

1. a)

Linear Stochastic Bandits:

$$X \in \mathbb{R}^n$$

$$\theta_* \in \mathbb{R}^n$$

$$f(x) = \langle x, \theta_* \rangle$$

$$r_t = \langle X_t, \theta_* \rangle + \varepsilon \quad \text{--- } R\text{-subgaussian}$$

Gaussian environment:

$$\mathcal{E}_N^h: \left\{ \mathcal{N}(\mu_i, \sigma_i^2) \mid \mu \in \mathbb{R}^h, \sigma^2 \in [0, \infty)^h \right\}$$

Stochastic:

$$k = \{1, \dots, h\} \text{ actions.}$$

$$v = (p_1, \dots, p_h)$$

$\mu_h(v) \rightarrow$ expectation of p_h in config v .

$$\hat{\mu}_h(t)$$

For each round t :

select $k_t \in k$

play k_t

$$\text{observe } r_t \sim \mathcal{N}(\mu_{k_t}, \sigma_{k_t}^2)$$

Now, $r_t = \langle X_t, \theta_* \rangle + \varepsilon$, ε is R -subgaussian

$\mathcal{N}(0, \sigma^2)$ is σ -subgaussian

Proof) $X \sim (0, 1)$

$$E[e^{tx}] = \int_{-\infty}^{\infty} e^{tx} e^{-\frac{x^2}{2}} \frac{1}{\sqrt{2\pi}} = e^{\frac{t^2}{2}} \leq e^{\frac{\sigma^2 t^2}{2}}$$

$\Rightarrow \sigma$ -subgaussian, $\sigma = 1$.

$$Y \sim \mathcal{N}(0, \sigma^2) \Rightarrow Y/\sigma \sim \mathcal{N}(0, 1)$$

$$\Rightarrow E[e^{tY}] = E[e^{t\sigma X}] \quad \text{let } t' = \sigma t$$

$$\Rightarrow E[e^{t'X}] = e^{t'^2/2} = e^{\sigma^2 t^2/2} \leq e^{\frac{\sigma^2 t^2}{2}}$$

$\Rightarrow \sigma$ -subgaussian. \blacksquare

Thus, $r_t - \mu_n \sim \mathcal{N}(0, \sigma^2)$

$$\Rightarrow r_t = \mu_n + \varepsilon \sim \sigma\text{-subgaussian}$$

Altogether:

Linear Stochastic Bandit
 $X \subseteq \mathbb{R}^k$, $X = \{\vec{1}_1, \dots, \vec{1}_n\}$ where

$\vec{1}_i$ is a vector of length k , with 0's for all entries except for a 1 at entry i

At each round t :

1. Select action $X_t \in X$
2. Play action X_t
3. Observe reward:

$$r_t = \langle X_t, \theta_* \rangle + \varepsilon_t \sim \mathcal{N}(0, \sigma_{X_t}^2)$$

$$\text{where } \theta_* = (\mu_1, \dots, \mu_n) \in \mathbb{R}^n \\ = \mu$$

b) Regret:

$$R_T = \sum_{t=1}^T \langle X_t, \theta_* \rangle - \sum_{t=1}^T \langle X_t, \theta_* \rangle$$

Suppose we have $K = \{1, 2, 3, 4, 5\}$,
where arm 5 has the largest mean.

$$\therefore R_T = \sum_{t=1}^T \langle [0, 0, 0, 0, 1], [\mu_1, \mu_2, \mu_3, \mu_4, \mu_5] \rangle - \sum_{t=1}^T \langle X_t, \theta_* \rangle$$

$$= R_T = \sum_{t=1}^T \mu_5 - \sum_{t=1}^T \langle X_t, \theta_* \rangle$$

$$= T\mu_5 - \sum_{t=1}^T \langle X_t, \theta_* \rangle$$

now, let's look at $\sum_{t=1}^T \langle X_t, \theta_* \rangle$

at time t , we chose action $X_j = \mathbb{I}_j$
 $\Rightarrow \langle X_j, \theta_* \rangle = \langle \mathbb{I}_j, \theta_* \rangle = \mu_j$

This can be reformulated as, at time t :
let $k_t = \text{index } j \text{ of } X_j \equiv \text{we pulled arm } j$

$$\Rightarrow \langle X_j, \theta_* \rangle = \mu_{k_t}$$

$$\text{Thus, } R_T = \sum_{t=1}^T \langle X_t, \theta_* \rangle - \sum_{t=1}^T \langle X_t, \theta_* \rangle \quad (\text{linear setting regret})$$

$$= T\mu_* - \sum_{t=1}^T \mu_{k_t}$$

where μ_* is the optimal μ_i for the configuration and

μ_{k_t} is the μ_j for arm $j = k_t$ in the given configuration.

\Rightarrow Linear setting regret is equivalent to
finitely-armed regret given the gaussian
reward configuration in the stochastic bandit setting

c) OFUL:

On round t :

1. choose optimist $\tilde{\theta}_t = \arg\max_{\theta \in C_{t-1}} (\max_{x \in X} \langle x, \theta \rangle)$
2. $x_t = \arg\max_{x \in X} \langle x, \tilde{\theta}_t \rangle$
3. play x_t
4. $r_t = \langle x_t, \theta^* \rangle + \epsilon_t$

UCB:

Actions k , confidence level δ

Play each action once,

$\forall t > k$:

Select $k_t = \arg\max_{k \in K} UCB_k(t-1, \delta)$

For UCB, we maintain upper confidence bounds
 $\forall k \in K = \{1, \dots, K\}$, and we select the greediest
action to maximize the upper confidence bound

For OFUL, we maintain a confidence set
 $C_{t-1} \subseteq \mathbb{R}^h$ for θ^* , and we select
the greediest action x_t to maximize
 $\langle x, \tilde{\theta}_t \rangle$, where $\tilde{\theta}_t = \arg\max_{\theta \in C_{t-1}} (\max_{x \in X} \langle x, \theta \rangle)$

Equivalently $(x_t, \tilde{\theta}_t) = \arg\max_{(x, \theta) \in X \times C_{t-1}} \langle x, \theta \rangle$

i.e. $x_t = \vec{1}_i$, so we are selecting
greediest action $k_t = i^{\text{th}}$ action to maximize
confidence set $C_{t-1, i} = UCB_i(t-1, \delta)$

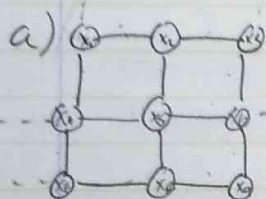
C_{t-1} is an ellipsoid around $\mu = \theta^*$, with
confidence level δ or equivalently

$$C_{t-1} = (UCB_1(t-1, \delta), \dots, UCB_n(t-1, \delta))$$

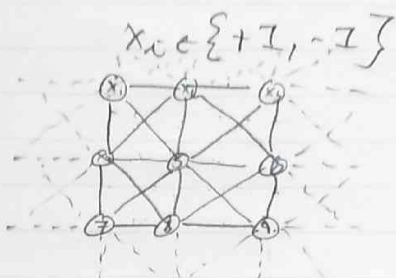
Thus, UCB in the finitely-armed setting maintains k confidence intervals for μ_1, \dots, μ_k , whereas OFUL maintains a confidence set, $C_t \subseteq \mathbb{R}^k$, which can be viewed as k confidence intervals, for μ_1, \dots, μ_k .

Thus, both seek to maximize the upper confidence bound, but the notation (k confidence intervals vs. k -element confidence set) is 'slightly' different.

2. Markov Random Field



\Rightarrow



$$p(x_1, \dots, x_9) = \frac{1}{Z} \prod_{i,j} \phi_{ij}(x_i, x_j) \quad (\text{Ising model})$$

We can represent the joint distribution as a product of clique potentials

$$\Rightarrow p(x_1, \dots, x_9) = \frac{1}{Z} \prod_{\text{cliques } c} \psi_c(x_c)$$

where x_c are the values for the variables that participate in clique c .

4 neighbours (left model): consider $\{x_1, \dots, x_9\}$

Cliques:

Size 1: $\{\{x_1\}, \dots, \{x_9\}\}$ 9 parameters.

Size 2: $\{\{x_1, x_2\}, \{x_1, x_4\}, \dots, \{x_8, x_9\}\}$

\Rightarrow 12 parameters.

Size 3: 0

\Rightarrow 21 parameters / energies.

8 neighbours (right model): consider $\{x_1, \dots, x_9\}$

Size 1: 9 parameters

Size 2: 20 parameters (i.e. count edges)

size 3:

Count triangles: 4 per square \cdot 4 squares
 $= 16$ parameters.

size 4:

Count squares with diagonals
 $\Rightarrow 4$ parameters.

Thus, there's an increase in parameters, as we

- a) have more 2-cliques.
- b) have 3-cliques
- c) have 4-cliques.

The parameters, thus, can be expressed as 1, 2, 3, 4-cliques.

b) Disadvantages:

More complex model means

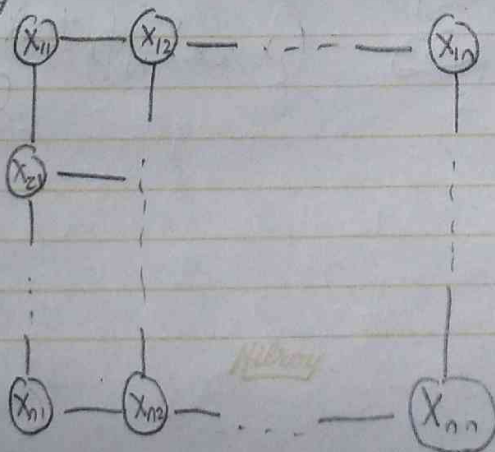
a) higher variance b) increased computational cost.

Since we have many more parameters to learn.

Advantages:

- More complex patterns (non-linear) can be captured.

c) Ising Model



X_{ij} is node: i^{th} row, j^{th} column
 $i=1, \dots, n$ $j=1, \dots, n$

let e_i , $i=1, \dots, n$ be the evidence injected for nodes $X_{i,1}$

$$E(\sigma) = - \sum_{i,j} \sigma_i \sigma_j, \quad \sigma_i: \text{configuration} = \pm 1 \text{ for node } i.$$

\hookrightarrow sum over all pairs of sites i, j which are neighbors

$$\pi_\sigma = \frac{e^{-\beta E(\sigma)}}{\sum_{\tau} e^{-\beta E(\tau)}} \quad \text{prob dist on set of configurations}$$

$\beta > 0$ favors neighbors of similar spin

$\beta < 0$ favors high-energy config.

$$\text{let } \sigma_{-n} = (\sigma_1, \dots, \sigma_{n-1}, \sigma_{n+1}, \dots, \sigma_{n^2})$$

$$\sigma_n^+ = (\sigma_1, \dots, \sigma_{n-1}, +1, \sigma_{n+1}, \dots, \sigma_{n^2})$$

$$\sigma_n^- = (\sigma_1, \dots, \sigma_{n-1}, -1, \sigma_{n+1}, \dots, \sigma_{n^2})$$

$$\Rightarrow p(\sigma_n = +1 | \sigma_{-n}) = \frac{p(\sigma_n^+)}{p(\sigma_n^+) + p(\sigma_n^-)} = \frac{p(\sigma_n^+)}{p(\sigma_n^+) + p(\sigma_n^-)}$$

$$= \frac{e^{-\beta E(\sigma_n^+)}}{e^{-\beta E(\sigma_n^+)} + e^{-\beta E(\sigma_n^-)}}$$

$$= \frac{1}{1 + e^{A(E(\sigma_n^+) - E(\sigma_n^-))}}$$

$$\text{now, } E(\sigma_n^+) = - \sum_{\substack{ij \\ h=1}} \sigma_i \sigma_j$$

$$= - \left(\sum_{\substack{ij \\ i,j \neq n}} \sigma_i \sigma_j + \sum_{i \neq n} \sigma_i \right)$$

$$E(\sigma_n^-) = - \left(\sum_{\substack{ij \\ i,j \neq n}} \sigma_i \sigma_j - \sum_{i \neq n} \sigma_i \right)$$

$$\Rightarrow E(\sigma_n^+) - E(\sigma_n^-) = -2 \sum_{i \neq n} \sigma_i$$

$$\Rightarrow p(\sigma_n = +1 | \sigma_{-n}) = \frac{1}{1 + e^{-2\beta \sum_{i \neq n} \sigma_i}}$$

$$\text{and } p(\sigma_n = -1 | \sigma_{-n}) = 1 - p(\sigma_n = +1 | \sigma_{-n})$$

Algorithm: (num is some number of iterations ≥ 0)

$X_{ij} = \text{random } \forall i, j$ (let \tilde{X} be lattice)

for num:

if num = 0

$\forall j = 1, \dots, n \quad i = 1, \dots, n:$
 $j = 1:$

$x_{ij} = e_i$

else:

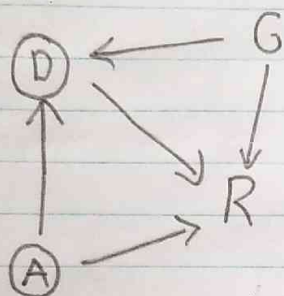
$x_{ij} = \text{sample } p(\sigma_{ij} | \sigma_{-\{i,j\}})$

else:

$\forall j = 1, \dots, n \quad i = 1, \dots, n:$
 $x_{ij} = \text{sample } p(\sigma_{ij} | \sigma_{-\{i,j\}})$

return \tilde{X}

3. $D|A, G$
 $R|D, A, G$
 A indep of G



$$\Rightarrow P(A, D, G, R)$$

$$= P(A)P(G)P(D|A, G)P(R|D, A, G)$$

$$p(R=r|D=d) = \frac{p(R=r, D=d)}{p(D=d)}$$

$r := \text{recover}$
 $d := \text{drug}$

$$P(R=r, D=d) = \sum_{A \in \{0,1\}} \sum_{G \in \{M, F\}} P(A, G, D=d, R=r)$$

$$= \sum_A \sum_G P(A) P(G) P(D=d|A, G) P(R=r|D=d, A, G)$$

$$= \sum_A P(A) \left[\sum_G P(G) P(D=d|A, G) P(R=r|D=d, A, G) \right]$$

$$P(D=d) = \sum_A \sum_G \sum_R P(A) P(G) P(D=d|A, G) P(R|D=d, A, G)$$

$$= \sum_A P(A) \sum_G P(G) P(D=d|A, G) \underbrace{\sum_R P(R|D=d, A, G)}_{=1}$$

$$= \sum_A P(A) \sum_G P(G) P(D=d|A, G)$$

$$\Rightarrow P(R=r|D=d) = \frac{\sum_A P(A) \sum_G P(G) P(D=d|A, G) P(R=r|D=d, A, G)}{\sum_A P(A) \sum_G P(G) P(D=d|A, G)}$$

filter

Thus, to calculate $p(r|d)$,

$$\begin{aligned}
 \text{i)} \quad & p(\text{old}) \left(p(\text{male}) p(\text{drug}|\text{male, old}) p(\text{recover}|\text{drug, old, male}) \right. \\
 & \quad \left. + p(\text{female}) p(\text{drug}|\text{female, old}) p(\text{recover}|\text{drug, old, female}) \right) \\
 & + p(\text{young}) \left(p(\text{male}) p(\text{drug}|\text{male, young}) p(\text{recover}|\text{drug, young, male}) \right. \\
 & \quad \left. + p(\text{female}) p(\text{drug}|\text{female, young}) p(\text{recover}|\text{drug, young, female}) \right)
 \end{aligned}$$

$$\begin{aligned}
 \text{ii)} \quad & p(\text{old}) \left(p(\text{male}) p(\text{drug}|\text{male, old}) \right. \\
 & \quad \left. + p(\text{female}) p(\text{drug}|\text{female, old}) \right) \\
 & + p(\text{young}) \left[p(\text{male}) p(\text{drug}|\text{male, young}) + p(\text{female}) p(\text{drug}|\text{female, young}) \right]
 \end{aligned}$$

$$p(r|d) = \frac{\text{(i)}}{\text{(ii)}}$$

where probabilities can be ascertained by ^{the} doctor

$$p(A) = \frac{\text{\# people in age group } a}{\text{Total people.}}$$

$$p(G) = \frac{\text{\# people of gender } g}{\text{Total people.}}$$

$$p(D=d|A, G) = \frac{\text{\# of people of age group } a, \text{ gender } g \text{ given drug } d}{\text{\# of people of age group } a, \text{ gender } g.}$$

$$p(R=r|D, A, G) = \frac{\text{\# of people of } a, g, \text{ given (or not) drug } d, \text{ who did recover}}{\text{\# of people of } a, g, d.}$$

$$P(R=r | D=d, A=y) = \frac{P(R=r, D=d, A=y)}{P(D=d, A=y)}$$

$$P(R=r, D=d, A=y) = \sum_G P(A=y) P(G) P(D=d | A=y, G) P(R=r | D=d, A=y, G)$$

$$= P(A=y) \sum_G P(G) P(D=d | A=y, G) P(R=r | D=d, A=y, G)$$

$$P(D=d, A=y) = \sum_G \sum_R P(A=y) P(G) P(D=d | A=y, G) P(R | D=d, A=y, G)$$

$$= P(A=y) \sum_G P(G) P(D=d | A=y, G) \underbrace{\sum_R P(R | D=d, A=y, G)}_{=1}$$

$$\Rightarrow P(R=r | D=d, A=y) = \frac{\sum_G P(G) P(D=d | A=y, G) P(R=r | D=d, A=y, G)}{\sum_G P(G) P(D=d | A=y, G)}$$

Thus, to calculate $p(r | d, y)$

$$\text{i) } P(\text{male}) P(\text{drug} | \text{young, male}) P(\text{recover} | \text{drug, young, male})$$

$$+ P(\text{female}) P(\text{drug} | \text{young, female}) P(\text{recover} | \text{drug, young, female})$$

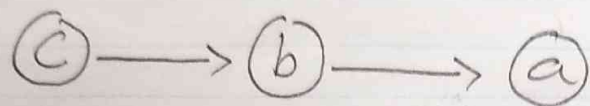
$$\text{ii) } P(\text{male}) P(\text{drug} | \text{young, male}) + P(\text{female}) P(\text{drug} | \text{young, female})$$

$$p(r | d, y) = \frac{\text{(i)}}{\text{(ii)}}$$

Probabilities ascertained similarly to previous page.

Hilroy

$$3b) \quad p(a,b,c) = p(a|b)p(b|c)p(c)$$



a, b, c are binary

$$p(a|b)p(b|c)p(c)$$

$$p(c) \rightarrow \psi ; \quad p(\neg c) = 1 - \psi$$

$$p(b|c) \rightarrow \begin{aligned} p(b|c=0) &= \psi, & p(\neg b|c=0) &= 1 - \psi \\ p(b|c=1) &= \alpha, & p(\neg b|c=1) &= 1 - \alpha \end{aligned}$$

$$p(a|b) \Rightarrow \begin{aligned} &1 \text{ parameters } b=0 \\ &1 \text{ param } \quad b=1 \end{aligned}$$

$$\Rightarrow 1 + 2 + 2$$

$$= 5 \text{ parameters } \left(\frac{10}{2} \text{ since knowing true for conditionals and probabilities gives false } (1 - p(\text{true})) \right)$$

$$p(a,b,c): 2^3 = 8 \text{ parameters}$$

(but, one is for free: 1 - summation of the 7 other parameters)

$$\Rightarrow 7 \text{ parameters.}$$

4a) 1000 training
d=6 dimensions
binary output
100 test set.

A big concern is the distribution of the classes in the training set. If the training set is unbalanced, we may need to oversample the minority class (ex. SMOTE [Synthetic Minority Over-sampling Technique] Boosting). Moreover, using a feed forward neural network may be too complex \Rightarrow add dropout to the network. Since we don't know if the function $F: X \rightarrow Y \in \{0,1\}$ is linear or not, a neural network w/ non-linear activation is the most appropriate, since it is able to learn basis functions to project the data into a space where it may be linearly separable (if $F: X \rightarrow Y$ is non-linear). If $F: X \rightarrow Y$ is linear, then the neural network will be able to find a function to linearly separate the data, without the need to project the data.

Thus, use a feed-forward neural network (w/ SMOTE boosting if unbalanced dataset).

b) We know:
10,000 dimensions
binary output
input $\xrightarrow{\text{linear}}$ output

We don't want to use too complex of a model, since overfitting is a big issue.

Use Linear SVM: these are perfect for classification (as it is a non-probabilistic binary linear classifier that will find a hyperplane to separate the data). Since the output is a linear function of the input, a linear kernel is utilized. Moreover, we can solve the dual problem for SVM, which is more efficient (since $d=10,000$ and only 1,000 training samples).

4 c)

Stock prices are an example of a time-series: data points indexed in the order. In analyzing time-series, trends and seasonality can be noticed and described, since the data can correlate with itself. Thus, we need a model that considers the past and the sequential relationship w/ previous points

↳ LSTM should be used.

We can use the previous week's data to predict the next day's price ($t+1$). Then, using the data + our prediction, we can predict $t+2$ days and, similarly, $t+3$.

LSTM's utilize the data and the order of the data to make predictions, whereas Feed-Forward neural networks wouldn't learn any information from the ordering of the data \Rightarrow LSTM's are more appropriate.

d) Logistic regression will give us the probability of failure we are interested.

Moreover, if $Y \in \{\text{Failure}^1, \text{No-Failure}^0\}$, X is predictor w/ density f .

$$\frac{P(Y=1|X=x)}{P(Y=0|X=x)} = \frac{P(Y=1) f_{X|Y=1}(x)}{P(Y=0) f_{X|Y=0}(x)}$$

$$\log\left(\frac{P(Y=1|X)}{P(Y=0|X)}\right) = \log\left(\frac{P(Y=1)}{P(Y=0)}\right) + \log\left(\frac{f_{X|Y=1}(x)}{f_{X|Y=0}(x)}\right)$$

↑

here, we can encode our prior information (i.e. leverage the fact that we know the likelihood of a random failure).

\Rightarrow Use logistic regression.