updateVehicles()

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lterator < Vehicle > iterator = vehicles.iterator()
```

iterator.hasNext()

updateVehicle(iterator)

createNewVehicle(id: int; from: String; to: String): Vehicle

DirectedEdge fromTo = new DirectedEdge(from, to)

directedEdges.get(fromTo).increment()

return vehicle

```
Vehicle vehicle = new Vehicle()

vehicle.id = id

vehicle.fromName = from

vehicle.toName = to

vehicle.currentPosition = entryPoints.get(from).coord

vehicle.toCoord = intersections.get(to).coord

vehicle.fromCoord = entryPoints.get(from).coord

vehicle.direction = subtract(vehicle.toCoord, vehicle.fromCoord)

vehicle.direction.normalize()

double randomValue = random.nextGaussian() * Vehicle.STANDARD_DEVIATION + Vehicle.EXPECTED_VELOCITY

vehicle.direction.multiply(randomValue)

vehicle.velocity = randomValue
```