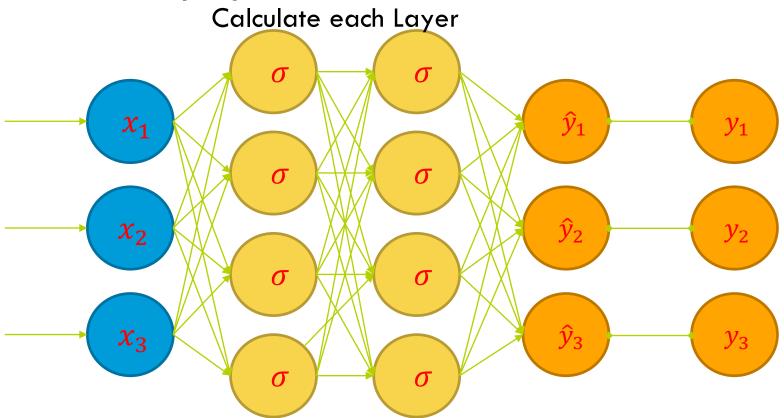
#### How have we trained before?

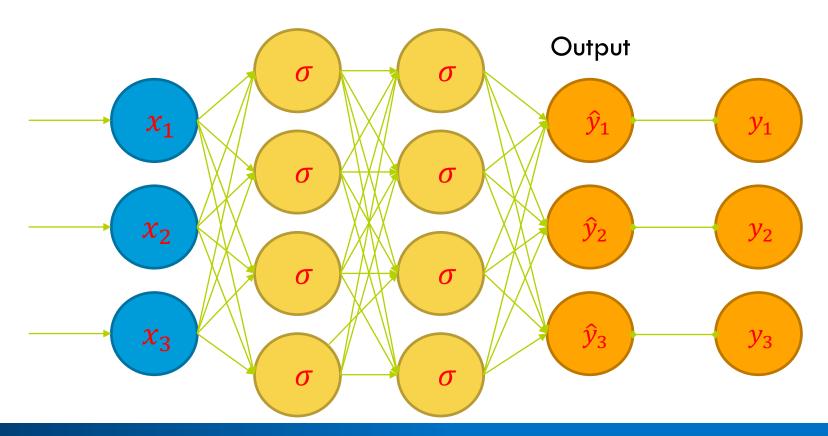
- **Gradient Descent!**
- 1. Make prediction } 'The Forward Pass'
- 2. Calculate Loss
- 3. Calculate gradient of the loss function w.r.t. parameters
- Update parameters by taking a step in the opposite direction
- Iterate

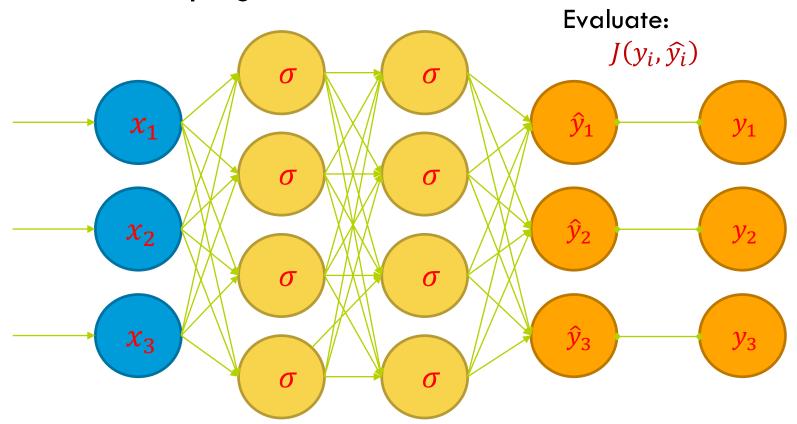
### Feedforward Neural Network











#### How have we trained before?

- Gradient Descent!
- 1. Make prediction
- 2. Calculate Loss
- 3. Calculate gradient of the loss function w.r.t. parameters
- 4. Update parameters by taking a step in the opposite direction
- 5. Iterate

## How to calculate gradient?

Chain rule



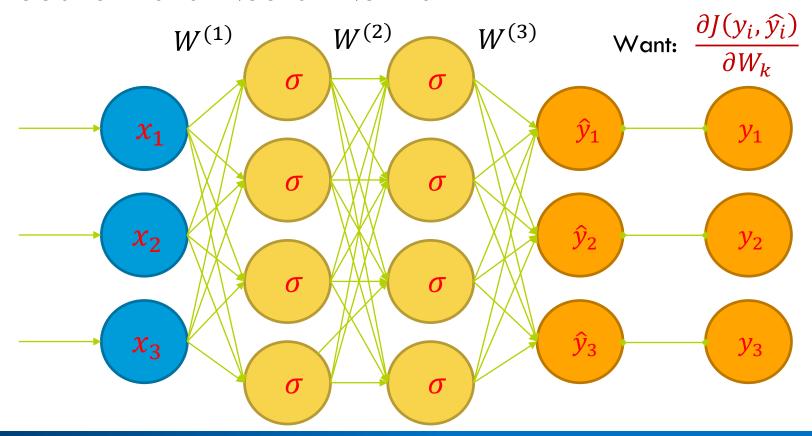
#### How to Train a Neural Net?

- How could we change the weights to make our Loss Function lower?
- Think of neural net as a function F: X -> Y
- F is a complex computation involving many weights W\_k
- Given the structure, the weights "define" the function F (and therefore define our model)
- Loss Function is J(y,F(x))
  - PS. Loss function may also look like L(y, F(x))PS. F(x) is the current prediction or  $y^*$ ; y is the ground truth (label)

#### How to Train a Neural Net?

- Get  $\frac{\partial J}{\partial W_k}$  for every weight in the network.
- This tells us what direction to adjust each  $W_k$  if we want to lower our loss function.
- Make an adjustment and repeat!

### Feedforward Neural Network



#### Calculus to the Rescue

- Use calculus, chain rule, etc. etc.
- Functions are chosen to have "nice" derivatives
- Numerical issues to be considered

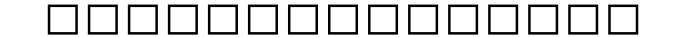
#### **Punchline**

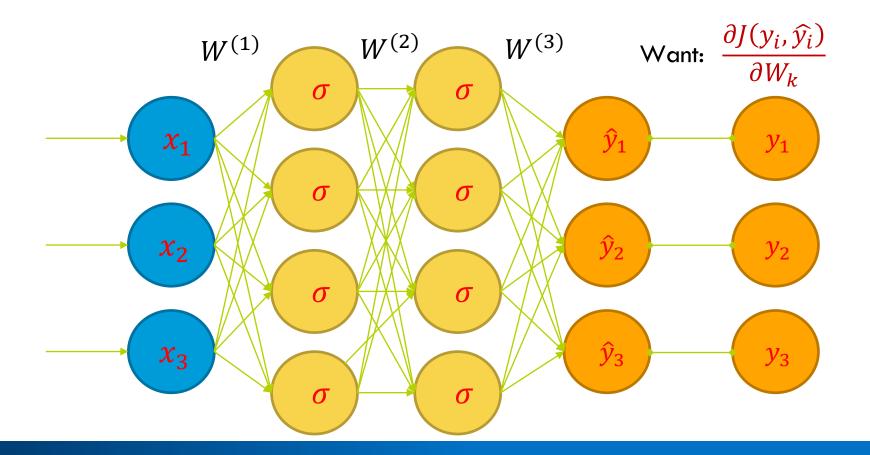
$$\frac{\partial J}{\partial W^{(3)}} = (\hat{y} - y) \cdot a^{(3)}$$

$$\frac{\partial J}{\partial W^{(2)}} = (\hat{y} - y) \cdot W^{(3)} \cdot \sigma'(z^{(3)}) \cdot a^{(2)}$$

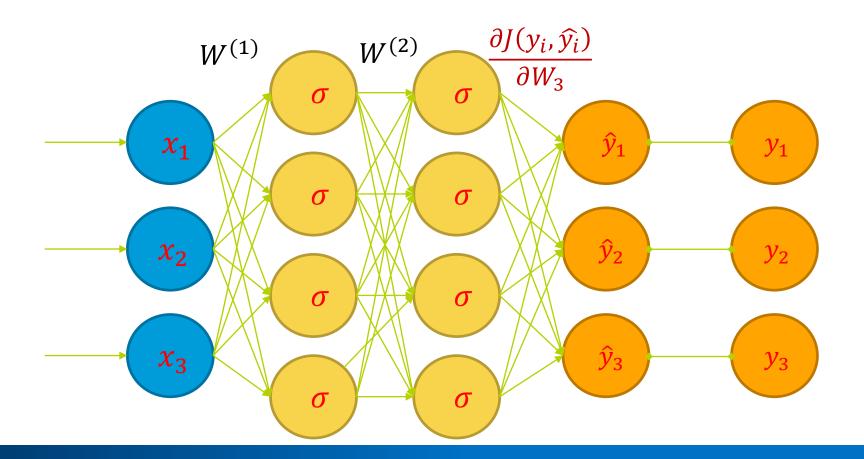
$$\frac{\partial J}{\partial W^{(1)}} = (\hat{y} - y) \cdot W^{(3)} \cdot \sigma'(z^{(3)}) \cdot W^{(2)} \cdot \sigma'(z^{(2)}) \cdot X$$

- Recall that:  $\sigma'(z) = \sigma(z)(1 \sigma(z))$
- Though they appear complex, above are easy to compute!

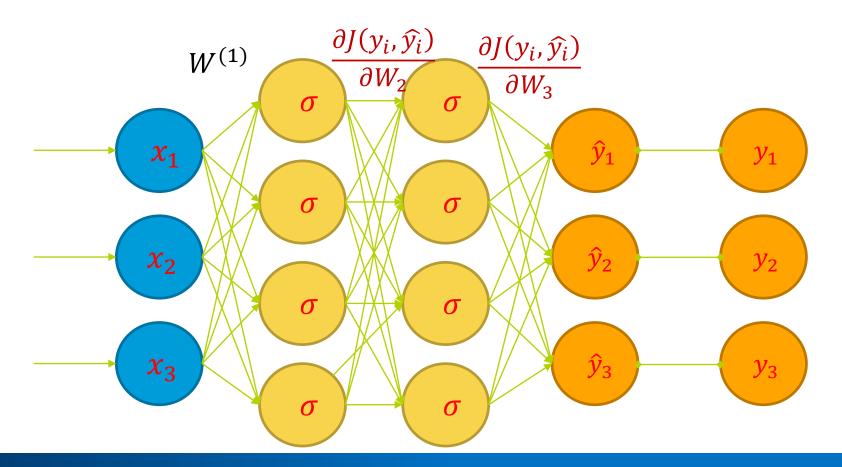




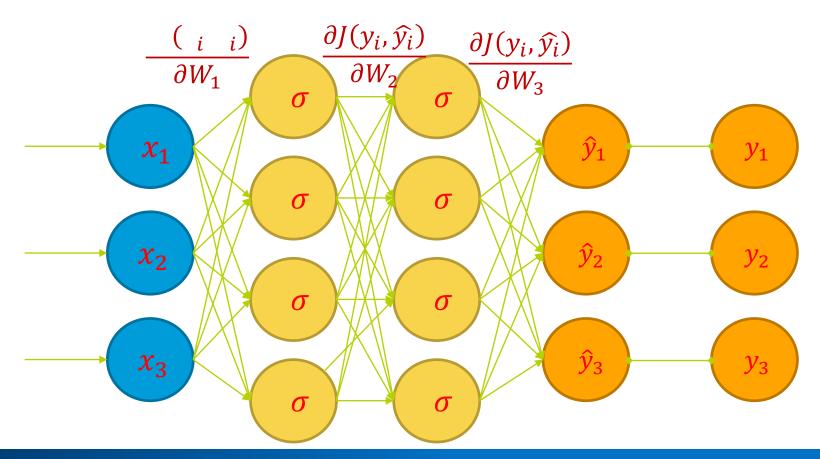












#### How have we trained before?

- Gradient Descent!
- 1. Make prediction
- 2. Calculate Loss
- 3. Calculate gradient of the loss function w.r.t. parameters
- 4. Update parameters by taking a step in the opposite direction
- 5. Iterate In short, FrontPropgation ~= passing back the loss

Activation Function: a(z) = zMean Squared Error Function:  $L(\hat{y}, y) = (\hat{y} - y)^2$ Learning Rate:  $\eta = 1$  Let's use the above example, 1D input, 1 scalar weight w1, and identity activation function.

First, it's Forward-passing. We have the MSE loss regarding our input x as

 $L \ = \ (y - \hat{y})^2 = \left(y - W^T X 
ight)^2 \ = \left(1 - 0.3 
ight)^2 = 0.49$ 

Next, backpropagation, we will solve the partial gradient of L regarding w1 using chain rule.

$$rac{\partial L}{\partial w} = rac{\partial L}{\partial \hat{u}} rac{\partial \hat{y}}{\partial w} = 2 \left(\hat{y} - y\right) x = 2 \left(-0.7\right) 3 = -4.2$$

Last, we will update w1 with the opposite of the gradient \* learning rate. The reason we go the opposite of the gradient is because the gradient points to the direction of the largest increase in L.

$$w_1^{new}=w_1-\etarac{\partial L}{\partial w_1}=0.1+1 imes 4.2=4.3$$

### Vanishing Gradients

Recall that:

$$\frac{\partial J}{\partial W^{(1)}} = (\hat{y} - y) \cdot W^{(3)} \cdot \sigma'(z^{(3)}) \cdot W^{(2)} \cdot \sigma'(z^{(2)}) \cdot X$$

- Remember:  $\sigma'(z) = \sigma(z)(1 \sigma(z)) \le .25$
- As we have more layers, the gradient gets very small at the early layers.
- This is known as the "vanishing gradient" problem.
- For this reason, other activations (such as ReLU) have become more common.

### **Other Activation Functions**

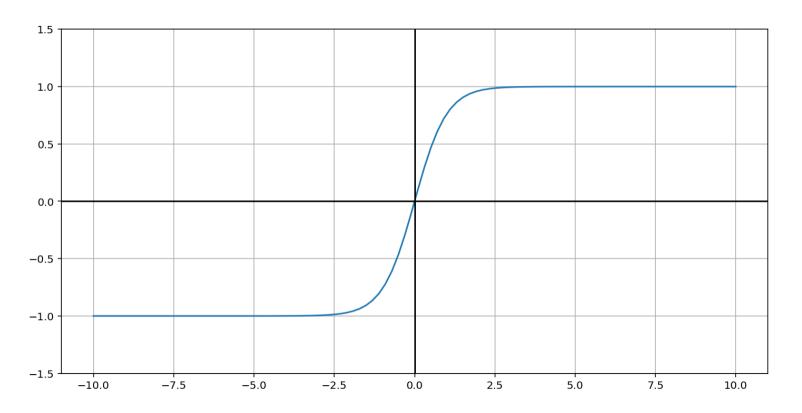
## Hyperbolic Tangent Function

- Hyperbolic tangent function
- Pronounced "tanch"

$$tanh(z) = \frac{\sinh(z)}{\cosh(z)} = \frac{e^{2x} - 1}{e^{2x} + 1}$$

$$tanh(0) = 0$$
$$tanh(\infty) = 1$$
$$tanh(-\infty) = -1$$

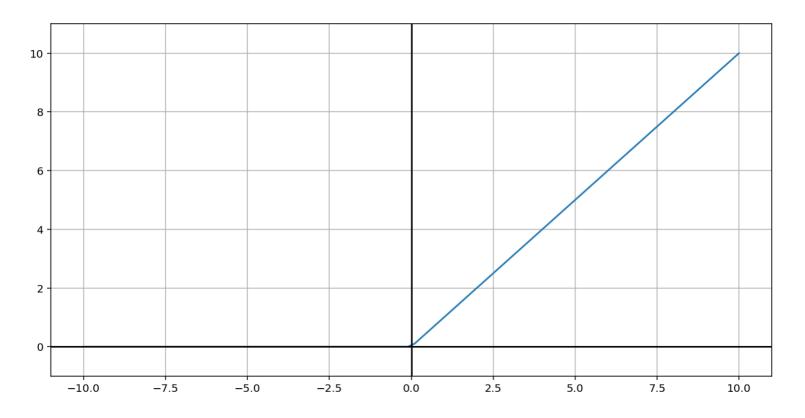
# Hyperbolic Tangent Function



## Rectified Linear Unit (ReLU)

$$ReLU(z) = \begin{cases} 0, & z < 0 \\ z, & z \ge 0 \end{cases}$$
$$= \max(0, z)$$
$$ReLU(0) = 0$$
$$ReLU(z) = z$$
$$ReLU(-z) = 0$$
for  $(z \gg 0)$ 

# Rectified Linear Unit (ReLU)



## "Leaky" Rectified Linear Unit (ReLU)

$$LReLU(z) = \begin{cases} \alpha z, & z < 0 \\ z, & z \ge 0 \end{cases}$$

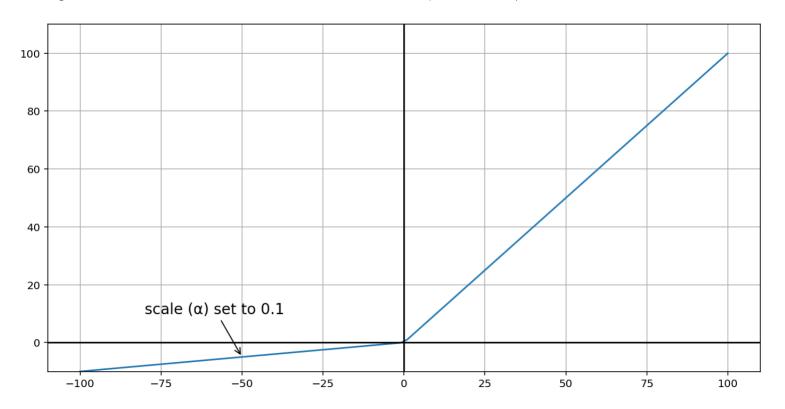
$$= \max(\alpha z, z) \quad \text{for } (\alpha < 1)$$

$$LReLU(0) = 0$$

$$LReLU(z) = z \quad \text{for } (z \gg 0)$$

$$LReLU(-z) = -\alpha z$$

## "Leaky" Rectified Linear Unit (ReLU)



#### What next?

- We now know how to make a single update to a model given some data.
- But how do we do the full training?