

# A Machine-Learning Based Approach for 2D Character Animation

<Subtitle>

## Bachelor Thesis

Bachelor Course on Creative Computing  
at St. Pölten University of Applied Sciences

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# Declaration

I assure that

- I have written this work independently, have not used other sources and aids than those indicated and have not made use of any other unauthorized assistance.

- I have not yet submitted this topic to an assessor in Austria or abroad for assessment or in any form as an examination paper.

- this work corresponds to the work assessed by the assessor.

Date: \_\_\_\_\_ Signature: \_\_\_\_\_

# **Abstract**

Introduction: Warum behandeln wir das Thema

Purpose: Welches Problem soll gelöst werden

Method: Wie wurde die Problemlösung gemacht

Product: Was war das Ergebnis

Conclusion: Was sind die Folgerungen / Schlussfolgerungen aus den gewonnen Erkenntnissen

keine Referenzen und Zitate

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# **1 Introduction**

## **2 Method**

### **Literature review**

I reviewed previous work, focusing on two areas. I explored already available methods for creating animations from sketches by performing skeleton classification and reviewed previous work dealing with the classification of sketched objects.

### **Related work**

Eitz et al. (2012) collected a dataset of 20,000 sketches and divided them into 250 categories of 80 images each. Humans recognized on average 73.1% of these sketches correctly. This dataset is used in my work to train and validate the classifier to choose which animation is the most appropriate to show.

Huang et al. (2022) proposes a pipeline to create rigged and animated characters from a single image. Their solution aims for a holistic approach, requiring no user intervention, to assist non-professional users in creating animated characters. The proposed pipeline performs contour extraction with salient object detection and extrudes a 3D mesh from geometry generated by applying constrained Delaunay to the contours. Afterwards, a skeleton is estimated using a mean curve method and an animation is transferred onto the skeleton. In our work, we want to follow a similar philosophy of no user interaction and hope to improve the believability of the animated results by not only classifying the skeleton type but also the subject class of the input sketch.

### **Training classification models**

We used a subset of the dataset provided by Eitz et al. (2012) and Sangkloy et al. (2016) to train our classification models. Only the classes "cat" and "dog" were taken as training data for our models. To train and evaluate our models we used the scikit-learn library introduced by Pedregosa et al. (2011).

### kNN classifier

We trained a kNN classifier with the pixel values of the input images. Before using the values to train the model, we resized the images to a size of 64 times 64 pixels, and flattened the array to get a feature vector with 12288 entries, ranging from 0 to 255 in value. To find the best-performing k, we performed a grid search with cross-validation on 3 folds leading to  $k = 5$  as the model with the highest accuracy at 61.8798%.

### SVM classifier

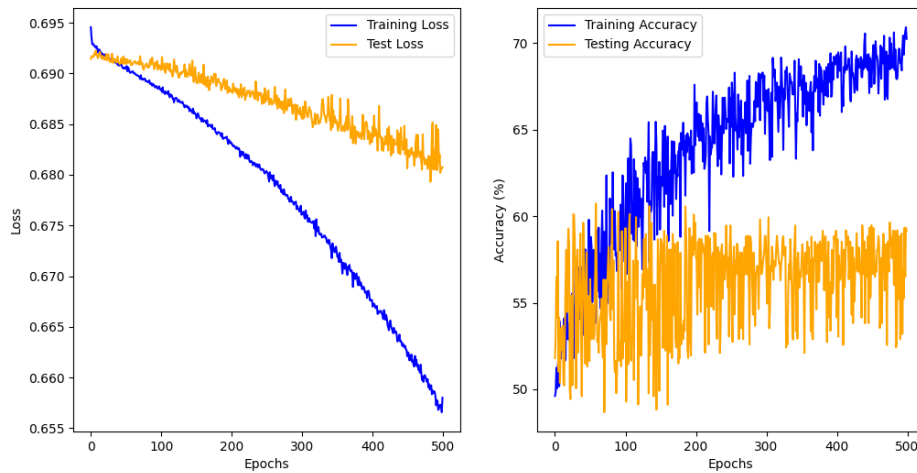
We trained an SVM classifier with a total of 1544 labeled images of sketches of cats and dogs. Before training the model we resized the images to a size of 64 times 64 pixels, and flattened the array to get a feature vector with 4480 entries. The images were imported as grayscale images. The SVM classifier performed with an accuracy of 53.7578%.

### Neural network classifier

We created and trained a Neural Network binary classifier using pytorch Paszke et al. (2019). This is the network's setup:

```
1 class MyNN(nn.Module):
2     def __init__(self):
3         super().__init__()
4         self.linear_relu_stack = nn.Sequential(
5             nn.Linear(in_features=3*128*128, out_features=16*16),
6             nn.ReLU(),
7             nn.Linear(in_features=16*16, out_features=16*16),
8             nn.ReLU(),
9             nn.Linear(in_features=16*16, out_features=1)
10        )
11    def forward(self, x, **kwargs):
12        x = x.view(x.size(0), -1)
13        logits = self.linear_relu_stack(x)
14        return logits
```

The network was trained on 80% of a collection of in total 1544 labeled images, depicting sketches of cats and dogs. The images were resized to a size of 128 times 128 pixels before being fed into the network. Training the network on 80% of the dataset for 500 epochs with a learning rate of 0.0001, led to the network performing with a 59.15% accuracy on the unseen test data.



### CNN classifier

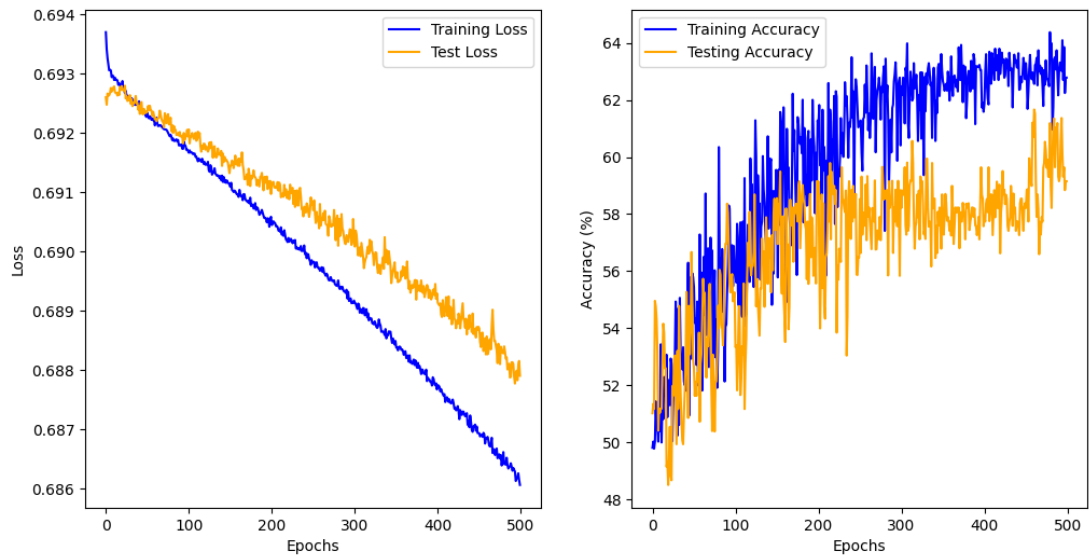
We trained a Convolutional Neural Network classifier. This is the network's setup:

```
1 class MyCNN(nn.Module):
2     def __init__(self):
3         super(MyCNN, self).__init__()
4         self.conv1 = nn.Conv2d(in_channels=3, out_channels=32,
5                                 kernel_size=3, stride=1,
6                                 padding=1)
7         self.conv2 = nn.Conv2d(in_channels=32, out_channels=64,
8                                 kernel_size=3,
9                                 stride=1,
10                                padding=1)
11        self.pool = nn.MaxPool2d(kernel_size=2, stride=2, padding=0)
12
13        self.fc1 = nn.Linear(64 * 32 * 32, 512)
14        self.fc2 = nn.Linear(512, 1)
15
16    def forward(self, x):
17        x = self.pool(F.relu(self.conv1(x)))
18        x = self.pool(F.relu(self.conv2(x)))
19        x = x.view(-1, 64 * 32 * 32)
20        x = F.relu(self.fc1(x))
21        x = self.fc2(x)
22        return x
```

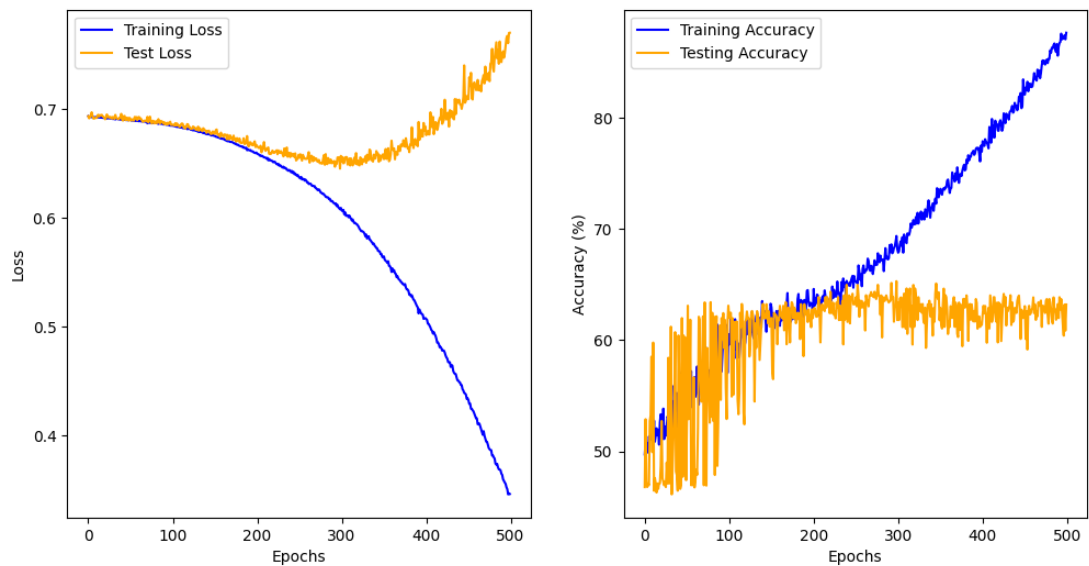
Training the network analogous to the previously mentioned Neural Network classifier for 500 epochs with a learning rate of 0.0001, yielded an accuracy of 59.15% on unseen test data.



## 2 Method



Repeating the setup with a learning rate of 0.001 led to an accuracy of 63.2% on unseen test data.



### Enhanced CNN

We used a slightly more complex CNN architecture adding batch normalization after each convolutional layer. Also we added an additional Convolution. Additionally we use a dropout layer before the final fully connected layer.

```
1 class EnhancedCNN(nn.Module):
2     def __init__(self):
3         super(EnhancedCNN, self).__init__()
4
5         self.conv1 = nn.Conv2d(in_channels=3, out_channels=32,
```

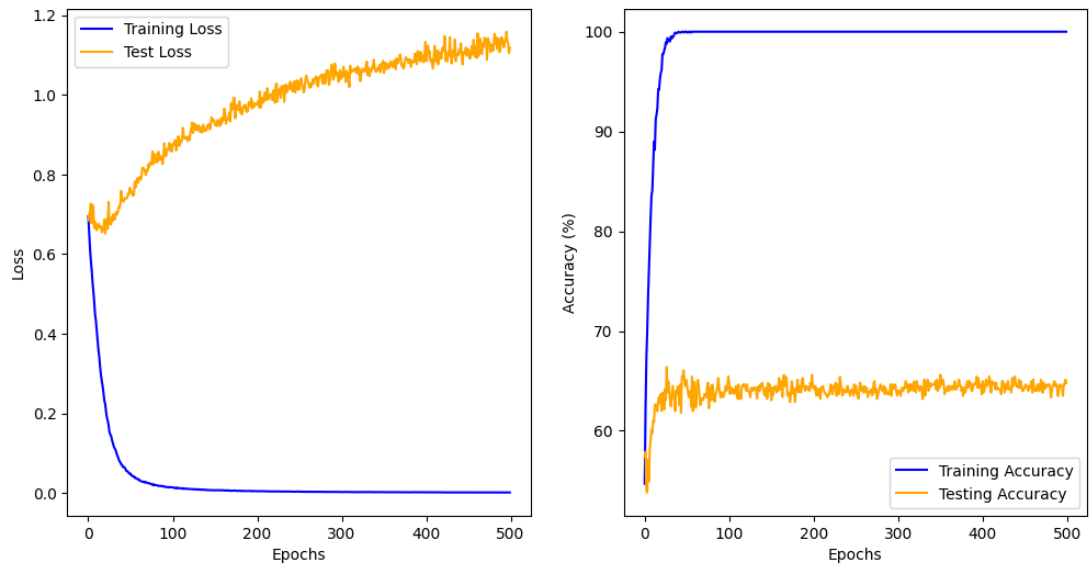
## 2 Method

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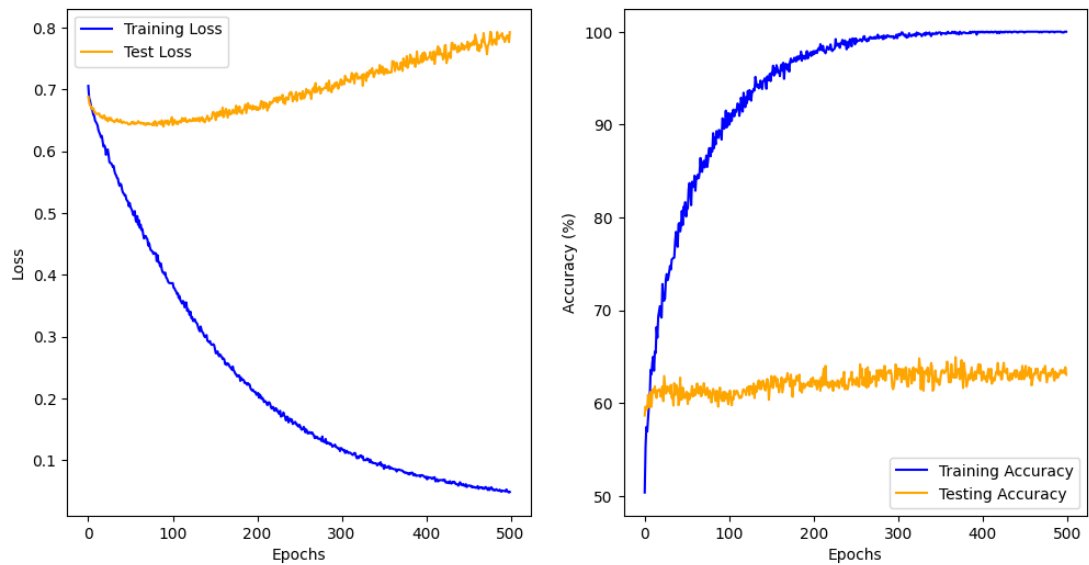
```
6         kernel_size=3, stride=1, padding=1)
7     self.bn1 = nn.BatchNorm2d(32)
8     self.conv2 = nn.Conv2d(in_channels=32, out_channels=32,
9         kernel_size=3, stride=1, padding=1)
10    self.bn2 = nn.BatchNorm2d(32)
11    self.pool1 = nn.MaxPool2d(kernel_size=2, stride=2)
12
13    self.conv3 = nn.Conv2d(in_channels=32, out_channels=64,
14        kernel_size=3, stride=1, padding=1)
15    self.bn3 = nn.BatchNorm2d(64)
16    self.conv4 = nn.Conv2d(in_channels=64, out_channels=64,
17        kernel_size=3, stride=1, padding=1)
18    self.bn4 = nn.BatchNorm2d(64)
19    self.pool2 = nn.MaxPool2d(kernel_size=2, stride=2)
20
21    self.fc1 = nn.Linear(64 * 32 * 32, 512)
22    self.dropout1 = nn.Dropout(0.5)
23    self.fc2 = nn.Linear(512, 1)
24
25    def forward(self, x):
26        x = self.pool1(
27            F.relu(
28                self.bn2(
29                    self.conv2(F.relu(self.bn1(self.conv1(x))))
30                )
31            )
32        )
33
34        x = self.pool2(
35            F.relu(
36                self.bn4(
37                    self.conv4(F.relu(self.bn3(self.conv3(x))))
38                )
39            )
40        )
41
42        x = x.view(-1, 64 * 32 * 32)
43
44        x = F.relu(self.fc1(x))
45        x = self.dropout1(x)
46        x = self.fc2(x)
47        return x
```

Training this model with a learning rate of 0.001 for 500 epochs resulted in an accuracy of 64.79% on previously unseen test data. It yielded an accuracy of 100% on the training data. We therefore suspect it to be overfitted.

## 2 Method



Training the model with a learning rate of 0.0001 for 500 epochs resulted in an accuracy of 64.07% on previously unseen test data.



We introduced 2 additional dropout layers to the network architecture. The network is described like this:

```
1 class EnhancedCNNMoreDropout(nn.Module):
2     def __init__(self):
3         super(EnhancedCNNMoreDropout, self).__init__()
4
5         self.conv1 = nn.Conv2d(in_channels=3, out_channels=32, kernel_size=3
6                                 , stride=1, padding=1)
7         self.bn1 = nn.BatchNorm2d(32)
8         self.conv2 = nn.Conv2d(in_channels=32, out_channels=32, kernel_size=
9                                 3, stride=1, padding=1)
```

## 2 Method

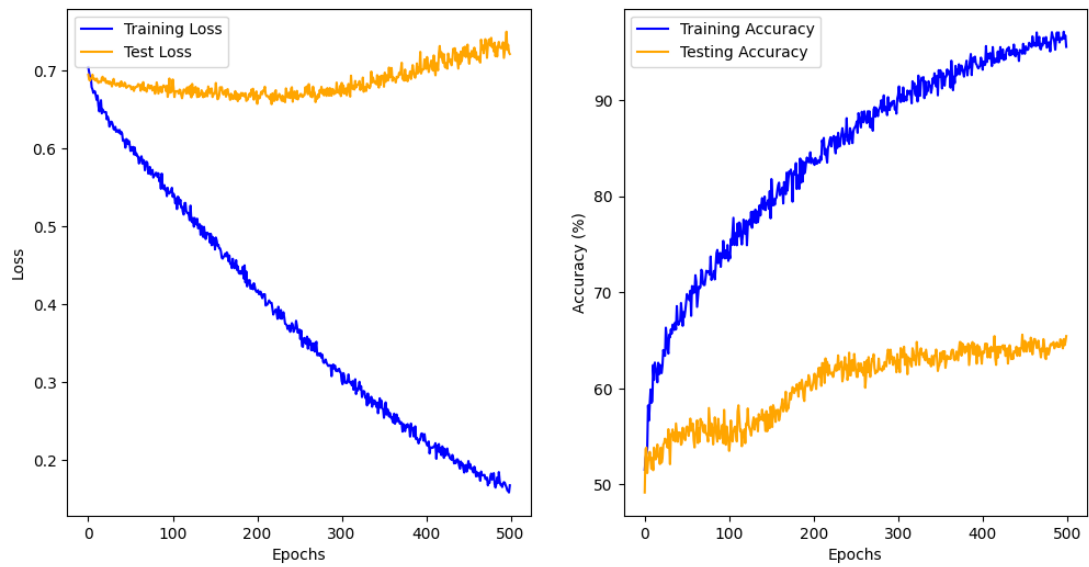
---

```
8     self.bn2 = nn.BatchNorm2d(32)
9     self.pool1 = nn.MaxPool2d(kernel_size=2, stride=2)
10    self.dropout1 = nn.Dropout(0.3)
11
12    self.conv3 = nn.Conv2d(in_channels=32, out_channels=64, kernel_size=
                               3, stride=1, padding=1)
13
14    self.bn3 = nn.BatchNorm2d(64)
15    self.conv4 = nn.Conv2d(in_channels=64, out_channels=64, kernel_size=
                               3, stride=1, padding=1)
16
17    self.bn4 = nn.BatchNorm2d(64)
18    self.pool2 = nn.MaxPool2d(kernel_size=2, stride=2)
19    self.dropout2 = nn.Dropout(0.4)
20
21    self.fc1 = nn.Linear(64 * 32 * 32, 512)
22    self.dropout3 = nn.Dropout(0.3)
23    self.fc2 = nn.Linear(512, 1)
24
25    def forward(self, x):
26        x = self.pool1(F.relu(self.bn2(self.conv2(F.relu(self.bn1(self.conv1
27                                                                    (x)))))))
28
29        x = self.dropout1(x)
30
31        x = self.pool2(F.relu(self.bn4(self.conv4(F.relu(self.bn3(self.conv3
32                                                                    (x)))))))
33
34        x = self.dropout2(x)
35
36        x = x.view(-1, 64 * 32 * 32)
37
38        x = F.relu(self.fc1(x))
39        x = self.dropout3(x)
40        x = self.fc2(x)
41        return x
```

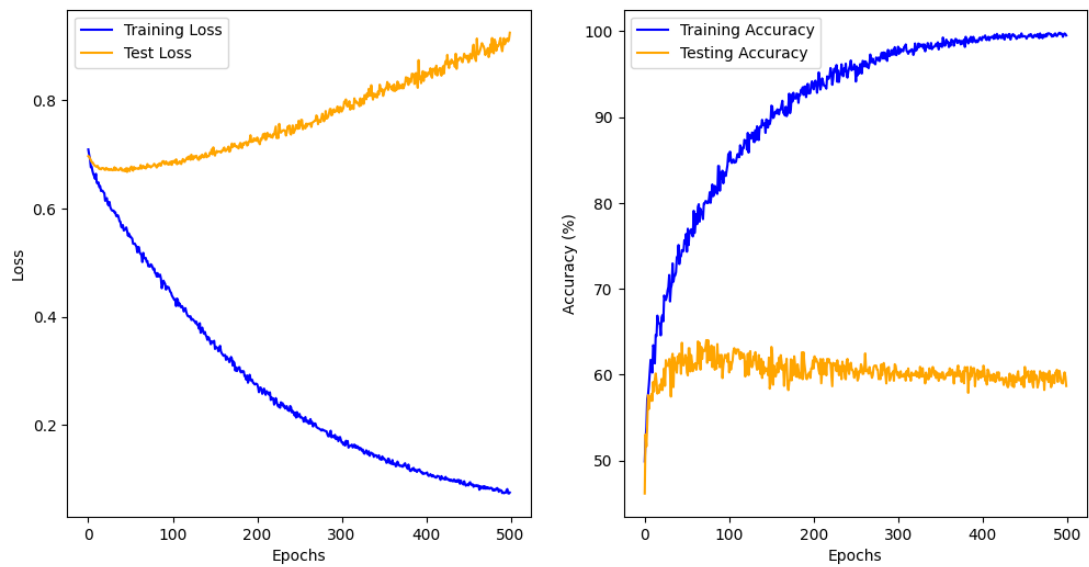
Introducing a dropout with a value of 0.3 after each convolution block resulted in a model that achieved 65.43% on previously unseen test data after being trained for 500 epochs with a learning rate of 0.0001.

## 2 Method

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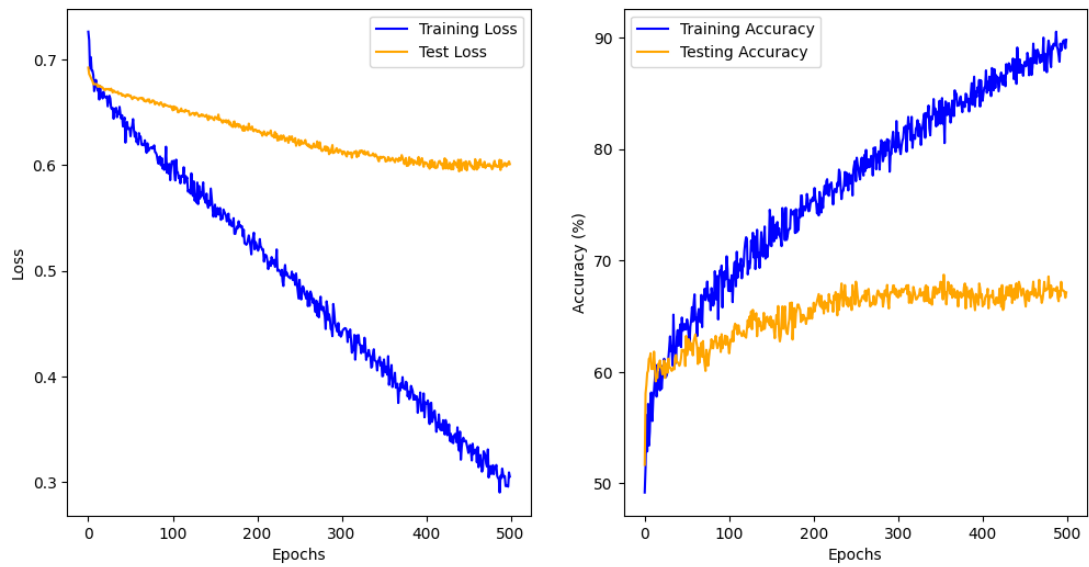


Setting the dropout to a value of 0.1 resulted in a model that achieved an accuracy of 58.68% on previously unseen test data after training for 500 epochs with a learning rate of 0.0001.

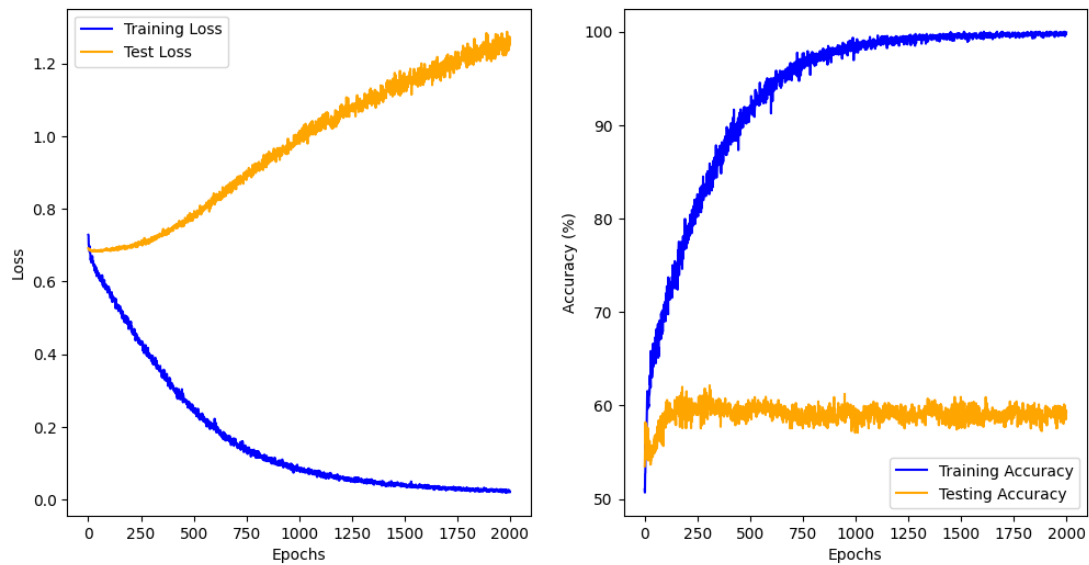


Setting the dropout to a value of 0.5 resulted in a model that achieved an accuracy of 67.14% on previously unseen test data after training for 500 epochs with a learning rate of 0.0001. The graph led us to believe the model might benefit from training for a larger amount of epochs.

## 2 Method



Training with 2000 epochs did not yield an improvement, during our experiment the model achieved an accuracy of 59.33% on previously unseen test data after training.



### ResNet50 classifier

We trained a ResNet50 classifier using this pytorch code:

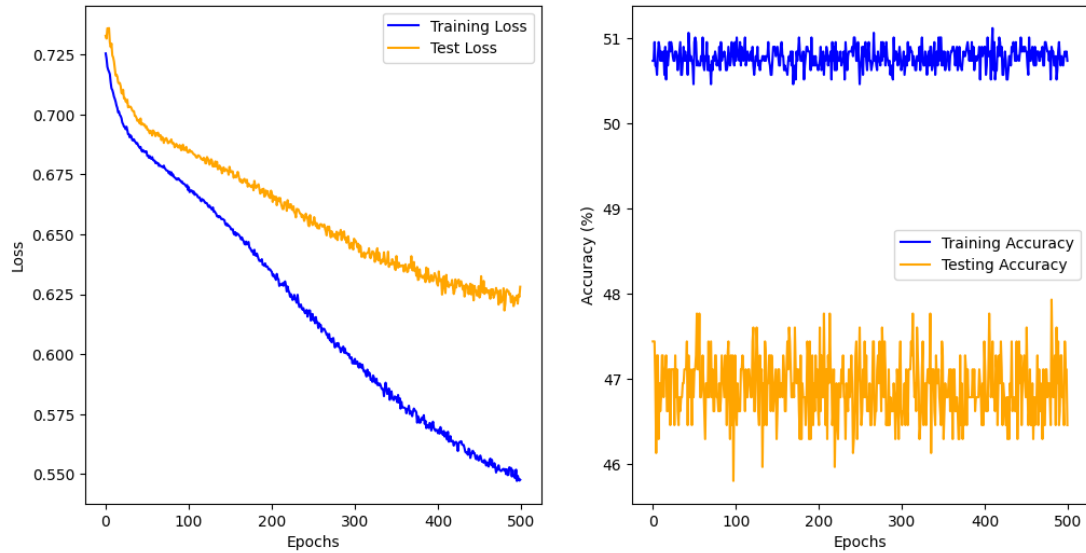
```
1 class MyResNet50(nn.Module):
2     def __init__(self):
3         super(MyResNet50, self).__init__()
4         self.resnet = models.resnet50(pretrained=True)
5         num_features = self.resnet.fc.in_features
6         self.resnet.fc = nn.Linear(num_features, 1)
7
```

## 2 Method

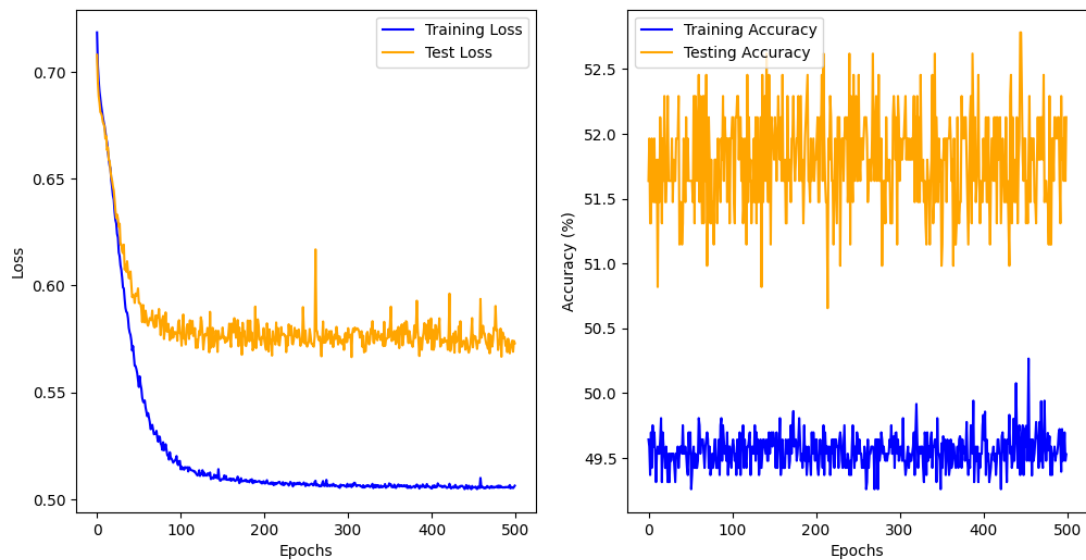
---

```
8 def forward(self, x):  
9     x = self.resnet(x)  
10    return torch.sigmoid(x)
```

Training the network for 500 epochs with a learning rate of 0.0001 resulted in an accuracy of 46.46% on previously unseen test data.



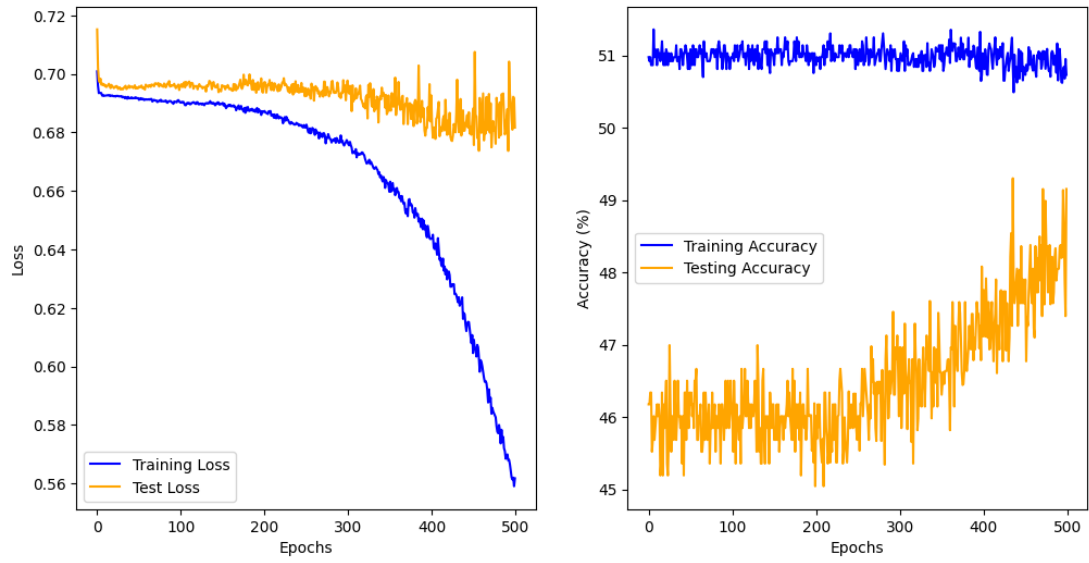
Training for 500 epochs with a learning rate of 0.001 resulted in an accuracy of 52.13% on previously unseen test data.



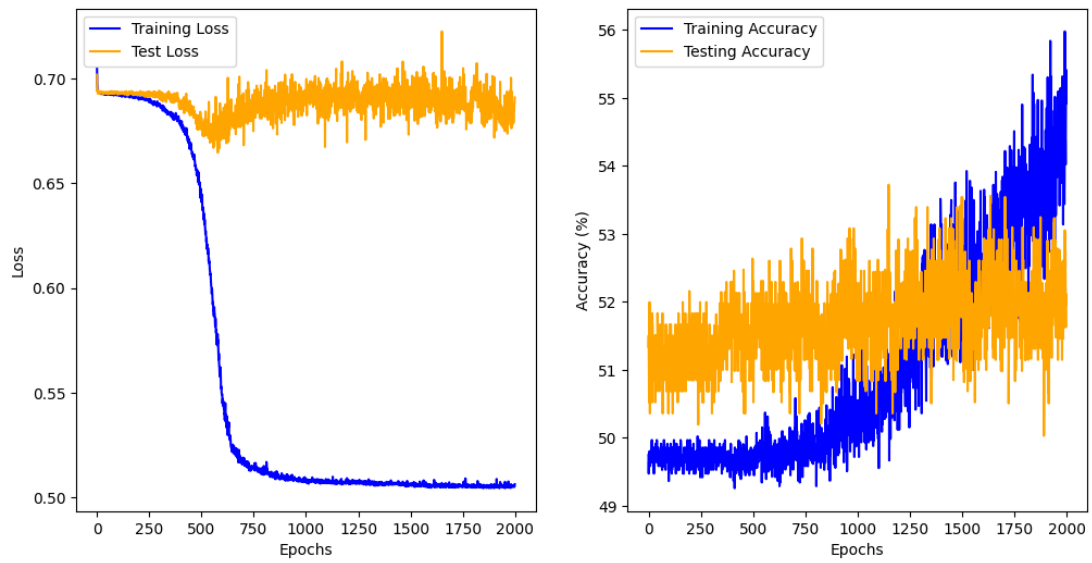
Training the model from scratch by setting pretrained=False, with a learning rate of 0.001 for 500 epochs resulted in an accuracy of 49.15% on previously unseen test data

## 2 Method

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Training the model from scratch, with a learning rate of 0.001 for 2000 epochs resulted in an accuracy of 51.64% on previously unseen test data



## Implementing the pipeline

For this work, we reimplemented the pipeline proposed by Korpitsch (2023), and adapted the code where needed.



### **Sketchdetection**

To repeat the steps introduced by Korpitsch (2023) we collected the dataset provided by Sarvadevabhatla et al. (2017). In Smith et al. (2023), a Mask-RCNN, as described by He et al. (2018), is used to detect the bounding boxes of figures drawn by children.

## **3 Results / Ergebnisse**

Presenting found literature in a useful way

### **3.1 First Section**

Ich bin Text, Text, Text<sup>1</sup>

#### **3.1.1 First Subsection**

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<sup>1</sup><http://mfg.fhstp.ac.at>

## **4 Discussion / Diskussion**

Comparison of presented technologies/methods/projects

Kritische Diskussion / Vergleich der Ansätze

Welche Methoden werden zumeist genutzt, warum?

Überblick / Zusammenfassung der gefundenen Literatur in einer sinnvollen Kategorisierung  
/ Charakterisierung

## **5 Conclusion / Fazit**

Was kann man daraus lernen?

Was fehlt?

Ideen für zukünftige Forschung

# Bibliography

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## List of Figures

## List of Tables

## Code Listings



# Appendices

## A Appendix

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## B Appendix

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