

1. PCA based data distribution visualizations

Let the data matrix \mathbf{X} be of $n \times p$ size.

First, perform SVD:

$$\mathbf{X} = \mathbf{U}\mathbf{S}\mathbf{V}^T \quad (1)$$

The columns of $\mathbf{U}\mathbf{S}$ are the principal components and the columns of \mathbf{V} are the eigenfaces.

For the principal components, only calculation for the highest dimension is necessary. For reduction to dimension k , the first k principal components can be obtained from the first k columns of \mathbf{U} and the diagonal matrix formed by the first k values along the diagonal of \mathbf{S} .

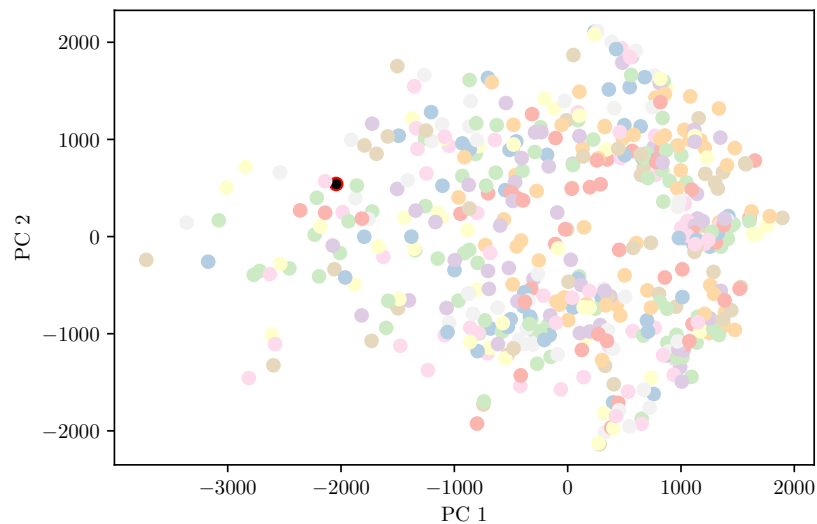


Figure 1: PCA projected data vector in 2D.

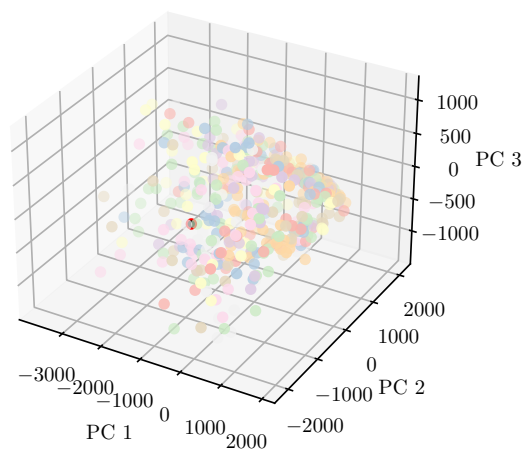
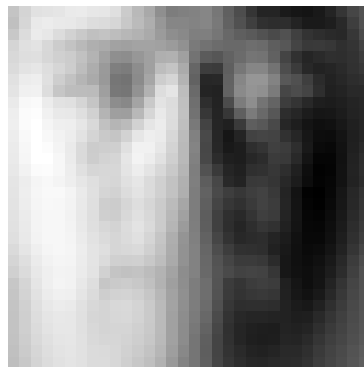


Figure 2: PCA projected data vector in 3D.



(a) eigenface 0



(b) eigenface 1



(c) eigenface 2

Figure 3: Corresponding 3 eigenfaces used for PCA dimensionality reduction.

Test Images	Dimensionality	Accuracy
CMU PIE	40	49.02 %
	80	52.47 %
	200	55.22 %
Selfies	40	0 %
	80	0 %
	200	0 %

Table 1: KNN classification accuracy for dimensionalities 40, 80 and 200 after PCA, for PIE images and selfies.

2. PCA plus nearest neighbor classification results

For classification with PCA, obtain \mathbf{XV} , projection of the faces in the test data matrix \mathbf{X} on the eigenface space. Each column of \mathbf{V} and therefore each column of \mathbf{XV} corresponds to a principal component. Again, only calculation for the highest dimension is necessary. The first k projections can be obtained with the test data matrix and the first k columns of \mathbf{V} .

It is expected that classification of selfies is unsuccessful. There are only three selfies in the test set and random sampling of 500 images for training included only one selfie which is an outlier in 3D as can be seen from the scatter plots. Moreover, my setup and lighting condition differs from those of the images in the PIE data set.

3. LDA based data distribution visualization

4. LDA plus nearest neighbor classification results

5. GMM for clustering

For GMM, the clustering result appears to be heavily influenced by shadows or dark regions in general. Each cluster occupies a row above their associated scatter plot, with every 15th face shown, up to a limit of 10. Regardless of how or whether the input was processed, there is always one row that is of relatively uniform gray level (within each image), one row with dark region on the left, and one row with dark region on the right. The algorithm does not appear to be grouping people with similar facial features together, with a European and an Asian appearing together in every cluster.

Consider the fact that we set the number of components to be 3. There are a lot of variations in facial features, but patches of black, regions of relative darkness are much more uniform. Therefore, the algorithm is working exactly as intended and grouping the most similar images together, those with the same illumination.

For clustering by facial features, we would need to set the number of components to be the number of distinct faces in the dataset. With 3 components, we are doing clustering by illumination.

Clustering by illumination also means that PCA, which finds components reflecting the largest sources of variance works extremely well for reducing the number of dimensions. In this case, illumination is the largest source of variation.

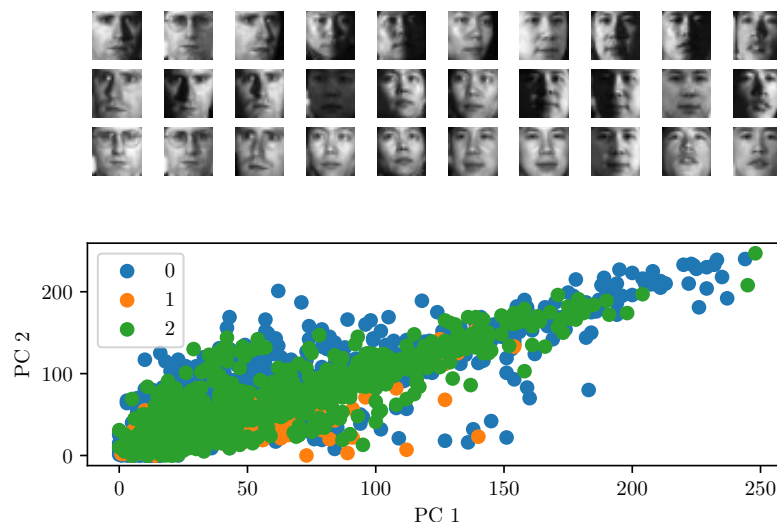


Figure 4: GMM clustering for raw face images (vectorized).

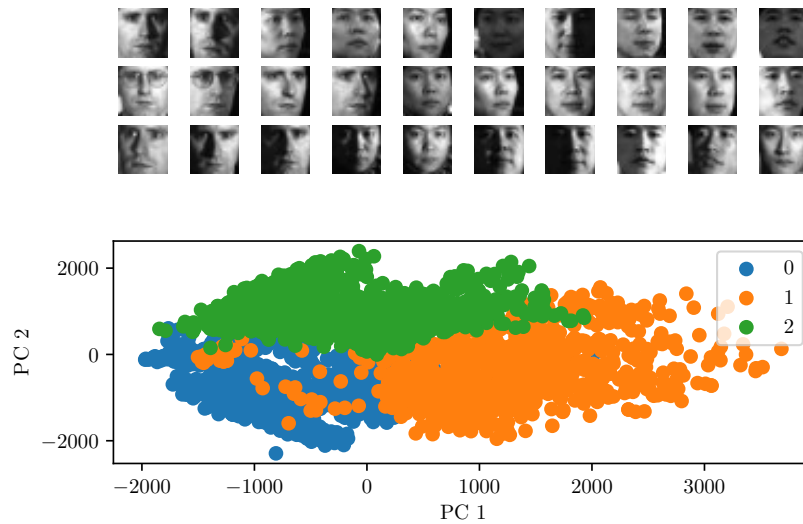


Figure 5: GMM clustering for face vectors after PCA pre-processing (with dimensionality of 200).

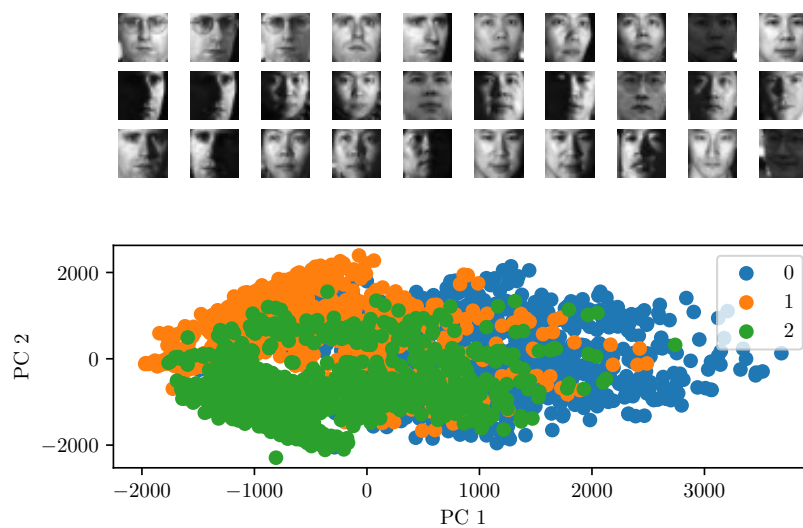


Figure 6: GMM clustering for face vectors after PCA pre-processing (with dimensionality of 80).

6. SVM classification results with different parameter values

From Tab. 2, we can see that SVM classification achieves much higher accuracy than that of KNN in Tab. 1. More principle components improves the classification accuracy, with 200 principle components, the classification accuracy is the same as using raw images.

However, the parameter C appears to have no impact on the classification accuracy. There is an explanation online for this [1]. Of the two criteria, the use of a linear SVM is stated in the instructions for this assignment.

According to Rasmussen & Williams [2], "In a feature space of dimension N , if $N > n$ then there will always be a separating hyperplane. However this hyperplane may not give rise to good generalization performance, especially if some of the labels are incorrect."

For PCA, 500 data points were sampled, less than 1024. The data is linearly separable, meeting the other criterion.

Therefore, "if C values change within a reasonable range, the optimal hyperplane will just randomly shift by a small amount within the margin (the gap formed by the support vectors). Intuitively, suppose the margin on training data is small, and/or there is no test data points within the margin too, the shifting of the optimal hyperplane within the margin will not affect classification error of the test set."

Test Images	C	Accuracy
Raw	0.01	98.4351 %
	0.1	98.4351 %
	1	98.4351 %
PCA (200)	0.01	98.4351 %
	0.1	98.4351 %
	1	98.4351 %
PCA (80)	0.01	97.9656 %
	0.1	97.9656 %
	1	97.9656 %

Table 2: SVM classification accuracy for dimensionalities 40, 80 and 200 after PCA.

7. CNN classification results with different network architectures

For CNN, the accuracy ranges from 95.00 % to 97.00 % with shuffling of the order of images.

Following the updated instructions received via email, my model includes two convolutional layers and two fully connected layers. The updated number of nodes is "20-50-500-26". There is an additional scaling layer at the start to scale the range of each pixel from the range 0–255 to 0–1. Although often recommended, scaling does not seem to improve the classification accuracy of this model.

For previous parts of this assignment, labels were taken directly from the folder names in the provided PIE dataset. However, for CNN, one hot encoding is necessary because there is no natural ordinal relationship for the order of PIE subjects. For classification of two or more labels using one-hot encoded representation, categorical crossentropy is the option in Keras. The final layer uses a softmax function to convert logits to probabilities. Otherwise, ReLU is used to introduce nonlinearity.

The latest optimizer offered by Keras, the AMSGrad variant of ADAM was used for best performance. As ADAM is an adaptive algorithm, no tuning of the learning rate was necessary or offered any improvement to classification accuracy.

```

Model: "sequential"
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Layer (type)                 Output Shape              Param #
-----
rescaling (Rescaling)        (None, 32, 32, 1)        0
conv2d (Conv2D)               (None, 28, 28, 20)       520
max_pooling2d (MaxPooling2D) (None, 14, 14, 20)       0
conv2d_1 (Conv2D)             (None, 10, 10, 50)      25050
max_pooling2d_1 (MaxPooling2D) (None, 5, 5, 50)       0
flatten (Flatten)            (None, 1250)              0
dense (Dense)                 (None, 500)              625500
dense_1 (Dense)               (None, 26)               13026
-----
Total params: 664,096
Trainable params: 664,096
Non-trainable params: 0
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```

For simplicity, I arbitrarily set the number epochs to 100 with batch size of 128.

It takes about 55 epochs to reach 100 % accuracy on the training set and for the training loss to fall from an initial value of about 3.25 to 0.

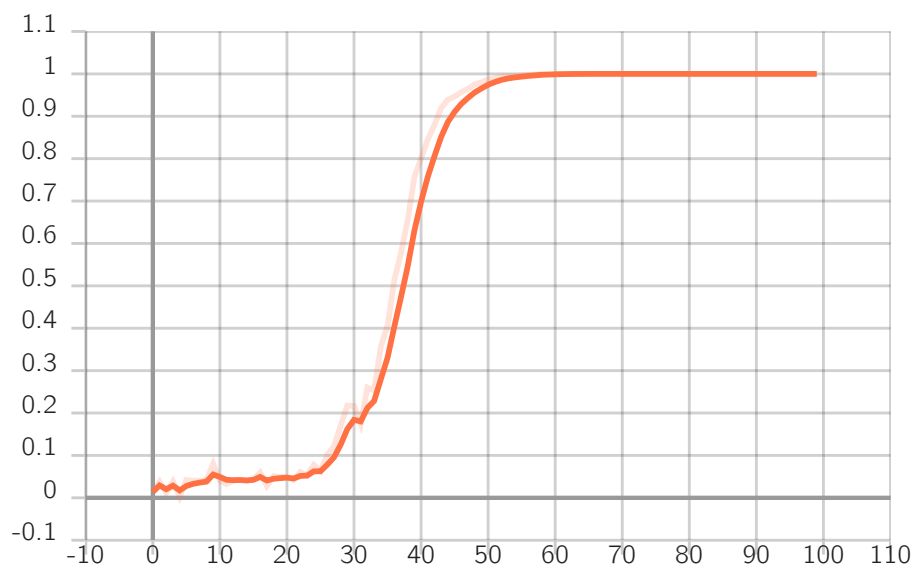


Figure 7: Epoch accuracy.

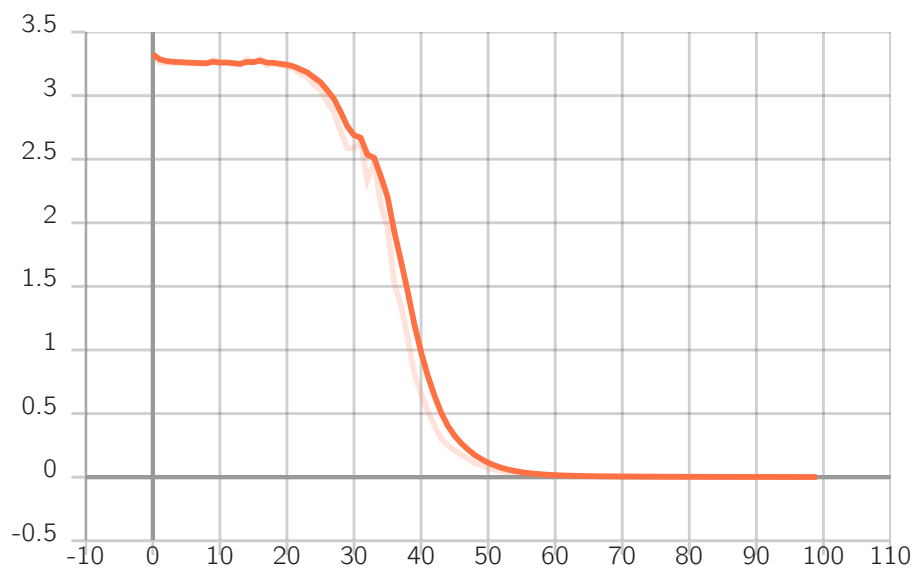


Figure 8: Epoch loss.

References

- [1] luz (<https://stats.stackexchange.com/users/133311/luz>), "What is the influence of c in svms with linear kernel?" Cross Validated, uRL:<https://stats.stackexchange.com/q/238209> (version: 2016-10-04). [Online]. Available: <https://stats.stackexchange.com/q/238209>
- [2] C. E. Rasmussen and C. K. I. Williams, *Gaussian Processes for Machine Learning (Adaptive Computation and Machine Learning)*. The MIT Press, 2005.