SF2943 Time Series Analysis: Lecture 4

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In this lecture, we will revisit the AR(1) process and introduce the ARMA(1,1), which combines the features of the AR(1) process and the MA(1) process. In particular, we will discuss the existence and uniqueness of these two processes.

1 Linear Process and Linear Filter

Before proceeding, we introduce a convenient notation.

Definition 1.1 The backward shift operator B is given by

$$BX_t = X_{t-1}.$$

Also, define B^0 as the identity operator I which satisfies $IX_t = X_t$, and for any $q \in \mathbb{N}$, denote

$$B^q X_t = B(B^{q-1} X_t).$$

With this notation, we know that $B^q X_t = X_{t-q}$ for any q. Furthermore, for any linear process $\{X_t\}$, it can be written as

$$X_t = \psi(B)Z_t$$

where $\{Z_t\} \sim \text{WN}(0, \sigma^2)$ and

$$\psi(B) \doteq \sum_{j=-\infty}^{\infty} \psi_j B^j$$

with

$$\sum_{j=-\infty}^{\infty} |\psi_j| < \infty.$$

This $\psi(B)$ is called a linear filter. Using this terminology, we can restate the last proposition and corollary mentioned in the previous lecture as the following:

1. If one applies a linear filter $\psi(B)$ to $\{Z_t\} \sim \text{WN}(0, \sigma^2)$, then one gets a linear process $\{X_t\}$ with acvf

$$\gamma_X(h) = \sum_{\ell = -\infty}^{\infty} \psi_{\ell} \psi_{\ell + h} \sigma^2. \tag{1.1}$$

2. If one applies a linear filter $\psi(B)$ to a stationary process $\{Y_t\}$ with acvf γ_Y , then the resulting process $\{X_t\}$ is a stationary process with acvf

$$\gamma_X(h) = \sum_{j=-\infty}^{\infty} \sum_{k=-\infty}^{\infty} \psi_j \psi_k \gamma_Y(h+k-j).$$

Another feature of linear filters is that the resulting process after applying two linear filters is independent of the order. To be more precise, let $\alpha(B) = \sum_{j=\infty}^{\infty} \alpha_j B^j$ and $\beta(B) = \sum_{j=\infty}^{\infty} \beta_j B^j$ be two linear filters, and $\{Y_t\}$ be a stationary process. Then $\alpha(B)[\beta(B)Y_t] = \beta(B)[\alpha(B)Y_t]$.

$2 \quad AR(1)$ process revisit

In the second lecture, we defined AR(1) process as a stationary process $\{X_t\}$ such that

$$X_t = \phi X_{t-1} + Z_t \text{ for all } t \tag{2.1}$$

with $\{Z_t\} \sim \text{WN}(0, \sigma^2)$, $|\phi| < 1$ and we assume that Z_t and X_s are uncorrelated for any s < t. However, we did not discuss if such a process exists or not. In this section, we will show the existence of such process. In fact, we will find a solution as a linear process and show this solution is only solution.

2.1 Existence

To find a possible solution, we make the following observation by using (2.1) repeatedly:

$$X_{t} = \phi X_{t-1} + Z_{t}$$

$$= \phi(\phi X_{t-2} + Z_{t-1}) + Z_{t} = \phi^{2} X_{t-2} + (\phi Z_{t-1} + Z_{t})$$

$$= \phi^{2}(\phi X_{t-3} + Z_{t-2}) + \phi Z_{t-1} + Z_{t} = \phi^{3} X_{t-3} + (\phi^{2} Z_{t-2} + \phi Z_{t-1} + Z_{t})$$

$$= \cdots = \phi^{n} X_{t-n} + (\phi^{n-1} Z_{t-(n-1)} + \cdots + \phi Z_{t-1} + Z_{t}).$$

This suggests that

$$X_{t} = Z_{t} + \phi Z_{t-1} + \phi^{2} Z_{t-2} + \dots = \sum_{j=0}^{\infty} \phi^{j} Z_{t-j}$$
(2.2)

could be a solution to (2.1). Since $|\phi| < 1$, we have

$$\sum_{j=0}^{\infty} |\phi|^j = \frac{1}{1-|\phi|} < \infty.$$

Thus, $\{X_t\}$ defined as (2.2) is a stationary linear process. Moreover, this $\{X_t\}$ satisfies (2.1) because for any t,

$$X_t - \phi X_{t-1} = \sum_{j=0}^{\infty} \phi^j Z_{t-j} - \sum_{j=0}^{\infty} \phi^j Z_{t-1-j} = \sum_{j=0}^{\infty} \phi^j Z_{t-j} - \sum_{k=1}^{\infty} \phi^k Z_{t-k} = Z_t.$$

Therefore, we show the existence of AR(1) process.

2.2 Uniqueness

For the uniqueness, we need to define a proper metric space.

Definition 2.1 $\sum_{k=1}^{n} X_k$ converges in mean square if there exists a random variable S such that

$$E\left[\left(\sum_{k=1}^{n} X_k - S\right)^2\right] \to 0 \text{ as } n \to \infty.$$

We say that this random variable S is the limit of $\{\sum_{k=1}^n X_k\}$ and use the notation $S \doteq \sum_{k=1}^\infty X_k$.

Remark 2.2 For those who know real analysis, this limit is unique in L^2 space.

For uniquesness of AR(1) process, suppose $\{Y_t\}$ is another AR(1) process, it means that $\{Y_t\}$ is stationary and $Y_t = \phi Y_{t-1} + Z_t$ for all t. By using this recursion repeatedly, we find

$$Y_t = \phi Y_{t-1} + Z_t = \dots = \sum_{j=0}^k \phi^j Z_{t-j} + \phi^{k+1} Y_{t-(k+1)}.$$

This implies that

$$E\left[\left(Y_{t} - \sum_{j=0}^{k} \phi^{j} Z_{t-j}\right)^{2}\right] = E\left[\left(\phi^{k+1} Y_{t-(k+1)}\right)^{2}\right] = \phi^{2k+2} E\left[\left(Y_{t-(k+1)}\right)^{2}\right] = \phi^{2k+2} \gamma_{Y}(0) \to 0,$$

as $k \to \infty$. Therefore,

$$Y_t = \sum_{j=0}^{\infty} \phi^j Z_{t-j} = X_t.$$

2.3 Autocovariance function

In the second lecture, we showed how to derive the acvf for an AR(1) process by deriving a recursive equation for $\gamma_X(h)$. In this subsection, we will use another method that simply utilizes the formula for acvf of a linear process (1.1). Recall that

$$X_t = \sum_{j=0}^{\infty} \phi^j Z_{t-j}.$$

In the notation of a linear process

$$X_t = \sum_{j=-\infty}^{\infty} \psi^j Z_{t-j}$$

with

$$\psi_j = \begin{cases} \phi^j, & \text{for } j \ge 0\\ 0, & \text{for } j < 0. \end{cases}$$

Hence, for any $h \ge 0$,

$$\gamma_X(h) = \sum_{\ell=-\infty}^{\infty} \psi_{\ell} \psi_{\ell+h} \sigma^2 = \sum_{\ell=0}^{\infty} \phi^{\ell} \phi^{\ell+h} \sigma^2 = \sum_{\ell=0}^{\infty} \phi^{2\ell+h} \sigma^2 = \frac{\sigma^2 \phi^h}{1 - \phi^2}.$$

Since acvf is even, for h < 0, we have

$$\gamma_X(h) = \gamma_X(-h) = \frac{\sigma^2 \phi^{-h}}{1 - \phi^2}.$$

2.4 Formal derivation of the solution

In this subsection we introduce a formal way to derive the solution. We will use this technique many times in our next few lectures. Recall that B is the backward shift operator. We can rewrite the recursion (2.1) as

$$\phi(B)X_t = Z_t, \tag{2.3}$$

where $\phi(B) = I - \phi B$. Since $|\phi| < 1$, we know that for any $|x| \le 1$

$$\chi(x) = \frac{1}{1 - \phi x} = \sum_{j=0}^{\infty} \phi^j x^j.$$

Consider a linear filter

$$\chi(B) = \sum_{j=0}^{\infty} \phi^j B^j.$$

We know $\chi(B)\phi(B)=I$ and apply the linear filter $\chi(B)$ to both sides of (2.3) to find the solution

$$X_t = \chi(B)Z_t = \left(\sum_{j=0}^{\infty} \phi^j B^j\right) Z_t = \sum_{j=0}^{\infty} \phi^j Z_{t-j}.$$

3 Causality and Invertibility

Let $\{Z_t\} \sim WN(0, \sigma^2)$. Recall that an AR(1) process $\{X_t\}$ can be represented as

$$X_t = \sum_{i=0}^{\infty} \phi^j Z_{t-j}.$$

And a MA(1) process $\{X_t\}$ can be represented as

$$X_t = Z_t + \theta Z_{t-1}.$$

From here we see that both processes at time t can be represented as a function of the white noise at "the past and present", i.e., Z_s with $s \le t$. We call processes with this property causal.

Definition 3.1 We say that a time series $\{X_t\}$ is a causal (or future-independent) function of $\{Z_t\}$ if X_t has a representation in terms of $\{Z_s, s \leq t\}$. If $\{X_t\}$ is not causal, we call it noncausal.

Causality means that X_t can be expressed in terms of $\{Z_s, s \leq t\}$. A dual concept, called invertibility, refers to that Z_t can be expressed in terms of $\{X_s, s \leq t\}$.

Definition 3.2 We say that a time series $\{X_t\}$ is a invertible function of $\{Z_t\}$ if Z_t has a representation in terms of $\{X_s, s \leq t\}$. If $\{X_t\}$ is not invertible, we call it noninvertible.

4 ARMA(1,1) Process

We can combine the features of both an AR(1) process and a MA(1) process to create ARMA(1,1) process.

Definition 4.1 A time series $\{X_t\}$ is an autoregressive moving average process of order (1,1) (or an ARMA(1,1) process) if $\{X_t\}$ is stationary and satisfies

$$\underbrace{X_t - \phi X_{t-1}}_{autoregressive\ part} = \underbrace{Z_t + \theta Z_{t-1}}_{moving\ average\ part} for\ all\ t,$$
(4.1)

where $\{Z_t\} \sim WN(0, \sigma^2)$ and $\phi + \theta \neq 0$.

Remark 4.2 If we use the backward shift operator notation B, then (4.1) is equivalent to

$$\phi(B)X_t = \theta(B)Z_t \qquad \text{for all } t \tag{4.2}$$

with $\phi(z) = 1 - \phi z$ and $\theta(z) = 1 + \theta z$. Notice that if $\phi + \theta = 0$, then $\phi(z) = 1 - \phi z = 1 + \theta z = \theta(z)$, which indicates that $X_t = Z_t$. Therefore, we require $\phi + \theta \neq 0$ to ensure that $\{X_t\}$ is not simply white noise.

4.1 Existence, uniqueness, and causality

A natural question to ask is for what values of ϕ and θ , there exists such a stationary process satisfying (4.1). We will answer this question by analyzing different ϕ .

Case 1: $|\phi| < 1$

In this case, we can consider the inverse function of $\phi(z)$,

$$\chi(z) = \frac{1}{\phi(z)} = \frac{1}{1 - \phi z} = \sum_{j=0}^{\infty} \phi^j z^j.$$

This function is well-defined for all $|z| \leq 1$ and $\chi(z)\phi(z) = 1$. As a result, we can apply the linear filter $\chi(B)$ to both sides of (4.2) can get

$$X_t = \chi(B)\phi(B)X_t = \chi(B)\theta(B)Z_t.$$

If we define $\psi(B) = \chi(B)\theta(B)$, then

$$\psi(z) = \chi(z)\theta(z) = \left(\sum_{j=0}^{\infty} \phi^{j} z^{j}\right) (1 + \theta z) = \sum_{j=0}^{\infty} \phi^{j} z^{j} + \theta \sum_{j=0}^{\infty} \phi^{j} z^{j+1}$$

$$= \sum_{j=0}^{\infty} \phi^{j} z^{j} + \theta \sum_{\ell=1}^{\infty} \phi^{\ell-1} z^{\ell} = 1 + \sum_{j=1}^{\infty} \phi^{j} z^{j} + \theta \sum_{j=1}^{\infty} \phi^{j-1} z^{j}$$

$$= 1 + \sum_{j=1}^{\infty} (\theta + \phi) \phi^{j-1} z^{j}.$$

Notice that $\psi(B)$ is a well-defined linear filter since

$$\sum_{j=1}^{\infty} (\theta + \phi)\phi^{j-1} = (\theta + \phi)\sum_{j=1}^{\infty} \phi^{j-1} = (\theta + \phi)\frac{1}{1 - \phi} < \infty.$$

Thus,

$$X_{t} = \chi(B)\theta(B)Z_{t} = \psi(B)Z_{t} = \left(I + \sum_{j=1}^{\infty} (\theta + \phi)\phi^{j-1}B^{j}\right)Z_{t} = Z_{t} + \sum_{j=1}^{\infty} (\theta + \phi)\phi^{j-1}Z_{t-j}.$$

This indicates that $\{X_t\}$ is a linear process; thus, it is stationary. Moreover, $\{X_t\}$ is causal. The uniqueness follows from the same argument as we did for the AR(1) process.

Remark 4.3 $\{X_t\}$ is also a $MA(\infty)$ process with $\theta_j = (\theta + \phi)\phi^{j-1}$ for all $j \in \mathbb{N}$.

Case 2: $|\phi| > 1$

In this case, we can consider the inverse function of $\phi(z)$,

$$\chi(z) = \frac{1}{\phi(z)} = \frac{1}{1 - \phi z} = \frac{-(\phi z)^{-1}}{-(\phi z)^{-1} + 1} = -(\phi z)^{-1} \frac{1}{1 - (\phi z)^{-1}}$$
$$= -(\phi z)^{-1} \sum_{j=0}^{\infty} \phi^{-j} z^{-j} = -\sum_{j=1}^{\infty} \phi^{-j} z^{-j}.$$

This function is well-defined for all $|z| \ge 1$ and $\chi(z)\phi(z) = 1$. As a result, we can apply the linear filter $\chi(B)$ to both sides of (4.2) can get

$$X_t = \chi(B)\phi(B)X_t = \chi(B)\theta(B)Z_t.$$

If we define $\psi(B) = \chi(B)\theta(B)$, then

$$\psi(z) = \chi(z)\theta(z) = \left(-\sum_{j=1}^{\infty} \phi^{-j} z^{-j}\right) (1 + \theta z) = -\sum_{j=1}^{\infty} \phi^{-j} z^{-j} - \theta \sum_{j=1}^{\infty} \phi^{-j} z^{-j+1}$$

$$= -\sum_{j=1}^{\infty} \phi^{-j} z^{-j} - \theta \sum_{\ell=0}^{\infty} \phi^{-\ell-1} z^{-\ell} = -\sum_{j=1}^{\infty} \phi^{-j} z^{-j} - \theta \phi^{-1} - \theta \sum_{j=1}^{\infty} \phi^{-j-1} z^{-j}$$

$$= -\theta \phi^{-1} - \sum_{j=1}^{\infty} (\theta + \phi) \phi^{-j-1} z^{-j}.$$

Notice that $\psi(B)$ is a well-defined linear filter since

$$\sum_{j=1}^{\infty} (\theta + \phi) \phi^{-j-1} = (\theta + \phi) \sum_{j=1}^{\infty} \phi^{-j-1} = (\theta + \phi) \frac{\phi^{-2}}{1 - \phi^{-1}} < \infty.$$

Thus,

$$X_{t} = \chi(B)\theta(B)Z_{t} = \psi(B)Z_{t} = \left(-\theta\phi^{-1}I - \sum_{j=1}^{\infty}(\theta + \phi)\phi^{-j-1}B^{-j}\right)Z_{t}$$
$$= -\theta\phi^{-1}Z_{t} - \sum_{j=1}^{\infty}(\theta + \phi)\phi^{-j-1}Z_{t+j}.$$

This indicates that $\{X_t\}$ is a linear process, thus, it is stationary. Moreover, $\{X_t\}$ is noncausal since X_t is not a function of $\{Z_s, s \leq t\}$. The uniqueness follows by the same argument as we did for AR(1) process.

Case 3: $|\phi| = 1$

There is no stationary solution of (4.1). Consequently, there is no well-defined ARMA(1,1) process in this case.

Remark 4.4 To sum up, the existence, uniqueness and causality of an ARMA(1,1) process depends only on the value ϕ (independent of the value of θ as long as $\phi + \theta \neq 1$). When $|\phi| \neq 1$, we have the existence and uniqueness. Moreover, when $|\phi| < 1$, the ARMA(1,1) process is causal. When $|\phi| > 1$, the ARMA(1,1) process is noncausal.

4.2 Invertibility

It turns out that the invertibility depends only on the value of θ .

Case 1: $|\theta| < 1$

In this case, we can consider the inverse function of $\theta(z)$,

$$\xi(z) = \frac{1}{\theta(z)} = \frac{1}{1 + \theta z} = \sum_{j=0}^{\infty} (-\theta)^j z^j.$$

This function is well-defined for all $|z| \le 1$ and $\xi(z)\theta(z) = 1$. As a result, we can apply the linear filter $\xi(B)$ to both sides of (4.2) can get

$$Z_t = \xi(B)\theta(B)Z_t = \xi(B)\phi(B)X_t.$$

If we define $\pi(B) = \xi(B)\phi(B)$, then

$$\pi(z) = \xi(z)\phi(z) = \left(\sum_{j=0}^{\infty} (-\theta)^{j} z^{j}\right) (1 - \phi z) = \sum_{j=0}^{\infty} (-\theta)^{j} z^{j} - \phi \sum_{j=0}^{\infty} (-\theta)^{j} z^{j+1}$$

$$= \sum_{j=0}^{\infty} (-\theta)^{j} z^{j} - \phi \sum_{\ell=1}^{\infty} (-\theta)^{\ell-1} z^{\ell} = 1 + \sum_{j=1}^{\infty} (-\theta)^{j} z^{j} - \phi \sum_{j=1}^{\infty} (-\theta)^{j-1} z^{j}$$

$$= 1 - \sum_{j=1}^{\infty} (\theta + \phi)(-\theta)^{j-1} z^{j}.$$

Notice that $\pi(B)$ is a well-defined linear filter since

$$\sum_{j=1}^{\infty} (\theta + \phi)(-\theta)^{j-1} = (\theta + \phi) \sum_{j=1}^{\infty} (-\theta)^{j-1} = (\theta + \phi) \frac{1}{1+\theta} < \infty.$$

Thus,

$$Z_t = \xi(B)\phi(B)X_t = \pi(B)X_t = \left(I - \sum_{j=1}^{\infty} (\theta + \phi)(-\theta)^{j-1}B^j\right)X_t = X_t - \sum_{j=1}^{\infty} (\theta + \phi)(-\theta)^{j-1}X_{t-j}.$$

This indicates that $\{X_t\}$ is invertible.

Case 2: $|\theta| > 1$

In this case, using a similar argument we can find that

$$Z_t = -\phi \theta^{-1} X_t + \sum_{i=1}^{\infty} (\theta + \phi) (-\theta)^{-j-1} X_{t+j}.$$

Hence, $\{X_t\}$ is noninvertible.

Remark 4.5 To sum up, the invertibility of an ARMA(1,1) process depends only on the value θ (independent of the value of ϕ as long as $\phi + \theta \neq 1$). The ARMA(1,1) process is invertible if and only if $|\theta| < 1$.