

Mastering Deep Learning Within a Few Hours

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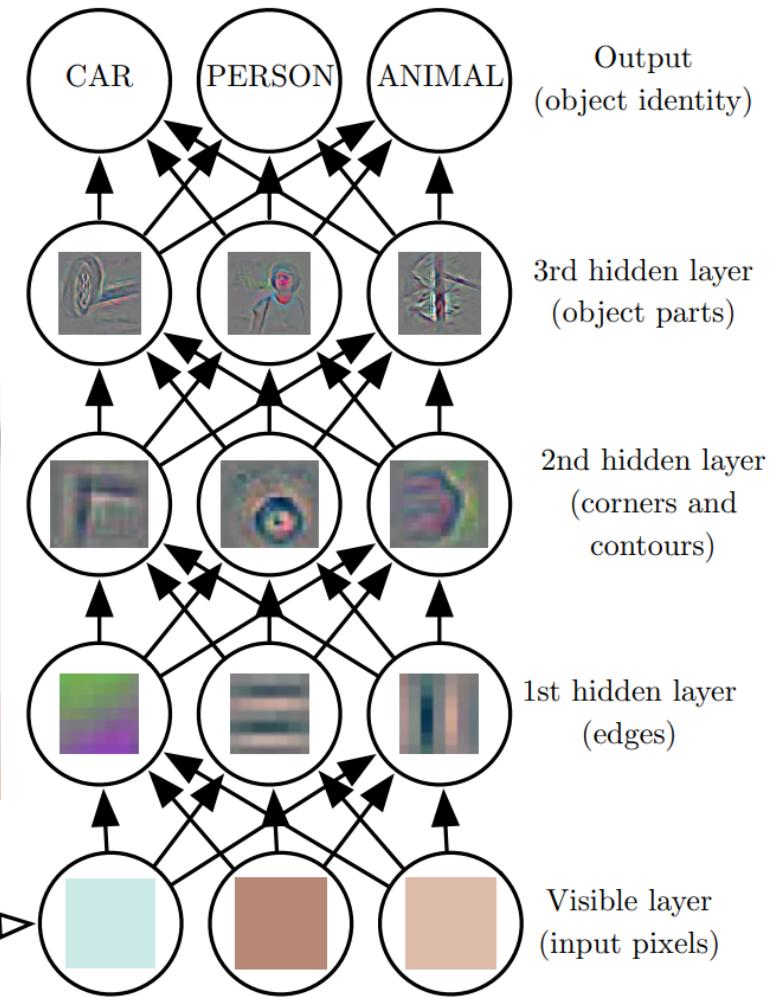
- Introduction
- Problem Formulation
- Implementation
- Experiments
- Advanced Topics

Introduction

Artificial v.s. Intelligence

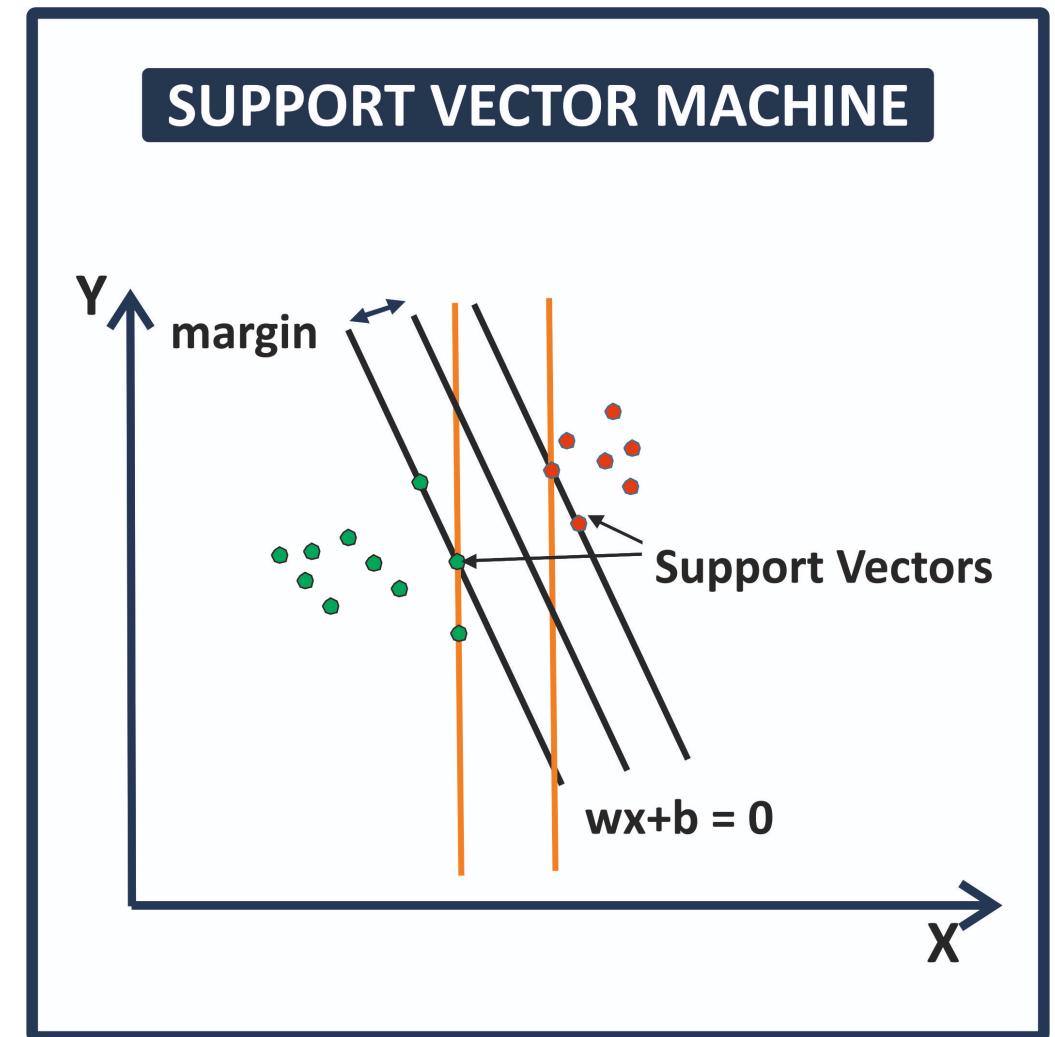
Intelligence

- Human Perception



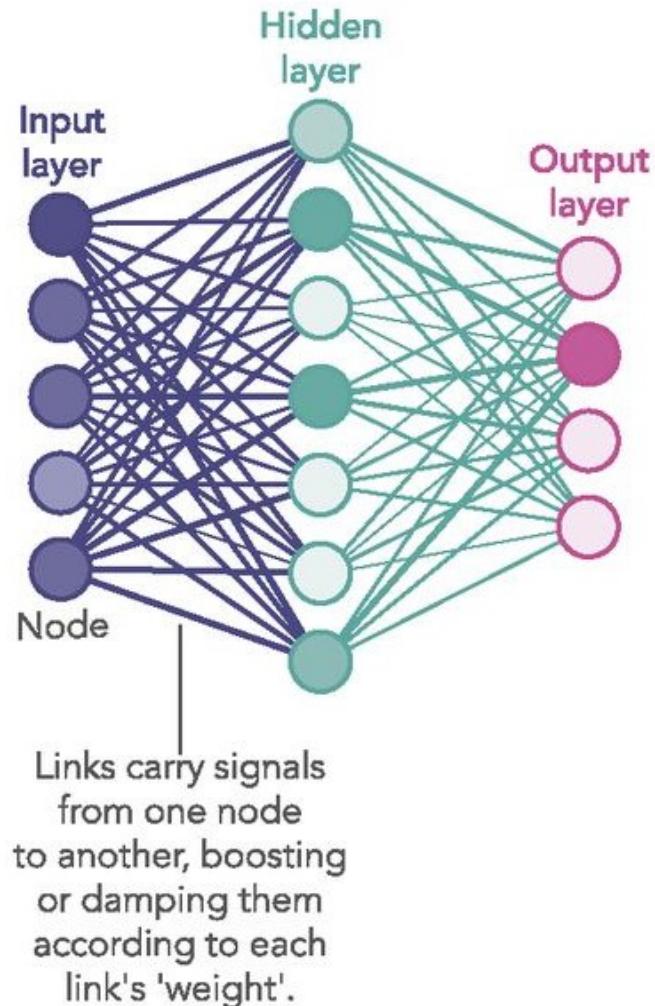
Artificial

- Machine Learning

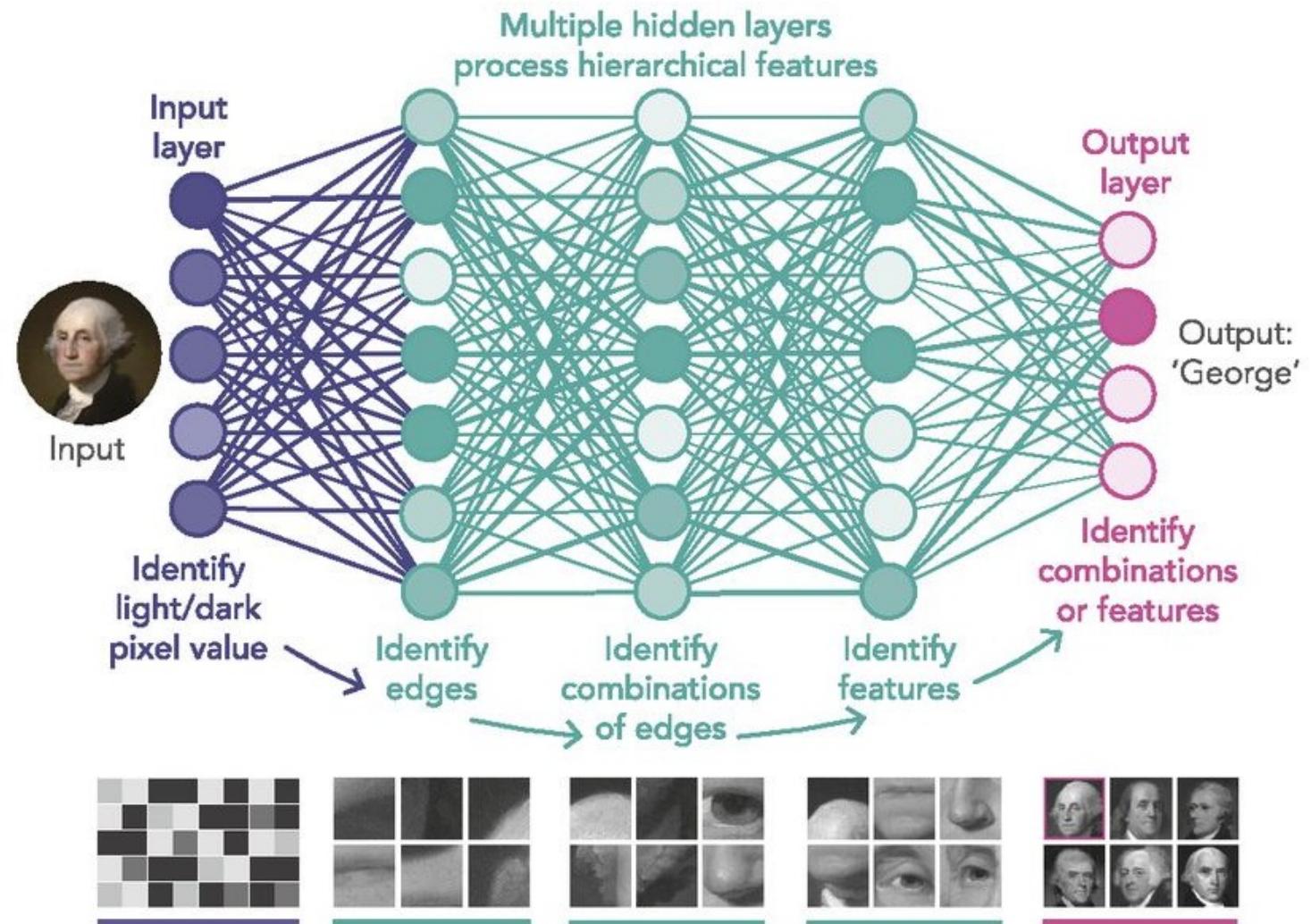


Deep Learning

1980S-ERA NEURAL NETWORK

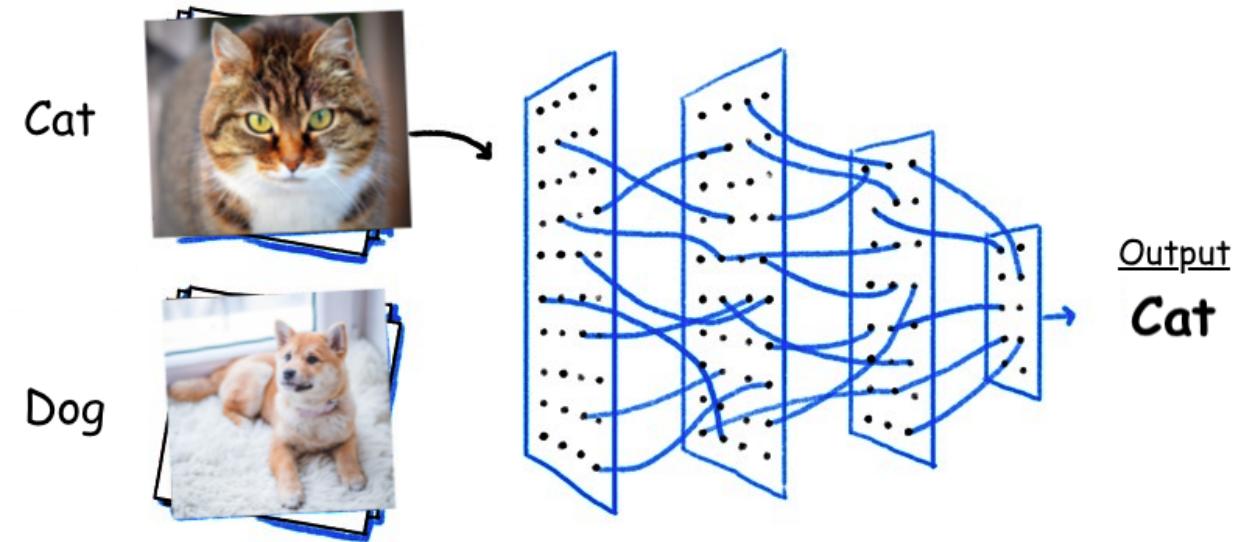


DEEP LEARNING NEURAL NETWORK



What Can Deep Learning Do?

- Classification
- What is this?



What Can Deep Learning Do?

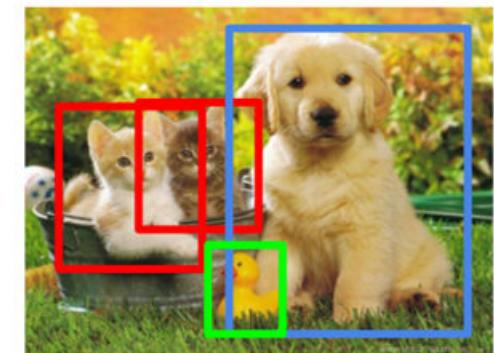
- Objective Detection
- Where is it?

Classification



CAT

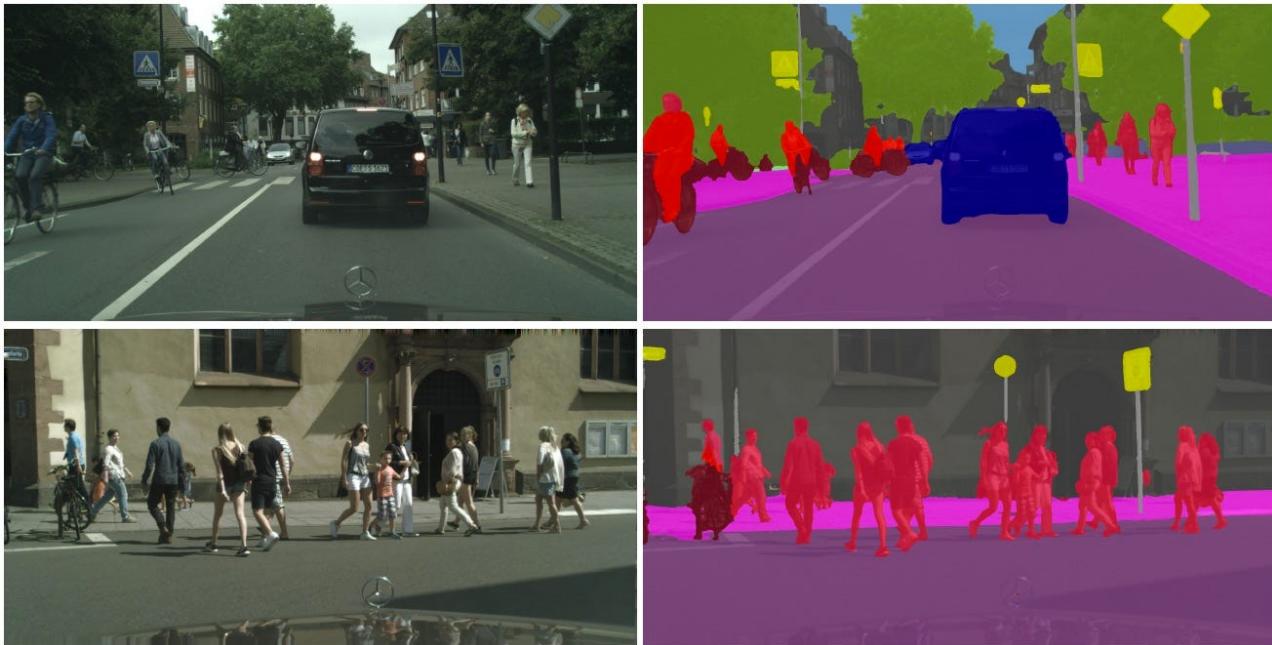
Object Detection



CAT, DOG, DUCK

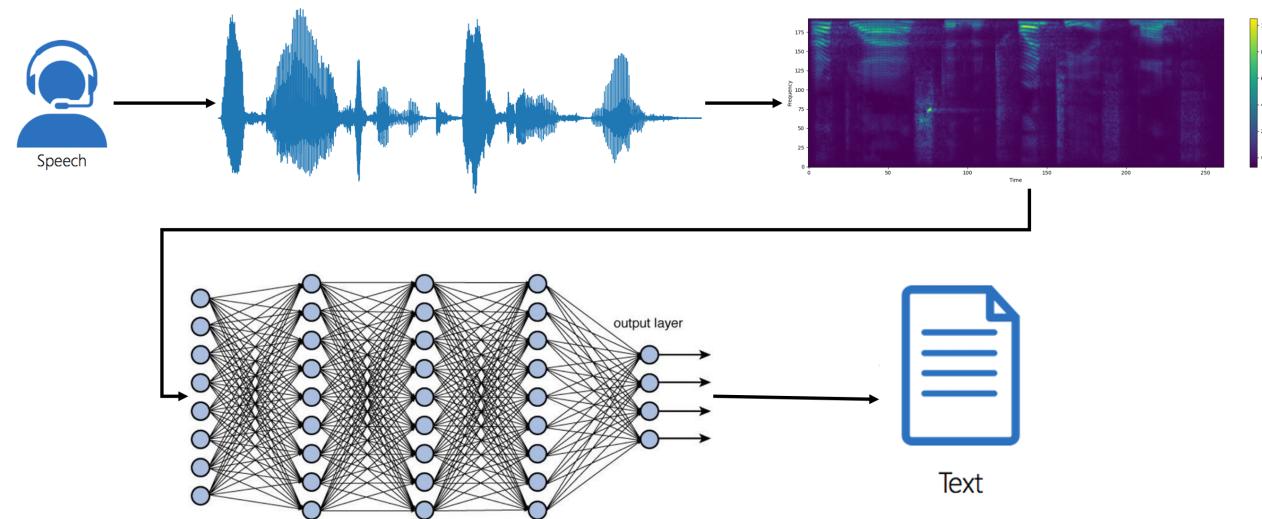
What Can Deep Learning Do?

- Semantic Segmentation
- Classify every pixel



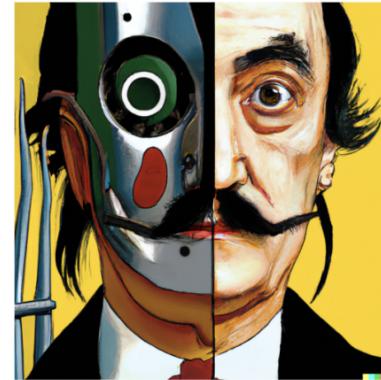
What Can Deep Learning Do?

- Speech Recognition
- Voice to text



What Can Deep Learning Do?

- AIGC: AI-Generated Content
- Text-to-image/image-to-image



vibrant portrait painting of Salvador Dalí with a robotic half face



a shiba inu wearing a beret and black turtleneck



a close up of a handpalm with leaves growing from it



an espresso machine that makes coffee from human souls, artstation



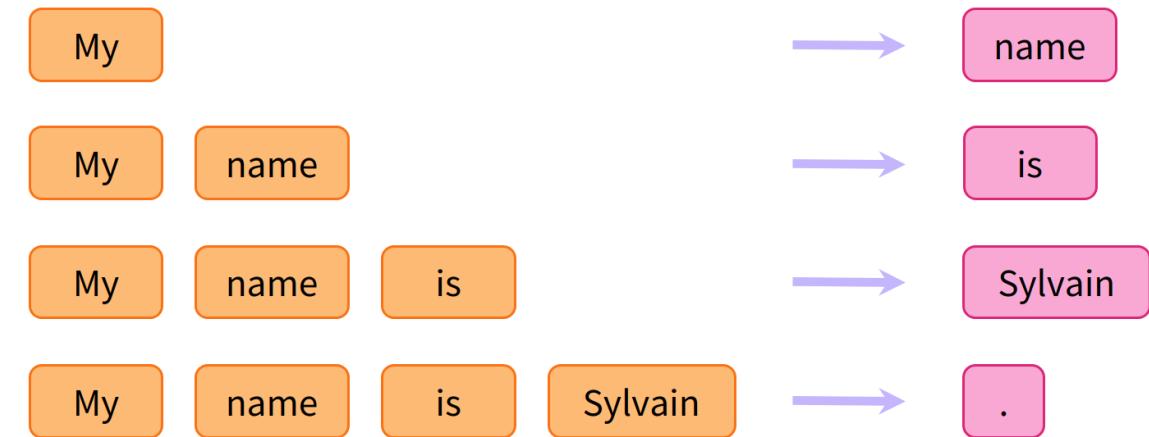
panda mad scientist mixing sparkling chemicals, artstation



a corgi's head depicted as an explosion of a nebula

What Can Deep Learning Do?

- GPT: Generative Pre-trained Transformer
- Autoregressive model



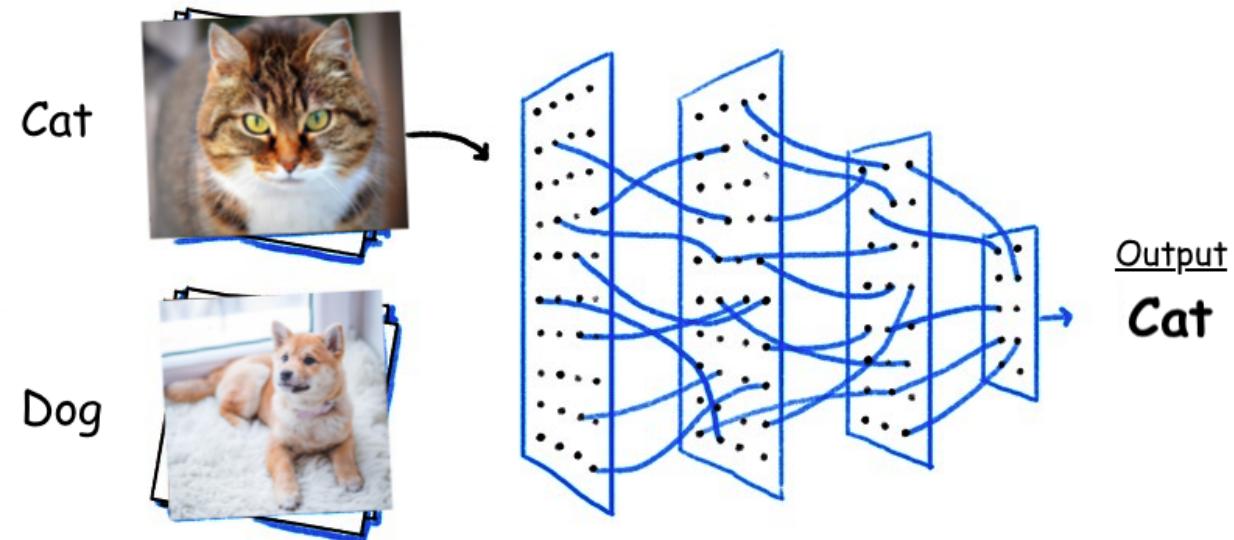
Problem Formulation

$$\bar{\mathbf{y}} = f(\mathbf{W}, \mathbf{x}) = f_M(W_M, f_{M-1}(W_{M-1}, \dots, f_1(W_1, \mathbf{x})))$$

$$\mathbf{W} = \arg \min_{\mathbf{W}} \sum_{i=1}^N L(\bar{\mathbf{y}}, \mathbf{y})$$

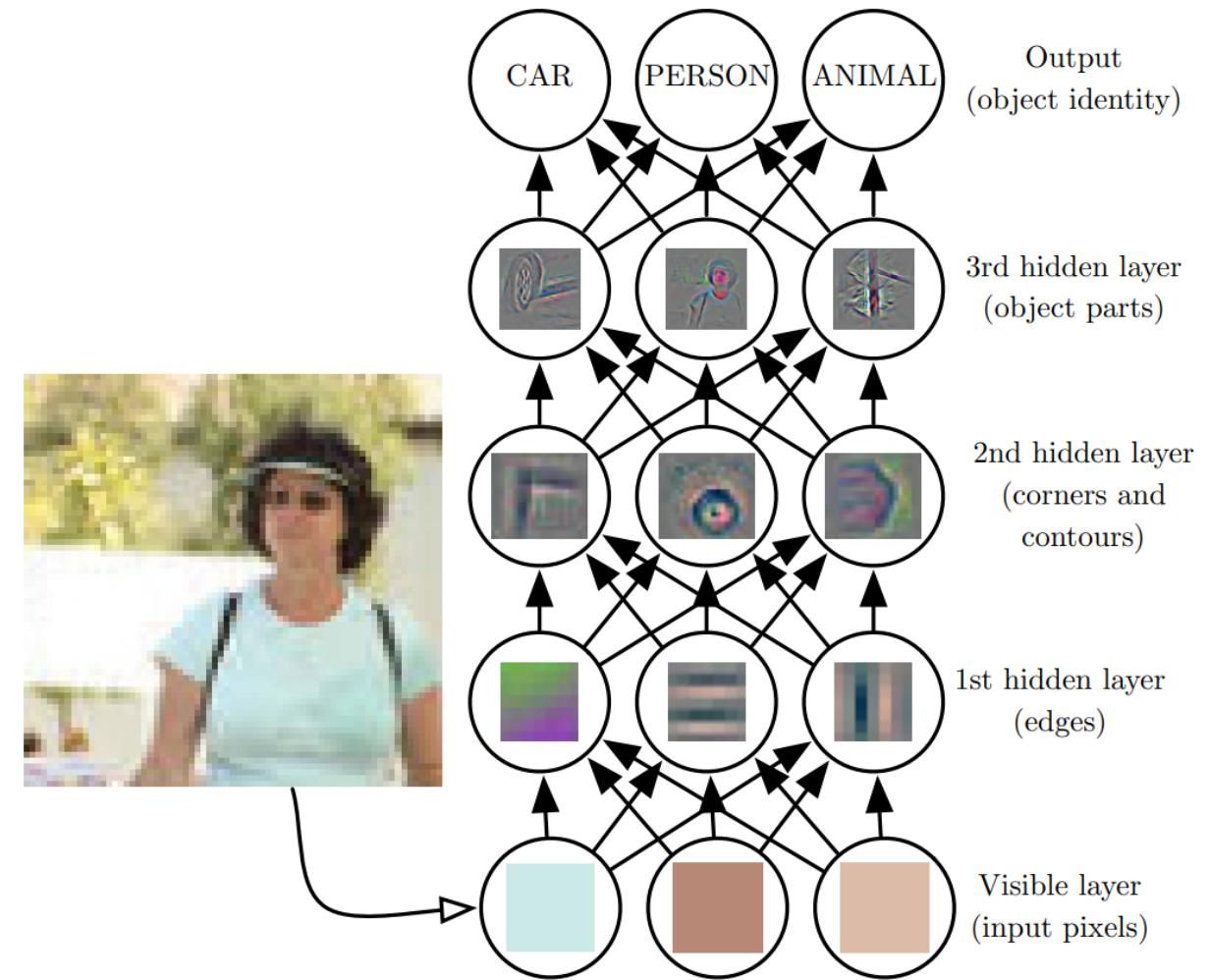
Revisiting Classification

- Input: \mathbf{x} is the image (RGB)
- Output: cat: $\mathbf{y} = [1, 0]$; dog: $\mathbf{y} = [0, 1]$
- $\bar{\mathbf{y}} = f(\mathbf{W}, \mathbf{x})$



Imitating Human Perception

- Input: \mathbf{x} is the image (RGB)
- 1st hidden layer:
$$\mathbf{x}_1 = \mathbf{f}_1(\mathbf{x}) = \sigma(\mathbf{W}_1 \mathbf{x} + \mathbf{b}_1)$$
- 2nd hidden layer:
$$\mathbf{x}_2 = \mathbf{f}_2(\mathbf{x}) = \sigma(\mathbf{W}_2 \mathbf{x}_1 + \mathbf{b}_2)$$
-



Matrix Multiplication

- W_1x

$$\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix} \times \begin{bmatrix} 7 \\ 8 \\ 9 \end{bmatrix} = \begin{bmatrix} (1)(7)+(2)(8)+(3)(9) \\ (4)(7)+(5)(8)+(6)(9) \end{bmatrix} = \begin{bmatrix} 7+16+27 \\ 28+40+54 \end{bmatrix} = \begin{bmatrix} 50 \\ 122 \end{bmatrix}$$

Dimensions:

1st Matrix: 2×3
columns on 1st = rows on 2nd

2nd Matrix: 3×1

Result: 2×1

Final Result: 2×1

The number of rows in the 1st matrix and the number of columns in the 2nd matrix, make the dimensions of the final matrix

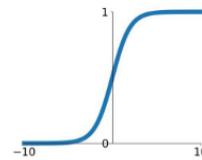
Activation Function

- $f_1(\mathbf{x}) = \sigma(\mathbf{W}_1\mathbf{x} + \mathbf{b}_1)$

Activation Functions

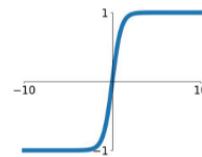
Sigmoid

$$\sigma(x) = \frac{1}{1+e^{-x}}$$



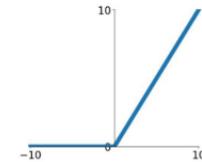
tanh

$$\tanh(x)$$

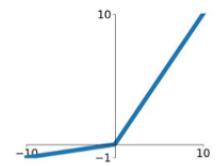


ReLU

$$\max(0, x)$$

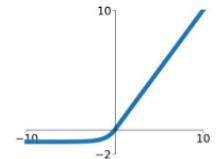


Leaky ReLU
 $\max(0.1x, x)$



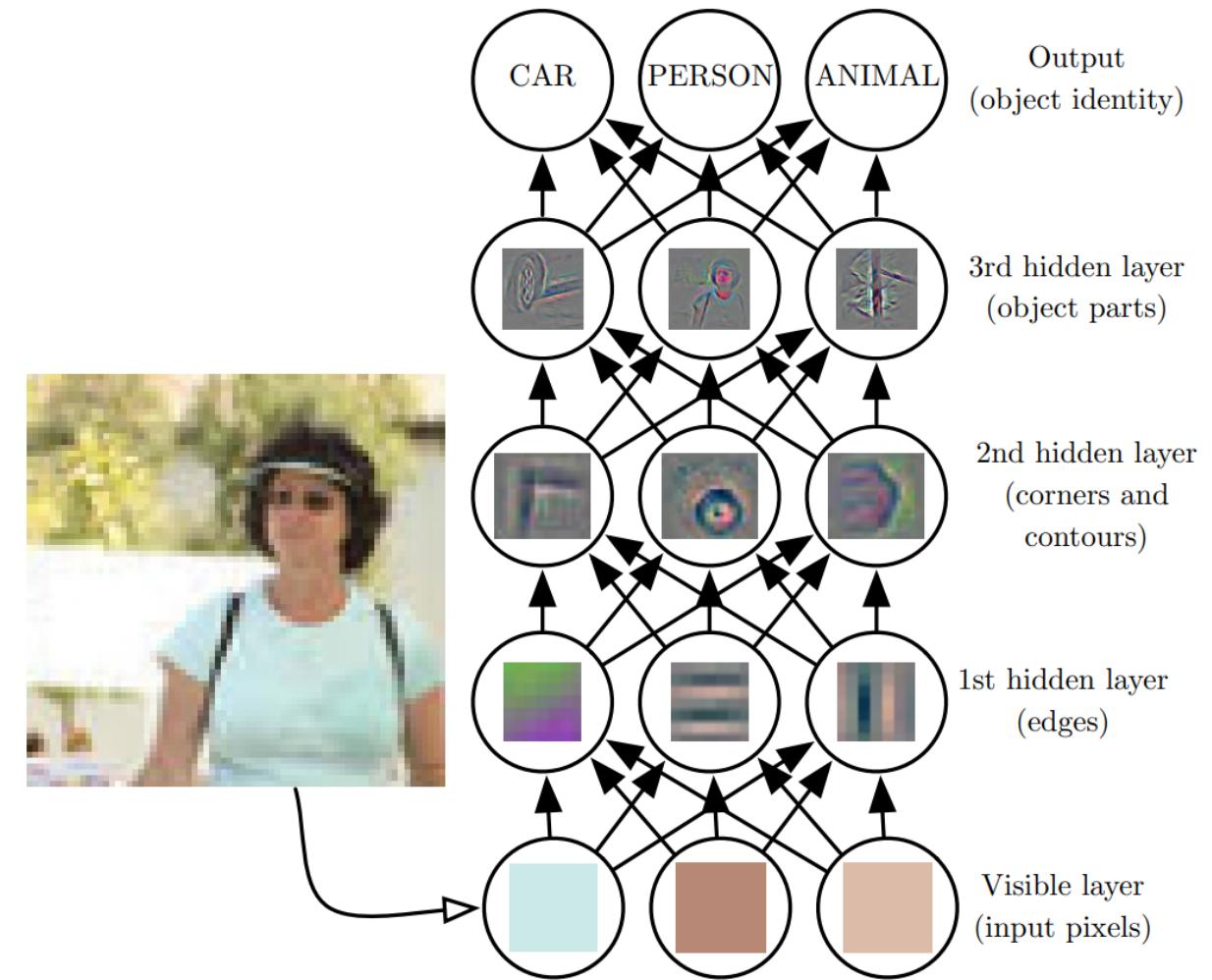
Maxout
 $\max(w_1^T x + b_1, w_2^T x + b_2)$

ELU
$$\begin{cases} x & x \geq 0 \\ \alpha(e^x - 1) & x < 0 \end{cases}$$



Imitating Human Perception

- Input: \mathbf{x} is the image (RGB)
- 1st hidden layer:
$$\mathbf{x}_1 = \mathbf{f}_1(\mathbf{x}) = \sigma(\mathbf{W}_1 \mathbf{x} + \mathbf{b}_1)$$
- 2nd hidden layer:
$$\mathbf{x}_2 = \mathbf{f}_2(\mathbf{x}) = \sigma(\mathbf{W}_2 \mathbf{x}_1 + \mathbf{b}_2)$$
-



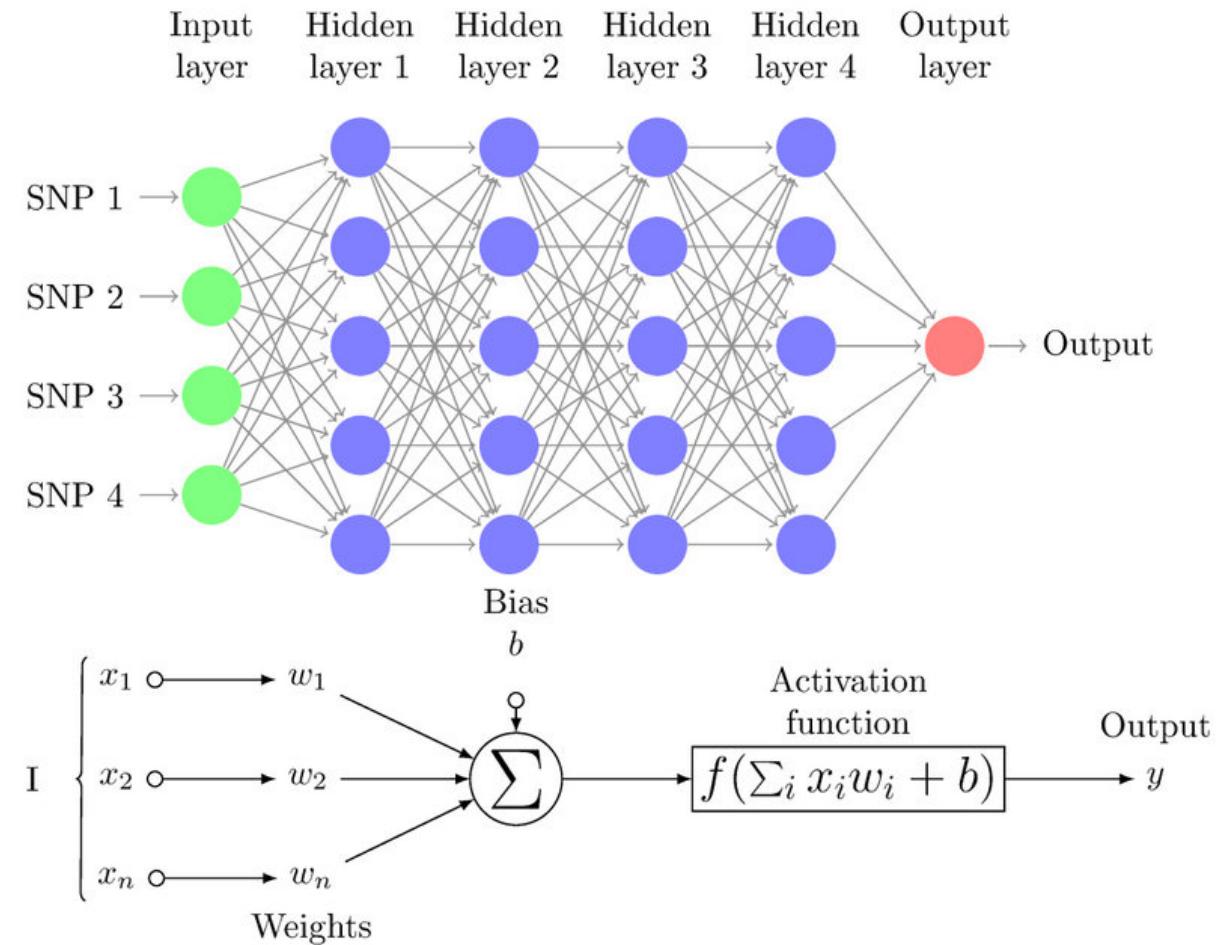
Output Function

- $\boldsymbol{x}_M = \text{softmax}(\boldsymbol{W}_M \boldsymbol{x}_{M-1} + \boldsymbol{b}_M)$
- $\text{softmax}(\boldsymbol{x}_M)_i = \frac{e^{x_{M,i}}}{\sum_j e^{x_{M,j}}}$
- Regarded as probabilities

$$\begin{bmatrix} \frac{e^{x_1}}{e^{x_1}+e^{x_2}+e^{x_3}+e^{x_4}} \\ \frac{e^{x_2}}{e^{x_1}+e^{x_2}+e^{x_3}+e^{x_4}} \\ \frac{e^{x_3}}{e^{x_1}+e^{x_2}+e^{x_3}+e^{x_4}} \\ \frac{e^{x_4}}{e^{x_1}+e^{x_2}+e^{x_3}+e^{x_4}} \end{bmatrix} = \begin{bmatrix} e^{x_1} \\ e^{x_2} \\ e^{x_3} \\ e^{x_4} \end{bmatrix} / (e^{x_1} + e^{x_2} + e^{x_3} + e^{x_4}) \implies e^x / \text{sum}(e^x)$$

Multi-layer Perceptrons (MLP)

- $f(\mathbf{x}) = f_M \circ f_{M-1} \circ \dots \circ f_1(\mathbf{x})$
- $\mathbf{W}_1, \mathbf{b}_1, \dots, \mathbf{W}_M, \mathbf{b}_M$ are trainable



Loss Function

- $L(\bar{y}, y)$, indicates the quality
- Smaller is better ↓
- Cross entropy is for classification
- e.g. $p = [1, 0]; q = [0.8, 0.2]$
- $CE(p, q) = -\log(0.8)$

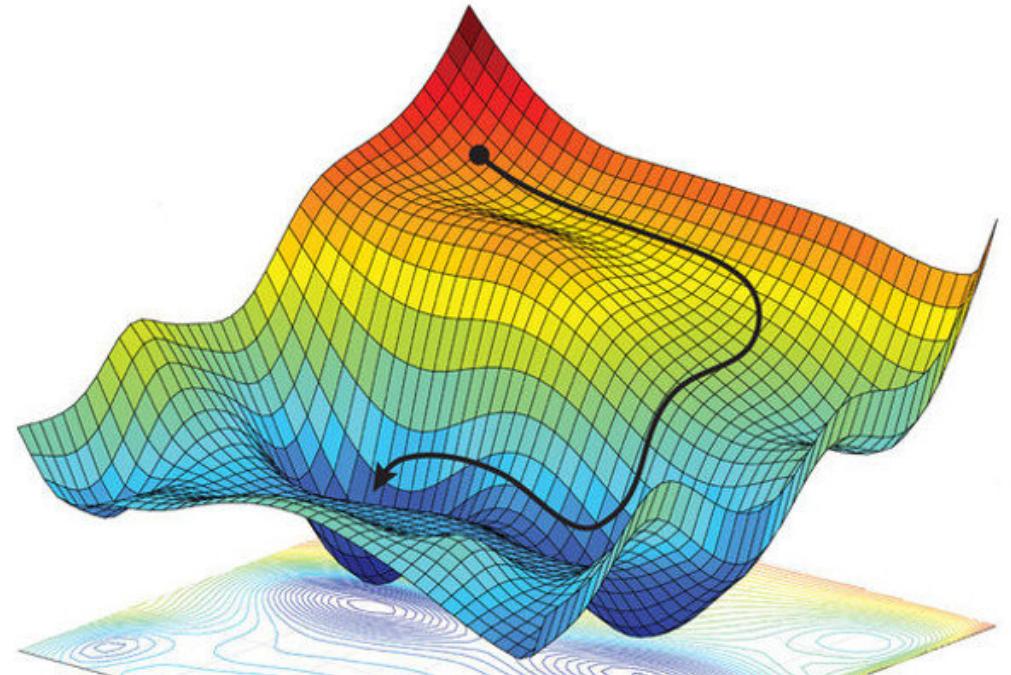
$$H(p, q) = - \sum_{x \in \text{classes}} p(x) \log q(x)$$

True probability distribution
(one-hot)

Your model's predicted
probability distribution

Gradient Descent

- Iterative algorithm
- $\mathbf{W}^{(t)} = \mathbf{W}^{(t-1)} - \gamma \frac{\partial L}{\partial \mathbf{W}^{(t)}}$
- γ is the learning rate
- Chain rule $\frac{dz}{dx} = \frac{dz}{dy} \frac{dy}{dx}$

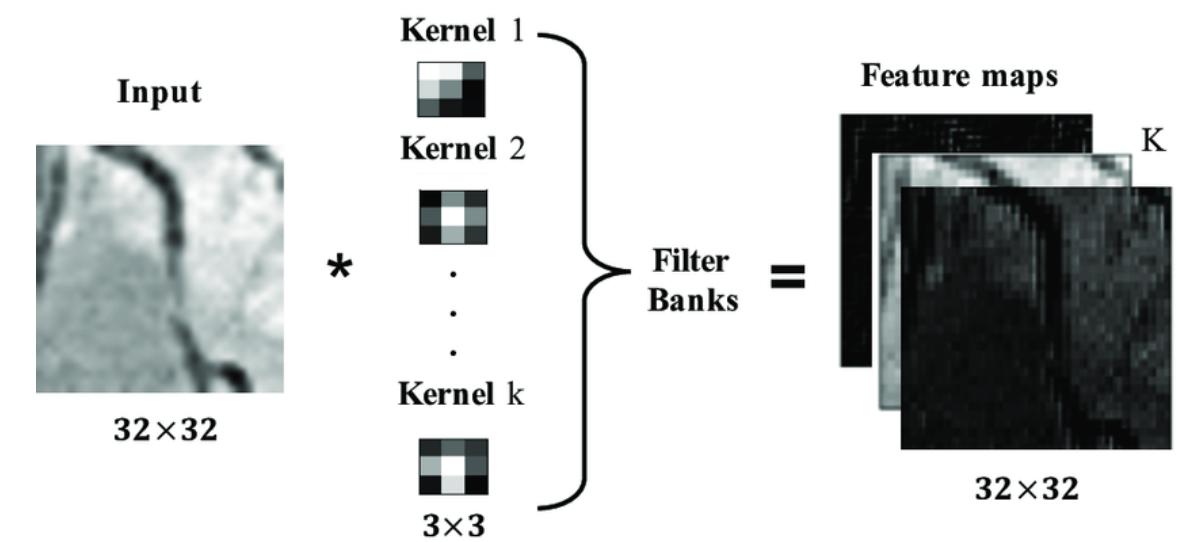


Implementation

- Convolutional Neural Networks
- Training and Testing
- PyTorch

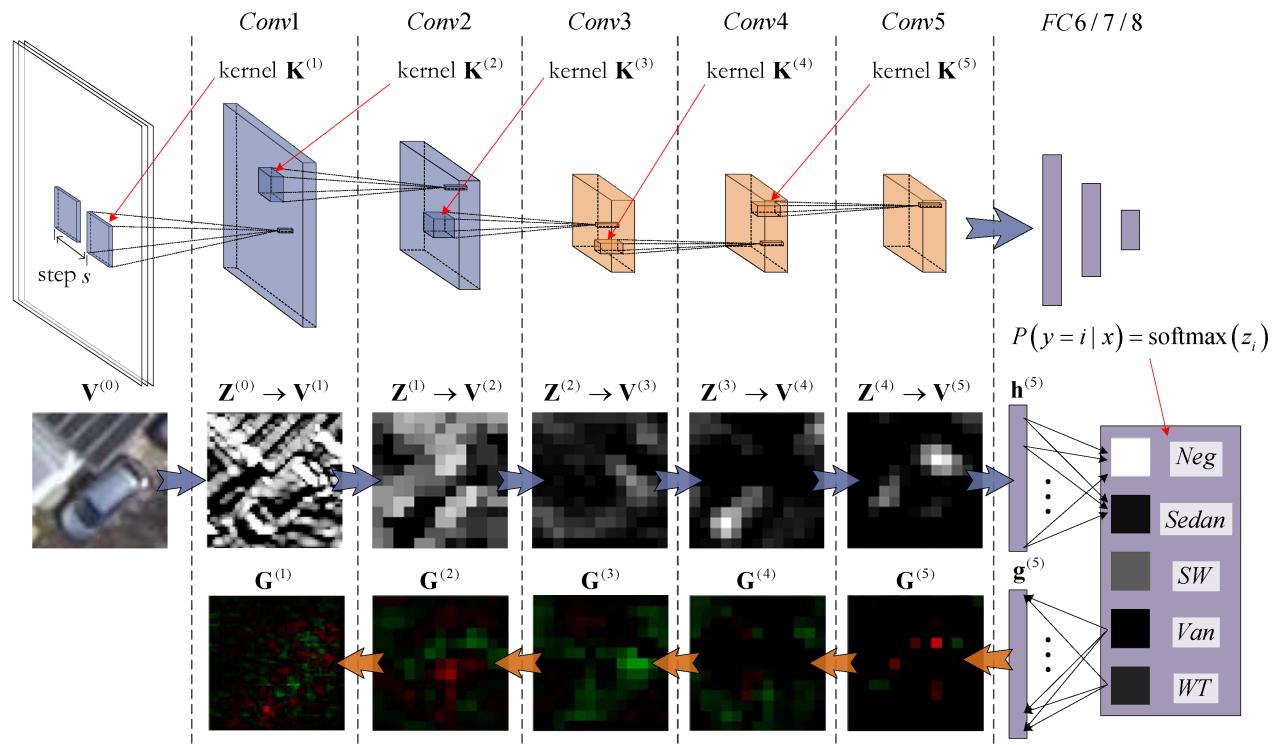
Convolution

- From signal processing
- For feature extraction



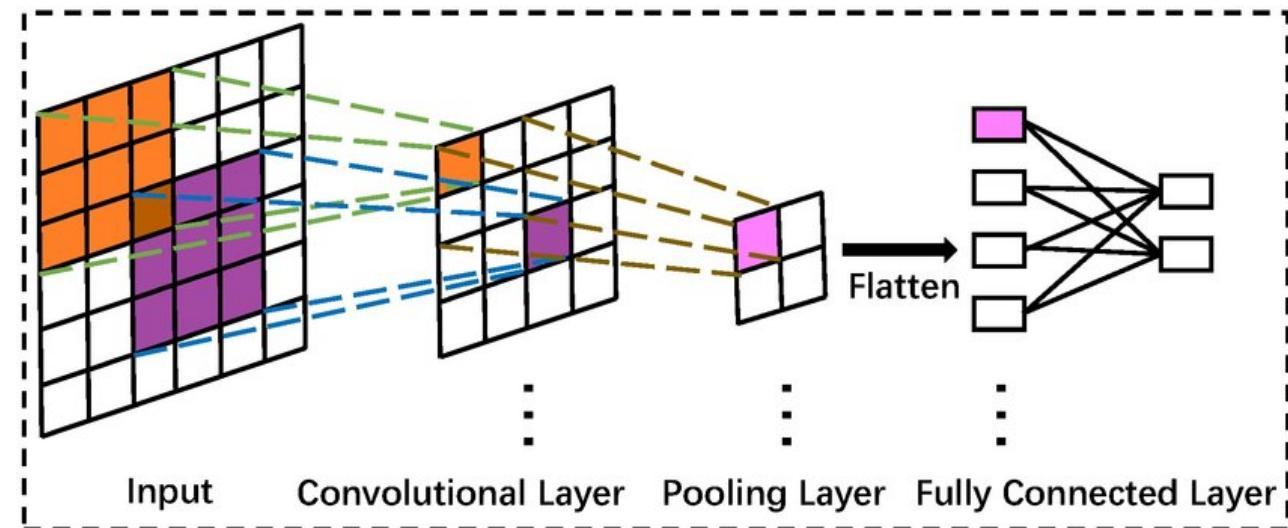
Convolutional Layers

- Convolutional layer
- Preserve 2D structure
- Local perception
- Less weights



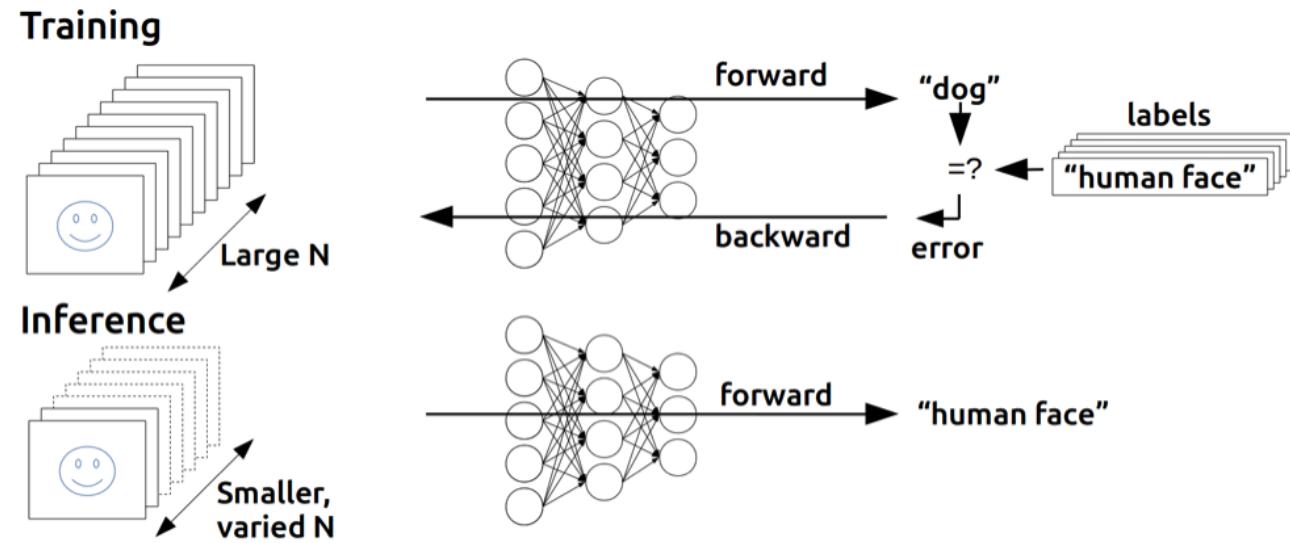
Convolutional Neural Networks

- Convolutional layer
- Max/avg. pooling layer
- Fully connected layer (MLP)



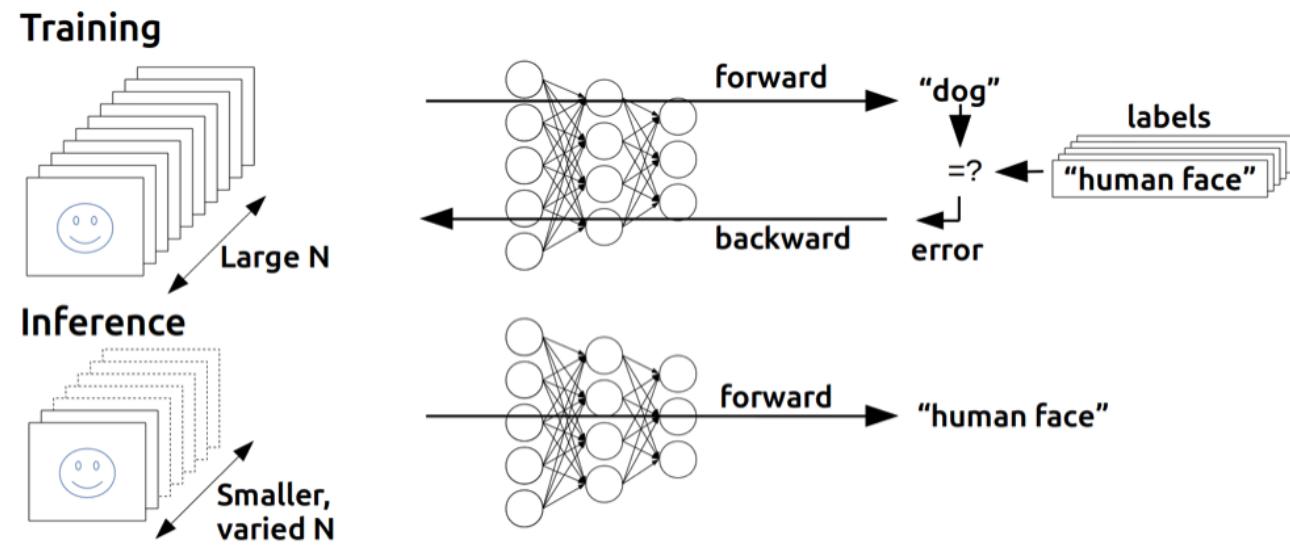
Training Neural Networks

- Sample a batch of data
- Forward: compute the loss
- Backward: update the weights
- $\mathbf{W}^{(t)} = \mathbf{W}^{(t-1)} - \gamma \frac{\partial L}{\partial \mathbf{W}^{(t)}}$



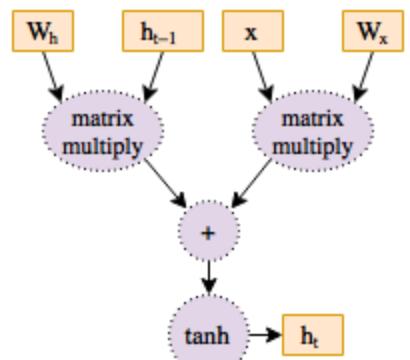
Testing Neural Networks

- Sample a batch of data
- Compute the loss and accuracy

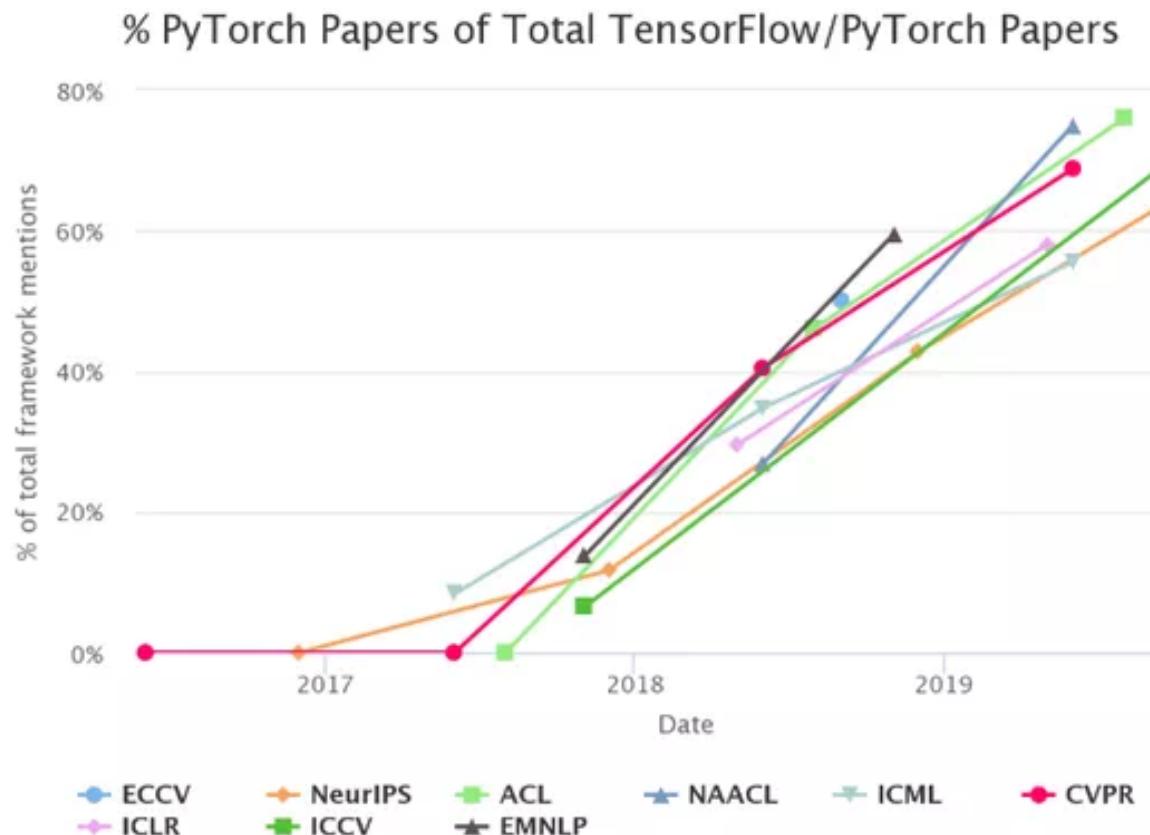


PyTorch

- PyTorch is famous
- Computation graph



$$h_t = \tanh(W_h h_{t-1}^T + W_x x^T)$$



Import Libraries

```
import torch
import torch.nn as nn
import torch.nn.functional as F
import torch.optim as optim
import torchvision
```

- "torch.nn" for neural network layers (Conv2D, Linear,)
- "torch.nn.functional" for basic functions (sigmoid, max_pool2d,)
- "torch.optim" for optimizers (gradient descent)
- "torchvision" for data preparation

Load Data

```
batch_size_train = 100 # Size of a batch of data for training
batch_size_test = 100 # Size of a batch of data for testing
train_loader = torch.utils.data.DataLoader(
    torchvision.datasets.MNIST('data/', train=True, download=True,
                               transform=torchvision.transforms.Compose([
                                   torchvision.transforms.ToTensor(),
                                   torchvision.transforms.Normalize((0.1307,), (0.3081,)))
                               ])),
    batch_size=batch_size_train, shuffle=True)

test_loader = torch.utils.data.DataLoader(
    torchvision.datasets.MNIST('data/', train=False, download=True,
                               transform=torchvision.transforms.Compose([
                                   torchvision.transforms.ToTensor(),
                                   torchvision.transforms.Normalize((0.1307,), (0.3081,)))
                               ])),
    batch_size=batch_size_test, shuffle=True)
```

MNIST Handwritten Digit Dataset

label = 5



label = 0



label = 4



label = 1



label = 9



label = 2



label = 1



label = 3



label = 1



label = 4



label = 3



label = 5



label = 3



label = 6



label = 1



label = 7



label = 2



label = 8



label = 6



label = 9



Define the Model

```
class Net(nn.Module):
    def __init__(self):
        super(Net, self).__init__()
        self.conv1 = nn.Conv2d(1, 10, kernel_size=5)
        self.conv2 = nn.Conv2d(10, 20, kernel_size=5)
        self.fc1 = nn.Linear(320, 50)
        self.fc2 = nn.Linear(50, 10)

    def forward(self, x):
        x = F.relu(F.max_pool2d(self.conv1(x), 2))
        x = F.relu(F.max_pool2d(self.conv2(x), 2))
        x = x.view(-1, 320)
        x = F.relu(self.fc1(x))
        x = F.dropout(x, training=self.training)
        x = self.fc2(x)
        return x
```

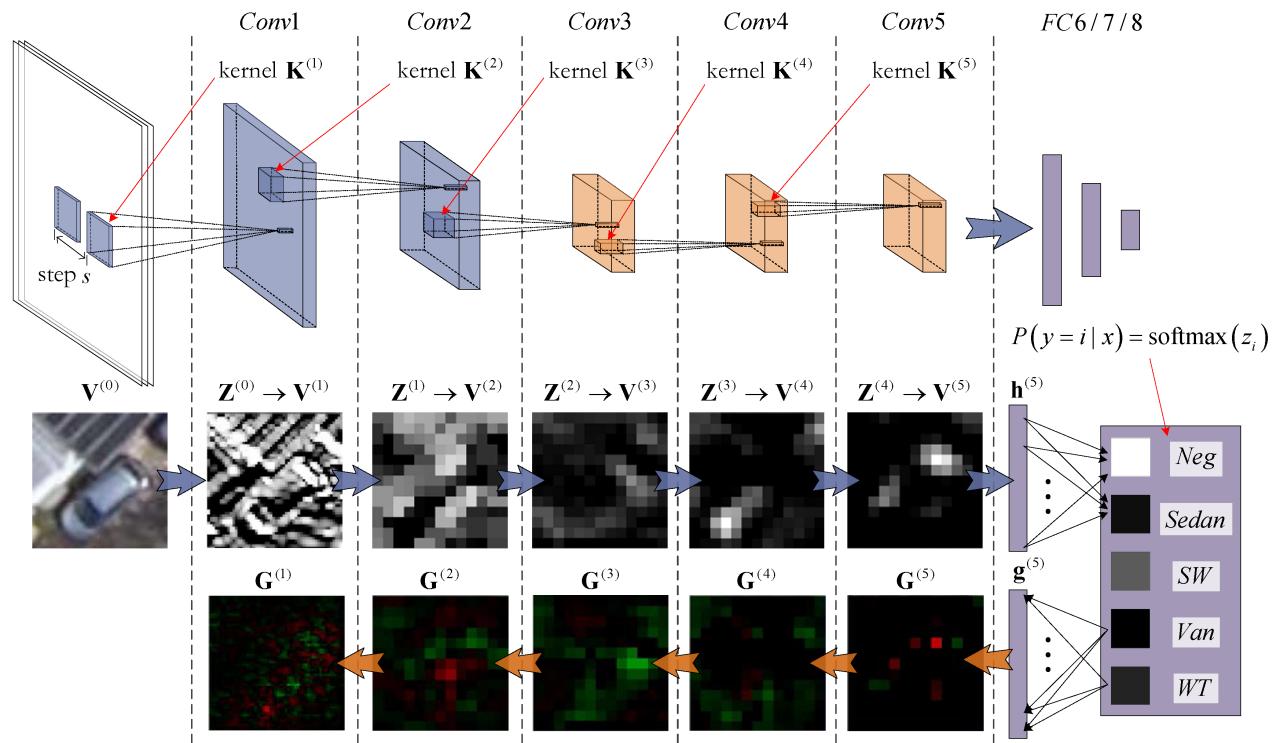
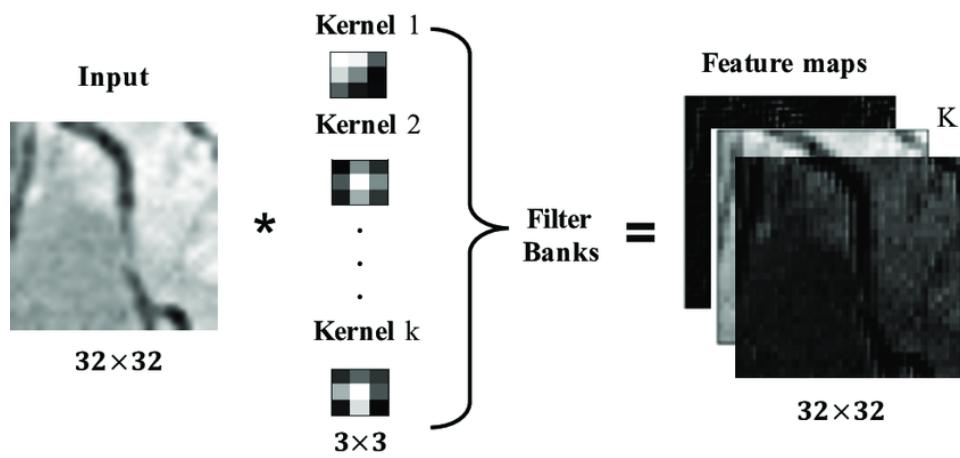
Define the Model

- Define the layers
- "self.conv1": convolution layer, input channel 1, output channels 10, kernel size 5
- "self.conv2": convolution layer, input channel 10, output channels 20, kernel size 5

```
class Net(nn.Module):  
    def __init__(self):  
        super(Net, self).__init__()  
        self.conv1 = nn.Conv2d(1, 10, kernel_size=5)  
        self.conv2 = nn.Conv2d(10, 20, kernel_size=5)  
        self.fc1 = nn.Linear(320, 50)  
        self.fc2 = nn.Linear(50, 10)
```

Convolution Layer

- Channels and kernel size



Define the Model

- "self.fc1": fully connected layer, input size 320, output size 50
- "self.fc2": fully connected layer, input size 50, output size 10
- How to get the input size of self.fc1 ?

```
class Net(nn.Module):
    def __init__(self):
        super(Net, self).__init__()
        self.conv1 = nn.Conv2d(1, 10, kernel_size=5)
        self.conv2 = nn.Conv2d(10, 20, kernel_size=5)
        self.fc1 = nn.Linear(320, 50)
        self.fc2 = nn.Linear(50, 10)
```

Define the Forward Pass

- conv1 → pooling → ReLU
- conv2 → pooling → ReLU
- fc1 → ReLU → fc2

```
class Net(nn.Module):
    def forward(self, x):
        x = F.relu(F.max_pool2d(self.conv1(x), 2))
        x = F.relu(F.max_pool2d(self.conv2(x), 2))
        x = x.view(-1, 320) # flatten
        x = F.relu(self.fc1(x))
        x = self.fc2(x)
        return x
```

Define the Forward Pass

- conv1 → pooling → ReLU → conv2 → pooling → ReLU → fc1 → ReLU → fc2

```
class Net(nn.Module):
    def forward(self, x):
        x = F.relu(F.max_pool2d(self.conv1(x), 2))
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        x = x.view(-1, 320) # flatten
        x = F.relu(self.fc1(x))
        x = self.fc2(x)
        return x
```

Instantiate the Model

- "network" is the model
- "optimizer" is for gradient descent
- Gradients are derived automatically

```
learning_rate = 0.01
# Instantiate the model
network = Net()
# Instantiate the optimizer
optimizer = optim.SGD(network.parameters(), lr=learning_rate)
```

Training and Testing

- Epoch: a pass of training on **the dataset**
- Step: an iteration of gradient descent on **a batch of data**

```
for epoch in range(n_epochs):
    # Training
    for step, (data, target) in enumerate(train_loader):
        # A training step
    # Testing
    for step, (data, target) in enumerate(test_loader):
        # A testing step
```

A Training Step

- "output" is the inferred results
- "loss" is the loss value
- "loss.backward()" computes the gradients
- "optimizer.step()" do gradient descent

```
# Inference
output = network(data)
# Compute the loss
loss = F.cross_entropy(output, target)
# Gradient descent
optimizer.zero_grad()
loss.backward()
optimizer.step()
```

A Testing Step

- "F.cross_entropy" computes the loss
- "pred" is the prediction (the class with the maximum probability)
- "(pred == target).sum()" computes the accuracy

```
# Inference
output = network(data)
# Compute the loss
test_loss += F.cross_entropy(output, target).item()
# Get the prediction
pred = output.max(dim=1)[1]
# Count correct predictions
correct += (pred == target).sum()
```

Experiments

- See `classification.ipynb`
- https://github.com/shelljane/dl_tutorial

Advanced Topics -- Deep Learning in Practice

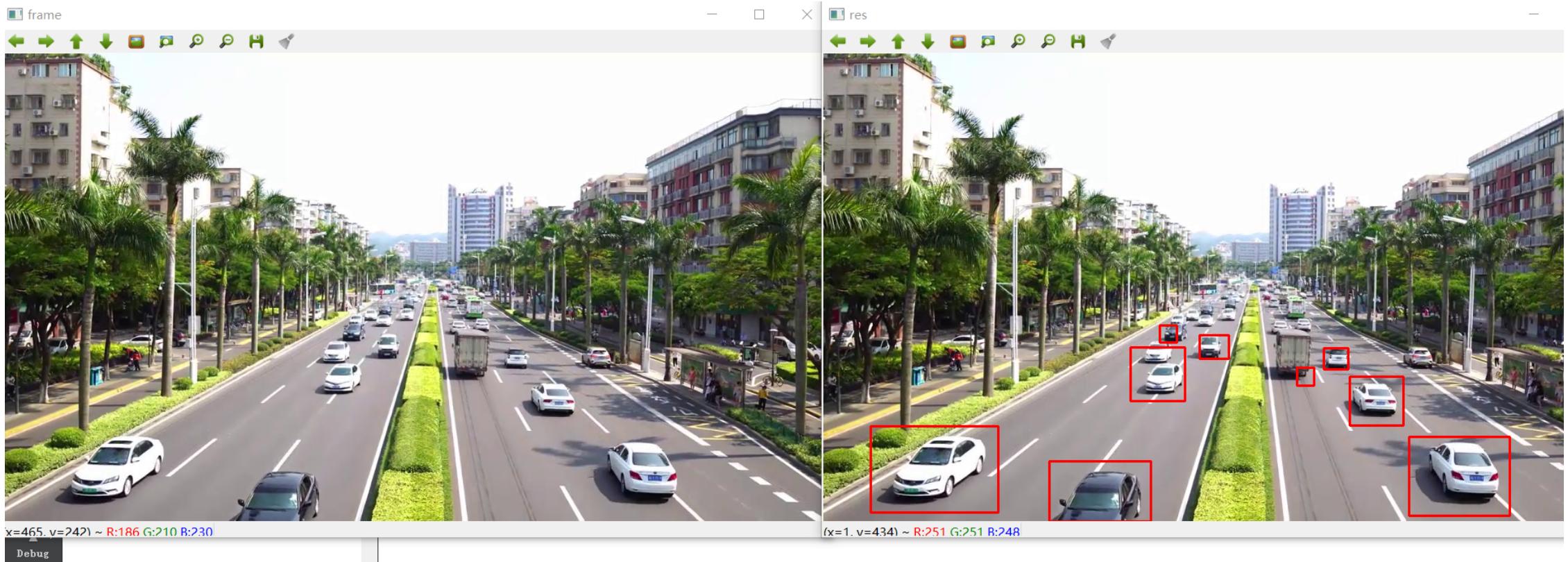
- Network as a black box
- Layer as a black box
- Useful tricks

Deep Learning in Practice

- Network as a black box
- (a) Formulate the task
 - > classification, detection, segmentation, image-to-image, ...
- (b) Find a state-of-the-art model
 - > Carefully choose the input size (32x32, 256x256, 1024x1024, ...)
- (c) Change the dataset to fit your task
 - > Pay attention to the data format

Deep Learning in Practice

- Example: Car Detection



Deep Learning in Practice

- Formulate the task:
-> *Objective detection*
- Find a state-of-the-art model:
-> *YOLO-X*

Deep Learning in Practice

- Find it on Github
-> <https://github.com/Megvii-BaseDetection/YOLOX>



Deep Learning in Practice

- Change the dataset to fit your task
-> YOLOX/docs/train_custom_data.md

1. Create your own dataset

Step 1 Prepare your own dataset with images and labels first. For labeling images, you can use tools like [Labelme](#) or [CVAT](#).

Step 2 Then, you should write the corresponding Dataset Class which can load images and labels through `__getitem__` method. We currently support COCO format and VOC format.

Step 3 Prepare the evaluator. We currently have [COCO evaluator](#) and [VOC evaluator](#). If you have your own format data or evaluation metric, you can write your own evaluator.

Step 4 Put your dataset under `$YOLOX_DIR/datasets`, for VOC:

```
ln -s /path/to/your/VOCdevkit ./datasets/VOCdevkit
```

Deep Learning in Practice

- Go training

Except special cases, we always recommend to use our [COCO pretrained weights](#) for initializing the model.

Once you get the Exp file and the COCO pretrained weights we provided, you can train your own model by the following below command:

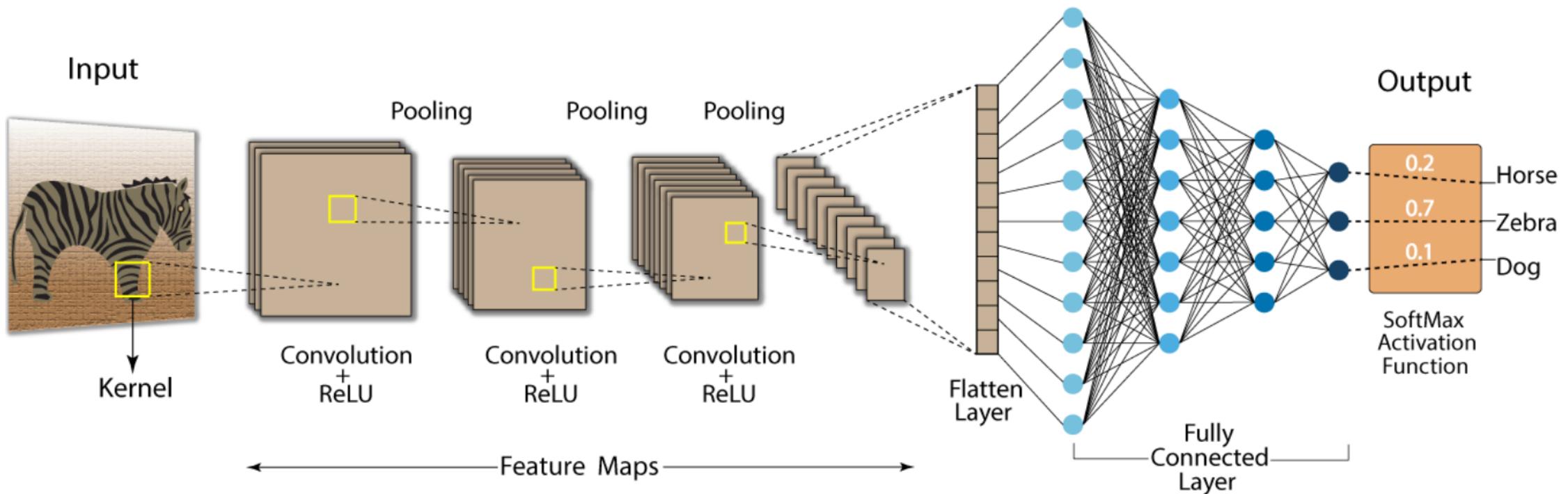
```
python tools/train.py -f /path/to/your/Exp/file -d 8 -b 64 --fp16 -o -c /path/to/the/pretrained/weights [--cache]
```

Deep Learning in Practice

- Layer as a black box
- (1) Find a backbone network
- (2) Design add-on layers or modify it

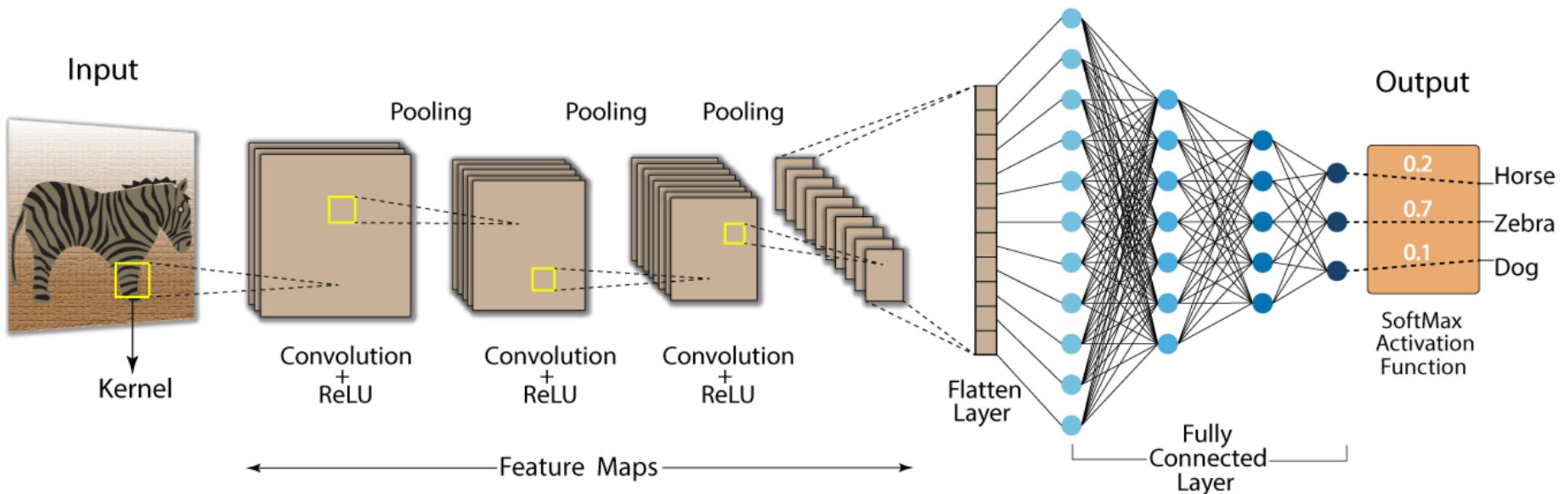
Deep Learning in Practice

- Care about the input/output size!
- Batched inputs:
 - (a) One image: $C \times H \times W$ array ($C=3$ for RGB)
 - (b) A batch of N images: $N \times C \times H \times W$ array



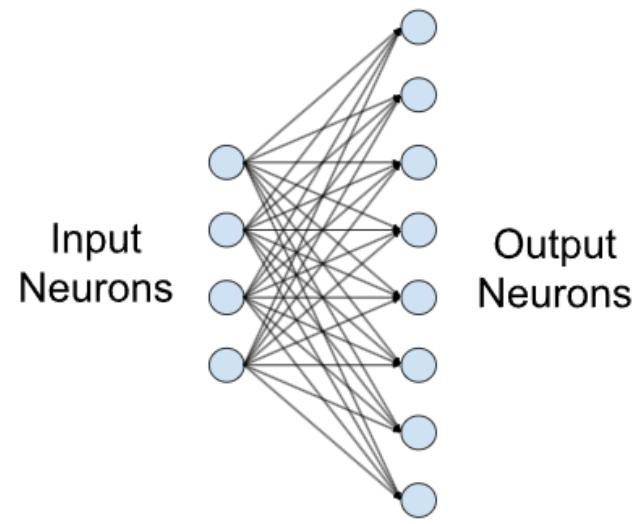
Deep Learning in Practice

- Care about the input/output size!
- Convolutional layer (Conv.):
 - (a) Input size: $[N, C_{i-1}, H_{i-1}, W_{i-1}]$
 - (b) Output size: $[N, C_i, H_i, W_i]$



Deep Learning in Practice

- Care about the size!
- Fully connected layer (FC)
- (a) Input size: $[N, M_{i-1}]$
- (b) Output size: $[N, M_i]$
- Flattening is needed between Conv. and FC layers



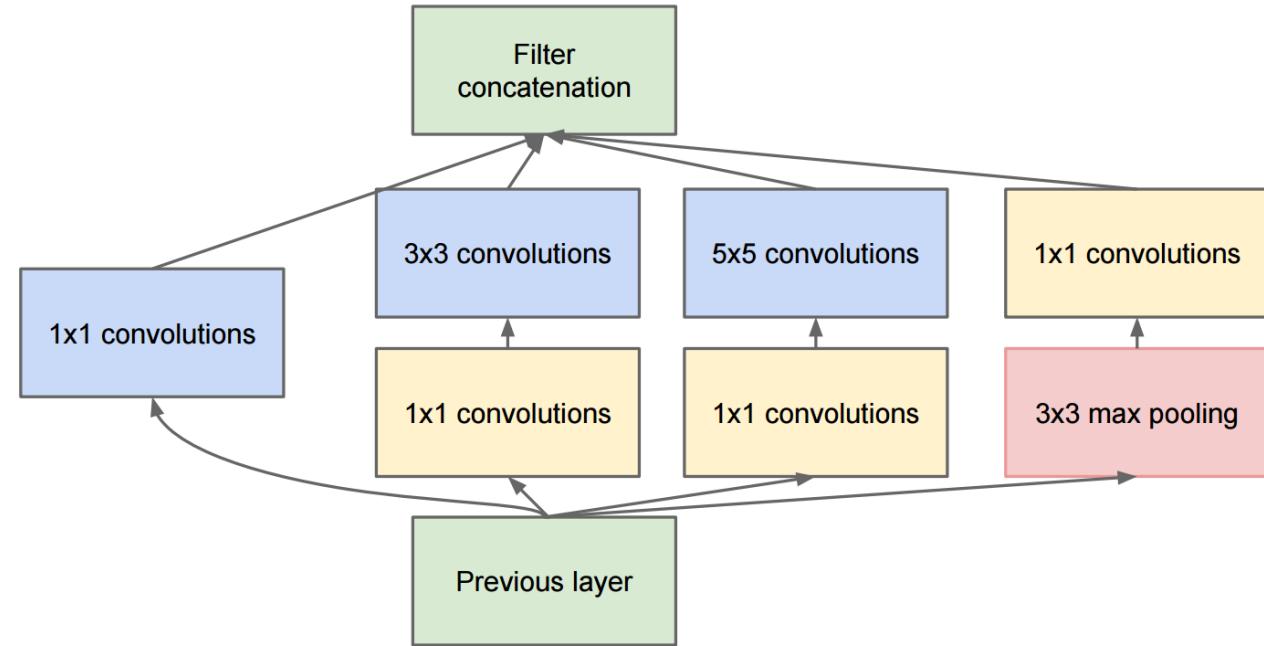
Deep Learning in Practice

- Then use them as LEGO blocks!



Deep Learning in Practice

- Inception Block



Deep Learning in Practice

- Inception V3 Network

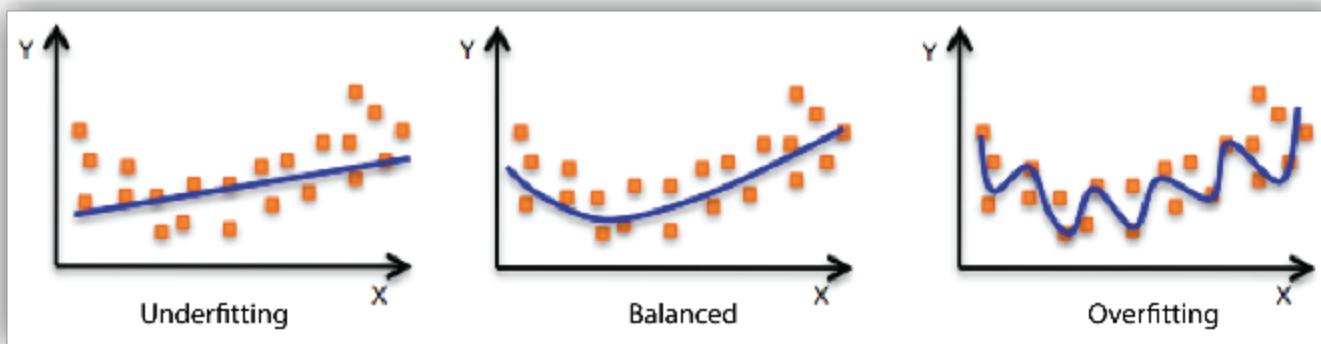
Type	Kernel size/stride	Input size
Convolution	$3 \times 3/2$	$299 \times 299 \times 3$
Convolution	$3 \times 3/1$	$149 \times 149 \times 32$
Convolution	$3 \times 3/1$	$147 \times 147 \times 32$
Pooling	$3 \times 3/2$	$147 \times 147 \times 64$
Convolution	$3 \times 3/1$	$73 \times 73 \times 64$
Convolution	$3 \times 3/2$	$71 \times 71 \times 80$
Convolution	$3 \times 3/1$	$35 \times 35 \times 192$
Inception module	Three modules	$35 \times 35 \times 288$
Inception module	Five modules	$17 \times 17 \times 768$
Inception module	Two modules	$8 \times 8 \times 1,280$
Pooling	8×8	$8 \times 8 \times 2,048$
Linear	Logits	$1 \times 1 \times 2,048$
Softmax	Output	$1 \times 1 \times 1,000$

Deep Learning in Practice

- Useful tricks
- (1) Number of parameters
- (2) Normalization
- (3) Other tricks

Deep Learning in Practice

- Underfitting and overfitting
- (a) Underfitting: low training accuracy
- (b) Overfitting: low testing accuracy but high training accuracy

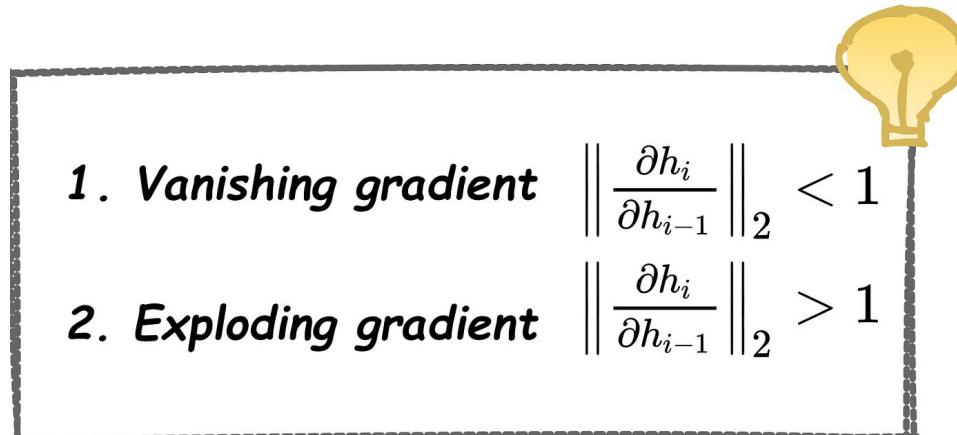


Deep Learning in Practice

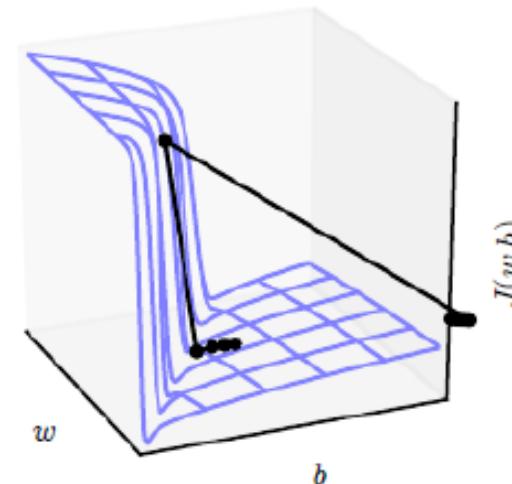
- Convolutional layer
- (a) Kernel size: 3x3, 5x5, 11x11,
- (b) Channel width: 16, 32, 64,
- Principles
- (a) Larger kernel and channel sizes => more parameters to train
- (b) More parameters => higher capacity, overfitting, harder to train

Deep Learning in Practice

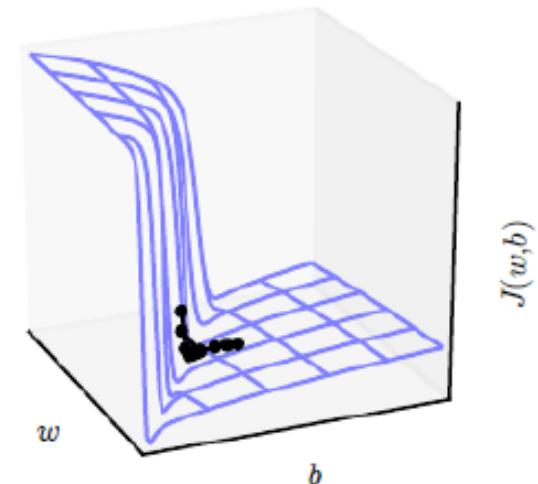
- Abnormal gradients
- (a) Gradient vanishing
- (b) Gradient explosion



Without clipping



With clipping



Deep Learning in Practice

- Batch normalization
-> Stabilize the training by normalizing the outputs of each layer

Input: Values of x over a mini-batch: $\mathcal{B} = \{x_1 \dots m\}$;
Parameters to be learned: γ, β

Output: $\{y_i = \text{BN}_{\gamma, \beta}(x_i)\}$

$$\mu_{\mathcal{B}} \leftarrow \frac{1}{m} \sum_{i=1}^m x_i \quad // \text{mini-batch mean}$$

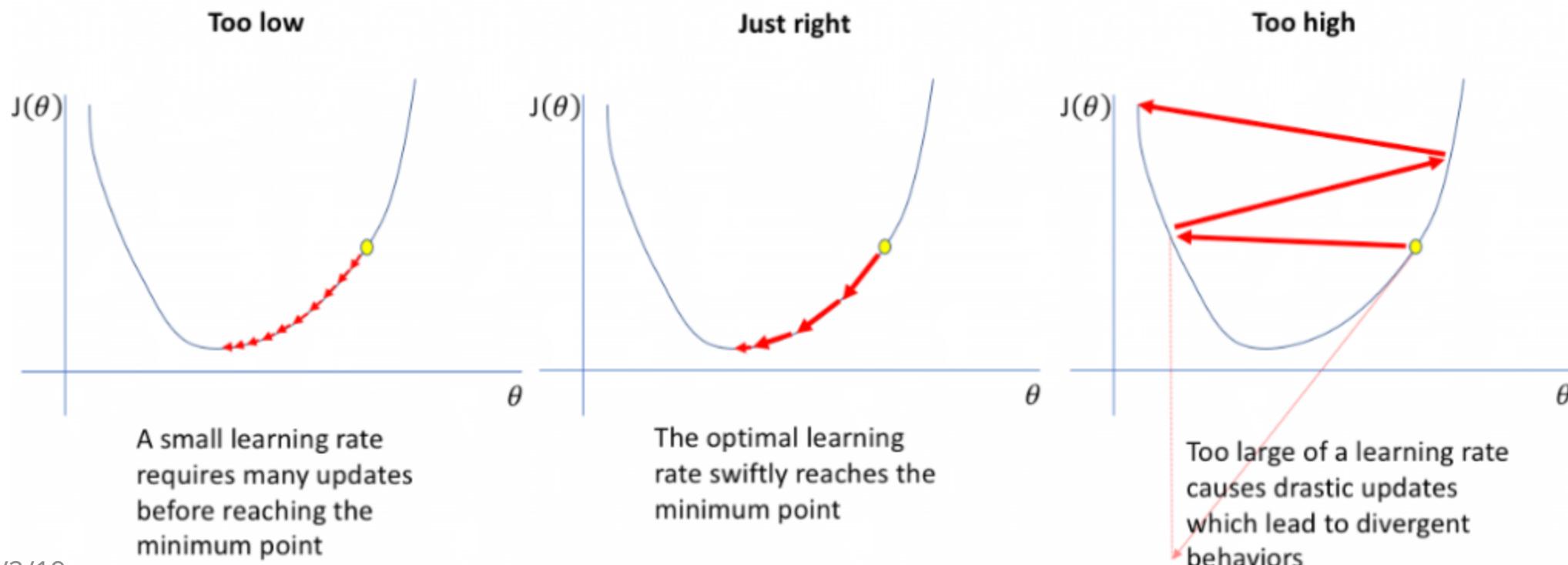
$$\sigma_{\mathcal{B}}^2 \leftarrow \frac{1}{m} \sum_{i=1}^m (x_i - \mu_{\mathcal{B}})^2 \quad // \text{mini-batch variance}$$

$$\hat{x}_i \leftarrow \frac{x_i - \mu_{\mathcal{B}}}{\sqrt{\sigma_{\mathcal{B}}^2 + \epsilon}} \quad // \text{normalize}$$

$$y_i \leftarrow \gamma \hat{x}_i + \beta \equiv \text{BN}_{\gamma, \beta}(x_i) \quad // \text{scale and shift}$$

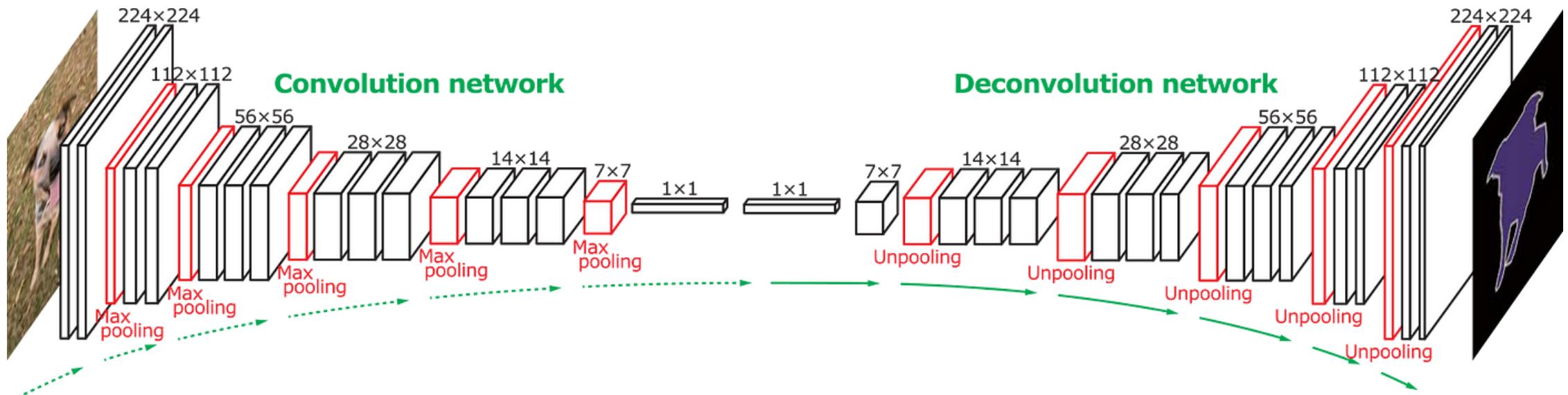
Deep Learning in Practice

- Other tricks, e.g.
- (a) Adjust the learning rate
- (b) Weight regularization
- (c) Dropout



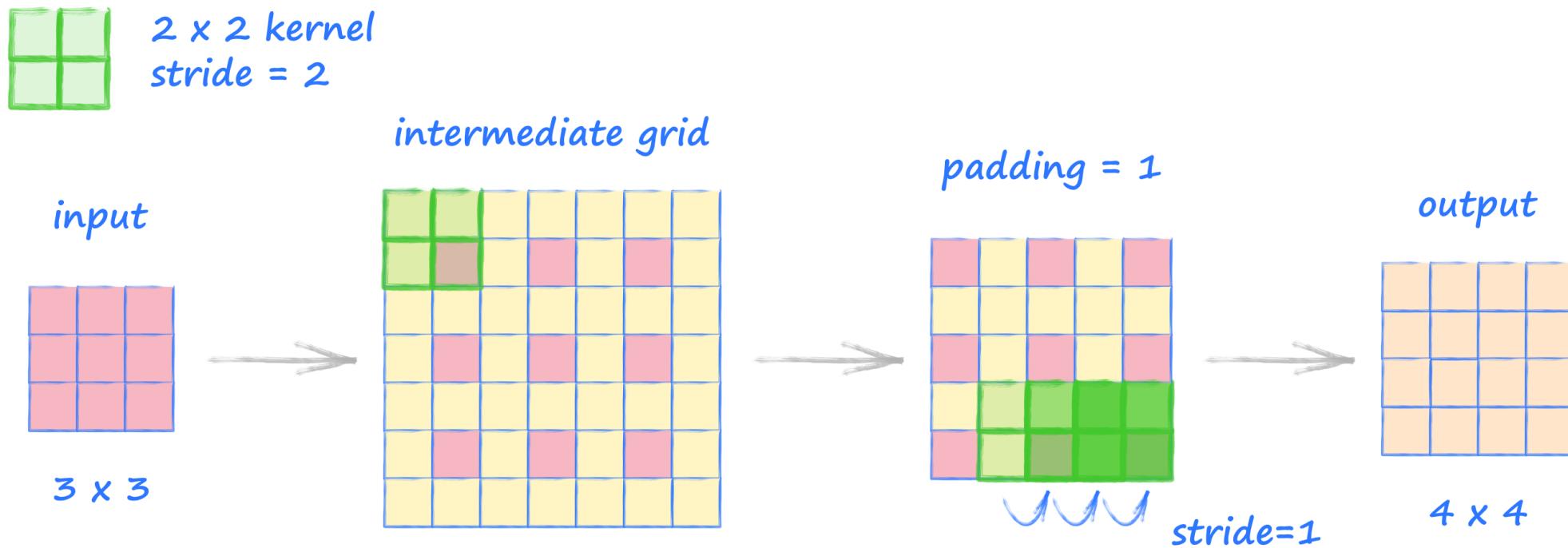
Advanced Topics -- Beyond Classification

- Semantic segmentation
- Image-to-image translation
- Deep learning for OPC



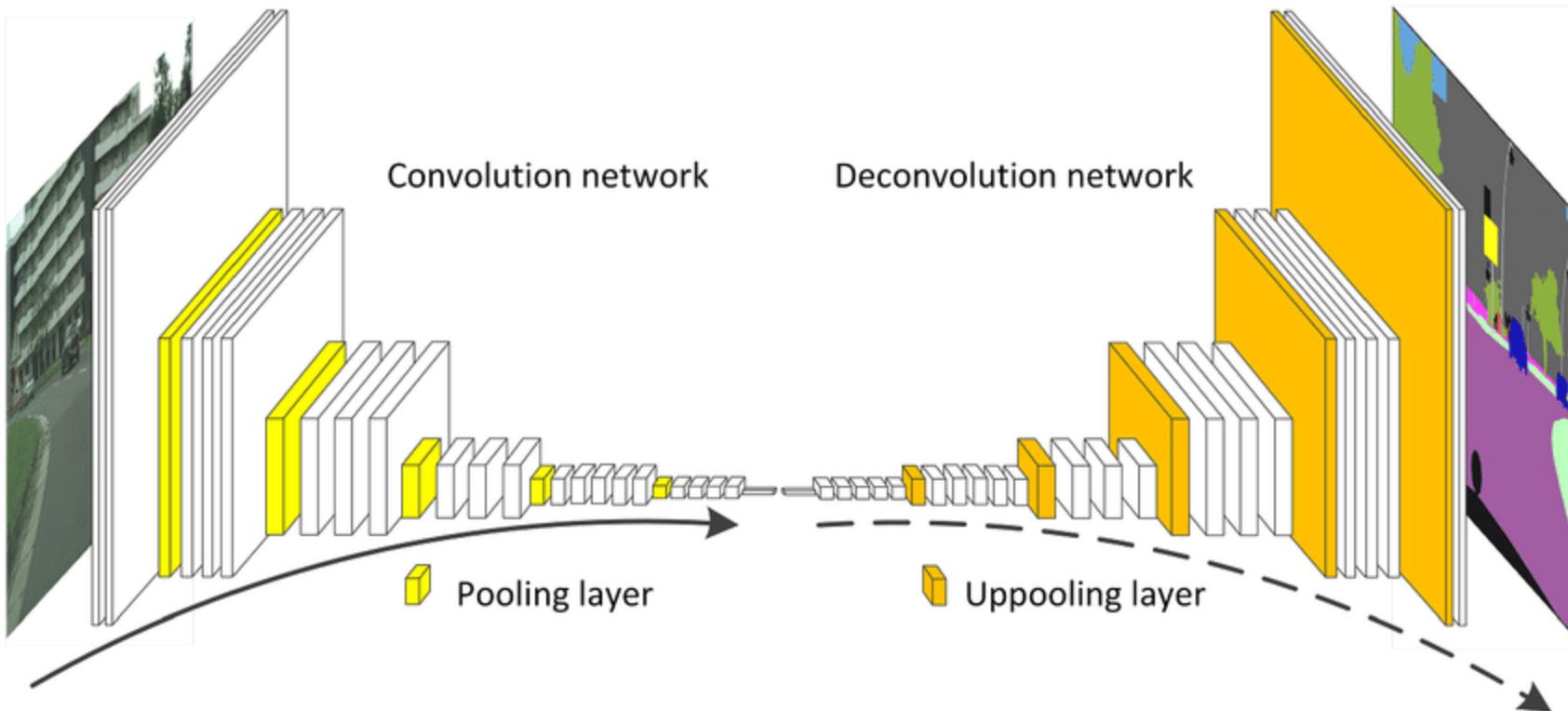
Semantic Segmentation

- Deconvolutional Layer



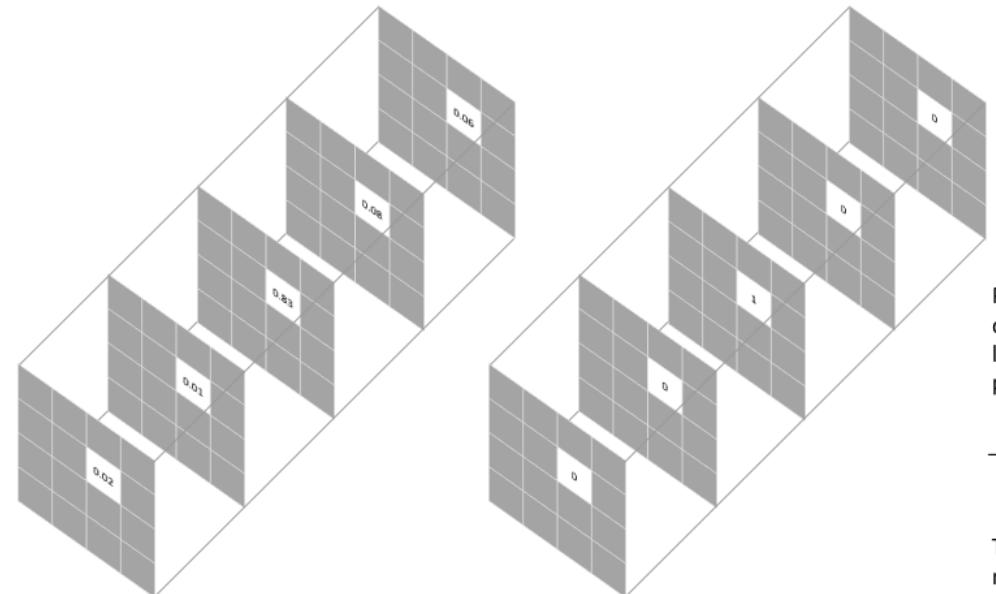
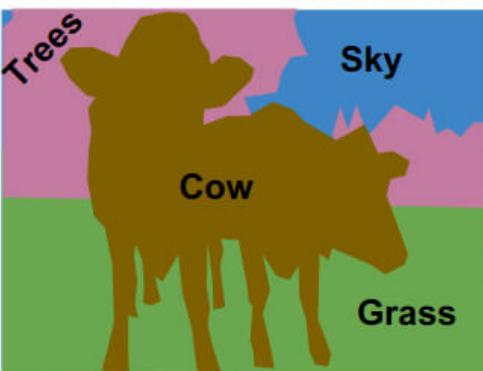
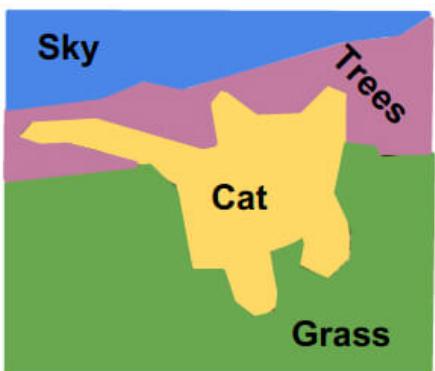
Semantic Segmentation

- Fully Convolutional Network (FCN)



Semantic Segmentation

- The last layer



Prediction for a selected pixel

Target for the corresponding pixel

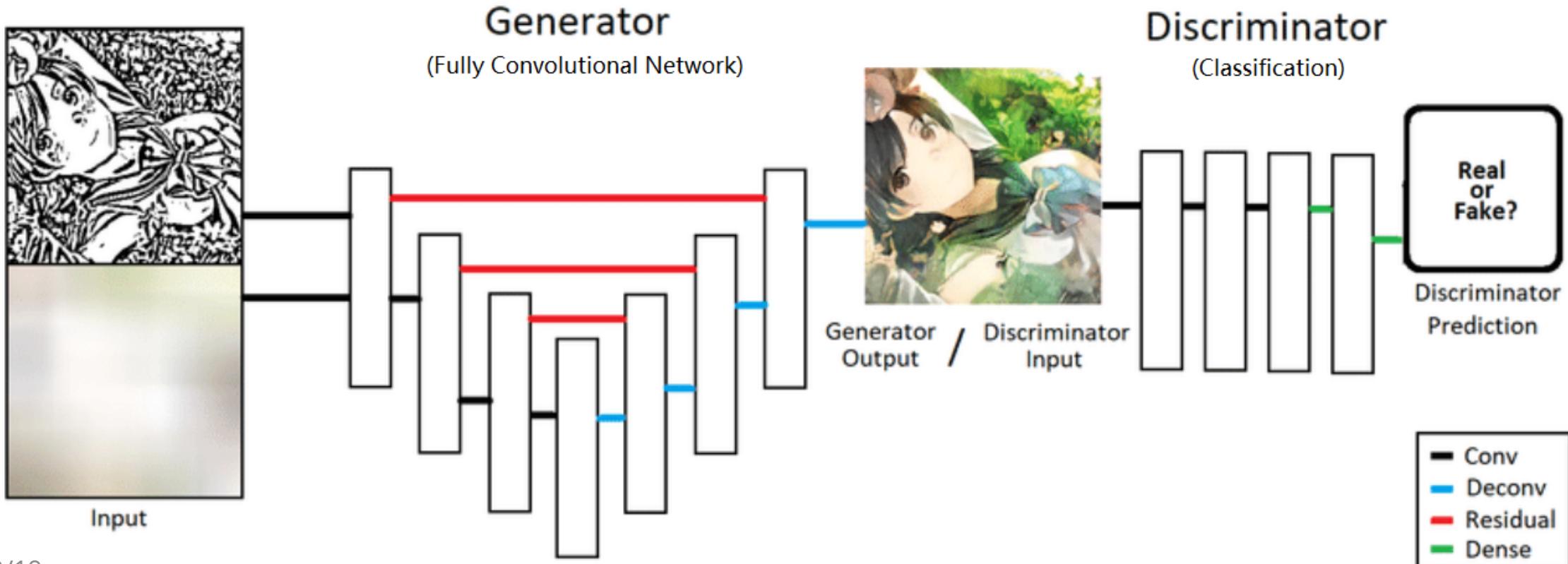
Pixel-wise loss is calculated as the log loss, summed over all possible classes

$$-\sum_{\text{classes}} y_{\text{true}} \log(y_{\text{pred}})$$

This scoring is repeated over all pixels and averaged

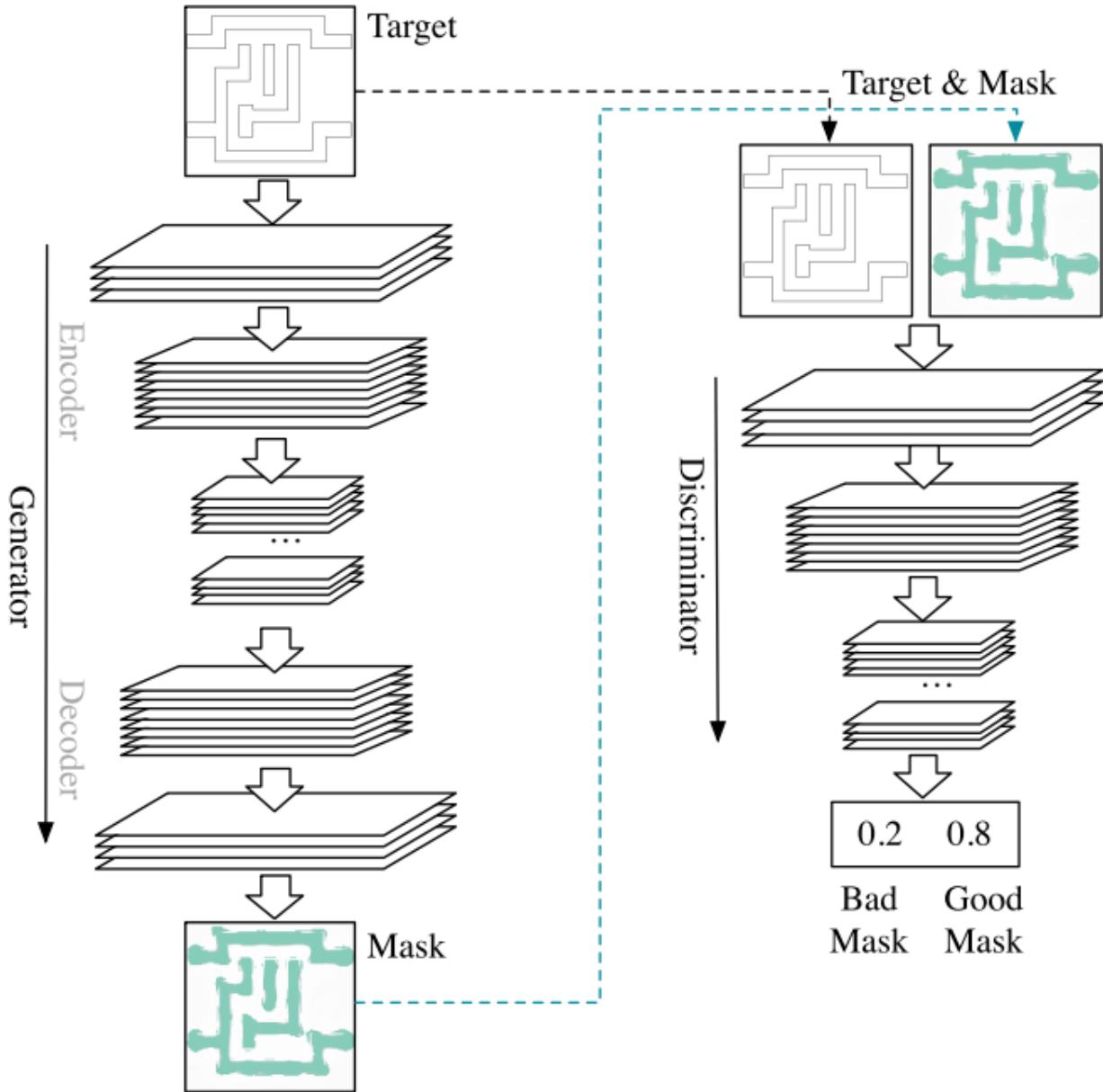
Image-to-image Translation

- Generative Adversarial Network (GAN)
- Generator: generate "fake" image
- Descriminator: distinguish real and "fake" images



Deep Learning for OPC

- Imag-to-image translation
- Input: target image Z_t
- Output: OPC image Z^*
- Target: $\|Litho(Z^*) - Z_t\|_2^2$
- Can be guided by ILT methods



Deep Learning for OPC

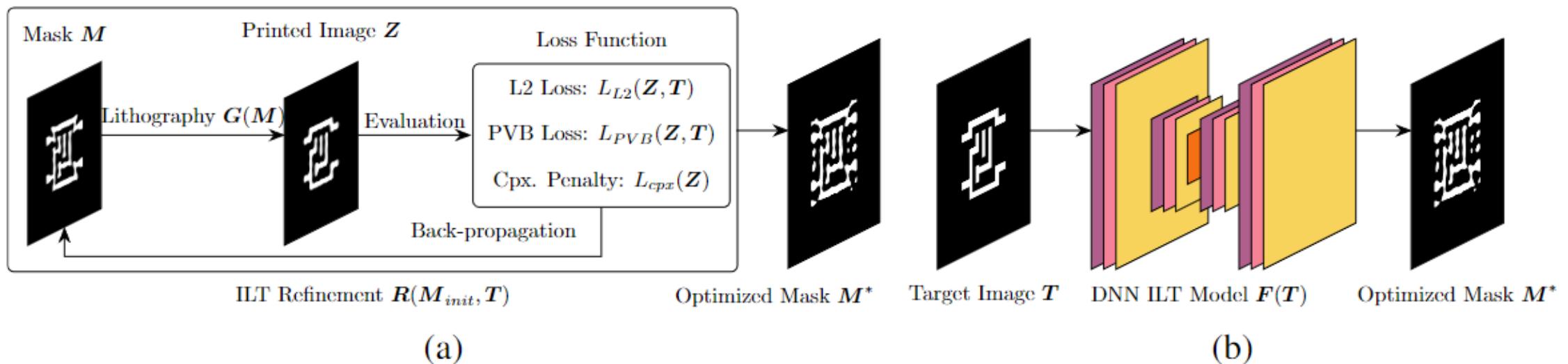


Figure 1: Overview of (a) traditional ILT and (b) DNN-based ILT.

Deep Learning for OPC



(a)



(b)



(c)



(d)



(e)

Figure 5: Mask optimization samples. (a)Ref.,(b)GAN-OPC,(c)Neural-ILT,(d)DAMO,(e)CFNO.

What's Next?

- Black-box optimization
- $\min_x f(x)$, f is a black-box

