MBAN6500 assignment1

January 18, 2021

1 Build an Expert System (ES) using experta

1.1 Submission

The assignment should be submitted as Python3 code and uploaded to Canvas. It is due by on February 1, 2021, at 8:30 am. The code will be tested and should produce results relatively well matching with reality.

1.2 Background

Experta is a Python alternative to CLIPS. CLIPS is a tool/language for building ES still in use today. However, for you not to have to learn a new language for a single assignment, we stick with Python instead. Most of what you learn with experta should be transferrable to CLIPS.

1.3 Assignment

- 1. Implement an ES that tells whether an animal is a bird, mammal, or unknown. It should require two percepts/declarations: cover and wings. The former can take one of two values, "fur" or "feathers", and the latter True or False. Given the declarations cover = "feathers" and wings = True, it should print "bird". Similarly, given cover = "fur" and wings = True, it should print "mammal", since a bat has wing and is a mammal. For cover = "feathers" and wings = False it should print "unknown" (since I don't know of any wingless bird).
- 2. Implement an AnimalIdentifier. Given some suitable number of declarations, this ES should be able to classify an animal into the following categories: "protozoa" (a single cell animal), "invertebrate", "fish", "bird", "mammal" or "unknown".
- 3. Implement an ES that can answer questions about a topic of your own interest. Include an explanation and description of its intended behavior as a comment.

1.4 Getting started

Please start by checking The Basics in the GitHub documentation under docs/source/thebasics.rst, and especially Facts and Rules. After that, take your time to look through the experta examples.

You can see what is available in experta by dir(experta). This will list all attributes of experta, i.e. the stuff you access by experta.experta.extribute.

To learn more about a particular attribute use experta. <attribute>? E.g.:

1.4.1 Python classes and decorators

If you have no previous experience with Python classes then the Python documentation may be helpful. Beyond that, there are plenty of tutorials on the web.

To form rules (i.e. sentences in FOL), experta uses decorators (i.e. the @-syntax). See here for a quick intro, or here for a more in-depth explanation.

1.4.2 The first example

Let's look at the first example in the experta documentation.

```
from random import choice
    from experta import Fact, KnowledgeEngine
    class Light(Fact):
        """Info about the traffic light."""
    class RobotCrossStreet(KnowledgeEngine):
        @Rule(Light(color='green'))
        def green_light(self):
            print("Walk")
        @Rule(Light(color='red'))
        def red_light(self):
            print("Don't walk")
        @Rule(AS.light << Light(color=L('yellow') | L('blinking-yellow')))</pre>
        def cautious(self, light):
            print("Be cautious because light is", light["color"])
In the class RobotCrossStreet, the rules (@Rule) are essentially FOL sentences. For example,
    @Rule(Light(color='green'))
    def green_light(self):
        print("Walk")
can be read as follows:
Light(green) \rightarrow Walk
or "if the light is green, then walk" (or rather, print the string 'Walk').
The third rule does two things:
    @Rule(AS.light << Light(color=L('yellow') | L('blinking-yellow')))</pre>
    def cautious(self, light):
        print("Be cautious because light is", light["color"])
```

```
First it says "if the light is yellow or blinking-yellow, then be cautious"
    or,
    Light(yellow) \lor Light(blinking - yellow) \rightarrow BeCatious.
    Second, the AS.light << ... binds the value of color (i.e. 'yellow' or 'blinkingyellow') to light
    so that the value of color can be accessed by light["color"].
    To use RobotCrossStreet we run the following:
    engine = RobotCrossStreet()
                                     # instantiates the class
    engine.reset()
                                     # resets to default values (if any)
    # randomly pick a color from the list
    light_color = choice(['green', 'yellow', 'blinking-yellow', 'red'])
    # qive this light color as input to the engine (the instantiation of RobotCrossStreet).
    # This would be equivalent to TELL(KB, MAKE-PERCEPT-SENTENCE(percept)) in Fig 7.1 (AIMA or cla
    engine.declare(Light(color=light_color))
    engine.run() # This is equivalent to ASK(KB, ...).
    Good luck!
[]:
```