

SHEN CHEN

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SUMMARY

Passionate computer engineer, able learn new skills fast for application. Interested in robotics and mobile autonomous systems.

EDUCATION

Renaissance Engineering Programme, Nanyang Technological University, Singapore <ul style="list-style-type: none">Bachelor of Engineering Science (Computer Engineering)Master of Science in Technology ManagementCGPA of 4.64/5.00	Aug 2017 – Dec 2021 (Expected)
Electrical Engineering and Computer Sciences, UC Berkeley, California <ul style="list-style-type: none">Courses Taken:<ul style="list-style-type: none">EECS 127 Optimization Models in EngineeringEL ENG 122 Communication NetworksEL ENG C128 Feedback Control SystemsEECS C106A Introduction to RoboticsEECS 192 Mechatronics	Aug 2019 – May 2020
Raffles Institution, Singapore <ul style="list-style-type: none">Graduated with a UAS of 88.75/90	Jan 2009 – Dec 2014

WORK EXPERIENCE

RDD Research, Dyson, Singapore <u>Robotics Research Intern (Mechatronics)</u> <ul style="list-style-type: none">Developed sensing solution based on requirements and considerationsIntegrated solution into existing robotics research infrastructure	Jun 2020 – Aug 2020
Cloud Application and Platform Lab (CAP), Nanyang Technological University, Singapore <u>Research Intern</u> <ul style="list-style-type: none">Developed and tested a model-based deep reinforcement learning framework, Baconian	May 2019 – Aug 2019
Shell EcoMarathon, Nanyang Technological University, Singapore <u>Autonomous System Team Member</u> <ul style="list-style-type: none">Planned overall autonomous system architectureDesigned auxiliary board to execute Jetson TX2 commands via ROS Serial and feedback control	Dec 2018 – May 2019

PROJECTS

- Programmed a CrazyFlie Drone with a path planning algorithm to land on a Turtlebot based on an OptiTrack mocap system and ROS
- Created an autonomous car capable of racing along a track with a camera sensor based on the BeagleBone Blue
- Developed a pair of autonomous robots capable of playing robot soccer based on the Arduino-Compatible Teensy 3.5
- Set-up a bearing levitation system with feedback control and Simulink

CO-CURRICULAR ACTIVITIES

Makers' Lab <u>Vice Chairperson, Technical Head, Technical Committee Member</u>	Aug 2017 – Dec 2021 (Expected)
<ul style="list-style-type: none">Organized events and workshops to introduce NTU students to the maker movement and prototyping skills	

AWARDS AND ACHIEVEMENTS

- Shell Imagine the Future Scenarios Competition 2018, 2nd Place
- Singapore Infocomm Technology Federation Awards 2014 – Best Student Project, Gold
- RoboCup Singapore Open 2012 & 2013 – 1st Robot Soccer Category, 1st Overall
- RoboCup Internationals 2011 – 2nd Individual, 2nd SuperTeam, RoboCup Junior, Robot Soccer Category

SKILLS

Programming Languages

C++	Python	Java + Kotlin	Dart
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Software Tools

Arduino	Autodesk AutoCAD	Solidworks	Siemens NX	Robot Operating System
Matlab	Bash	Android Studio	KiCad	Git VCS

Hardware Experience

Embedded Systems	Motor Control	Sensor Systems	Signaling (I ² C, SPI, etc.)	Laser Cutter
Power Tools	3D Printer	PCB Design		

Languages

English (Native Speaker)	Mandarin (Native Speaker)
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