Probability on Graphs

Shend Thaqi

June 18, 2023

Contents

1	Basics of graph theory 1.1 Random walks on networks	5
2	Chapter two	13
3	Chapter three	13
4	Chapter four	13
5	Chapter five	13
6	Chapter six	13
A	Measure theory A.1 Convergence	14 14
В	Probability theory B.1 Calculus of probability	15 15 15
\mathbf{C}	Markov chains	15

1 Basics of graph theory

Definition 1 (Graph).

A graph G = (V, E) is a consists of

1) $V \neq \emptyset$;

ede

2) $E \subseteq \{\{u, v\} | u, v \in V\}.$

We call elements of V vertices or nodes and elements of E edges or bonds. We write $v \sim u$ if $\{u, v\} \in E$. A graph G = (V, E) is called network if for $e = \{u, v\} \in V$, we assign a weight c(u, v) > 0. For $v \in V$, we set $c(v) = \sum_{u \sim v} c(u, v)$. We further define

- A vertex v is called *incident* to an edge e if $v \in e$;
- the degree of a vertex v is the number of edges incident to it: $\deg v = |\{\{u,v\} \in E \mid u \sim v\}|;$
- the graph G is called *locally finite* if for all $v \in V$, $\deg v < \infty$;
- for $u, v \in V$, $\pi = (x_1, \dots, x_N)$ is called a path from u to v if $v = x_1, x_N = v$ and $\{x_{n-1}, x_n\} \in E$;
- a path from u to u is called a cycle;
- a graph G is called *connected* if for any $u, v \in V$ there is a finite path from u to v.

Definition 2 (Product of graphs).

Let G_1, G_2 be graphs. We define

$$G_1 \boxtimes G_2 := (V_1 \times V_2, \{((x_1, y_1), (x_2, y_2)) \mid \text{ either } (x_1 = x_2, (y_1, y_2) \in E_2) \text{ or } (y_1 = y_2, (x_1, x_2) \in E_1)\})$$

as the product of G_1 and G_2 .

Definition 3 (Vertex simple and edge simple paths).

Let G be a graph. A path is a (possibly infinite) sequence of vertices v_1, v_2, \ldots such that $(v_n, v_{n+1}) \in E$.

- 1) If a path does not visit any vertex more that once, it is called a vertex simple path.
- 2) If a path does not visit any edge more than once, it is called an edge simple path.

Definition 4 (Network).

A network is a graph G combined with a function $c: E \to [0, \infty)$ with if c(u, v) = 0 if $(v, u) \notin E$. We call a network connected if $(V, \{e \in E \mid c(e) > 0\})$ is connected. A network is locally finite if for any $v \in V$, we have $c(v) = \sum_{u \sim v} c(u, v) < \infty$.

Lemma 1 (Example).

$$V = \mathbb{Z}, E = \{(v, u) \mid u \neq v \in V\} \text{ with } c(v, u) = \frac{1}{|u - v|^2}.$$

Definition 5 (Cycle).

A cycle is a path starting and ending in the same point. A cycle is simple if the only vertex appearing more than once is the first (and last) vertex.

Definition 6 (Induced graphs and networks).

Let G = (V, E) be a graph and let $K \subseteq V$. The induced graph is the graph $G_K = (K, \{e \in E \mid e \subseteq K\})$. The induced network is defined similarly.

Definition 7 (Connected component).

Let G be a graph a graph or a network. A connected component is a set K of vertices such that G_K is connected, but for every $K \subseteq H$, G_H is not connected.

Definition 8 (Contraction of graphs).

Let G = (V, E, c) be a graph (or network) and let $K \subseteq G$. The connected graph (or network) G/K is the graph $(V \setminus \bigcup \{z\}, \{e \in E \mid e \subseteq V \setminus K\} \cup \{(v, z) \mid v \notin K, \exists u \in K : (v, u) \in E\})$. For all $u, v \notin K$, take conductance c'(v, u) = c(v, u) for $v \notin K$ take $c(v, u) = \sum_{u \in K} c(v, u)$.

Definition 9 (Forest and tree).

A forest is a graph with no (simple) cycles. A tree is a connected forest.

Remark.

A contraction of an edge lets it "disappear" in a sense that the vertices are merged.

Definition 10 (Homomorphisms).

Let G_1, G_2 be graphs. Let $\phi: V_1 \to V_2$ be a function.

- 1. ϕ is called a homomorphism if for all $(u, v) \in E_1$, we have that $(\phi(u), \phi(v)) \in E_2$;
- 2. ϕ is called an *isomorphism* if ϕ is bijective, and ϕ , ϕ^{-1} are homomorphisms. In this case, G_1, G_2 are called *isomorpic*;
- 3. ϕ is called an *automorphism* if ϕ is an isomorphism with $G_1 = G_2$.

Definition 11 (Transitivity).

A graph G = (V, E) is called (vertex) transitive if for all $v, u \in V$ there is an automorphism ϕ such that $\phi(v) = u$. G is called edge transitive if for every $e_1, e_2 \in E$ there is an automorphism $\phi(e_1) = e_2$.

Remark

There are graphs that are vertex transitive but not edge transitive.

Remark.

Good source of example for transitive graphs: Let G be a graph, and let $Y \subseteq G \setminus \{\text{unit}\}$. Take the graph V = G and $(u, v) \in E$ if there is $y \in Y$ such that u = yv or v = yu.

1.1 Random walks on networks

Definition 12 (Simple rnadom walk on networks).

Let G = (V, E, c) be a network and assume that G is locally finite. The simple random walk on G is the (discrete time) Markov chain with transition matrix

$$\Pi(x,y) = \frac{c(x,y)}{\sum_{z} c(x,z)} \cdot \mathbb{1}\left[\sum_{z} c(x,z) > 0\right] + 1 \cdot \mathbb{1}\left[\sum_{z} c(x,z) = 0\right]$$

A random walk on a locally finite graph G = (V, E) is a random walk on the network (V, E, 1).

Remark.

Question: Does \mathbb{Z}^d have a transient subgraph?

Answer: No, every subgraph of a recurrent graph is recurrent.

The main tool to provide the proof for the answer is based on the connection between the random walk and electrical networks.

Lemma 2.

Let G = (V, E, c) be a finite connected network. For every $x \in V$, let p^x be the distribution of the random walk on G started on x. Let $a, z \in V$. Let τ_a (τ_z) be the first time hitting a (z), and let $\tau_{a,z}$ be first time hitting either of them. Then, $\tau_a, \tau_z, \tau_{a,z} < \infty$.

Fact.

Let G = (V, E, c) be a finite connected network. We consider the simple random walk defined as above. Then, every state x is recurrent. We have $\mathbb{P}_x(\tau_a < \infty) = \mathbb{P}_x(\tau_z < \infty) = 1$.

Proof. For every x, let γ_x be a path from x to a. Let h_x be the probability that the random walk takes the path γ_x immediately starting in x. Let $h = \min_{x \in V} h_x > 0$. Let $\mathcal{F}_n) = \sigma(X_1, \ldots, X_N)$, $\mathcal{F} = \sigma(X_1, X_2, \ldots)$. Then, $\{\tau_a < \infty\} \in \mathcal{F}$. By Kolmogorov's 0-1-law, $\mathbb{P}_x(\tau_a < \infty \mid \mathcal{F}) \in \{0, 1\}$. We have $\mathbb{P}_x(\tau_a < \infty \mid \mathcal{F}) = \lim_{n \to \infty} \mathbb{P}_x(\tau_a < \infty \mid \mathcal{F})$. We have $\mathbb{P}_x(\tau_a < \infty \mid \mathcal{F}) \geq h$. Thus, $\mathbb{P}_x(\tau_a < \infty \mid \mathcal{F}) \geq h$. It follows from the 0-1-law, $\mathbb{P}_x(\tau_a < \infty \mid \mathcal{F}) = 1$ and thus $\mathbb{P}_x(\tau_a < \infty) = \mathbb{E}\left[\mathbb{P}_x(\tau_a < \infty \mid \mathcal{F})\right]$.

Definition 13 (Voltage function).

The voltage function is defined as

$$\mathcal{U}: V \to \mathbb{R}, x \mapsto \mathcal{U}(x) := \mathbb{P}_x(\tau_{a,z} = \tau_a)$$

Lemma 3 (Properties of the voltage function).

Let $\mathcal{U}: V \to \mathbb{R}, x \mapsto \mathbb{P}_x(\tau_{a,z} = \tau_a)$ be the voltage function. Then, the following statements hold:

- 1. U(a) = 1;
- 2. U(z) = 0;
- 3. For $x \neq a, z$, we have

$$\mathcal{U}(x) = \sum_{y \in V} \mathbb{P}_x(X_1 = y)\mathcal{U}(y) = \sum_{y \in V} \frac{c(x, y)}{\sum_{z \in V} c(x, z)} \mathcal{U}(y) = \sum_{y \in V} c(x, y) \frac{\mathcal{U}(y)}{c(x)}$$

(harmonicity)

Proof. To show the harmonicity, we use the Markov property. Since $x \neq a, z, p^x(\tau_a \geq 1) = 1$. The Markov property implies

$$p^{x}(\tau_{a} \leq \tau_{z}) = \mathbb{E}_{x} \left[p^{x}(\tau_{a} < \tau_{z}) \right]$$

$$= \sum_{y} p^{x}(X_{1} = y) \cdot p^{y}(\tau_{a} < \tau_{z})$$

$$= \sum_{y} p^{x}(X_{1} = y) \cdot \mathcal{U}(y)$$

Lemma 4 (Uniqueness of voltage function).

The voltage function \mathcal{U} is the only function satisfying the properties above.

Proof. Assume U_1, U_2 satisfy the properties of the voltage function. We show $h \equiv U_1 - U_2 = 0$.

- 1. By properties 1 and 2, h(a) = h(z) = 0.
- 2. For $x \neq a, z$, we have $h(x) = \sum_y \frac{c(x,y)}{c(x)} h(y)$ (h(x) is a weighted average over its neighbors). Assume $h(x) \neq 0$. We assume $\operatorname{Eh}(x) > 0$. Let $M = \max\{h(x) \mid x \in V\} > 0$. Let $H = \{x \mid h(x) = M\}$. Note that $a, z \notin H$. Let x be an element of H with a neighbor w outside of H. Then, the following are true
 - (a) $x \in H$, thus h(x) = M.

(b)

$$\begin{split} h(x) &= \sum_{y} \frac{c(x,y)}{c(x)} h(y) \\ &= \frac{c(x,w)}{c(x)} h(w) + \sum_{y \neq w} \frac{c(x,y)}{c(x)} h(y) \\ &\leq h(w) \frac{c(x,w)}{c(x)} + M \sum_{y \neq w} \frac{c(x,y)}{c(x)} \\ h(w) \frac{c(x,w)}{c(x)} + M \left(1 - \frac{c(x,w)}{c(x)}\right) \\ &= M + \underbrace{(h(w) - M)}_{<0} \cdot \underbrace{\frac{c(x,w)}{c(x)}}_{<0} < M \end{split}$$

This is a contradiction to $h \neq 0$.

Remark.

The proof is similar to the proof of uniqueness of the solution to the Dirichlet problem.

Remark.

In the theory of electrical networks, the (physical) voltage function satisfies the same three properties (up to normalization of the boundary conditions). Therefore, everything that is known about physical electrical networks has the potential of being useful in the understanding of random walks on networks.

Definition 14 (Resistance).

For an edge e, we define its resistance as

$$r(e) = \frac{1}{e}$$

1.2 Currents and flows

Definition 15 (Current).

Let $e = (x, y) \in E$. For every x, y we define the current as

$$I(x,y) = \frac{\mathcal{U}(x) - \mathcal{U}(y)}{r(x,y)} = (\mathcal{U}(x) - \mathcal{U}(y)) c(x,y)$$

Lemma 5 (Properties of the current).

Let I be the current. Then, the following statements hold:

- 1. I(x,y) = -I(y,x) (Antisymmetry)
- 2. For $x \neq a, z, \sum_{y \neq x} I(x, y) = 0$ (Kirchhof's node law)
- 3. For a cycle $x_0, \ldots, x_N = x_0$, then $\sum_{n=1}^N I(x_{n-1}, x_n) r(x_{n-1}, x_n) = 0$ (Kirchhof's circuit law)

Proof.

- 1. follows from c(x, y) = c(y, x).
- 2. Notice that

$$\begin{split} \sum_{y \neq x} I(x,y) &= \sum_{y \neq x} c(x,y) \left(v(x) - v(y) \right) \\ &= v(x) \sum_{y \neq x} c(x,y) - \sum_{y \neq x} c(x,y) v(y) \\ &= v(x) c(x) - c(x) \sum_{y \neq x} \frac{c(x,y)}{c(x)} v(y) \\ &= 0 \end{split}$$

where we used the harmonity of v.

3. By definition of I, we have $(I \cdot r)(x,y) = v(x) - v(y)$. Thus, we have

$$\sum_{n=1}^{N} I(x_{n-1,x_n})r(x_{n-1},x_n) = \sum_{n=1}^{N} v(x_{n-1}) - v(x_n) = 0$$

Definition 16 (Flow).

A flow is a function $F: V^2 \to \mathbb{R}$, such that

- 1. F(x,y) = -F(y,x)
- 2. If $x \nsim y$, then F(x,y) = 0
- 3. For all $x \neq a, z$, we have $\sum_{y \neq x} F(x, y) = 0$ (Kirchhof's node law)

Definition 17 (Total current).

The total current in a network is defined as

$$\sum_{x \neq a} I(a,x) = \sum_{x \neq z} I(x,z)$$

Proof. We prove equality for the two descriptions of total current.

$$\sum_{x \neq a} I(a, x) - \sum_{x \neq z} I(x, z) = \sum_{x \neq a} I(a, x) + \sum_{x \neq z} I(z, x) + \underbrace{\sum_{y \neq a, z} \sum_{x \neq y} I(y, x)}_{=0}$$

$$\stackrel{(I)}{=} \sum_{y} \sum_{x \neq y} I(y, x)$$

$$= \sum_{\{x, y\} \subseteq V} I(x, y) + I(y, x)$$

$$= 0$$

Definition 18 (Effective resistance).

The effective resistance in a network is defined as

$$R_{\text{eff}}(a, z) = \frac{1}{\text{total current}}$$

Similarly, we denote

$$c_{\text{eff}}(a,z) = \text{total current}$$

Notation (Stopping times).

We use the following notation for stopping times

$$\tau_{x} = \inf\{t \ge 0 \mid X_{t} = x\}$$

$$\sigma_{x} = \inf\{t \ge 0 \mid X_{t} \ne x\}$$

$$\eta_{x}^{0} = 0$$

$$\eta_{x} = \inf\{t > 0 \mid X_{t} = x\}$$

$$\eta_{x}^{n+1} = \inf\{t > \eta_{x}^{n} \mid X_{t} = x\}$$

Notice that $\tau_x \neq \eta_x$ under \mathbb{P}_x and $\tau_x = \eta_x$ under \mathbb{P}_y for $y \neq x$.

Lemma 6 (*n*-th return time of Markov chains).

Notice that if X is a Markov chain, then we have

$$\eta_x^{n+1} = (\tau_x \circ \theta_{\sigma_x} + \sigma_x) \circ \theta_{\eta_x^n} + \eta_x^n$$

Theorem 1.

Let G=(V,E,c) be a connected network, $a\neq z\in V$. Let $\tau_x:=\inf\{n\geq 0\,|\, X_n=x\}$ and $\eta_x=\inf\{n\geq 1\,|\, X_n=1\}$. Then,

$$\mathbb{P}_a\left(\tau_z < \eta_a\right) = \frac{c_{\text{eff}}(a, z)}{c(a)}$$

Proof. We have that

$$\mathbb{P}_{a}(\tau_{z} < \eta_{a}) = \sum_{x} \mathbb{P}_{a}(X_{1} = x) \mathbb{P}_{x}(\tau_{z} < \eta_{a})$$

$$= \sum_{x} \frac{c(a, x)}{c(a)} \cdot (\underbrace{1}_{v(a)} - \underbrace{\mathbb{P}_{x}(\tau_{a} - \tau_{z})}_{v(x)})$$

$$= \frac{1}{c(a)} \sum_{x} c(a, x) (v(a) - v(x))$$

$$= \frac{1}{c(a)} \sum_{x} I(a, x)$$

$$= \frac{c_{\text{eff}}(a, z)}{c(a)}$$

Theorem 2 (Commute time formula).

We have that

$$\mathbb{E}_{a}\left[\tau_{z}\right] + \mathbb{E}_{z}\left[\tau_{a}\right] = 2R_{\text{eff}}(a, z) + \sum_{e \in E} c(e)$$

Proof. We first provide facts about Markov chains.

1. Every Markov chain on a finite state space has an invariant distribution. If the Markov chain is a random walk on a finite connected network, then

$$\mu(x) = \frac{c(x)}{2\sum_{e \in E} c(e)}$$

is the unique invariant distribution, since

i) μ is a distribution: $\mu(x) \geq 0$ holds since $c \geq 0$, and

$$\sum_{x} \mu(x) = \frac{1}{2\sum_{e \in E} c(e)} \sum_{x} \left(\sum_{y} c(x, y) \right)$$
$$= \frac{1}{2\sum_{e \in E} c(e)} \cdot 2\sum_{e \in E} c(e)$$
$$= 1$$

ii) μ is invariant: Let $X =_d \mu$, then for every x

$$\begin{split} \mathbb{P}_{\mu} &= \sum_{y} \mathbb{P}_{\mu}(X_0 = y) \mathbb{P}_{\mu}(X_1 \mid X_0 = y) \\ &= \sum_{y} \mu(y) \cdot \frac{c(x, y)}{c(y)} \\ &= \frac{1}{2 \sum_{e} c(e)} \sum_{y} c(y) \frac{c(x, y)}{c(y)} \\ &= \frac{1}{2 \sum_{e} c(e)} c(x) \\ &= \mu(x) \end{split}$$

2. $\mathbb{E}_x[\eta_x] = \frac{1}{\mu(x)}$. We sketch the proof of this claim: Let μ be stationary and invariant distribution, i.e. $X_n =_d \mu$ for all $n \geq 0$. Then, for large N, $\mu(x) \cdot N$ is approximately the number of times we are at x. Thus, for the average distance between appearances of x, we have $\mathbb{E}[\eta_x^{n+1} - \eta_x^n] = \frac{1}{\mu(x)}$. This can be shown using the Markov property to derive $\eta_x^1 =_d \eta_x^{n+1} - \eta_x^n$ and using the Law of Large Numbers.

3. Let $\eta_a^1, \eta_a^2, \ldots$ be the consecutive return times to a. Let $m := \inf\{k \geq 0 \mid \eta_a^{k-1} < \tau_z < \eta_a^k\}$. Then

$$\begin{split} \mathbb{E}_{a}[\tau_{z}] + \mathbb{E}_{z}[\tau_{a}] &= \mathbb{E}_{a}[\eta_{a}^{m}] \\ &= \mathbb{E}_{a}[\eta_{a}^{m-1}] + \mathbb{E}_{a}[\eta_{a}^{m} - \eta_{a}^{m-1}] \\ &= \mathbb{E}_{a}[m-1]\mathbb{E}\left[\eta_{a}^{1} \mid \eta_{a}^{1} < \tau_{z}\right] + \mathbb{E}_{a}\left[\eta_{a}^{1} \mid \tau_{z} < \eta_{a}^{n}\right] \\ &= \mathbb{E}[\operatorname{Geom}(\mathbb{P}_{a}(\tau_{z} < \eta_{A}) - 1] \cdot \mathbb{E}_{a}\left[\eta_{a}^{1} \mid \eta_{a}^{1} < \tau_{z}\right] + \frac{\mathbb{P}_{a}(\tau_{z} < \eta_{a}^{1})}{\mathbb{P}_{a}(\tau_{z} < \eta_{a}^{1})} \mathbb{E}_{a}\left[\eta_{a}^{1} \mid \tau_{z} < \eta_{a}^{1}\right] \\ &= \left(\frac{1}{\mathbb{P}_{a}(\tau_{z} < \eta_{a}^{1})} - 1\right) \mathbb{E}_{a}\left[\eta_{a}^{1} \mid \eta_{a}^{1} < \tau_{z}\right] + \frac{\mathbb{P}_{a}(\tau_{z} < \eta_{a}^{1})}{\mathbb{P}_{a}(\tau_{z} < \eta_{a}^{1})} \mathbb{E}\left[\eta_{a}^{1} \mid \tau_{z} < \eta_{a}^{1}\right] \\ &= \frac{1}{\mathbb{P}_{a}(\tau_{z} < \eta_{a}^{1})} \left[\mathbb{P}_{a}(\eta_{a}^{1} < \tau_{z})\mathbb{E}_{a}\left[\eta_{a}^{1} \mid \eta_{a}^{1} < \tau_{z}\right] + \mathbb{P}_{a}(\tau_{z} < \eta_{a}^{1})\mathbb{E}_{a}\left[\eta_{a}^{1} \mid \tau_{z} < \eta_{a}\right]\right] \\ &= \frac{1}{\mathbb{P}_{a}(\tau_{z} < \eta_{a}^{1})} \mathbb{E}_{a}[\eta_{a}^{1}] \\ &= \frac{2\sum_{e}c(e)}{c(a)} / \frac{c_{\text{eff}(a,z)}}{c(a)} \\ &= 2\frac{\sum_{e}c(e)}{c_{\text{eff}}(a,z)} \\ &= 2R_{\text{eff}(a,z)} \sum_{e}c(e) \end{split}$$

Exercise.

We have that

$$\mathbb{P}_x(\tau_a < \tau_z) \le \frac{c_{\text{eff}}(x, a)}{c_{\text{eff}}(x, z)}$$

To make use of these theorem, we need to be able to estimate (or calculate) effective resistance/conductance. In some examples we are capable of calculating effective resistances.

Fact

We have the following:

- 1) in d = 1, $R_{\text{eff}}(0, n) = n$
- 2) in d = 2, $R_{\text{eff}}((0,0),(n,n)) = \mathcal{O}(\ln n)$
- 3) in d = 3, $R_{\text{eff}}((0,0,0),(n,n,n)) = \mathcal{O}(n)$

Thus, we have

$$\mathbb{E}_{a,0}[\tau_{n,n}] = \frac{1}{2} (\mathbb{E}_{a,0}[\tau_{n,n}] + \mathbb{E}_{n,n}[\tau_{0,0}])$$
$$= \frac{1}{2} 2R_{\text{eff}} ((0,0), (n,n)) \sum_{e} c(e)$$
$$= \mathcal{O}(n^2 \cdot \ln n)$$

Definition 19 (Associated Hilbert space).

Let G = (V, E) be a graph of bounded degree, i.e. $\sup_{v \in V} \deg v < \infty$. We define the associated Hilbert space

$$\ell^2(V) := \left\{ f: V \to \mathbb{R} \,\middle|\, \sum_v f^2(v) < \infty \right\}$$

with the scalar product

$$\langle f,g\rangle = \sum_v f(v)\cdot g(v) \quad \text{for } f,g \in \ell^2(V).$$

For e = (u, v), we define $\check{e} = u$, $\hat{e} = v$ and -e = (v, u). We define the associated Hilbert space

$$\ell_{-}^{2}(E) := \left\{ \theta : E \to \mathbb{R} \left| \sum_{e} \theta(e) < \infty, \ \theta(-e) = -\theta(e) \right\} \right\}$$

with the scalar product

$$\langle \theta, \eta \rangle = \frac{1}{2} \sum_{e} \theta(e) \cdot \eta(e)$$

Definition 20 (Boundary and coboundary operator).

We define the *coboundary operator* as

$$d: \ell^2(V) \to \ell^2_-(E), df(e) = f(\check{e}) - f(\widehat{e})$$
 for $e \in E$.

and the boundary operator as

$$d^*:\ell^2_-(E)\to\ell^2(V),\,d^*\theta(v)=\sum_{e:\check{e}=v}\theta(e)\quad\text{for }v\in V.$$

Exercise.

Show that d, d^* are well-defined.

Lemma 7.

 d, d^* are adjoint linear maps, i.e. for all $f \in \ell^2(V), \theta \in \ell^2(E)$, we have $\langle \theta, df \rangle = \langle d^*\theta, f \rangle$.

Proof. We show the proof in two steps:

1.
$$-\sum_{e:\hat{e}=v} \theta(e) = \sum_{e:\hat{e}=v} \theta(-e) = \sum_{e:\check{e}=v} \theta(e) = d^*\theta(v)$$
.

2. By definition of the scalar product, we have

$$\begin{split} \langle \theta, df \rangle &= \frac{1}{2} \sum_{e} \theta(e) \cdot (f(\tilde{e}) - f(\hat{e})) \\ &= \frac{1}{2} \sum_{e} \theta(e) f(\tilde{e}) - \frac{1}{2} \sum_{e} \theta(e) f(\hat{e}) \\ &= \frac{1}{2} \sum_{v} f(v) \sum_{e: \check{e} = v} \theta(e) - \frac{1}{2} \sum_{v} f(v) \sum_{e: \hat{e} = v} \theta(v) \\ &\stackrel{1:}{=} \sum_{v} f(v) \cdot d^* \theta(v) \\ &= \langle d^* \theta, f \rangle \end{split}$$

Remark.

We have the following results:

• Ohm's law: $dU(e) = i(e) \cdot r_e$;

• Kirchhoff's node law: $d^*i(v) = 0$ for $v \in V \setminus (A \cup Z)$.

Definition 21 (Flow and strength).

 θ is called a *flow* ffrom A to Z if

1) $d^*\theta \ge 0$ on A;

2) $d^*\theta = 0$ on $V \setminus (A \cup Z)$;

3) $d^*\theta < 0$ on Z.

We define the strength of a flow θ as strength $(\theta) = \sum_{a \in A} d^*\theta(a)$.

Lemma 8 (Flow conversion).

Let G be a finite graph and theta be a flow from A to Z with $A, Z \subseteq V$ and $A \cap Z = \emptyset$. Then,

$$\sum_{a \in A} d^*\theta(a) = -\sum_{z \in Z} d^*\theta(z)$$

Furthermore, if $f: V \to \mathbb{R}$ such that $f|_A = \alpha$ and $f|_Z = \zeta$, then $\langle \theta, df \rangle = \operatorname{strength}(\theta)(\alpha - \zeta)$.

Proof. We show the proof in two steps:

1. We have by defintion of the scalar product

$$\sum_{a \in A} d^* \theta(a) + \sum_{v \in V \setminus (A \cap Z)} d^* \theta(v) + \sum_{z \in Z} d^* \theta(z) = \langle d^* \theta, \mathbb{1}_V \rangle$$
$$= \langle \theta, d \mathbb{1}_V \rangle$$
$$= 0$$

2. To show the second statement, notice that

$$\begin{split} \langle \theta, df \rangle &= \langle d^*\theta, f \rangle \\ &= \sum_{v \in V} d^*\theta(v) \cdot f(v) \\ &= \sum_{a \in A} d^*\theta(a) \cdot f(a) + \sum_{z \in Z} d^*\theta(z) \cdot f(z) \\ &\stackrel{1}{=} \operatorname{strength}(\theta)(\alpha - \zeta) \end{split}$$

Definition 22 (Energy).

For antisymmetric functions θ, η , we define the scalar product

$$\langle \theta, \eta \rangle_r = \frac{1}{2} \sum_e \theta(e) \cdot \eta(e) \cdot r_e$$

We define the energy of an antisymmetric function θ as $\mathcal{E}(\theta) = \|\theta\|_r^2 = \frac{1}{2} \sum_e \theta(e) \cdot r_e$.

Lemma 9.

Let $i: E \to \mathbb{R}$ be a unit current flow from A to Z such that the voltage \mathcal{U} satisfies $\mathcal{U}|_A = \mathcal{U}_A$ and $\mathcal{U}|_Z = \mathcal{U}_Z$. Then, $\mathcal{E}(i) = \mathcal{U}_A - \mathcal{U}_Z = R_{\text{eff}}(A \leftrightarrow Z)$.

Proof. By Ohm's law, we have

$$\mathcal{E}(i) = \langle i, i \rangle_r$$

$$= \langle i, ri \rangle$$

$$= \langle i, dU \rangle$$

$$= (\mathcal{U}_A - \mathcal{U}_Z) \underbrace{\text{strength}(i)}_{=1}$$

$$= \mathcal{U}_A - \mathcal{U}_Z$$

Since all vertices in A have the same voltage, we can identify them as one point a. Then,

$$c_{\text{eff}}(a \leftrightarrow Z) = \sum_{x \neq a} \theta(a, x)$$
$$= \sum_{x \neq a} \frac{i(a, x)}{\mathcal{U}_A - \mathcal{U}_Z}$$
$$= \frac{1}{\mathcal{U}_A - \mathcal{U}_Z}$$

This is equivalent to $R_{\text{eff}} = \mathcal{U}_A \cdot \mathcal{U}_Z$.

Lemma 10.

Let $i: E \to \mathbb{R}$ be antisymmetric satisfying Kirchhoff's cycle law. Suppose i satisfies Kirchhoff's node law on $W \subseteq V$. Then, there exists a function (voltage) $\mathcal{U}: V \to \mathbb{R}$, such that U is harmonic on W and i is the current associated with \mathcal{U} . The voltage is unique up to addition.

Proof. We show the proof in two steps:

1. Existence: Let $v_0 \in V$ and set $\mathcal{U}(v_0) = 0$. For $u \in V$, let $(v_0, \ldots, v_N = u)$ be a path from v_0 to u. We define

$$\mathcal{U}(u) = \sum_{n=1}^{N} r_{\{v_{n-1}, v_n\}} i(v_n, v_{n-1})$$

Let $(w_0 = v_0, \ldots, w_m = v_n)$ be a second path, then $(v_0, \ldots, v_n = w_m, \ldots, w_0 = v_0)$ is a cycle, Thus,

$$\sum_{n=1}^{N} r_{\{v_{n-1}, v_n\}} i(v_n, v_{n-1}) = 0$$

Thus, \mathcal{U} is well-defined. For $\{u,v\}\in E$, we can join the edge to the path

$$\mathcal{U}(v) = \mathcal{U} + r_{\{u,v\}}i(v,u)$$

Then, we have $i(v, u) = \frac{1}{r_{\{u,v\}}} (\mathcal{U}(v) - \mathcal{U}(u))$. Then, the current i is associated to \mathcal{U} . Harmonicity on W follows from Kirchhoff's node law.

2. Uniqueness: For a given $\mathcal{U}(v_0)$, we can define $\mathcal{U}(u)$ inductively by Ohm's law.

1.2.1 Thomson's principle and corollaries

Theorem 3 (Thomson's principle).

It holds

$$R_{\text{eff}}(a, z) = \inf \{ \mathcal{E}(F) \mid F \text{ unit flow from } a \text{ to } z \}$$

Furthermore, the infimum is attained at the unit current flow.

Corollary 1.

Let $G_1 = (V, E_1, c_1)$ and $G_2 = (V, E_2, c_2)$, $a \neq z \in V$. Assume $E_1 \subseteq E_2$ and for all $e \in E_1$, we have $c_2(e) \geq c_1(e)$. Then,

$$\begin{split} C_{\text{eff}}^{G_1}(a,z) &\leq C_{\text{eff}}^{G_2}(a,z) \\ \mathbb{P}^{G_2}(\tau_z < \eta_a) &\geq \mathbb{P}^{G_2}(\tau < \eta_a). \end{split}$$

Proof. Let I be the unit current flow from a to z in G_1 . Then,

$$\begin{split} R_{\text{eff}}^{G_2} &= \inf_F \mathcal{E}^{G_2}(F) \\ &\leq \mathcal{E}^{G_2}(I) \\ &= \sum_{e \in E_2} \frac{|I(e)|^2}{c_2(e)} \\ &\stackrel{(a)}{=} \sum_{e \in E_1} \frac{|I(e)|^2}{c_2(e)} \\ &\leq \sum_{e \in E_1} \frac{|I(e)|^2}{c_2(e)} \\ &= \mathcal{E}^{G_1}(I) \\ &= R_{\text{eff}}^{G_1}(a, z) \end{split}$$

Hence, $C_{\text{eff}}^{G_1}(a,z) \leq C_{\text{eff}}^{G_2}(a,z)$. The second result follows from noting that

$$\mathbb{P}^{G_2}(\tau_z < \eta_a) = \frac{C_{\text{eff}}^{G_2}(a, z)}{c^{G_2}(a)}$$

$$\geq \frac{C_{\text{eff}}^{G_1}(a, z)}{c^{G_1}(a)}$$

$$= \mathbb{P}^{G_2}(\tau_z < \eta_a)$$

Corollary 2 (Monotonicity of effective conductance).

Let G = (V, E, c) be a network, $a \in V$, $\emptyset \neq Z_1 \subseteq Z_2 \subseteq V \setminus \{a\}$. Then, $C_{\text{eff}}(a, Z_1) \leq C_{\text{eff}}(a, Z_2)$.

Definition 23 (Exhaustion).

Let G = (V, E, c) be an infinite, locally finite, connected graph (including \mathbb{Z}^d , regular trees, Cayley graphs). A sequence $(V_n)_n$ of sets of vertices is called an *exhaustion* of the graph if

- 1) for all $n \in \mathbb{N}$, $|V_n| < \infty$;
- 2) for all $n \in \mathbb{N}$, $V_n \subseteq V_{n+1} \subseteq V$;
- 3) $\bigcup_{n=1}^{\infty} V_n = V$.

We define $G_n := G/(V \setminus C_n)$ as the graph with $V \setminus V_n$ reduced to a single vertex.

Definition 24 (Effective conductance to infinity).

Let $a \in V$. We define the effective conductance between a and ∞ as

$$C_{\mathrm{eff}}(a,\infty) = \lim_{n \to \infty} C_{\mathrm{eff}}^{G_n}(a, V \setminus V_n).$$

 ${f Fact}$ (Well-definedness of effective conductance to infinity).

The conductance $C_{\text{eff}}(a, \infty) = \lim_{n \to \infty} C_{\text{eff}}^{G_n}(a, V \setminus V_n)$ is well-defined.

Proof. We have to show existence of the limit and independence of the choice of exhaustion.

- 1. Existence: By monotonicity of effective conductance, $C_{\text{eff}}(a, G \setminus V_n) \ge C_{\text{eff}}(a, G \setminus V_{n+1})$. Hence $(C_{\text{eff}}(a, G \setminus V_n))$ is monotonically decreasing. It is also bounded from below, hence convergent.
- 2. Let $(V_n)_n$ and $(W_n)_n$ be two exhaustions. Then, for each n there is some m such that $V_n \subseteq W_m$ and vice-versa. Thus,

$$\lim_{m \to \infty} C_{\text{eff}}(a, G \setminus W_m) \le C_{\text{eff}}(a, G \setminus V_n) \xrightarrow[n \to \infty]{} \lim_{n \to \infty} C_{\text{eff}}(a, G \setminus V_n)$$

$$\lim_{n \to \infty} C_{\text{eff}}(a, G \setminus V_n) \le C_{\text{eff}}(a, G \setminus W_m) \xrightarrow[m \to \infty]{} \lim_{m \to \infty} C_{\text{eff}}(a, G \setminus W_m)$$

Thus, we have equality.

Theorem 4.

The random walk starting at a is recurrent if and only if $R_{\text{eff}}(a, \infty) = \infty$ (i.e. $C_{\text{eff}}(a, \infty) = 0$).

Proof. Let $(V_n)_n$ be an exhaustion. Then,

$$\begin{split} \mathbb{P}(\eta_a < \infty) &= \lim_{n \to \infty} \mathbb{P}(\eta < \tau_{G \setminus V_n}) \\ &= 1 - \lim_{n \to \infty} \mathbb{P}(\eta_a > \tau_{G \setminus V_n}) \\ &= 1 - \frac{1}{c(a)} \lim_{n \to \infty} C_{\text{eff}}(a, G \setminus V_n) \\ &= 1 - \frac{C_{\text{eff}}(a, \infty)}{\underbrace{c(a)}_{\in (0, \infty)}} \end{split}$$

 $R_{\text{eff}}(a,\infty) = \infty$ is equivalent to $C_{\text{eff}}(a,\infty) = 0$. By our calculations, this is equivalent to $\mathbb{P}(\eta_a < \infty) = 1$.

12

Theorem 5 (Thomson's principle for infinite networks).

A unit flow from a to ∞ in G is an antisymmetric edge function F such that for all $u \in V$, we have

$$\sum_{v \neq u} F(u, v) = \begin{cases} [1, & x = a \\ 0, & x \neq a \end{cases}$$

Then,

$$R_{\mathrm{eff}}(a,\infty) = \inf\{\mathcal{E}(F) \,|\, F \text{ is unit flow from } a \text{ to } \infty\} \quad \text{for } \mathcal{E}(F) := \sum_e \frac{\left|F(e)\right|^2}{c(e)}.$$

Remark.

In order to prove that a graph (or network) is transient, all we need to find is a flow of finite energy

Example 1 (Binary tree).

What is $\mathcal{E}(F)$ of a binary tree with three edges at the origin? At level n, we have $3 \cdot 2^n$ edges, each carries a flow of $(3 \cdot 2^n)^{-1}$. Thus, $\mathcal{E}(F) = \sum_{n=0}^{\infty} 3 \cdot 2^n \cdot 3 \cdot 2^{n-2} < \infty$.

- 2 Chapter two
- 3 Chapter three
- 4 Chapter four
- 5 Chapter five
- 6 Chapter six

A Measure theory

Theorem 6 (Layer-cake representation).

Let $f: \Omega \to \mathbb{R}$ such that $f \geq 0, f' \geq 0$. Then

$$\mathbb{E}[f(X)] = \int_0^\infty \mathbb{P}(f(X) > t) \, \mathrm{d}t = \int_{f^{-1}(0)}^{f^{-1}(\infty)} \mathbb{P}(X > t) f'(t) \, \mathrm{d}t$$

A.1 Convergence

Theorem 7 (Fatou's lemma).

Let $(X_n)_n$ consist of non-negative random variables. Then,

$$\mathbb{E}[\underline{\lim}_{n\to\infty} X_n] \le \underline{\lim}_{n\to\infty} \mathbb{E}[X_n]$$

Theorem 8 (Monotone convergence theorem).

Let $(X_n)_n$ consist of non-negative increasing random variables. Then,

$$\mathbb{E}[\lim_{n\to\infty} X_n] = \lim_{n\to\infty} \mathbb{E}[X_n]$$

Theorem 9 (Dominated convergence theorem).

Let $(X_n)_n$ consist of converging random variables that are absolutely dominated by $Y \in L^1(\Omega, \mathbb{P})$. Then.

$$\mathbb{E}[\lim_{n\to\infty} X_n] = \lim_{n\to\infty} \mathbb{E}[X_n]$$

B Probability theory

B.1 Calculus of probability

Theorem 10 (Chebychev's inequality).

Let $\phi : \mathbb{R} \to [0, \infty)$ be increasing. Then

$$\mathbb{P}(X \ge \lambda) \le \frac{\mathbb{E}[\phi(X)]}{\phi(\lambda)}$$

Remark.

Chebychev's inequality can be used to find sharp estimations by considering parametrized functions such as $\phi(\xi) = \exp(t\xi)$) or $\phi(\xi) = (\xi + t)^2$ and optimizing t.

Definition 25 (Limit of events).

We define

$$\overline{\lim}_{n\to\infty} A_n = \bigcap_{n=1}^{\infty} \bigcup_{k=n}^{\infty} A_n$$

$$\lim_{n \to \infty} A_n = \bigcup_{n=1}^{\infty} \bigcap_{k=n}^{\infty} A_n$$

14

Theorem 11 (Calculus of probability).

Theorem 12 (Borel-Cantelli).

Let $A_n\Omega$. Then

- 1. If $\sum_{n=1}^{\infty} \mathbb{P}(A_n) < \infty$, then $\mathbb{P}(\overline{\lim}_{n \to \infty} A_n) = 0$ (A_n happens finitely).
- 2. If $\sum_{n=1}^{\infty} \mathbb{P}(A_n) = \infty$ and $(A_n)_n$ are independent, then $\mathbb{P}(\overline{\lim}_{n\to\infty} \mathbb{P}(A_n) = 1)$

B.2 Conditional expectation

Definition 26 (Conditional expectation). Y is called \mathcal{G} -conditional expectation of X if

- 1. Y is \mathcal{G} -measurable
- 2. for each $A \in \mathcal{G}$, $\mathbb{E}[Y \mathbb{1}_A] = \mathbb{E}[X \mathbb{1}_A]$

We write $Y = \mathbb{E}[X|\mathcal{G}]$.

B.3 Radon-Nikodym theorem

Theorem 13 (Radon-Nikodym).

B.4 Stochastic processes

Definition 27 (Martingale).

Theorem 14 (Doob's maximal inequality).

B.4.1 Stopping times

Theorem 15 (Optional stopping).

C Markov chains

Definition 28 (Discrete-time Markov chain).

A discrete-time Markov chain is a sequence $X = (X_n)_n$ of random variables with

1.
$$\mathbb{P}(X_{n+1} = y \mid X_1 = x_1, \dots, X_n = x_n) = \mathbb{P}(X_{n+1} = y \mid X_n = x_n)$$

One might also use the following characterization which extends more easily to $X = (X_t)_{t \geq 0}$:

1. $\mathbb{E}_x[g \circ \theta_s \mid \mathcal{F}_s] = \mathbb{E}_{X_s}[g]$ for all measurable and bounded g

where $\mathbb{P}_x(X_0 = x) = 1$.

Definition 29 (Time-homogeneity).

A Markov chain X is called time-homogeneous if

$$\mathbb{P}(X_{n+1} = y \mid X_n = x) = \mathbb{P}(X_1 = y \mid X_0 = x)$$

Definition 30 (Stationarity).

A Markov chain X is called stationary if

$$\mathbb{P}(X_k = x_0, \dots, X_{n+k} = x_n) = \mathbb{P}(X_0 = x_0, \dots, X_n = x_n)$$

Definition 31 (Standard stopping times).

For a (right-continuous) family of random variables $X = (X_t)_{t \in \mathcal{T}}$, where we allow $\mathcal{T} = \mathbb{R}, \mathbb{N}$, we write

- 1. $\tau_x = \inf\{t > 0 \mid X_t = x\}$
- 2. $\sigma_x = \inf\{t > 0 \mid X_t \neq x\}$
- 3. $R_x^n = 0$, $R_x^{n+1} = (\tau_x \circ \theta_{\sigma_x} + \sigma_x) \circ \theta_{R_x^n} + R_x^n$

Notice that a process X is a Markov chain if $(R_x^{n+1} - R_x^n) =_d R_x^1$ and $(R_x^{n+1} - R_x^n)_n$ forms independent and identically distributed random variables. (So called recurrence times)

Remark.

The standard approach to prove statements about probabilities of Markov chains is as follows:

Definition 32 (Invariant measure).

A measure π is called invariant for the Markov chain X if $\pi\Pi = \pi$

1.
$$\pi(y) = \sum_{x} \pi(x) p(x, y)$$

Definition 33 (Reversible measure).

A measure π is called reversible for the Markov chain X if

1.
$$\pi(x)p(x,y) = \pi(y)p(y,x)$$

Definition 34 (Irreducible Markov chain).

A Markov chain X is called irreducible if for all x, y there is $n \ge 1$ such that $\mathbb{P}_x(X_n = y) > 0$.

Remark.

Irreducibility means there is the probability that a chain starting in x might reach y. It does not have to occur, though.

Definition 35 (Recurrence and transience).

x is called recurrent if $\mathbb{P}_x(R_x^1 < \infty) = 1$, otherwise transient.

Theorem 16 (Invariant distribution implies recurrence).

An irreducible Markov chain with an invariant distribution is recurrent.

Theorem 17 (Existence of an invariant measure).

An irreducible and recurrent Markov chain has an invariant distribution which is unique and strictly positive.

Theorem 18 (Characterization of invariant distribution).

Let X be a Markov chain with an invariant distribution π . Then

$$\pi(y) = \lim_{n \to \infty} \mathbb{P}_x(X_n = y)$$

regardless of the choice for x.

Theorem 19 (Cycle characterization of reversibility).

A discrete-time Markov chain X is reversible if and only if for all states x_1, \ldots, x_N with $x_1 = x_N$, we have

$$\prod_{n=1}^{N} p(x_n, x_{n+1}) = \prod_{n=1}^{N} p(x_{N-n+1}, p_{N-n})$$

Proof.