SHASHANK SHEKHAR

PERSONAL INFORMATION

Nationality Indian

Website https://shekharsai.github.io/

Address 4 Alexander Yannai, Beer-Sheva, Israel - 8455902

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EDUCATION

March 2021 - Ben-Gurion University of the Negev, Israel

Postdoctoral The Department of Computer Science

Researcher working with Prof. Ronen I Brafman on Decision Making under Uncertainty

Ben-Gurion University of the Negev, Israel

Doctor of The Department of Computer Science

Philosophy Thesis: Collaborative Multi-Agent Planning with Partial Observability and

(Ph.D.) Interacting actions (submitted in March)
Advisor: Prof. Ronen I Brafman

2013-2016 Indian Institute of Technology Madras

Master of Department of Computer Science & Engineering

Science (M.S.) by Thesis: Learning and Strengthening Meta-Heuristics in Plan-Space Planning

Research Advisor: Prof. Deepak KHEMANI

2007-2011 Guru Gobind Singh Indraprastha University

Bachelor of Department of Information Technology, Delhi Technology Information Technology (with distinction)

SKILLS

Software Java, C#, C++, Python, Linux, ROS, OpenCV, PCL, Pytorch, TensorFlow, Git

Planning (Multi Agent-)PDDL, (Multi Agent-)STRIPS, Action Description Language

Languages (ADL), and RDDL

Research Multi-Agent Systems, AI Planning, Pathfinding, Heuristic Search, Robotics, Interests Decision Making under Uncertainty, Learning, Epistemic Planning,

Decision Making under Uncertainty, Learning, Epistemic Planning, Human-Robot Interaction, Reinforcement Learning, Intelligent Interactive

Robots/Vehicles

WORK EXPERIENCE

2011-2012 System Engineer, Infosys Limited, India

Infosys Limited Java and C# developer, Mangalore DC, Karnataka

1. JOURNAL PUBLICATION(S)

Safe multi-agent pathfinding with time uncertainty

J. Artif. Intell. Authors: Tomer Shahar, Shashank Shekhar, Dor Atzmon, Abdallah

Res. SAFFIDINE, Brendan Juba, and Roni Stern

2020 Representing and planning with interacting actions

and privacy

Artif. Intell. Authors: Shashank Shekhar and Ronen I. Brafman

2. CONFERENCE PUBLICATION(S)

Verifying plans and scripts for robotics tasks using performance level profiles

ICAPS Authors: Alexander Kovalchuk, Shashank Shekhar, and Ronen Brafman

Improved knowledge modeling and its use for signaling in multi-agent planning with partial observability

AAAI Authors: Shashank Shekhar, Ronen I. Brafman, and Guy Shani

2019 A factored approach to deterministic contingent multi-agent planning

ICAPS Authors: Shashank Shekhar, Ronen I. Brafman, and Guy Shani

2018 Representing and planning with interacting actions and privacy

ICAPS Authors: Shashank Shekhar and Ronen I. Brafman

Learning and tuning meta-heuristics in plan space planning

ArXiv Authors: Shashank Shekhar and Deepak Khemani

2015 Improving heuristics on-the-fly for effective search in plan space

KI (German Conference on AI)

Authors: Shashank Shekhar and Deepak Khemani

3. WORKSHOP PUBLICATION(S)

2020 Signaling in contingent multi-agent planning

EpiP @ICAPS Authors: Shashank Shekhar, Ronen I. Brafman, and Guy Shani

2020 ROS-POMDP - A Platform for Robotics Planning using PLPs and RDDL in ROS

PlanRobAuthors: Or Wertheim, Ronen I. Brafman, Shashank Shekhar, Tal Feiner,@ICAPS 2020and Igal Pinsky

2020 Safe multi-agent pathfinding with time uncertainty

WoMAPF Authors: Tomer Shahar, Shashank Shekhar, Dor Atzmon, Abdallah @IJCAI 2020 Saffidine, Brendan Juba, and Roni Stern

SYNERGISTIC ACTIVITIES

Served on the Program Committee of AAAI 2021, DMAP @ICAPS2021, and co-organized planning workshop (DMAP'21) at ICAPS

REFERENCES

Ronen I. Ph.D. Advisor · Professor, The Dept. of Comp. Sci., BGU of the Negev, Beer Sheva, Israel, Email: brafman@cs.bgu.ac.il

Guy Shani Ph.D. Committee Member · Faculty member, The Dept. of SISE, BGU of the

Negev, Beer Sheva, Israel, Email: shanigu@bgu.ac.il

Roni Stern Ph.D. Committee Member · Faculty member, The Dept. of SISE, BGU of the Negev, Beer Sheva, Israel, Email: roni.stern@gmail.com