

# SHASHANK SHEKHAR

## PERSONAL INFORMATION

**Nationality** Indian  
**Website** <https://shekharsai.github.io/>  
**Address** Apt. 25, 18 Rue, Notre Dame, Toulouse, 31400  
**Email** [shashankshekhhar2010@gmail.com](mailto:shashankshekhhar2010@gmail.com)

## WORK EXPERIENCE

**Research Associate**  
from Oct., 2021 LAAS-CNRS, France  
Robotics and InteractionS team at LAAS, Toulouse  
working with Dr. Rachid ALAMI on *human aware task planning and human robot interaction*

**Postdoctoral Researcher**  
Mar. Sept., 2021 Ben-Gurion University of the Negev, Israel  
The Department of Computer Science  
worked with Prof. Ronen I BRAFMAN on *multi-agent planning and decision making under uncertainty and partial observability*

**Infosys Limited**  
2011-2012 System Engineer, INFOSYS LIMITED, India  
Java and C# developer, Mangalore DC, Karnataka

## EDUCATION

**Doctor of Philosophy (Ph.D.)**  
2016-2021 Ben-Gurion University of the Negev, Israel  
The Department of Computer Science  
Thesis: *Collaborative Multi-Agent Planning with Partial Observability and Interacting actions*  
Advisor: Prof. Ronen I BRAFMAN

**Master of Science (M.S.) by Research**  
2013-2016 Indian Institute of Technology Madras, Chennai  
Department of Computer Science & Engineering  
Thesis: *Learning and Strengthening Meta-Heuristics in Plan-Space Planning*  
Advisor: Prof. Deepak KHEMANI

**Bachelor of Technology**  
2007-2011 Guru Gobind Singh Indraprastha University  
Department of Information Technology, CBPGEC Delhi  
Information Technology (*with distinction*)

## SKILLS

**Software** Java, C#, C++, Python, Linux, ROS, OpenCV, PCL, Pytorch, TensorFlow, Git

**Research Interests** Multi-Agent Systems, Planning/Pathfinding, Robotics, Decision Making Under Uncertainty, Human-Robot Interaction, Reinforcement Learning, Cooperative Planning or Automated Intersections for Intelligent Robots/Vehicles

## 1. JOURNAL PUBLICATION(S)

2021 *Safe multi-agent pathfinding with time uncertainty*  
**J. Artif. Intell. Res.** Authors: Tomer SHAHAR, **Shashank SHEKHAR**, Dor ATZMON, Abdallah SAFFIDINE, Brendan JUBA, and Roni STERN

2020 *Representing and planning with interacting actions and privacy*

*Artif. Intell.*

Authors: **Shashank** SHEKHAR and Ronen I. BRAFMAN

## 2. CONFERENCE PUBLICATION(S)

2022 *Robust Planning for Human-Robot Joint Tasks with Explicit Reasoning on Human Mental State*

*AAAI Symposium*

Authors: Anthony FAVIER, **Shashank** SHEKHAR, and Rachid ALAMI

2021 *Verifying plans and scripts for robotics tasks using performance level profiles*

*ICAPS*

Authors: Alexander KOVALCHUK, **Shashank** SHEKHAR, and Ronen BRAFMAN

2021 *Improved knowledge modeling and its use for signaling in multi-agent planning with partial observability*

*AAAI*

Authors: **Shashank** SHEKHAR, Ronen I. BRAFMAN, and Guy SHANI

2019 *A factored approach to deterministic contingent multi-agent planning*

*ICAPS*

Authors: **Shashank** SHEKHAR, Ronen I. BRAFMAN, and Guy SHANI

2018 *Representing and planning with interacting actions and privacy*

*ICAPS*

Authors: **Shashank** SHEKHAR and Ronen I. BRAFMAN

2016 *Learning and tuning meta-heuristics in plan space planning*

*ArXiv (informal)*

Authors: **Shashank** SHEKHAR and Deepak KHEMANI

2015 *Improving heuristics on-the-fly for effective search in plan space*

*KI (German Conference on AI)*

Authors: **Shashank** SHEKHAR and Deepak KHEMANI

## 3. WORKSHOP PUBLICATION(S)

2020 *Signaling in contingent multi-agent planning*

*EpiP @ICAPS 2020*

Authors: **Shashank** SHEKHAR, Ronen I. BRAFMAN, and Guy SHANI

2020 *ROS-POMDP - A Platform for Robotics Planning using PLPs and RDDL in ROS*

*PlanRob @ICAPS 2020*

Authors: Or WERTHEIM, Ronen I. BRAFMAN, **Shashank** SHEKHAR, Tal FEINER, and Igal PINSKY

2020 *Safe multi-agent pathfinding with time uncertainty*

*WoMAPF @IJCAI 2020*

Authors: Tomer SHAHAR, **Shashank** SHEKHAR, Dor ATZMON, Abdallah SAFFIDINE, Brendan JUBA, and Roni STERN

## SYNERGISTIC ACTIVITIES

*IEEE Robotics and Automation Letters*  
*SN journal of CS*  
*AAAI*

(2022) · I am a Reviewer.

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(2021, 2022) · I served on the Program Committee.

**DMAP @ICAPS**

(2020) · I co-organized the Workshop on Distributed and Multi-Agent Planning.

#### REFERENCES

- Ronen Brafman**      Ph.D. Advisor · Professor, The Dept. of Comp. Sci., BGU of the Negev, Beer Sheva, Israel, *Email:* brafman@cs.bgu.ac.il
- Rachid Alami**      Host @LAAS-CNRS · “Directeur de Recherche”, LAAS-CNRS, Toulouse, France *Email:* rachid.alami@laas.fr
- Guy Shani**      Ph.D. Committee Member · Faculty member, The Dept. of SISE, BGU of the Negev, Beer Sheva, Israel, *Email:* shanigu@bgu.ac.il
- Roni Stern**      Ph.D. Committee Member · Faculty member, The Dept. of SISE, BGU of the Negev, Beer Sheva, Israel, *Email:* roni.stern@gmail.com

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